

Automatic Differentiation of Functional Programs or Lambda the Ultimate Calculus

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Purdue University

University of South Carolina
11 September 2009

Part of this talk covers joint work with Barak A. Pearlmutter.

The Essence

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(define (f x) 2x3)
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$(\text{define } (g\ x)\ \text{sinf}(x)) \rightsquigarrow (\text{define } (g'\ x)\ f'(x)\ \text{cosf}(x))$

$(\mathcal{D}\ g) \implies (\mathcal{D}\ \langle\{f \mapsto \lambda x\ 2x^3\}, \lambda x\ \text{sinf}(x)\rangle)$

$\implies \langle\{f \mapsto \lambda x\ 2x^3, f' \mapsto \lambda x\ 6x^2\}, \lambda x\ f'(x)\ \text{cosf}(x)\rangle$

$(\text{map-closure } f\ \langle\{x_1 \mapsto v_1, \dots\}, e\rangle) \implies \langle\{x_1 \mapsto f(v_1), \dots\}, e\rangle$

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need reflective transformation of closure bodies

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need reflective transformation of closure bodies
want transformation done at compile time
need flow analysis

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need reflective transformation of closure bodies
want transformation done at compile time
need **polyvariant** flow analysis

Nesting

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$$\max_x \min_y f(x, y)$$

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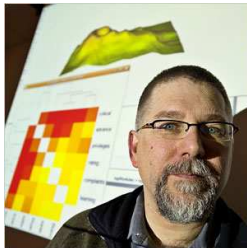
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The Essence of Forward-Mode AD

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \dots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \dots$$

Taylor, B. (1715). *Methodus Incrementorum Directa et Inversa*. London.

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To compute $\mathcal{D}f c$:

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To compute $\mathcal{D}f c$:

- evaluate f

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$(\mathcal{D}f)$ is $\mathcal{O}(1)$ relative to f (both space and time).

$$a + bi$$

Hamilton, W. R. (1837). *Theory of conjugate functions, or algebraic couples; with a preliminary and elementary essay on algebra as the science of pure time*. Transactions of the Royal Irish Academy, **17**(1):293–422.

Arithmetic on Complex Numbers

$$a + bi$$

$$i^2 = -1$$

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$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

$$(x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, **4**:381–95.

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$$\langle x, x' \rangle$$

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$$\langle x, x' \rangle$$

$$\langle x_1, x'_1 \rangle + \langle x_2, x'_2 \rangle = \langle (x_1 + x_2), (x'_1 + x'_2) \rangle$$
$$\langle x_1, x'_1 \rangle \times \langle x_2, x'_2 \rangle = \langle (x_1 \times x_2), (x_1 \times x'_2 + x_2 \times x'_1) \rangle$$

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Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
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(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
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(define ((D f) x) (tangent (f (make-bundle x 1))))
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Convenient

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Convenient but **slow**

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(D (D f))
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Dynamic Overloading: SCMUTILS

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(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
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(define ((D f) x)
  (fluid-let ((+ (lambda (x1 x2)
                   (make-bundle (+ (primal x1) (primal x2))
                                   (+ (tangent x1) (tangent x2))))))
    (* (lambda (x1 x2)
        (make-bundle (* (primal x1) (primal x2))
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      (tangent (f (make-bundle x 1))))))

(define (f x) (* 2 (* x (* x x))))

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(D (D f))
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      (tangent (f (make-bundle x 1))))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

Convenient but **slow**

Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```


Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

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Fast

Preprocessor: ADIFOR and TAPENADE

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gf = 2.0d0*x*x*x
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```

Fast but **inconvenient**

Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

AD_TOP = f

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
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AD_TOP = f
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function f(x)
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```

```
AD_TOP = gf
AD_IVARS = x, gx
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Fast but **inconvenient**

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function f(x)
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AD_TOP = f
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```

```
AD_TOP = gf
AD_IVARS = x, gx
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```
function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
double precision x, gx, gx, ggx, ggf, gresult, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

Preprocessor: ADIFOR and TAPENADE

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function f(x)
double precision x, f
f = 2.0d0*x*x*x
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```
AD_TOP = f
AD_IVARS = x
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function gf(x, gx, gresult)
double precision x, gx, gf, gresult
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AD_TOP = gf
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function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
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function f(x)
double precision x, f
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```
AD_TOP = f
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AD_DVARS = f
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```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
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AD_TOP = gf
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function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
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end
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function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
AD_PREFIX = h
```

