

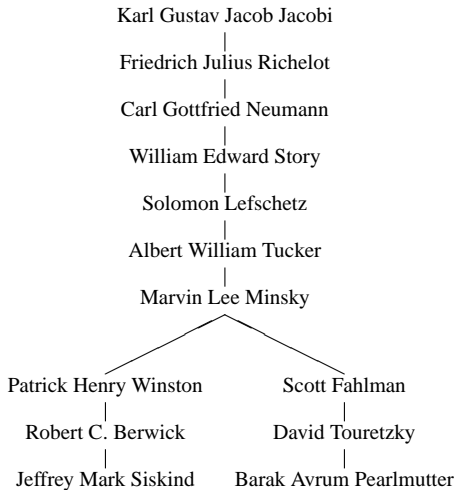
Automatic Differentiation of Functional Programs or Lambda the Ultimate Calculus

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Joint work with Barak A. Pearlmutter.



It is, of course, not excluded that the range of arguments or range of values of a function should consist wholly or partly of functions. The derivative, as this notion appears in the elementary differential calculus, is a familiar mathematical example of a function for which both ranges consist of functions.

(¶4)

Church, A. (1941). *The Calculi of Lambda Conversion*, Princeton University Press, Princeton, NJ.

Gottfried Leibniz
|
Jacob Bernoulli
|
Johann Bernoulli
|
Leonhard Euler
|
Joseph Louis Lagrange
|
Simeon Poisson
|
Michel Chasles
|
Hubert Anson Newton
|
Eliakim Hastings Moore
|
Oswald Veblen
|
Alonzo Church

Leibnitz (1664) + Church (1941) = Siskind & Pearlmutter (2008)

Leibnitz, G. W. (1664). A new method for maxima and minima as well as tangents, which is impeded neither by fractional nor irrational quantities, and a remarkable type of calculus for this, *Acta Eruditorum*.

Higher-order functions are common in mathematics, physics, and engineering:

*derivatives, gradients, Jacobians, summations, comprehensions,
quantifications, optimizations, integrals, convolutions, filters, edge
detectors, Fourier transforms, differential equations, Hamiltonians,*

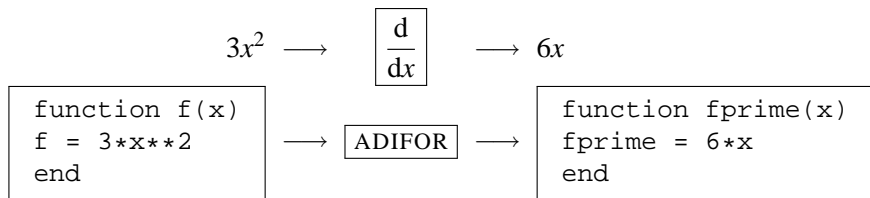
...

where they are traditionally called *operators*.

Automatic Differentiation (AD)

$$3x^2 \longrightarrow \boxed{\frac{d}{dx}} \longrightarrow 6x$$

Automatic Differentiation (AD)



Wengert, R. E. (1964). A simple automatic derivative evaluation program, *Communications of the ACM*, **7**(8):463–4.

Beda, L. M. *et al.* (1959). *Programs for Automatic Differentiation for the Machine BESM*, Inst. for Precise Mechanics and Computation Techniques, Academy of Science, Moscow

$$\frac{f(x + \Delta x) - f(x)}{\Delta x}$$

A Xillion Implementations of AD

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MAPLE: GRADIENT (Monagan & Neuenschwander, 1993)

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HASKELL: (Karczmarczuk, 1998, 1999, 2001; Nilsson, 2003)

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⋮

<http://www.autodiff.org>

What's Novel?

- AD for functional programs

Karczmarczuk, J. K. (2001). Functional differentiation of computer programs, *Higher Order and Symbolic Computation*, **14**:35–57.

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What's Novel?

- AD for functional programs
- formulated as a higher-order function (in the language)
- that reflectively transforms code and data (in closures)
- in a way that exhibits closure properties
- and a compiler that compiles away that reflection

Karczmarczuk, J. K. (2001). Functional differentiation of computer programs, *Higher Order and Symbolic Computation*, **14**:35–57.

