1 Definition

The Laplace transform is an operator that transforms a function of time, \( f(t) \), into a new function of complex variable, \( F(s) \), where \( s = \sigma + j\omega \), as illustrated in Figure 1. The operator \( \mathcal{L} \) denotes that the time function \( f(t) \) has been transformed to its Laplace transform, denoted \( F(s) \). The Laplace transform is very useful in solving linear differential equations and hence in analyzing control systems.

To obtain the Laplace transform of the given function of time, \( f(t) \),

1. multiply \( f(t) \) by a converging factor \( e^{-st} \). This is a factor that decreases to zero as time increases to infinity;

2. Integrate \( f(t)e^{-st} \) with respect to time between the limits \( 0^- \) and \( \infty \) to obtain the Laplace transform of \( f(t) \),

\[
F(s) = \mathcal{L}(f(t)) = \int_{0^-}^{\infty} f(t)e^{-st} \, dt
\]

The lower limit of integration is \( 0^- \), rather than 0, to account for the effect of "instantaneous energy transfer".

Figure 1: Schematic representation of the Laplace transform operator.
The above definition of the Laplace transform is also referred to as the *one-sided* or *unilateral* Laplace transform. In the two-sided, or bilateral, Laplace transform, the lower limit is $-\infty$. For our purposes the one-sided Laplace transform is sufficient.

If we want to reverse the operation and take the inverse transform, back to the time domain, we write

$$L^{-1}(F(s)) = f(t).$$

Taking the inverse Laplace transform is illustrated in Figure 2.

Because we are using the one-sided Laplace transform, we define all functions, whose Laplace transforms we compute, to be zero for $t < 0^-$. To proceed, we recall the definition of the unit step function, $u(t)$,

$$u(t) = \begin{cases} 1 & \text{if } t \geq 0 \\ 0 & \text{if } t < 0. \end{cases}$$

The unit step function is also called the Heaviside function.

**Example 1** Find the Laplace transform of

$$f(t) = e^{-at}u(t),$$

where $a$ is a real constant. A graph of $f(t)$ for $a = 3$ is shown in Figure 3. We have

$$L(e^{-at}u(t)) = \int_{-\infty}^{\infty} e^{-at} e^{-st}u(t)dt = \int_{0^-}^{\infty} e^{-(a+s)t}dt.$$

The above integral exists if

$$\Re(a + s) > 0.$$
The region of the $s$-plane for which the Laplace transform exists is called the Region of Convergence and abbreviated ROC. Since $s = \sigma + j\omega$, the ROC, in our example, is the region in the $s$-plane where

$$0 < \Re(a + s) = \Re(a + \sigma + j\omega) = a + \sigma,$$

that is, the region where $\sigma > -a$. Proceeding with the integration, we obtain

$$\mathcal{L}(e^{-at}u(t)) = \left(-\frac{1}{a+s}e^{-(a+s)t}\right)\bigg|_{0^{-}}^{\infty} = \left(-\frac{1}{a+s}e^{-(a+s)0^{-}}\right) - \left(-\frac{1}{a+s}e^{-(a+s)0^{-}}\right).$$

For $s$ in the ROC, the first term tends to zero. Hence,

$$\mathcal{L}(e^{-at}u(t)) = \frac{1}{s+a}$$

Figure 3: A plot of $e^{-3t}u(t)$. 

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For $s$ in the ROC, the first term tends to zero. Hence,

$$\mathcal{L}(e^{-at}u(t)) = \frac{1}{s+a}$$
Using the Laplace transform of the exponential function, we can easily find the Laplace transform of the unit step. Indeed, if \( a = 0 \), then \( f(t) = e^{-at}u(t) = u(t) \). Hence,

\[
\mathcal{L}(u(t)) = \frac{1}{s}
\]  (1)

2 Linearity Property of the Laplace Transform

The Laplace transform of the sum, or difference, of two functions of time is equal to the sum, or difference, of the transforms of each function, that is,

\[
\mathcal{L}(f_1(t) \pm f_2(t)) = \mathcal{L}(f_1(t)) \pm \mathcal{L}(f_2(t))
\]  (2)