```
function hgf(x, hx, gx, hgx, gresult, hgresult, hresult)
double precision x, hx, gx, hgx, hgf, hresult, gresult, hgresult
hgf = 2.0d0*x*x*x
hresult = 6.0d0*x*x*hx
gresult = 6.0d0*x*x*gx
hgresult = 6.0d0*x*x*hgx+12.0d0*x*gx*hx
end
```

Fast but **inconvenient**

Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

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double f(double x) {return 2*x*x*x;}  
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```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

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```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
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Slow

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... f(x).d(0).d(0) ...
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Slow and **inconvenient**

Static Overloading: FADBAD++

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```

Slow and **inconvenient**

Static Overloading: FADBAD++

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Slow and **inconvenient**

Differential geometry bundles points \mathbb{R}^n in a manifold with tangent vectors $\overline{\mathbb{R}^h}$

Our API for Functional Forward AD

$$\text{bundle} : \mathbb{R}^n \times \overline{\mathbb{R}^h} \rightarrow (\mathbb{R}^n \triangleright \overline{\mathbb{R}^h})$$

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$$j^* : (\mathbb{R}^n \rightarrow \mathbb{R}^m) \rightarrow ((\mathbb{R}^n \triangleright \overline{\mathbb{R}^h}) \rightarrow (\mathbb{R}^m \triangleright \overline{\mathbb{R}^m}))$$

Differential geometry bundles points \mathbb{R}^n in a manifold with tangent vectors $\overline{\mathbb{R}^h}$
 j^* maps a **function** to its *push forward*

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Differential geometry bundles points \mathbb{R}^n in a manifold with tangent vectors $\overline{\mathbb{R}^n}$
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Generalize to arbitrary types

Our API for Functional Forward AD

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Differential geometry bundles points \mathbb{R}^n in a manifold with tangent vectors $\overline{\mathbb{R}^n}$
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Generalize to arbitrary types

What is the tangent of a discrete value or a function?

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Can abbreviate $\tau \triangleright \overline{\tau}$ as $\overline{\tau}^{\rightarrow}$

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(define ((D f) x) (tangent ((j* f) (bundle x 1))))
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Differential geometry bundles points \mathbb{R}^n in a manifold with tangent vectors $\overrightarrow{\mathbb{R}^n}$

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Convenient

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```
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What is $(j^* j^*)$?

Convenient and **fast**

A property

A property

$x : \mathbb{R}^n$

A property

$$x : \mathbb{R}^n$$

$$\overline{x} : \mathbb{R}^n$$

A property

$$x : \mathbb{R}^n$$

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$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

A property

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$$((\mathcal{J} f) x)[i, j] = \frac{\partial f(x)[i]}{\partial x[j]}$$

A property

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$$((\mathcal{J} f) \overline{x}) : \mathbb{R}^{m \times n}$$

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A property

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A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J} f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J} f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J} f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x)\end{aligned}$$

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$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J} f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J} f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J} f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J} f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J} f) x) \bar{x})\end{aligned}$$