Everything You Always Wanted to Know About the Lambda Calculus*

*But Were Afraid To Ask

Everything You Always Wanted to Know About the Lambda Calculus*

(in 8 slides)

*But Were Afraid To Ask

```
int f(int n)
{ int i, p = 1;
  for (i = 1; i<n; i++)
    { p = p*i; }
  return p; }
```

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{ int i, p = 1;
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```

$$f\ n \triangleq \begin{cases} \mathbf{if}\ n = 0 \\ \mathbf{then}\ 1 \\ \mathbf{else}\ n \times (f\ (n - 1)) \end{cases}$$

Higher-Order Functions

$$\sum_{i=1}^n \exp i$$

$$\prod_{i=1}^n \sin i$$

Higher-Order Functions

$$\sum_{i=1}^n \exp i \qquad \prod_{i=1}^n \sin i$$

FOLD $i, a, f, g \triangleq$ **if** $i = 0$
then a
else FOLD $(i - 1), (g a, (f i)), f, g$

Higher-Order Functions

$$\sum_{i=1}^n \exp i \qquad \prod_{i=1}^n \sin i$$

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FOLD $n, 0, \exp, +$ FOLD $n, 1, \sin, \times$

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$$\sum_{i=1}^n 2i + 1$$

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FOLD $i, a, f, g \triangleq$ **if** $i = 0$
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else FOLD $(i - 1), (g a, (f i)), f, g$
FOLD $n, 0, \exp, +$ FOLD $n, 1, \sin, \times$

$$\sum_{i=1}^n 2i + 1$$

$f i \triangleq 2i + 1$ FOLD $n, 0, f, +$

FOLD $n, 0, (\lambda i 2i + 1), +$

$$(\lambda x 2x) 3 = 6$$

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$$(\lambda x \lambda y x + y) 3 4 = 7$$

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$$(\lambda x \lambda y x + y) 3 4 = 7$$

$$(\lambda x \lambda y x + y) 3 = ?$$

$$(\lambda x 2x) 3 = 6$$

$$(\lambda x \lambda y x + y) 3 4 = 7$$

$$(\lambda x \lambda y x + y) 3 = \langle \{x \mapsto 3\}, \lambda y x + y \rangle$$

$$(\lambda x 2x) 3 = 6$$

$$(\lambda x \lambda y x + y) 3 4 = 7$$

$$(\lambda x \lambda y x + y) 3 = \langle \{x \mapsto 3\}, \lambda y x + y \rangle$$

$$\lambda x \lambda y x + y \qquad \lambda(x, y) x + y$$

Closure Conversion

$$f = \lambda y x + y$$
$$f\ 4$$

Closure Conversion

$$\boxed{\begin{array}{l} f = \lambda y x + y \\ f 4 \end{array}} \rightsquigarrow \boxed{\begin{array}{l} f = (x, \lambda y x + y) \\ (\text{CDR } f) ((\text{CAR } f), 4) \end{array}}$$

Johnsson, T. (1985). Lambda Lifting: Transforming Programs to Recursive Equations, *Proceedings Functional Programming Languages and Computer Architecture*.

if e_1 **then** e_2 **else** e_3 **fi** \rightsquigarrow IF e_1 $(\lambda x e_2)$ $(\lambda x e_3)$ []

if e_1 **then** e_2 **else** e_3 **fi** \rightsquigarrow $\text{IF } e_1 (\lambda x e_2) (\lambda x e_3) []$

$e ::= x \mid e_1 e_2 \mid \lambda x e$

$$\mathbf{let } x = e_1 \mathbf{ in } e_2 \quad \rightsquigarrow \quad (\lambda x e_2) e_1$$

A-Normal Form

let $x = e_1$ **in** e_2

let $x_1 = e_1;$

$x_2 = e_2;$

\vdots

in e

$\rightsquigarrow (\lambda x e_2) e_1$

\rightsquigarrow **let** $x_1 = e_1$

in let $x_2 = e_2;$

\vdots

in e

A-Normal Form

let $x = e_1$ in e_2	\rightsquigarrow	$(\lambda x e_2) e_1$
let $x_1 = e_1;$ $x_2 = e_2;$ \vdots in e	\rightsquigarrow	let $x_1 = e_1$ in let $x_2 = e_2;$ \vdots in e
$(f_n \dots (f_2 (f_1 x_0)) \dots)$	\rightsquigarrow	let $x_1 = f_1 x_0;$ $x_2 = f_2 x_1;$ \vdots $x_n = f_n x_{n-1}$ in x_n

Sabry, A. and Felleisen, M. (1993). Reasoning about Programs in Continuation-Passing Style, *Lisp and Symbolic Computation*, 3(3–4):289–360.

Nonstandard Interpretations

$$3 + 4 = 7$$

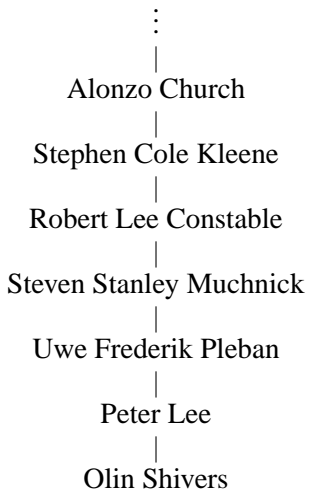
let $+ = -$	$= -1$
in $3 + 4$	

Monovariant Flow Analysis

needs work

needs work

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*, Ph.D. thesis, CMU.



