

Homework # 2 Solution

13.13 – 3

We have

$$v_{0s} = r_s \cdot i_{0s} + L_{ls} \cdot \frac{d}{dt} i_{0s}$$

Since i_{0s} is zero (by wye-connection) it follows that $v_{0s} = 0$

13.13-4

The negative voltage must occur when the lower diode is conducting, therefore the diode drop is 1 V
The small positive voltage must occur when the lower IGBT is conducting, therefore the switch drop is 1.5V

13.13-6

From Eqn (13.3-1), we have that

$$v_{abs} = \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \cos\left(\theta_c + \frac{\pi}{6}\right) + \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \sum_{j=1}^{\infty} \left[\frac{-1}{6 \cdot j - 1} \cdot \cos\left[(6 \cdot j - 1)\left(\theta_c + \frac{\pi}{6}\right)\right] + \frac{1}{6 \cdot j + 1} \cdot \cos\left[(6 \cdot j + 1)\left(\theta_c + \frac{\pi}{6}\right)\right] \right]$$

In the steady state, v_{bcs} and v_{cas} are 120 and 240 behind v_{abs} . Thus we set

$$v_{bcs} = \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \cos\left(\theta_c - \frac{\pi}{2}\right) + \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \sum_{j=1}^{\infty} \left[\frac{-1}{6 \cdot j - 1} \cdot \cos\left[(6 \cdot j - 1)\left(\theta_c - \frac{\pi}{2}\right)\right] + \frac{1}{6 \cdot j + 1} \cdot \cos\left[(6 \cdot j + 1)\left(\theta_c - \frac{\pi}{2}\right)\right] \right]$$

$$v_{cas} = \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \cos\left(\theta_c + \frac{5 \cdot \pi}{6}\right) + \frac{2 \cdot \sqrt{3}}{\pi} \cdot v_{dc} \cdot \sum_{j=1}^{\infty} \left[\frac{-1}{6 \cdot j - 1} \cdot \cos\left[(6 \cdot j - 1)\left(\theta_c + \frac{5 \cdot \pi}{6}\right)\right] + \frac{1}{6 \cdot j + 1} \cdot \cos\left[(6 \cdot j + 1)\left(\theta_c + \frac{5 \cdot \pi}{6}\right)\right] \right]$$

13.13 – 9

we have:

$$-v_{ag} + v_{as} + v_{ng} = 0 \quad (1)$$

$$-v_{bg} + v_{bs} + v_{ng} = 0 \quad (2)$$

$$-v_{cg} + v_{cs} + v_{ng} = 0 \quad (3)$$

$$\frac{v_{as}}{R_a} + \frac{v_{bs}}{R_b} + \frac{v_{cs}}{R_c} + 0 \quad (4)$$

Combining (1-4)

$$\frac{v_{ag} - v_{ng}}{R_a} + \frac{v_{bg} - v_{ng}}{R_b} + \frac{v_{cg} - v_{ng}}{R_c} = 0 \quad (5)$$

Solving (5) for the line-to-neutral voltage

$$v_{ng} = \frac{(v_{ag} \cdot R_b \cdot R_c + v_{bg} \cdot R_a \cdot R_c + v_{cg} \cdot R_a \cdot R_b)}{(R_b \cdot R_c + R_a \cdot R_c + R_a \cdot R_b)} \quad (6)$$

Substitution of (6) into (1) and solving

$$v_{as} = R_a \cdot \frac{(v_{ag} \cdot R_c + v_{ag} \cdot R_b - v_{bg} \cdot R_c - v_{cg} \cdot R_b)}{(R_b \cdot R_c + R_a \cdot R_c + R_a \cdot R_b)} \quad (7)$$

