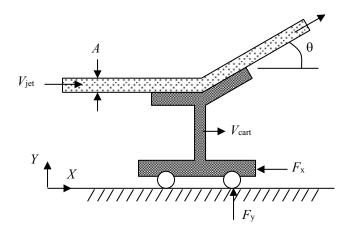
A jet of water is deflected by a vane mounted on a cart. The water jet has an area, A, everywhere and is turned an angle  $\theta$  with respect to the horizontal. The pressure everywhere within the jet is atmospheric. The incoming jet velocity with respect to the ground (axes XY) is  $V_{\text{jet}}$ . The cart has mass M. Determine:

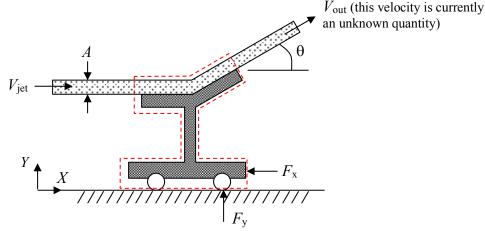
- a. the force components,  $F_x$  and  $F_y$ , required to hold the cart stationary,
- b. the horizontal force component,  $F_x$ , if the cart moves to the right at the constant velocity,  $V_{\text{cart}}$  ( $V_{\text{cart}} < V_{\text{jet}}$ )



SOLUTION:

Part (a):

Apply conservation of mass and conservation of linear momentum to a control volume surrounding the cart. Use an inertial frame of reference fixed to the ground (XY).



First apply conservation of mass to the control volume to determine  $V_{\text{out}}$ .

$$\frac{d}{dt} \int_{CV} \rho dV + \int_{CS} \rho \mathbf{u}_{\text{rel}} \cdot d\mathbf{A} = 0 \tag{1}$$

where

 $\frac{d}{dt} \int_{CV} \rho dV = 0$  (the mass within the control volume doesn't change)

$$\int_{CS} \rho \mathbf{u}_{\text{rel}} \cdot d\mathbf{A} = \begin{pmatrix} \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho V_{\text{jet}} \hat{\mathbf{i}} \cdot -A \hat{\mathbf{i}} \\ \end{pmatrix} + \begin{bmatrix} \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho V_{\text{out}} \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \cdot A \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \\ \text{left side} & \text{right side} \\ = -\rho V_{\text{jet}} A + \rho V_{\text{out}} A \left( \cos^2 \theta + \sin^2 \theta \right) \\ = -\rho V_{\text{jet}} A + \rho V_{\text{out}} A \end{pmatrix}$$

(Note that the jet area remains constant.)

Substitute and re-arrange.

$$-\rho V_{\text{jet}} A + \rho V_{\text{out}} A = 0$$

$$V_{\text{out}} = V_{\text{jet}}$$
(2)

Now apply conservation of linear momentum in the X-direction:

$$\frac{d}{dt} \int_{CV} u_X \rho dV + \int_{CS} u_X \rho \mathbf{u}_{rel} \cdot d\mathbf{A} = F_{B,X} + F_{S,X}$$
(3)

where

 $\frac{d}{dt} \int_{CV} u_X \rho dV = 0$  (the momentum within the control volume doesn't change with time)

$$\begin{split} \int_{\text{CS}} u_X \left( \rho \mathbf{u}_{\text{rel}} \cdot d \mathbf{A} \right) &= \begin{pmatrix} V_{\text{jet}} \end{pmatrix} \begin{pmatrix} = \mathbf{u}_{\text{rel}} &= \mathbf{A} \\ \rho V_{\text{jet}} \hat{\mathbf{i}} \cdot -A \hat{\mathbf{i}} \\ \end{pmatrix} + \begin{pmatrix} V_{\text{jet}} \cos \theta \end{pmatrix} \begin{pmatrix} = \mathbf{u}_{\text{rel}} &= \mathbf{A} \\ \rho V_{\text{jet}} \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \cdot A \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \end{pmatrix} \\ & \text{left side} & \text{right side} \\ &= -\rho V_{\text{jet}}^2 A + \rho V_{\text{jet}}^2 A \cos \theta \left( \cos^2 \theta + \sin^2 \theta \right) \\ &= 1 \\ &= \rho V_{\text{jet}}^2 A \left( \cos \theta - 1 \right) \end{split}$$

 $F_{B,X} = 0$  (no body forces in the x-direction)

 $F_{S,X} = -F_x$  (all of the pressure forces cancel out)

Substitute and re-arrange.

$$\rho V_{\text{jet}}^2 A(\cos \theta - 1) = -F_x$$

$$\boxed{F_x = \rho V_{\text{jet}}^2 A(1 - \cos \theta)}$$
(4)