Indeed,

\[
\mathcal{L}(f_1(t) \pm f_2(t)) = \int_0^\infty (f_1(t) \pm f_2(t)) e^{-st} dt \\
= \int_0^\infty f_1(t)e^{-st} dt \pm \int_0^\infty f_2(t)e^{-st} dt \\
= \mathcal{L}(f_1(t)) \pm \mathcal{L}(f_2(t)).
\]

The Laplace transform of the product of a real or complex constant \( K \) and a time function \( f(t) \) is equal to the product of the constant and the transform of the time function, that is,

\[
\mathcal{L}(Kf(t)) = K \mathcal{L}(f(t)).
\]  (3)

Indeed,

\[
\mathcal{L}(Kf(t)) = \int_0^\infty Kf(t)e^{-st} dt = K \int_0^\infty f(t)e^{-st} dt = K \mathcal{L}(f(t)).
\]

The above two properties can be represented in the form

\[
\mathcal{L}(Kf_1(t) \pm f_2(t)) = K \mathcal{L}(f_1(t)) \pm \mathcal{L}(f_2(t))
\]

Example 2 To find the Laplace transform of

\[
f(t) = Ku(t),
\]

where \( K \) is a constant, we can use (3) and the Laplace transform of the unit step, given by (1), to obtain

\[
\mathcal{L}(Ku(t)) = K \mathcal{L}(u(t)) = \frac{K}{s}.
\]
Example 3 We will use the linear property of the Laplace transform to find the Laplace transform of $f(t) = \sin \omega t$.

First, recall the Euler formula, 

$$e^{j\omega t} = \cos \omega t + j \sin \omega t.$$ 

Hence, 

$$e^{-j\omega t} = \cos \omega t - j \sin \omega t.$$ 

Subtracting the second of the above expressions from the first one and dividing the result by $2j$ gives 

$$\sin \omega t = \frac{e^{j\omega t} - e^{-j\omega t}}{2j}.$$ 

Therefore, 

$$\mathcal{L}(\sin \omega t) = \mathcal{L}\left(\frac{e^{j\omega t} - e^{-j\omega t}}{2j}\right) = \mathcal{L}\left(\frac{1}{2j} (e^{j\omega t} - e^{-j\omega t})\right).$$ 

Applying to the above (3) yields 

$$\mathcal{L}(\sin \omega t) = \frac{1}{2j} \mathcal{L}(e^{j\omega t} - e^{-j\omega t}).$$ 

Applying now (2), we obtain 

$$\mathcal{L}(\sin \omega t) = \frac{1}{2j} \left(\mathcal{L}(e^{j\omega t}) - \mathcal{L}(e^{-j\omega t})\right).$$ 

We then use twice the formula for the Laplace transform of the exponential to get 

$$\mathcal{L}(\sin \omega t) = \frac{1}{2j} \left(\frac{1}{s-j\omega} - \frac{1}{s+j\omega}\right).$$ 

Performing algebraic manipulations gives 

$$\mathcal{L}(\sin \omega t) = \frac{\omega}{s^2 + \omega^2}.$$ 

Similarly, we obtain 

$$\mathcal{L}(\cos \omega t) = \mathcal{L}\left(\frac{e^{j\omega t} + e^{-j\omega t}}{2}\right).$$ 

Hence, 

$$\mathcal{L}(\cos \omega t) = \frac{s}{s^2 + \omega^2}.$$
3 Laplace Transforms of Derivatives