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A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J}f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J}f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J} f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J} f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J} f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J} f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J} f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J} f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j] \\ f &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m\end{aligned}$$

A property

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$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J}f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J}f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

$$((\mathcal{J}f) x)$$

A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J} f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J} f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J} f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J} f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J} f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J} f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

$$((\mathcal{J} f) x) = \frac{\partial f(x)[i]}{\partial x[j]}$$

A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J}f)x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f)x) &: \mathbb{R}^{m \times n} & ((\mathcal{J}f)x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f)x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f)x) \bar{x}) \\((j^* f)x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

$$((\mathcal{J}f)x) = \frac{\partial f(x)[i]}{\partial x[j]} = \begin{cases} 1 & \text{when } (f x)[i] = x[j] \\ 0 & \text{otherwise} \end{cases}$$

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$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J}f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J}f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) ((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

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$$((\mathcal{J}f) x) = \frac{\partial f(x)[i]}{\partial x[j]} = \begin{cases} 1 & \text{when } (f x)[i] = x[j] \\ 0 & \text{otherwise} \end{cases} = f$$

when f is a rearrangement function

$$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$$

A property

$$x : \mathbb{R}^n \qquad \bar{x} : \mathbb{R}^n \qquad f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$
$$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J}f) x) : \mathbb{R}^{m \times n} \quad ((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

$$(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) = (f x)$$

$$(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) = ((\mathcal{J}f) x) \times \bar{x}$$

$$(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) = (((\mathcal{J}f) x) \bar{x})$$

$$((j^* f) x) = (\text{bundle } (f (\text{primal } x)) ((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))$$

rearrangement function: $(\forall i)(\exists j)(f x)[i] = x[j]$

$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

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A property

$$\begin{aligned}x &: \tau_1 & \bar{x} &: \tau_1 & f &: \tau_1 \rightarrow \tau_2 \\((\mathcal{J}f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f) x) &: \tau_1 \xrightarrow{L} \tau_2 \\(\text{primal } ((j* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f) x) \times \bar{x} \\(\text{tangent } ((j* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f) x) \bar{x}) \\((j* f) x) &= (\text{bundle } (f (\text{primal } x)) (((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x))) \\ \text{rearrangement function: } &(\forall i)(\exists j)(f x)[i] = x[j]\end{aligned}$$

$$f: \tau_1 \xrightarrow{L} \tau_2$$

0/1 matrix, every row has exactly one 1

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$$f : \tau_1 \xrightarrow{L} \tau_2$$

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when f is a rearrangement function

$$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$$

What is the tangent of $\#t$?

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What if we take $\overline{\#t} = \#f$?