Now look at the Y-direction:

$$\frac{d}{dt} \int_{CV} u_Y \rho dV + \int_{CS} u_Y \rho \mathbf{u}_{rel} \cdot d\mathbf{A} = F_{B,Y} + F_{S,Y}$$
(5)

where

 $\frac{d}{dt} \int_{CV} u_Y \rho dV = 0$  (the momentum within the control volume doesn't change with time)

$$\int_{CS} u_Y \left( \rho \mathbf{u}_{rel} \cdot d\mathbf{A} \right) = \left( V_{jet} \sin \theta \right) \begin{bmatrix} = \mathbf{u}_{rel} & = \mathbf{A} \\ \rho V_{jet} \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \cdot A \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \end{bmatrix}$$
right side
$$= \rho V_{jet}^2 A \sin \theta \left( \cos^2 \theta + \sin^2 \theta \right)$$

$$= \rho V_{jet}^2 A \sin \theta$$

 $F_{B,Y} = -Mg$  (assume that the fluid weight in the CV is negligible compared to the cart weight)

 $F_{S,Y} = F_y$  (all of the pressure forces cancel out)

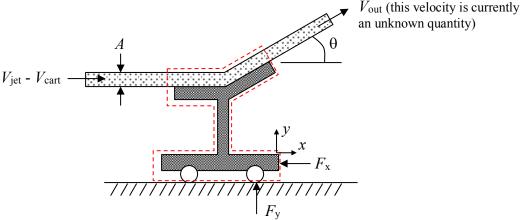
Substitute and re-arrange.

$$\rho V_{\text{jet}}^2 A \sin \theta = -Mg + F_y$$

$$F_y = \rho V_{\text{jet}}^2 A \sin \theta + Mg$$
(6)

## Part (b):

Apply conservation of linear momentum to a control volume surrounding the cart. Use a frame of reference fixed to the cart (xy). Note that this is an inertial frame of reference since the cart moves in a straight line at a constant speed. In addition, in this frame of reference, the cart appears stationary and the jet velocity at the left is equal to  $V_{\text{jet}}$ - $V_{\text{cart}}$ .



First apply conservation of mass to the control volume to determine  $V_{\text{out}}$ 

$$\frac{d}{dt} \int_{\text{CV}} \rho dV + \int_{\text{CS}} \rho \mathbf{u}_{\text{rel}} \cdot d\mathbf{A} = 0 \tag{7}$$

 $\frac{d}{dt} \int_{CV} \rho dV = 0$  (the mass within the control volume doesn't change)

$$\int_{CS} \rho \mathbf{u}_{rel} \cdot d\mathbf{A} = \begin{bmatrix} = \mathbf{u}_{rel} & = \mathbf{A} \\ \rho (V_{jet} - V_{cart}) \hat{\mathbf{i}} \cdot -A \hat{\mathbf{i}} \end{bmatrix} + \begin{bmatrix} = \mathbf{u}_{rel} & = \mathbf{A} \\ \rho V_{out} (\cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}}) \cdot A (\cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}}) \end{bmatrix}$$

$$= -\rho (V_{jet} - V_{cart}) A + \rho V_{out} A (\cos^2 \theta + \sin^2 \theta)$$

$$= -\rho (V_{jet} - V_{cart}) A + \rho V_{out} A$$

(Note that the jet area remains constant.)

Substitute and re-arrange.

$$-\rho \left(V_{\text{jet}} - V_{\text{cart}}\right) A + \rho V_{\text{out}} A = 0$$

$$V_{\text{out}} = V_{\text{jet}} - V_{\text{cart}}$$
(8)

Now apply conservation of linear momentum in the *x*-direction:

$$\frac{d}{dt} \int_{CV} u_x \rho dV + \int_{CS} u_x \rho \mathbf{u}_{rel} \cdot d\mathbf{A} = F_{B,x} + F_{S,x}$$
(9)

where

 $\frac{d}{dt} \int_{\partial V} u_x \rho dV = 0$  (the momentum within the control volume doesn't change with time)

$$\int_{\text{CS}}^{=u_{x}} u_{x} (\rho \mathbf{u}_{\text{rel}} \cdot d\mathbf{A}) = (V_{\text{jet}} - V_{\text{cart}}) \begin{bmatrix} = \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho (V_{\text{jet}} - V_{\text{cart}}) \hat{\mathbf{i}} \cdot -A \hat{\mathbf{i}} \end{bmatrix} + (V_{\text{jet}} - V_{\text{cart}}) \cos \theta \begin{bmatrix} = \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho (V_{\text{jet}} - V_{\text{cart}}) (\cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}}) \cdot A (\cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}}) \end{bmatrix}$$

