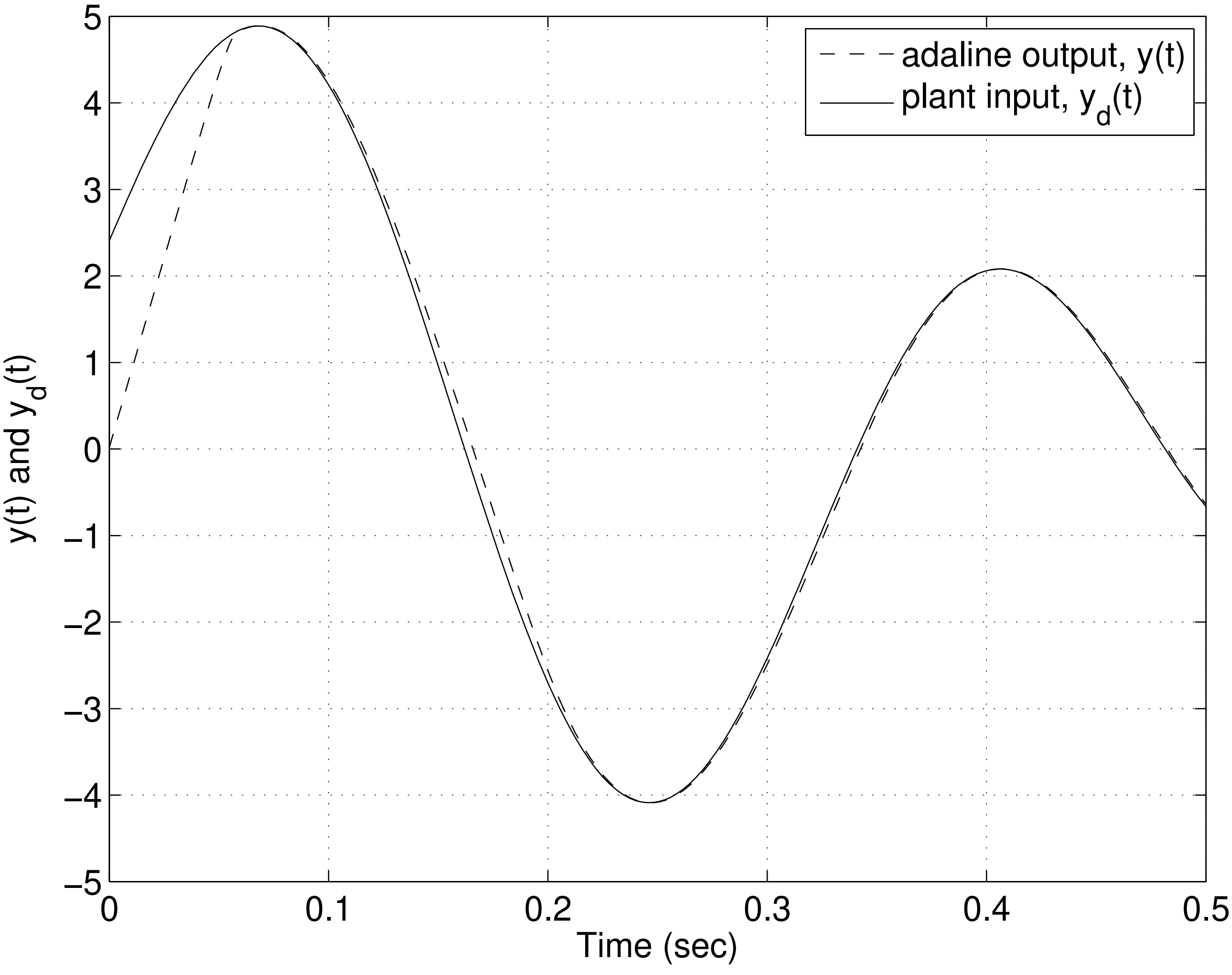

adaline output, y(t)
plant input, $y_d(t)$
y(t) and $y_d(t)$
Time (sec)
5
4
3
2
1
0
−1
−2
−3
−4
−5
0
0.1
0.2
0.3
0.4
0.5