Problem parameters

$$v_{dc} := 100$$

$$R_a := 2 \quad R_b := 4 \quad R_c := 4$$

Now lets make a function of it

$$v_{ag}(\theta_c) := \text{if} \left(\cos(\theta_c) > 0, v_{dc}, 0 \right)$$

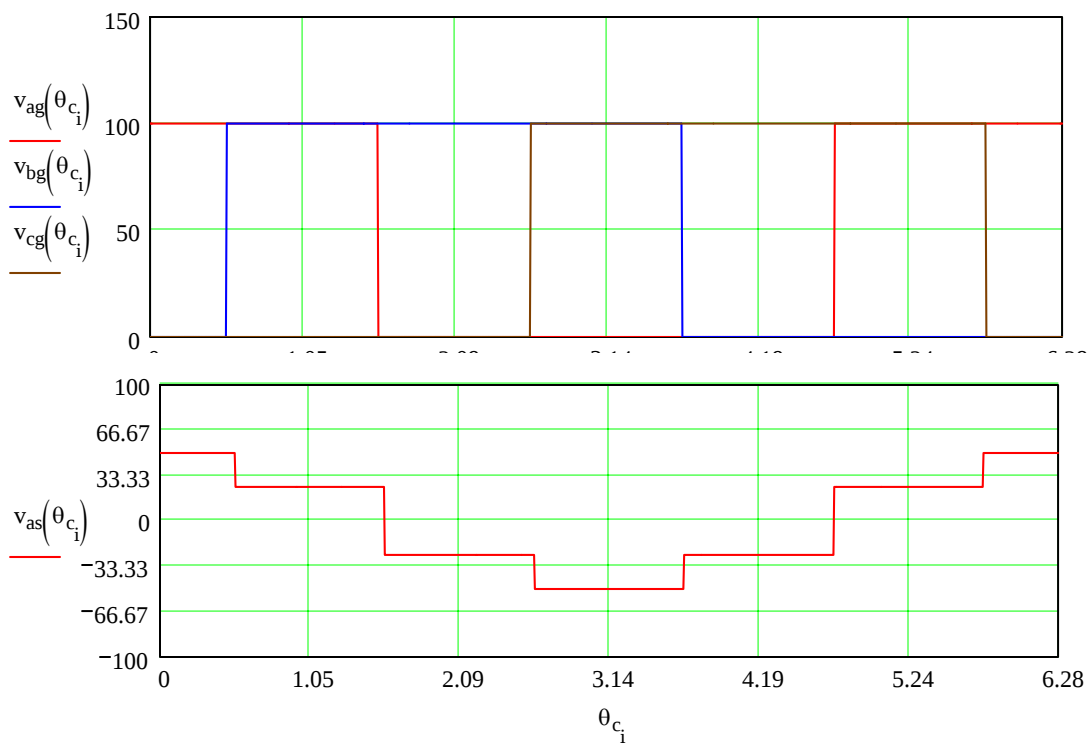
$$v_{bg}(\theta_c) := \text{if} \left(\cos \left(\theta_c - \frac{2 \cdot \pi}{3} \right) > 0, v_{dc}, 0.0 \right)$$

$$v_{cg}(\theta_c) := \text{if} \left(\cos \left(\theta_c + \frac{2 \cdot \pi}{3} \right) > 0, v_{dc}, 0.0 \right)$$

$$v_{as}(\theta_c) := R_a \cdot \frac{(v_{ag}(\theta_c) \cdot R_c + v_{ag}(\theta_c) \cdot R_b - v_{bg}(\theta_c) \cdot R_c - v_{cg}(\theta_c) \cdot R_b)}{(R_b \cdot R_c + R_a \cdot R_c + R_a \cdot R_b)}$$

$$N := 1000 \quad i := 0..N - 1$$

$$\theta_{c_i} := \frac{i}{N - 1} \cdot 2 \cdot \pi$$



13.3 – 10

$$v_{\text{ttl}} := 5.0$$

$$v_{\text{thresh}} := 3.4$$

$$R := 1000$$

$$t_{\text{delay}} := 1.5 \cdot 10^{-6}$$

Following a turn on, the voltage at the input node of the and gate will be described by

$$v = v_{\text{ttl}} \left(1 - e^{\frac{-t}{R \cdot C}} \right)$$

$$v_{\text{thresh}} = v_{\text{ttl}} \left(1 - e^{\frac{-t_{\text{delay}}}{R \cdot C}} \right)$$

$$\ln \left(1 - \frac{v_{\text{thresh}}}{v_{\text{ttl}}} \right) = \frac{-t_{\text{delay}}}{R \cdot C}$$

$$C := \frac{-t_{\text{delay}}}{\left[\ln \left[\frac{(v_{\text{ttl}} - v_{\text{thresh}})}{v_{\text{ttl}}} \right] \cdot R \right]}$$

$$C = 1.316 \times 10^{-9}$$

13.13 – 14

We have

$$v_{dc} := 100$$

We want

$$v_{qsr} := 50$$

$$v_{dsr} := 10$$

Now, in the converter reference frame we have that

$$v_{qsc} = \frac{1}{2}d \cdot v_{dc}$$

$$v_{dsc} = 0$$

From the frame to frame transformation

$$\begin{pmatrix} v_{qsr} \\ v_{dsr} \end{pmatrix} = \begin{pmatrix} \cos(\theta_{rc}) & -\sin(\theta_{rc}) \\ \sin(\theta_{rc}) & \cos(\theta_{rc}) \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{2}d \cdot v_{dsc} \\ 0 \end{pmatrix}$$

Thus

$$v_{qsr} + j \cdot v_{dsr} = \frac{1}{2} \cdot d \cdot v_{dc} \cdot e^{j\theta_{rc}}$$

So

$$d := \frac{2}{v_{dc}} \cdot \sqrt{v_{qsr}^2 + v_{dsr}^2} \quad d = 1.02$$

$$\theta_{rc} := \arg(v_{qsr} + j \cdot v_{dsr}) \quad \theta_{rc} = 0.197$$

$$\theta_r = \theta_c - \theta_{rc}$$