$$= \lim_{\text{left side}} \operatorname{right side}$$

$$= -\rho (V_{\text{jet}} - V_{\text{cart}})^{2} A + \rho (V_{\text{jet}} - V_{\text{cart}})^{2} A \cos \theta (\cos^{2} \theta + \sin^{2} \theta)$$

$$= 1$$

$$= \rho (V_{\text{jet}} - V_{\text{cart}})^{2} A (\cos \theta - 1)$$

 $F_{B.x} = 0$  (no body forces in the x-direction)

 $F_{S,x} = -F_x$  (all of the pressure forces cancel out)

Substitute and re-arrange.

$$\rho \left(V_{\text{jet}} - V_{\text{cart}}\right)^{2} A(\cos \theta - 1) = -F_{x}$$

$$\boxed{F_{x} = \rho \left(V_{\text{jet}} - V_{\text{cart}}\right)^{2} A(1 - \cos \theta)}$$
(10)

Now solve the problem using an inertial frame of reference fixed to the ground (frame XY). From Eqn. (8) we know that using a frame of reference fixed to the cart, the jet velocity on the right hand side is:

$$\mathbf{V}_{\text{out,}} = \left(V_{\text{jet}} - V_{\text{cart}}\right) \left(\cos\theta \hat{\mathbf{i}} + \sin\theta \hat{\mathbf{j}}\right)$$
relative to cart

Hence, relative to the ground the jet velocity on the right hand side is:

$$\mathbf{V}_{\text{out,}} = \mathbf{V}_{\text{out,}} + \mathbf{V}_{\text{cart}} = (V_{\text{jet}} - V_{\text{cart}}) \left(\cos\theta \,\hat{\mathbf{i}} + \sin\theta \,\hat{\mathbf{j}}\right) + V_{\text{cart}} \,\hat{\mathbf{i}}$$
(12)

Now consider conservation of linear momentum in the *X* direction.

$$\frac{d}{dt} \int_{CV} u_X \rho dV + \int_{CS} u_X \rho \mathbf{u}_{rel} \cdot d\mathbf{A} = F_{B,X} + F_{S,X}$$
(13)

where

 $\frac{d}{dt} \int_{CV} u_X \rho dV = 0$  (the momentum within the control volume doesn't change with time)

$$\int_{CS} u_X \left( \rho \mathbf{u}_{\text{rel}} \cdot d\mathbf{A} \right) = V_{\text{jet}} \begin{bmatrix} = \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho \left( V_{\text{jet}} - V_{\text{cart}} \right) \hat{\mathbf{i}} \cdot -A \hat{\mathbf{i}} \end{bmatrix} + \begin{bmatrix} = u_X \\ \left[ \left( V_{\text{jet}} - V_{\text{cart}} \right) \cos \theta + V_{\text{cart}} \right] \end{bmatrix} \begin{bmatrix} = \mathbf{u}_{\text{rel}} & = \mathbf{A} \\ \rho \left( V_{\text{jet}} - V_{\text{cart}} \right) \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \cdot A \left( \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}} \right) \end{bmatrix}$$

$$= \begin{bmatrix} \log t \sin \theta \\ = -\rho V_{\text{jet}} \left( V_{\text{jet}} - V_{\text{cart}} \right) A + \rho \left[ \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 \cos \theta + V_{\text{cart}} \left( V_{\text{jet}} - V_{\text{cart}} \right) \right] A \left( \cos^2 \theta + \sin^2 \theta \right) \end{bmatrix}$$

$$= \begin{bmatrix} -V_{\text{jet}}^2 + V_{\text{jet}} V_{\text{cart}} + \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 \cos \theta + V_{\text{cart}} V_{\text{jet}} - V_{\text{cart}}^2 \right] A$$

$$= \rho \left[ \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 \cos \theta - \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 \right] A$$

$$= \rho \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 \left( \cos \theta - 1 \right) A$$

 $F_{B.X} = 0$  (no body forces in the x-direction)

 $F_{S,X} = -F_x$  (all of the pressure forces cancel out)

Substitute and re-arrange.

$$\rho \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 A(\cos \theta - 1) = -F_x$$

$$\boxed{F_x = \rho \left( V_{\text{jet}} - V_{\text{cart}} \right)^2 A(1 - \cos \theta)} \quad \text{(Same answer as before!)}$$

Note that using a frame of reference that is fixed to the control volume is easier than using one fixed to the ground. This is often the case.