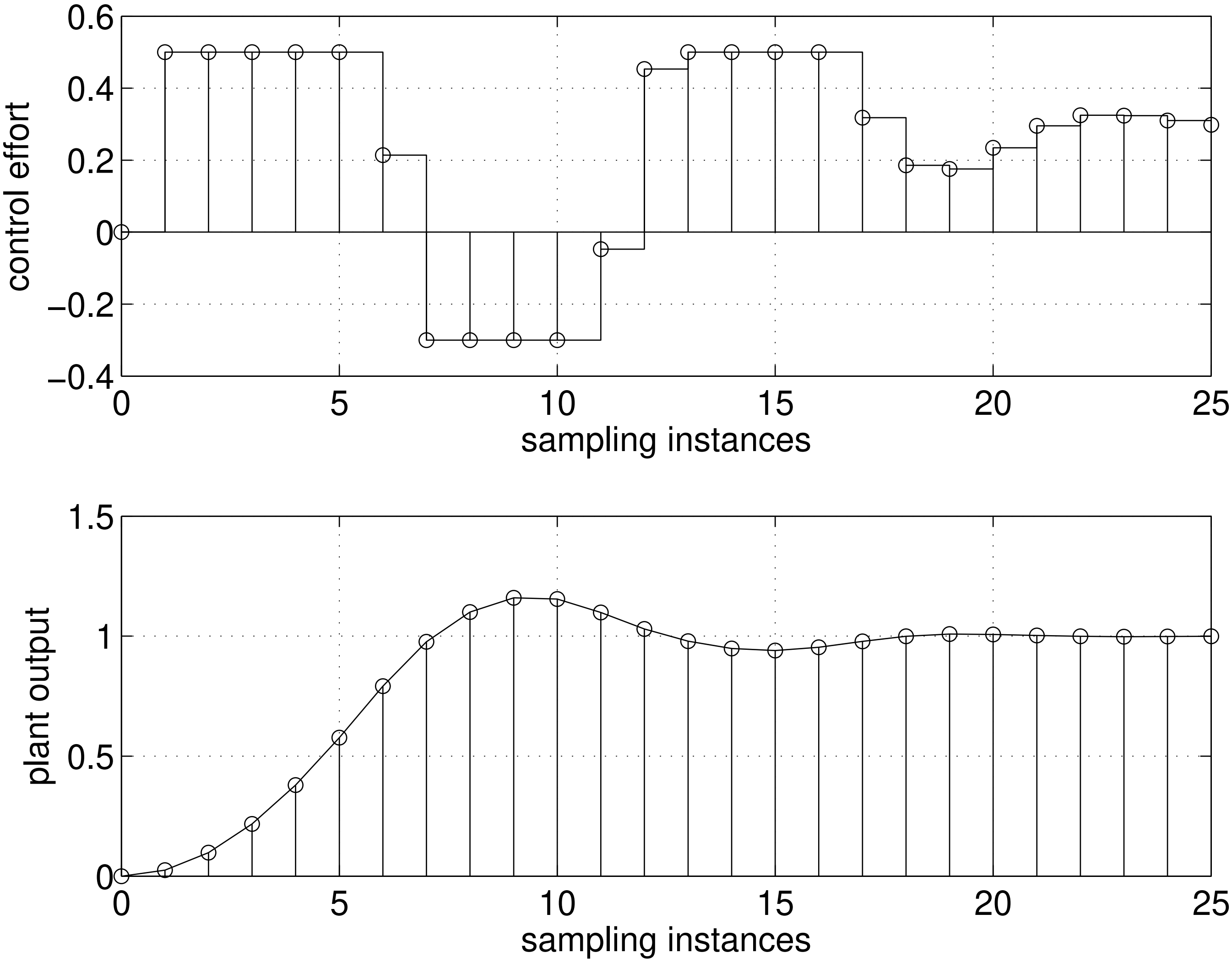

control effort
0.6
0.4
0.2
0
−0.2
−0.4
0
5
10
15
20
25
sampling instances
plant output
1.5
1
0.5
0
0
5
10
15
20
25
sampling instances