We will now show that
\[ L \left( \frac{df(t)}{dt} \right) = sF(s) - f(0^-) \]
where \( F(s) = L(f(t)) \) and \( f(0^-) \) is the initial value of \( f \), that is, the value of \( f \) at \( 0^- \). Thus, differentiating in the time domain corresponds to multiplying \( F(s) \) by \( s \) and then subtracting the initial value of \( f(t) \). To derive the above formula, we apply the definition of the Laplace transform,
\[ L \left( \frac{df(t)}{dt} \right) = \int_0^\infty \frac{df(t)}{dt} e^{-st} dt, \quad \text{(4)} \]
and then evaluate the integral by integrating by parts. Recall that the formula for integrating by parts can easily be derived from the formula for the derivative of the product of two functions. We use the notation,
\[ u' = \frac{du(t)}{dt}. \]
Then, we have
\[ (uv)' = u'v + uv'. \]
Integrating the above and rearranging gives
\[ \int u'v = uv - \int uv'. \quad \text{(5)} \]
We let
\[ u' = \frac{df}{dt} \quad \text{and} \quad v = e^{-st}. \]
Then applying (5) to (4), we obtain
\[ L \left( \frac{df(t)}{dt} \right) = e^{-st} f(t) \bigg|_{0^-}^{\infty} - \int_0^\infty f(t) \left( -se^{-st} \right) dt. \]
Assuming that \( f(t) \) is Laplace transformable, the value of \( e^{-st}f(t) \) at \( t = \infty \) is zero. Hence, the right-hand side of the above reduces to
\[ L \left( \frac{df(t)}{dt} \right) = -f(0^-) + s \int_0^\infty f(t)e^{-st} dt = sF(s) - f(0^-). \]
Thus, we showed that differentiation in the time domain corresponds to an algebraic operation in the \( s \) domain.

Using the Laplace transform of the first derivative of a time function, we can easily determine the Laplace transform of higher-order derivatives. Indeed, to find the Laplace transform of \( \frac{d^2f(t)}{dt^2} \), we let
\[ g(t) = \frac{df(t)}{dt}. \]
Then,
\[
\mathcal{L}(g(t)) = G(s) = \mathcal{L}\left(\frac{df(t)}{dt}\right) = sF(s) - f(0^-) .
\]

Note that
\[
\frac{d^2f(t)}{dt^2} = \frac{dg(t)}{dt} .
\]

Hence,
\[
\mathcal{L}\left(\frac{d^2f(t)}{dt^2}\right) = \mathcal{L}\left(\frac{dg(t)}{dt}\right) = sG(s) - g(0^-) .
\]

Substituting into the above (6) gives
\[
\mathcal{L}\left(\frac{d^2f(t)}{dt^2}\right) = s\left(sF(s) - f(0^-)\right) - g(0^-) .
\]

Observing that \( g(0^-) = \frac{df(0^-)}{dt} \), we get
\[
\mathcal{L}\left(\frac{d^2f(t)}{dt^2}\right) = s^2F(s) - sf(0^-) - \frac{df(0^-)}{dt} .
\]

Successively applying the above arguments, we can obtain the Laplace transform of the \( n \)-th time derivative,
\[
\mathcal{L}\left(\frac{d^f(t)}{dt^n}\right) = s^nF(s) - s^{n-1}f(0^-) - s^{n-2}\frac{df(0^-)}{dt} - \cdots - s\frac{d^{n-2}f(0^-)}{dt^{n-2}} - \frac{d^{n-1}f(0^-)}{dt^{n-1}} .
\]

### 4 Solving Differential Equations Using Laplace Transform

We now illustrate how to use the Laplace transform and inverse Laplace transform to solve linear ordinary differential equations. After taking the Laplace transform of both sides of a differential equation and performing required manipulations in the \( s \) domain, we need to reconstruct the solution in the time domain. This is achieved using the inverse Laplace transform.

**Example 4** We will solve the following differential equation using the Laplace transform,
\[
2\frac{d^2x(t)}{dt^2} + 7\frac{dx(t)}{dt} + 5x(t) = 10u(t),
\]
subject to the initial conditions
\[
\frac{dx(0^-)}{dt} = 1, \quad x(0^-) = -2 .
\]
where \( u(t) \) is the unit step function.