Differential Calculus for Dummies

Differential Calculus for Dummies

(in 7 slides)

$$\frac{dax^2}{dx} \rightsquigarrow 2ax$$

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$$\frac{d}{dx} : \underbrace{f}_{\mathbb{R} \rightarrow \mathbb{R}} \mapsto \underbrace{f'}_{\mathbb{R} \rightarrow \mathbb{R}}$$

$$\frac{dax^2}{dx} \rightsquigarrow 2ax$$

$$\frac{d}{dx} : \underbrace{f}_{\mathbb{R} \rightarrow \mathbb{R}} \mapsto \underbrace{f'}_{\mathbb{R} \rightarrow \mathbb{R}}$$

$$\frac{d}{dx} : (\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$$

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$$\mathcal{D} : (\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$$

$$\mathcal{D} \lambda x ax^2$$

Partial Derivatives

$$\frac{\partial ax^2y^3}{\partial x}$$

$$\frac{\partial ax^2y^3}{\partial y}$$

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$$\frac{\partial ax^2y^3}{\partial x}$$

$$\mathcal{D}_{\lambda x} ax^2y^3$$

$$\frac{\partial ax^2y^3}{\partial y}$$

$$\mathcal{D}_{\lambda y} ax^2y^3$$

Partial Derivatives

$$\frac{\partial ax^2y^3}{\partial x}$$

$$\mathcal{D} \lambda x ax^2y^3$$

$$\mathcal{D}_1 \lambda(x, y) ax^2y^3$$

$$\frac{\partial ax^2y^3}{\partial y}$$

$$\mathcal{D} \lambda y ax^2y^3$$

$$\mathcal{D}_2 \lambda(x, y) ax^2y^3$$

Partial Derivatives

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$$\mathcal{D} \lambda y ax^2y^3$$

$$\mathcal{D}_1 \lambda(x, y) ax^2y^3$$

$$\mathcal{D}_2 \lambda(x, y) ax^2y^3$$

$$\frac{\partial}{\partial x} : \underbrace{f}_{\mathbb{R}^n \rightarrow \mathbb{R}} \mapsto \underbrace{f'}_{\mathbb{R}^n \rightarrow \mathbb{R}}$$

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$$\frac{\partial}{\partial x} : (\mathbb{R}^n \rightarrow \mathbb{R}) \rightarrow (\mathbb{R}^n \rightarrow \mathbb{R})$$

$$\mathcal{D}_i : (\mathbb{R}^n \rightarrow \mathbb{R}) \rightarrow (\mathbb{R}^n \rightarrow \mathbb{R})$$

$$\nabla f \mathbf{x} = (\mathcal{D}_1 f \mathbf{x}), \dots, (\mathcal{D}_n f \mathbf{x})$$

$$\nabla : (\mathbb{R}^n \rightarrow \mathbb{R}) \rightarrow (\mathbb{R}^n \rightarrow \mathbb{R}^n)$$

$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\mathbf{f} : (\mathbb{R}^n \rightarrow \mathbb{R})^m$$

$$(\mathcal{J} f \mathbf{x})[i,j] = (\nabla (\mathbf{f}[i]))[j]$$

$$\mathcal{J} : (\mathbb{R}^n \rightarrow \mathbb{R}^m) \rightarrow (\mathbb{R}^n \rightarrow \mathbb{R}^{m \times n})$$

The Chain Rule

$$(f \circ g) x = g (f x)$$

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$$\frac{dg}{dx} = \frac{dg}{df} \frac{df}{dx}$$

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$$\mathcal{J} (f \circ g) \mathbf{x} = (\mathcal{J} g (f \mathbf{x})) \times (\mathcal{J} f \mathbf{x})$$

Matrix Transposition

$$\mathbf{A}^T[i, j] = \mathbf{A}[j, i]$$

Matrix Transposition

$$\mathbf{A}^{\top}[i,j] = \mathbf{A}[j,i]$$

$$(\mathbf{A} \times \mathbf{B})^{\top} = \mathbf{B}^{\top} \times \mathbf{A}^{\top}$$

Taylor Expansions

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \cdots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \cdots$$

Taylor, B. (1715). *Methodus Incrementorum Directa et Inversa*, London.