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when f is a rearrangement function

$((j * f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

What is the tangent of #t?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j * f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t \ x \ y) \mapsto (\#t \ x \ y)$ but $f : (\#f \ x \ y) \mapsto (\#f \ y \ x)$

What is the tangent of #t?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j * f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

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f is a rearrangement function

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$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t x y) \mapsto (\#t x y)$ but $f : (\#f x y) \mapsto (\#f y x)$

f is a rearrangement function

$((j* f) (\text{bundle } (\#t x y) (\#f \overline{x} \overline{y})))$

What is the tangent of #t?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t x y) \mapsto (\#t x y)$ but $f : (\#f x y) \mapsto (\#f y x)$

f is a rearrangement function

$((j* f) (\text{bundle } (\#t x y) (\#f \overline{x'} \overline{y'})))$

$= (\text{bundle } (\#t x y) (\#f \overline{y'} \overline{x'}))$

What is the tangent of #t?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t x y) \mapsto (\#t x y)$ but $f : (\#f x y) \mapsto (\#f y x)$

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$((j* f) (\text{bundle } (\#t x y) (\#f \overline{x} \overline{y})))$

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What is the tangent of #t?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t x y) \mapsto (\#t x y)$ but $f : (\#f x y) \mapsto (\#f y x)$

f is a rearrangement function

$((j* f) (\text{bundle } (\#t x y) (\#f \overline{x} \overline{y})))$

$= (\text{bundle } (\#t x y) (\#f \overline{y} \overline{x}))$

What is the tangent of $\#t$?

What if we take $\overline{\#t} = \#f$?

when f is a rearrangement function

$((j* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$

$f : (\#t x y) \mapsto (\#t x y)$ but $f : (\#f x y) \mapsto (\#f y x)$

f is a rearrangement function

$((j* f) (\text{bundle } (\#t x y) (\#f \overline{x} \overline{y})))$

$= (\text{bundle } (\#t x y) (\#f \overline{y} \overline{x}))$

Problem avoided if we take $\overline{\#t} = \#t$

What is $(j^* \ j^*)$?

What is $(j^* \quad j^*)$?

when f is a rearrangement function

$$((j^* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$$

What is $(j^* \ j^*)$?

when f is a rearrangement function

$$((j^* f) x) = (\text{bundle } (f \ (\text{primal } x)) \ (f \ (\text{tangent } x)))$$

bundle , primal , tangent , and j^* are rearrangement functions

What is $(j^* j^*)$?

when f is a rearrangement function

$$((j^* f) x) = (\text{bundle } (f \text{ (primal } x)) \text{ (} f \text{ (tangent } x)))$$

bundle, primal, tangent, and j^* are rearrangement functions

$$((j^* \text{ bundle}) x) = (\text{bundle } (\text{bundle } (\text{primal } x)) \text{ (bundle } (\text{tangent } x)))$$

$$((j^* \text{ primal}) x) = (\text{bundle } (\text{primal } (\text{primal } x)) \text{ (primal } (\text{tangent } x)))$$

$$((j^* \text{ tangent}) x) = (\text{bundle } (\text{tangent } (\text{primal } x)) \text{ (tangent } (\text{tangent } x)))$$

$$((j^* j^*) x) = (\text{bundle } (j^* (\text{primal } x)) \text{ (} j^* \text{ (tangent } x)))$$

A (Not So) Brief Tutorial on AD

$$z = g(f(x))$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}z &= g(f(x)) \\ &= (f \circ g)(x)\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}z &= g(f(x)) \\ &= (f \circ g)(x)\end{aligned}$$

$$\begin{aligned}y &= f(x) \\ z &= g(y)\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}z &= g(f(x)) \\ &= (f \circ g)(x)\end{aligned}$$

$$\begin{aligned}y &= f(x) \\ z &= g(y)\end{aligned}$$

$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}z &= g(f(x)) \\ &= (f \circ g)(x)\end{aligned}$$

$$\begin{aligned}y &= f(x) \\ z &= g(y)\end{aligned}$$

$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$

$$\mathcal{D} (f \circ g) x = (\mathcal{D} g y) \times (\mathcal{D} f x)$$

A (Not So) Brief Tutorial on AD

$$f = f_1 \circ \cdots \circ f_n$$

A (Not So) Brief Tutorial on AD

$$f = f_1 \circ \cdots \circ f_n$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

A (Not So) Brief Tutorial on AD