We take the Laplace transform of both sides of the differential equation to get

\[
2L \left( \frac{d^2x(t)}{dt^2} \right) + 7L \left( \frac{dx(t)}{dt} \right) + 5L (x(t)) = 10L (u(t)).
\]

Using Laplace transforms of time derivatives of a function of time and the Laplace transform of the unit step function, we obtain

\[
2 \left( s^2X(s) - sx (0^-) - \frac{dx (0^-)}{dt} \right) + 7 \left( sX(s) - x (0^-) \right) + 5X(s) = \frac{10}{s}.
\]

Substituting into the above the initial conditions and rearranging gives

\[
(2s^2 + 7s + 5) X(s) = \frac{10}{s} - 4s - 12 = \frac{10 - 4s^2 - 12s}{s}.
\]

Hence,

\[
X(s) = \frac{-4s^2 - 12s + 10}{s (2s^2 + 7s + 5)} = \frac{-2s^2 - 6s + 5}{s (s^2 + 3.5s + 2.5)} = \frac{-2s^2 - 6s + 5}{s (s + 2.5) (s + 1)}. \tag{7}
\]

We now need to reconstruct the solution of the differential equation in the time domain. In other words, given \( X(s) \) we want to obtain \( x(t) \) in which \( x(t) \) is zero for \( t < 0 \) such that \( X(s) = L(x(t)) \). Thus,

\[
x(t) = L^{-1} (X(s)).
\]

To proceed, note that \( X(s) \) as given by (7) is a rational function of \( s \), that is, \( X(s) \) is a ratio of two polynomials in \( s \), in which the degree of the numerator with respect to \( s \) is smaller than the degree of the denominator. Such a rational function is called strictly proper and can be expanded into a sum of partial fractions by writing a term or a series of terms for each zero of the denominator. We obtain

\[
X(s) = \frac{K_1}{s} + \frac{K_2}{s + 2.5} + \frac{K_3}{s + 1}. \tag{8}
\]

We will now compute the constants \( K_i \)'s. We can do so by representing the right-hand side of the above as a rational function and then comparing the resulting numerator with the numerator of (7). We represent (8) as

\[
X(s) = \frac{K_1 (s + 2.5) (s + 1) + K_2 s (s + 1) + K_3 s (s + 2.5)}{s (s + 2.5) (s + 1)} = \frac{(K_1 + K_2 + K_3) s^2 + (3.5K_1 + K_2 + 2.5K_3) s + 2.5K_1}{s (s + 2.5) (s + 1)}. \tag{9}
\]
Comparing coefficients of like powers of the numerators of (7) and (9) gives three algebraic equations in three unknowns,

\[
\begin{align*}
K_1 + K_2 + K_3 &= -2 \\
3.5K_1 + K_2 + 2.5K_3 &= -6 \\
5 &= 2.5K_1
\end{align*}
\]

Solving the above system of equations gives

\[K_1 = 2, \quad K_2 = 2, \quad K_3 = -6.\]

Substituting the above into (8) yields

\[X(s) = \frac{2}{s} + \frac{2}{s + 2.5} - \frac{6}{s + 1}.\]

Applying the inverse Laplace transform to the above, we obtain

\[x(t) = \mathcal{L}^{-1} \left( \frac{2}{s} + \frac{2}{s + 2.5} - \frac{6}{s + 1} \right) = (2 + 2e^{-2.5t} - 6e^{-t}) u(t).\]

## 5 Laplace Transforms of Integrals

We first consider taking the Laplace transform of

\[\int_{0^-}^{t} f(x)dx.\]  \hspace{1cm} (10)

Let \(F(s)\) denote the Laplace transform of \(f(t)\), that is, \(F(s) = \mathcal{L}(f(t))\). We find the Laplace transform of (10) using integration by parts to obtain

\[
\mathcal{L} \left( \int_{0^-}^{t} f(x)dx \right) = \int_{0^-}^{\infty} \left( \int_{0^-}^{t} f(x)dx \right) e^{-st}dt.
\]\n
Recall the formula for integration by parts,

\[
\int u'v = uv - \int uv'.
\]

Let

\[u = -\frac{1}{s}e^{-st} \quad \text{and} \quad v = \int_{0^-}^{t} f(x)dx.\]
Note that\[ \frac{dv}{dt} = \frac{d}{dt} \int_{0^-}^{t} f(x)dx = f(t). \]

Integrating (11) by parts gives
\[ \mathcal{L} \left( \int_{0^-}^{t} f(x)dx \right) = -\frac{1}{s} e^{-st} \int_{0^-}^{t} f(x)dx \bigg|_{0^-}^{\infty} + \frac{1}{s} \int_{0^-}^{\infty} e^{-st} f(t)dt. \]
The first term on the right-hand side is zero at both the lower and upper limits. The value at the lower limit, \( t = 0^- \), is clearly zero. The value at the upper limit, \( t = \infty \), is zero because we assumed that \( f(t) \) is Laplace transformable. Hence,
\[ \mathcal{L} \left( \int_{0^-}^{t} f(x)dx \right) = \frac{F(s)}{s} \] (12)