The Essence of Forward-Mode AD

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!} \varepsilon + \frac{f''(c)}{2!} \varepsilon^2 + \dots + \frac{f^{(i)}(c)}{i!} \varepsilon^i + \dots$$

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To compute $\mathcal{D} f c$:

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To compute $\mathcal{D}f c$:

- evaluate f

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To compute $\mathcal{D}f c$:

- evaluate f at the **term** $c + \varepsilon$

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To compute $\mathcal{D}f\ c$:

- evaluate f at the **term** $c + \varepsilon$ to get a **power series**,
- extract the coefficient of ε , and
- multiply by $1!$

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Can do a *nonstandard interpretation* of f over **truncated power series**.

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Preserves control flow: Augments **original values** with **derivatives**.

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$(\mathcal{D}f)$ is $\mathcal{O}(1)$ relative to f (both space and time).

$$a + bi$$

Hamilton, W. R. (1837). Theory of conjugate functions, or algebraic couples; with a preliminary and elementary essay on algebra as the science of pure time, *Transactions of the Royal Irish Academy*, **17**(1):293–422.

Arithmetic on Complex Numbers

$$a + bi$$

$$i^2 = -1$$

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Traditional Forward-Mode AD

$$\mathbb{R}^n \rightarrow \mathbb{R}^m \quad \rightsquigarrow \quad (\mathbb{R}^n \triangleright \overline{\mathbb{R}^n}) \rightarrow (\mathbb{R}^m \triangleright \overline{\mathbb{R}^m})$$

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Modularity

 $\nabla f \mathbf{x}$

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$$\text{NEUTRONFLUX } \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin } \overrightarrow{\text{DEVIATION}}$$

Fermi, E. (1946). *The Development of the first chain reaction pile.*

Proceedings of the American Philosophy Society, **90**:20–4.

Breaking Modularity

$$\nabla \overleftarrow{f} \mathbf{x} \quad \triangleq \quad \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{argmin } \overrightarrow{f} \quad \triangleq \quad \dots \text{GRADIENTDESCENT } \overrightarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin } \overrightarrow{\text{DEVIATION}}$$

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$$\nabla \overleftarrow{f} \mathbf{x} \quad \triangleq \quad \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{argmin } \overrightarrow{f} \quad \triangleq \quad \dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \xrightarrow{\text{ADIFOR}} \quad \overrightarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin } \overrightarrow{\text{DEVIATION}}$$

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$$\nabla \overleftarrow{f} \mathbf{x} \quad \triangleq \quad \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT} \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{argmin} \overleftarrow{f} \quad \triangleq \quad \dots \text{GRADIENTDESCENT} \overleftarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX} \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \xrightarrow{\text{ADIFOR}} \quad \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION} \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX} \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \xrightarrow{\text{ADIFOR}} \quad \overline{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin} \overline{\text{DEVIATION}}$$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overrightarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$$\nabla \overleftarrow{f} \mathbf{x} \quad \triangleq \quad \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT} \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H}f \mathbf{x}_i \dots$$

$$\text{argmin} \overleftarrow{f} \quad \triangleq \quad \dots \text{GRADIENTDESCENT} \overleftarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX} \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \overset{\text{TAPENADE}}{\rightsquigarrow} \quad \overleftarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION} \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX} \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \overset{\text{TAPENADE}}{\rightsquigarrow} \quad \overleftarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin} \overleftarrow{\text{DEVIATION}}$$

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Breaking Modularity

$$\nabla \overleftarrow{f} \mathbf{x} \quad \triangleq \quad \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT} \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \quad \triangleq \quad \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$$

$$\text{argmin} \overleftarrow{f} \quad \triangleq \quad \dots \text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX} \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \overset{\text{TAPENADE}}{\rightsquigarrow} \quad \overleftarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION} \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX} \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \quad \overset{\text{TAPENADE}}{\rightsquigarrow} \quad \overleftarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \quad \triangleq \quad \text{argmin} \overleftarrow{\text{DEVIATION}}$$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	$\dots \overleftarrow{\overleftarrow{f}} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
$\operatorname{argmin} \overleftarrow{f}$	\triangleq	$\dots \operatorname{NEWTNSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	$\operatorname{argmin} \overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}} \overrightarrow{\text{DEVIATION}}$

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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	TAPENADE \rightsquigarrow	$\overleftarrow{\text{NEUTRONFLUX}}$
$\overleftarrow{\text{NEUTRONFLUX}}$	TAPENADE \rightsquigarrow	$\overrightarrow{\overleftarrow{\text{NEUTRONFLUX}}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	TAPENADE \rightsquigarrow	$\overleftarrow{\text{DEVIATION}}$
$\overleftarrow{\text{DEVIATION}}$	TAPENADE \rightsquigarrow	$\overrightarrow{\overleftarrow{\text{DEVIATION}}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}} \overrightarrow{\overleftarrow{\text{DEVIATION}}}$

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	<i>classified</i>
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_1'), \dots, ((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_n')$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	<i>classified</i>
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

Fermi, E. (1946). *The Development of the first chain reaction pile*.
Proceedings of the American Philosophy Society, **90**:20–4.

Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	$\dots (\overrightarrow{\mathcal{J}} (\overleftarrow{\mathcal{J}} f)) \dots \mathbf{x} \dots$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{NEWTONSMETHOD } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
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polynomials

Closure Properties

polynomials , product rule

Closure Properties

polynomials , product rule , quotient rule

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

chain rule

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

Base case: arithmetic basis

chain rule

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

Base case: arithmetic basis

chain rule

Inductive case: function composition

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

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An inductive definition of the space of expressions

Closure Properties

polynomials , product rule , quotient rule , transcendental functions

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An inductive definition of the space of expressions

Consequence 1: could take the derivative of *any* (differentiable) expression

Closure Properties

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Inductive case: function composition

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output space \subseteq input space

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An inductive definition of the space of expressions

Consequence 1: could take the derivative of *any* (differentiable) expression

output space \subseteq input space

Consequence 2: could take higher-order derivatives

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polynomials , product rule , quotient rule , transcendental functions

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Base case: *arithmetic basis*

AD

Inductive case: *lambda calculus*

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Consequence 1: could take the derivative of *any* (differentiable) *program*

output space \subseteq *input space*

Consequence 2: could take higher-order derivatives *of programs*

FORTRAN

Backus, J. W. (1954). Preliminary Report: Specifications for the IBM Mathematical FORMula TRANslating System, FORTRAN, International Business Machines.

A Brief History of Programming Languages

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SCHEME **recursion**

arrays of arrays

escaping closures

Sussman, G. J. and Steele, Jr., G. L. (1975). *Scheme: an Interpreter for Extended Lambda Calculus*, MIT AI memo 349.

needs work

von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

needs work

Goldstine, A. (1946). *Report on the ENIAC (Electronic Numerical Integrator and Computer)*, Moore School of Electrical Engineering, University of Pennsylvania.

needs work

Sprague, C. S. and George, R. H. (1939). Cathod Ray Deflecting Electrode. US Patent 2,161,437.

George, R. H. (1940). Cathod Ray Tube. US Patent 2,222,942.

STALIN ∇ vs. SCHEME

Example	Language/Implementation										
	STALIN ∇	IKARUS	STALIN	SCHEME->C	CHICKEN	BIGLOO	GAMBIT	LARCENY	MzC	MzSCHEME	SCMUTILS
saddle	1.00	61.71	94.85	112.90	233.35	175.07	130.50	184.90	613.45	720.41	705.10
particle	1.00	146.96	248.00	308.34	609.30	501.59	351.20	537.07	1453.19	1868.88	1512.90

Example	Language/Implementation				
	STALIN ∇	MLTON	SML/NJ	OCAML	GHC
saddle	1.00	11.19	16.68	21.25	31.08
particle	1.00	33.13	40.34	58.53	74.56

The State of the Art Regarding Closure Properties

The State of the Art Regarding Closure Properties

ADIFOR

The State of the Art Regarding Closure Properties

ADIFOR miscomputes call graph

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 confuses nesting with recursion

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ADIFOR miscalculates call graph
 confuses nesting with recursion
 cannot handle indirect function calls

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The State of the Art Regarding Closure Properties

- ADIFOR
 - miscomputes call graph
 - confuses nesting with recursion
 - cannot handle indirect function calls
 - generates incorrect derivative code
 - gives wrong answer without warning
 - to get it to work
 - specialize indirect function calls
 - copy code
 - split code into separate files
 - manually edit both input code and generated code

The State of the Art Regarding Closure Properties

ADIFOR miscomputes call graph
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TAPENADE

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 - generates code with syntax errors

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- ADIC
 - generates code with syntax errors
 - cannot transform its own output

The State of the Art Regarding Closure Properties

- ADIFOR
 - miscomputes call graph
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 - manually edit both input code and generated code
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 - generates code with syntax errors
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- FADBAD++

The State of the Art Regarding Closure Properties

- ADIFOR
 - miscomputes call graph
 - confuses nesting with recursion
 - cannot handle indirect function calls
 - generates incorrect derivative code
 - gives wrong answer without warning
 - to get it to work
 - specialize indirect function calls
 - copy code
 - split code into separate files
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- TAPENADE
 - generates code with syntax errors
 - cannot handle indirect function calls
 - generates incorrect derivative code
 - gives wrong answer (with aliasing warning)
 - to get it to work
 - specialize indirect function calls
 - manually edit both input code and generated code
- ADIC
 - generates code with syntax errors
 - cannot transform its own output
- FADBAD++
 - cannot take derivatives of arbitrary unmodified C++ programs