$$f = f_1 \circ \cdots \circ f_n$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\mathcal{J} f \mathbf{x}_0 = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0)$$

A (Not So) Brief Tutorial on AD

$$f = f_1 \circ \cdots \circ f_n$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\mathcal{J} f \mathbf{x}_0 = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0)$$

$$(\mathcal{J} f \mathbf{x}_0)^\top = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{X}}_n = \mathcal{J} f \mathbf{x}_0$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n &= \mathcal{J} f \mathbf{x}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_2 \mathbf{x}_1) \times (\mathcal{J} f_1 \mathbf{x}_0)\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n &= \mathcal{J} f \mathbf{x}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_2 \mathbf{x}_1) \times (\mathcal{J} f_1 \mathbf{x}_0)\end{aligned}$$

$$\overline{\mathbf{X}}_1 = (\mathcal{J} f_1 \mathbf{x}_0)$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n &= \mathcal{J} f \mathbf{x}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_2 \mathbf{x}_1) \times (\mathcal{J} f_1 \mathbf{x}_0)\end{aligned}$$

$$\overline{\mathbf{X}}_1 = (\mathcal{J} f_1 \mathbf{x}_0)$$

$$\overline{\mathbf{X}}_2 = (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}}_1$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n &= \mathcal{J} f \mathbf{x}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_2 \mathbf{x}_1) \times (\mathcal{J} f_1 \mathbf{x}_0)\end{aligned}$$

$$\overline{\mathbf{X}}_1 = (\mathcal{J} f_1 \mathbf{x}_0)$$

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⋮

$$\overline{\mathbf{X}}_n = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{X}}_{n-1}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{X}_0} = (\mathcal{J} f \mathbf{x}_0)^\top$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top\end{aligned}$$

$$\overline{\mathbf{X}_{n-1}} = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top\end{aligned}$$

$$\overline{\mathbf{X}_{n-1}} = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top$$

$$\overline{\mathbf{X}_{n-2}} = (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}_{n-1}}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_0 &= (\mathcal{J} f \mathbf{x}_0)^\top \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{X}}_{n-1} &= (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overline{\mathbf{X}}_{n-2} &= (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}}_{n-1} \\ &\vdots \\ \overline{\mathbf{X}}_0 &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}}_1\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{array}{ll} \overline{\mathbf{X}}_1 &= (\mathcal{J} f_1 \mathbf{x}_0) \\ \overline{\mathbf{X}}_2 &= (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}}_1 \\ &\vdots \\ \overline{\mathbf{X}}_n &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{X}}_{n-1} \end{array} \qquad \begin{array}{ll} \overline{\mathbf{X}}_{n-1} &= (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overline{\mathbf{X}}_{n-2} &= (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}}_{n-1} \\ &\vdots \\ \overline{\mathbf{X}}_0 &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}}_1 \end{array}$$

A (Not So) Brief Tutorial on AD

$$\begin{array}{ll} \overline{\mathbf{X}}_1 & = (\mathcal{J} f_1 \mathbf{x}_0) \\ \overline{\mathbf{X}}_2 & = (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}}_1 \\ & \vdots \\ \overline{\mathbf{X}}_n & = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{X}}_{n-1} \end{array} \quad \begin{array}{ll} \overline{\mathbf{X}}_{n-1} & = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overline{\mathbf{X}}_{n-2} & = (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}}_{n-1} \\ & \vdots \\ \overline{\mathbf{X}}_0 & = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}}_1 \end{array}$$

A (Not So) Brief Tutorial on AD