We next find the Laplace transform of
\[ \int_{-\infty}^{t} f(x)dx. \] (13)

Applying the definition and using the fact that the Laplace transform is linear yields
\[ \mathcal{L} \left( \int_{-\infty}^{t} f(x)dx \right) = \mathcal{L} \left( \int_{-\infty}^{0^-} f(x)dx \right) + \mathcal{L} \left( \int_{0^-}^{t} f(x)dx \right) = F_1(s) + F_2(s). \]
The limits of the first integral are constant, therefore the integral will be a constant. Hence,
\[ F_1(s) = \frac{\int_{-\infty}^{0^-} f(x)dx}{s}, \]
while by (12),
\[ F_2(s) = \frac{F(s)}{s}. \]

Therefore,
\[ \mathcal{L} \left( \int_{-\infty}^{t} f(x)dx \right) = \frac{F(s)}{s} + \frac{\int_{-\infty}^{0^-} f(x)dx}{s} \] (14)

**Example 5** We find the Laplace transform of the voltage, \( v_C(t) \), across a capacitor \( C \). We have
\[ v_C(t) = \frac{1}{C} \int_{-\infty}^{t} i(x)dx. \]
Using (14) gives
\[ \mathcal{L} (v_C(t)) = \frac{1}{C} \frac{I(s)}{s} + \frac{1}{C} \frac{\int_{-\infty}^{0^-} i(x)dx}{s}. \]
Since \( \int_{-\infty}^{0^-} i(x)dx \) is the charge, \( q \), on the capacitor at \( t = 0^- \) and \( v = q/C \), we obtain
\[ \mathcal{L} (v_C(t)) = \frac{1}{C} \frac{I(s)}{s} + \frac{v_C(0^-)}{s} \]
6 More Properties of the Laplace Transform

We will now show that translation in the time domain corresponds to multiplication by an exponential in the $s$ domain, that is,

\[ \mathcal{L}(f(t-a)u(t-a)) = e^{-as}F(s), \quad a > 0 \]

where $F(s) = \mathcal{L}(f(t))$. We have

\[ \mathcal{L}(f(t-a)u(t-a)) = \int_{0^-}^{\infty} f(t-a)u(t-a)e^{-st}dt = \int_{a^-}^{\infty} f(t-a)e^{-st}dt, \quad (15) \]

because $u(t-a) = 0$ for $t < a$. Next, we change the variable of integration. We let

\[ x = t - a. \]

Then, $x = 0^-$ when $t = a^-$, $x = \infty$ when $t = \infty$, and $dx = dt$. Substituting the above into (15) yields

\[ \mathcal{L}(f(t-a)u(t-a)) = \int_{0^-}^{\infty} f(x)e^{-s(x+a)}dx = e^{-sa} \int_{0^-}^{\infty} f(x)e^{-sx}dx = e^{-as}F(s), \]

which is the desired result.

We will now prove the time/frequency scaling property,

\[ \mathcal{L}(f(at)) = \frac{1}{a} F\left(\frac{s}{a}\right), \quad a > 0 \]

Indeed, applying the Laplace transform yields

\[ \mathcal{L}(f(at)) = \int_{0^-}^{\infty} f(at)e^{-st}dt. \quad (16) \]

Let $x = at$. Then, $dt = \frac{1}{a}dx$. Substituting the above into (16) gives

\[ \mathcal{L}(f(at)) = \frac{1}{a} \int_{0^-}^{\infty} f(x)e^{-\left(\frac{s}{a}\right)x}dx = \frac{1}{a} F\left(\frac{s}{a}\right), \]

which was to be shown.
7 The Impulse Function and Its Properties

The impulse function, denoted $\delta(t)$, also called the Dirac function, is a signal of infinite amplitude, zero duration, and unity area. We can construct an impulse function as the limit of pulse functions

$$p_{\varepsilon_i}(t) = \frac{1}{\varepsilon_i} (u(t) - u(t - \varepsilon_i))$$

as $\varepsilon_i \to 0$. This is illustrated in Figure 4. Note that the pulse functions have the following features as $\varepsilon_i \to 0$:

1. the amplitude approaches infinity,
2. the duration of the pulses approaches zero,
3. the area under each pulse is constant; in our example the area equals unity.