The State of the Art Regarding Closure Properties

- ADIFOR
 - miscomputes call graph
 - confuses nesting with recursion
 - cannot handle indirect function calls
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 - to get it to work
 - specialize indirect function calls
 - copy code
 - split code into separate files
 - manually edit both input code and generated code
- TAPENADE
 - generates code with syntax errors
 - cannot handle indirect function calls
 - generates incorrect derivative code
 - gives wrong answer (with aliasing warning)
 - to get it to work
 - specialize indirect function calls
 - manually edit both input code and generated code
- ADIC
 - generates code with syntax errors
 - cannot transform its own output
- FADBAD++
 - cannot take derivatives of arbitrary unmodified C++ programs
 - to get it to work
 - rewrite code using templates

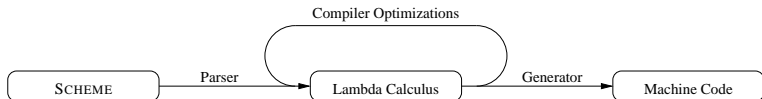
STALIN ∇ vs C++ and FORTRAN

Example	Language/Implementation			
	STALIN ∇	FADBAD++	ADIFOR	TAPENADE
saddle	1.00	5.71	0.49	0.73
particle	1.00	30.07	0.85	1.76

Static Floating-Point Instruction Density

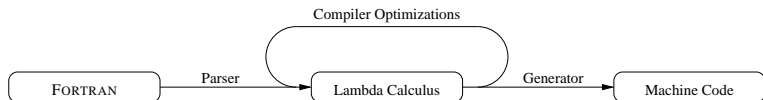
Example	Language/Implementation			
	STALIN ∇	FADBAD++	ADIFOR	TAPENADE
saddle	16.9%	1.3%	9.3%	7.8%
particle	20.9%	1.6%	7.0%	4.4%

Lambda the Ultimate Intermediate Language



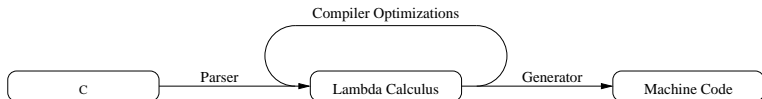
Steele, Jr., G. L. and Sussman, G. J. (1976). *Lambda, the Ultimate Imperative*, MIT AI memo 353.

Lambda the Ultimate Intermediate Language



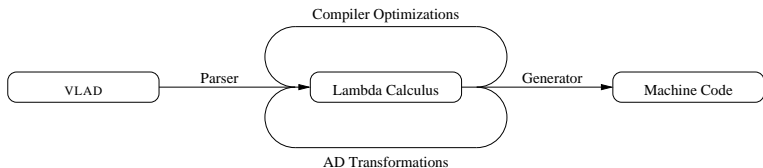
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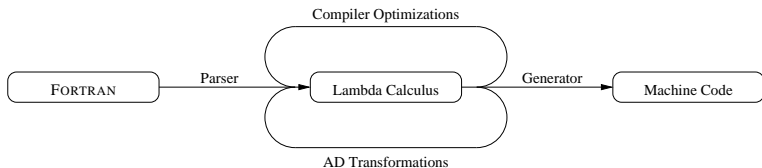
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Lambda the Ultimate Intermediate Language *for AD*



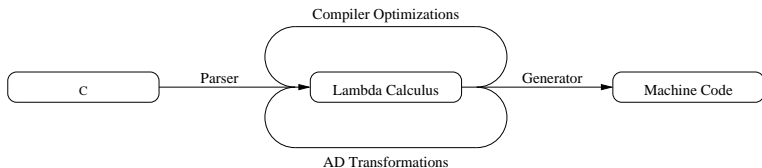
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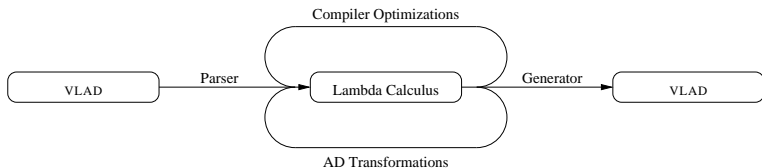
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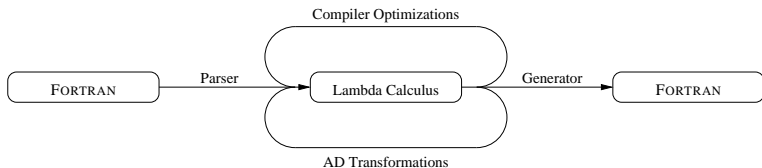
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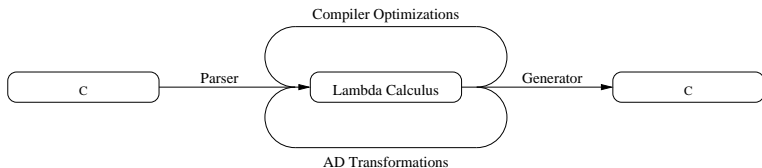
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⋮
|
Marvin Lee Minsky
|
Gerald Jay Sussman
|
Guy Lewis Steele, Jr.