$$\begin{array}{ll} \overline{\mathbf{X}}_1 & = (\mathcal{J} f_1 \mathbf{x}_0) \\ \overline{\mathbf{X}}_2 & = (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}}_1 \\ & \vdots \\ \overline{\mathbf{X}}_n & = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{X}}_{n-1} \end{array} \qquad \begin{array}{ll} \overline{\mathbf{X}}_{n-1} & = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overline{\mathbf{X}}_{n-2} & = (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}}_{n-1} \\ & \vdots \\ \overline{\mathbf{X}}_0 & = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}}_1 \end{array}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}_n = (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_n &= (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) \times \overline{\mathbf{x}}_0\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_n &= (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0 \\ &= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) \times \overline{\mathbf{x}}_0\end{aligned}$$

$$\overline{\mathbf{x}}_1 = (\mathcal{J} f_1 \mathbf{x}_0) \times \overline{\mathbf{x}}_0$$

⋮

$$\overline{\mathbf{x}}_n = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{x}}_{n-1}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}_0 = (\mathcal{J} f \mathbf{x}_0)^\top \times \overline{\mathbf{x}}_n$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \times \overline{\mathbf{x}_n} \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \times \overline{\mathbf{x}_n}\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \times \overline{\mathbf{x}_n} \\ &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \times \overline{\mathbf{x}_n}\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{x}_{n-1}} &= (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \times \overline{\mathbf{x}_n} \\ &\vdots \\ \overline{\mathbf{x}_0} &= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{x}_1}\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\mathbf{y} = \mathbf{A} \times \mathbf{x}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\overline{\mathbf{x}}'_n = (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}'_0$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{x}}_n &= (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0 \\ &= \overline{f'} \mathbf{x}_0 \overline{\mathbf{x}}_0\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{x}}_n &= (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0 \\ &= \overline{f'} \mathbf{x}_0 \overline{\mathbf{x}}_0\end{aligned}$$

$$\overline{\mathbf{x}}_0 = (\mathcal{J} f \mathbf{x}_0)^\top \times \overline{\mathbf{x}}_n$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{x}}_n &= (\mathcal{J} f \mathbf{x}_0) \times \overline{\mathbf{x}}_0 \\ &= \overline{f} \mathbf{x}_0 \overline{\mathbf{x}}_0\end{aligned}$$

$$\begin{aligned}\overleftarrow{\mathbf{x}}_0 &= (\mathcal{J} f \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}}_n \\ &= \overleftarrow{f} \mathbf{x}_0 \overleftarrow{\mathbf{x}}_n\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}_n[:,j] = \overline{f'} \mathbf{x}_0 \overline{\mathbf{e}}_j$$

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$$\begin{aligned}\overline{\mathbf{x}}_n[;j] &= \overline{f}' \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[;j]\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[j] &= \overline{f}' \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[j]\end{aligned}$$

$$\underline{\mathbf{X}}_0[i] = \underline{f}' \mathbf{x}_0 \underline{\mathbf{e}}_i$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[j]\end{aligned}$$

$$\begin{aligned}\overleftarrow{\mathbf{X}}_0[i] &= \overleftarrow{f} \mathbf{x}_0 \overleftarrow{\mathbf{e}}_i \\ &= (\mathcal{J} f \mathbf{x}_0)^\top[i]\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[j]\end{aligned}$$

$$\begin{aligned}\overleftarrow{\mathbf{X}}_0[i] &= \overleftarrow{f} \mathbf{x}_0 \overleftarrow{\mathbf{e}}_i \\ &= (\mathcal{J} f \mathbf{x}_0)^\top[i] \\ &= (\mathcal{J} f \mathbf{x}_0)[i;]\end{aligned}$$

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$$\mathbf{y} = \mathbf{B} \times (\mathbf{A} \times \mathbf{x})$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x}\end{aligned}$$

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$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x}))\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

$$(\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) = (\overline{f_1} \mathbf{x}_0) \circ \cdots \circ (\overline{f_n} \mathbf{x}_{n-1})$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