The unit impulse function is defined as

$$\int_{-\infty}^{\infty} \delta(t) \, dt = 1 \quad \text{and} \quad \delta(t) = 0 \quad \text{for} \quad t \neq 0.$$

The above definition states that the area under the impulse function is constant. The area represents the strength of the impulse function. The impulse function of strength $K$ is denoted $K\delta(t)$. Its graphical representation is depicted in Figure 5. The strength of the impulse is shown next to the arrow’s head. The shifted impulse function of strength $K$ is also shown in Figure 5. The unit impulse function can be thought of as a derivative of the
unit step function, that is,

\[ \delta(t) = \frac{du(t)}{dt}. \]

The function shown in Figure 6 approaches the unit step function as \( \varepsilon \to 0 \). The function shown in Figure 7, which is the derivative of the function from Figure 6, approaches the unit impulse function as \( \varepsilon \to 0 \).

The impulse function has the sifting property,

\[
\int_{-\infty}^{\infty} f(t) \delta(t-a) dt = f(a)
\]

where \( f(t) \) is a continuous function of time. It follows from the above that the impulse function sifts out everything except the value of \( f \) at \( t = a \)—hence the name of the property. To verify the validity of the sifting property, we note that \( \delta(t-a) \) is zero everywhere except at \( t = a \). Hence, we can write,

\[
\int_{-\infty}^{\infty} f(t) \delta(t-a) dt = \int_{a-\varepsilon}^{a+\varepsilon} f(t) \delta(t-a) dt.
\]

By assumption, \( f \) is continuous at \( a \). Therefore, it must take the value of \( f(a) \) as \( t \to a \). Thus,

\[
\int_{a-\varepsilon}^{a+\varepsilon} f(t) \delta(t-a) dt = f(a) \int_{a-\varepsilon}^{a+\varepsilon} \delta(t-a) dt = f(a),
\]

which was to be demonstrated.

Using the sifting property we can show that

\[
\mathcal{L}(\delta(t)) = 1
\]
Figure 6: The function $u_\varepsilon$ approaches the unit step as $\varepsilon \to 0$.

Figure 7: The derivative of $u_\varepsilon(t)$ shown in Figure 6. As $\varepsilon \to 0$, $\delta_\varepsilon(t)$ approaches $\delta(t)$. 
Indeed, applying the definition of the Laplace transform and using the sifting property, we obtain

\[ \mathcal{L}(\delta(t)) = \int_{0^{-}}^{\infty} \delta(t)e^{-st}dt = e^0 \int_{0^{-}}^{0^{+}} \delta(t)dt = 1. \]

We now discuss another important property of the impulse function—the sampling property. Since \( \delta(t-a) = 0 \) for \( t \neq a \),

\[ f(t)\delta(t-a) = 0 \quad \text{for} \quad t \neq a \]

as is

\[ f(a)\delta(t-a) = 0 \quad \text{for} \quad t \neq a. \]

However, when \( t = a \), we have

\[ f(t)\delta(t-a) = f(a)\delta(t-a) \quad \text{for} \quad t = a \]

provided that \( f(a) \) exists. Therefore,

\[ f(t)\delta(t-a) = f(a)\delta(t-a) \quad \text{for all} \quad t \]

The above property is called the sampling property of the impulse function.

**Examples**

(i) \( (\cos 3t)\delta(t-\pi) = (\cos 3\pi)\delta(t-\pi) = -\delta(t-\pi) \);

(ii) \( e^{-2t}\delta(t) = e^{-2(0)}\delta(t) = \delta(t) \);

(iii) \( (1-e^{-4t}) \delta(t) = (1-e^{0}) \delta(t) = 0\delta(t) = 0 \).