Something for Matthias Blume

$$(\text{zero } \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (\text{zero } v_1), \dots\}, \dots \rangle$$

Something for Matthias Blume

$$\begin{aligned}(\text{zero } \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) &= \langle \{x_1 \mapsto (\text{zero } v_1), \dots\}, \dots \rangle \\(\text{primal } \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) &= \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, \dots \rangle\end{aligned}$$

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ditto for our *entire* AD basis (perturb, unperturb, bundle, sensitize, unsensitize, plus, *j, and *j-inverse)

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ditto for our *entire* AD basis (perturb, unperturb, bundle, sensitize, unsensitize, plus, *j, and *j-inverse)

$$(\text{map-closure } f \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (f \ v_1), \dots\}, \dots \rangle$$

Siskind, J. M. and Pearlmutter, B. A. (2007). First-Class Nonstandard Interpretations by Opening Closures, *Proceedings of the 34th Symposium on Principles of Programming Languages*, 71–6.

Something for Robby Findler

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$

Something for Robby Findler

$$\begin{aligned}(\text{j}^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) &= \langle \{x_1 \mapsto (\text{j}^* v_1), \dots\}, \dots \rangle \\(\text{j}^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) &= \langle \{x_1 \mapsto (\text{j}^* v_1), \dots\}, \overline{e} \rangle\end{aligned}$$

Something for Robby Findler

$$\begin{aligned}(\text{j* } \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) &= \langle \{x_1 \mapsto (\text{j* } v_1), \dots\}, \dots \rangle \\(\text{j* } \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) &= \langle \{x_1 \mapsto (\text{j* } v_1), \dots\}, \overline{e} \rangle \\(\text{*j } \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) &= \langle \{x_1 \mapsto (\text{*j } v_1), \dots\}, \overleftarrow{e} \rangle \\(\text{primal } \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) &= \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle \\(\text{*j-inverse } \langle \{x_1 \mapsto v_1, \dots\}, \overleftarrow{e} \rangle) &= \\ \langle \{x_1 \mapsto (\text{*j-inverse } v_1), \dots\}, e \rangle\end{aligned}$$

Something for Robby Findler

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \overline{e} \rangle$$

$$(*j \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (*j v_1), \dots\}, \overleftarrow{e} \rangle$$

$$(\text{primal} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) = \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle$$

$$(*j\text{-inverse} \langle \{x_1 \mapsto v_1, \dots\}, \overleftarrow{e} \rangle) =$$

$$\langle \{x_1 \mapsto (*j\text{-inverse } v_1), \dots\}, e \rangle$$

$$(\text{map-closure-and-transform } f \ \mathcal{T} \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \\ \langle \{x_1 \mapsto (f \ v_1), \dots\}, \mathcal{T}(e) \rangle$$

Something for Robby Findler

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \overline{e} \rangle$$

$$(*j \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (*j v_1), \dots\}, \overleftarrow{e} \rangle$$

$$(\text{primal} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) = \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle$$

$$(*j\text{-inverse} \langle \{x_1 \mapsto v_1, \dots\}, \overleftarrow{e} \rangle) =$$

$$\langle \{x_1 \mapsto (*j\text{-inverse } v_1), \dots\}, e \rangle$$

$$(\text{map-closure-and-transform } f \ \mathcal{T} \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) =$$
$$\langle \{x_1 \mapsto (f \ v_1), \dots\}, \mathcal{T}(e) \rangle \text{ But what is } \mathcal{T}?$$

Something for Robby Findler

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \overline{e} \rangle$$

$$(*j \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (*j v_1), \dots\}, \overline{e} \rangle$$

$$(\text{primal} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) = \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle$$

$$(*j\text{-inverse} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) =$$

$$\langle \{x_1 \mapsto (*j\text{-inverse } v_1), \dots\}, e \rangle$$

$$(\text{map-closure-and-transform } f \ \mathcal{T} \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) =$$
$$\langle \{x_1 \mapsto (f \ v_1), \dots\}, \mathcal{T}(e) \rangle \text{ But what is } \mathcal{T}?$$

- a procedural macro, `defmacro`

Something for Robby Fandler

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$
$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \overline{e} \rangle$$
$$(*j \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (*j v_1), \dots\}, \overline{e} \rangle$$
$$(\text{primal} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) = \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle$$
$$(*j\text{-inverse} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) =$$
$$\langle \{x_1 \mapsto (*j\text{-inverse } v_1), \dots\}, e \rangle$$
$$(\text{map-closure-and-transform } f \ \mathcal{T} \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) =$$
$$\langle \{x_1 \mapsto (f \ v_1), \dots\}, \mathcal{T}(e) \rangle \text{ But what is } \mathcal{T}?$$

- a procedural macro, defmacro
- a hygienic macro, syntax-rules, syntax-case, ...

Something for Robby FINDER

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, \dots \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \dots \rangle$$

$$(j^* \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (j^* v_1), \dots\}, \overline{e} \rangle$$

$$(*j \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (*j v_1), \dots\}, \overline{e} \rangle$$

$$(\text{primal} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) = \langle \{x_1 \mapsto (\text{primal } v_1), \dots\}, e \rangle$$

$$(*j\text{-inverse} \langle \{x_1 \mapsto v_1, \dots\}, \overline{e} \rangle) =$$

$$\langle \{x_1 \mapsto (*j\text{-inverse } v_1), \dots\}, e \rangle$$

$$(\text{map-closure-and-transform } f \ T \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) = \langle \{x_1 \mapsto (f \ v_1), \dots\}, T(e) \rangle \text{ But what is } T?$$

- a procedural macro, defmacro
- a hygienic macro, syntax-rules, syntax-case, ...
- a rewrite system, PLT REDEX

Something for Dave MacQueen and John Reppy

zero : $\tau \rightarrow \tau$

perturb : $\tau \rightarrow \overline{\tau}$

unperturb : $\overline{\tau} \rightarrow \tau$

primal : $\overline{\tau} \rightarrow \tau$

tangent : $\overline{\tau} \rightarrow \overline{\tau}$

bundle : $\tau \times \overline{\tau} \rightarrow \overline{\tau}$

j* : $\tau \rightarrow \overline{\tau}$

sensitize : $\tau \rightarrow \sqrt{\tau}$

unsensitize : $\sqrt{\tau} \rightarrow \tau$

plus : $\tau \times \tau \rightarrow \tau$

*j : $\tau \rightarrow \overleftarrow{\tau}$

*j-inverse : $\overleftarrow{\tau} \rightarrow \tau$

$f : \tau_1 \rightarrow \tau_2 \quad x : \tau_1$

$(fx) : \tau_2$

$(j* f) (j* x)$

$(j* f : \tau) : \overline{\tau}$

$(j* f : \tau_1 \rightarrow \tau_2) : \overline{\tau_1 \rightarrow \tau_2}$

TAPENADE 2.1 User's Guide (p. 72):

10. KNOWN PROBLEMS AND DEVELOPMENTS TO COME

10.4 Pointers and dynamic allocation

For example, how should we handle a memory deallocation in the reverse mode? During the reverse sweep, the memory must be reallocated somehow, and the pointers must point back into this reallocated memory. Finding the more efficient way to handle this is still an open problem.

<http://www-unix.mcs.anl.gov/~utke/OpenAD/>:

4. Language-coverage and library handling in adjoint code

2. language concepts (e.g., array arithmetic, pointers and dynamic memory allocation, polymorphism):

Many language concepts, in particular those found in object-oriented languages, have never been considered in the context of automatic adjoint code generation. We are aware of several hard theoretical and technical problems that need to be

Review 3

significance: 2/5 originality: 2/5

The authors present the "inability to nest" as a "central limitation" that prevents current AD tools from being truly automatic. [...] What constitutes a "central limitation" is, however, a rather subjective criterion. There are other problems that are in my view much more critical to the practical use of AD tools. Take, for instance, adjoining parallelized models.

Dear Dr. Pearlmutter,

[...] The problems with nesting transformations of the current Fortran/C - AD tools - contrary claims on their respective websites notwithstanding - are a known fact but there nesting has not been a priority. [...] The suggested road map connecting vlad and stalingrad to other language front-ends is in our view not necessary. [...] It merely highlights the fact that after criticizing the other tools vlad and stalingrad cannot readily be used either to differentiate Fortran or C programs, do reverse mode with checkpointing, cross