$$\begin{aligned}(\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) &= (\overline{f_1} \mathbf{x}_0) \circ \cdots \circ (\overline{f_n} \mathbf{x}_{n-1}) \\ (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top &= (\overline{f_n} \mathbf{x}_{n-1}) \circ \cdots \circ (\overline{f_1} \mathbf{x}_0)\end{aligned}$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{u_i \mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{u_i \mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{u_i \mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

$$\mathbf{x}[L_i] := b(\mathbf{x}[R_i], \mathbf{x}[S_i])$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

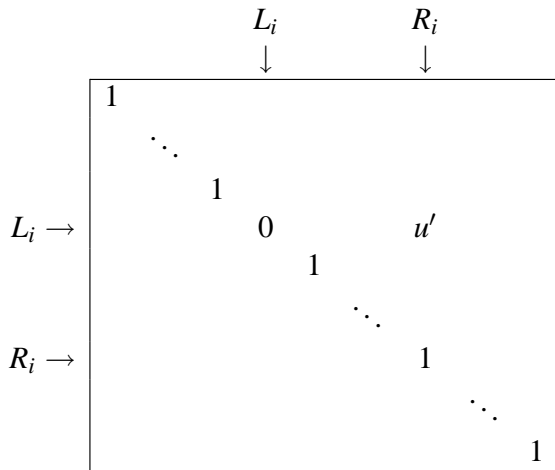
$$\mathbf{x}[L_i] := b(\mathbf{x}[R_i], \mathbf{x}[S_i])$$

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$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

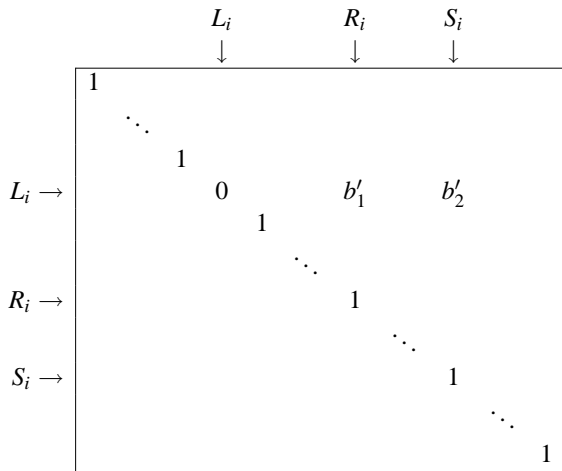
$$\mathbf{x}[L_i] := b(\mathbf{x}[R_i], \mathbf{x}[S_i])$$

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$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

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$$b'_1 = \mathcal{D}_1 b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$

$$b'_2 = \mathcal{D}_2 b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$

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$$\overline{\mathbf{x}}_i' = \overline{f}_i \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1}'$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_i &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}}_{i-1}\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}_i = \overline{f}_i \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_i &= \overline{f}_i \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}}_{i-1}\end{aligned}$$

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$$\overline{\mathbf{x}_{i-1}} = \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_{i-1} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}}_i \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}}_i\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}_{i-1}} = \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i}$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}_{i-1} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}}_i \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}}_i\end{aligned}$$

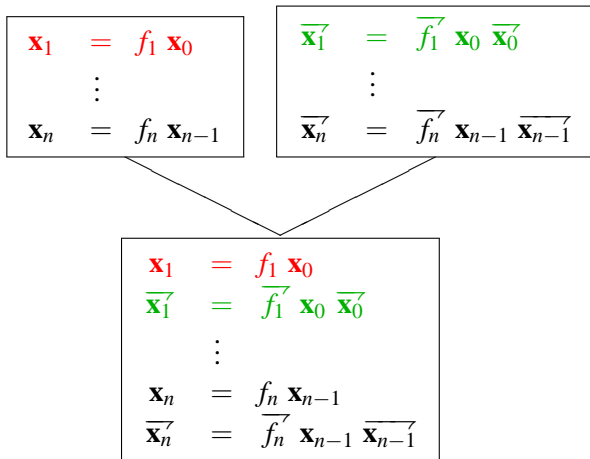
A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1}\end{aligned}$$

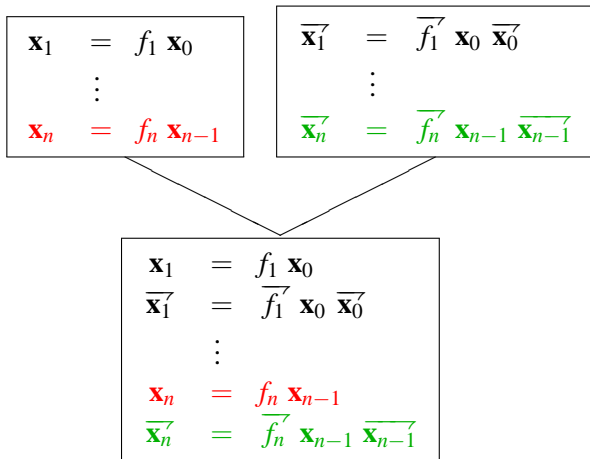
$$\begin{aligned}\overline{\mathbf{x}}_1' &= \overline{f_1}' \mathbf{x}_0 \overline{\mathbf{x}}_0' \\ &\vdots \\ \overline{\mathbf{x}}_n' &= \overline{f_n}' \mathbf{x}_{n-1} \overline{\mathbf{x}}_{n-1}'\end{aligned}$$

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ \overline{\mathbf{x}}_1' &= \overline{f_1}' \mathbf{x}_0 \overline{\mathbf{x}}_0' \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}}_n' &= \overline{f_n}' \mathbf{x}_{n-1} \overline{\mathbf{x}}_{n-1}'\end{aligned}$$

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A (Not So) Brief Tutorial on AD



A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ \overline{\mathbf{x}}_1' &= \overline{f_1}' \mathbf{x}_0 \overline{\mathbf{x}}_0' \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}}_n' &= \overline{f_n}' \mathbf{x}_{n-1} \overline{\mathbf{x}}_{n-1}'\end{aligned}$$

$$\begin{aligned}(\mathbf{x}_1, \overline{\mathbf{x}}_1') &= ((f_1 \mathbf{x}_0), (\overline{f_1}' \mathbf{x}_0 \overline{\mathbf{x}}_0')) \\ &\vdots \\ (\mathbf{x}_n, \overline{\mathbf{x}}_n') &= ((f_n \mathbf{x}_{n-1}), (\overline{f_n}' \mathbf{x}_{n-1} \overline{\mathbf{x}}_{n-1}'))\end{aligned}$$

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$$\left. \begin{array}{l} \mathbf{x}_1 = f_1 \mathbf{x}_0 \\ \vdots \\ \mathbf{x}_n = f_n \mathbf{x}_{n-1} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \overrightarrow{\mathbf{x}}_1 = \overrightarrow{f}_1 \overrightarrow{\mathbf{x}}_0 \\ \vdots \\ \overrightarrow{\mathbf{x}}_n = \overrightarrow{f}_n \overrightarrow{\mathbf{x}}_{n-1} \end{array} \right.$$

$$\begin{aligned} \overrightarrow{\mathbf{x}} &\equiv (\mathbf{x}, \overline{\mathbf{x}}) \\ \overrightarrow{f} \overrightarrow{\mathbf{x}} &\equiv ((f \mathbf{x}), (\overline{f} \mathbf{x} \overline{\mathbf{x}})) \end{aligned}$$

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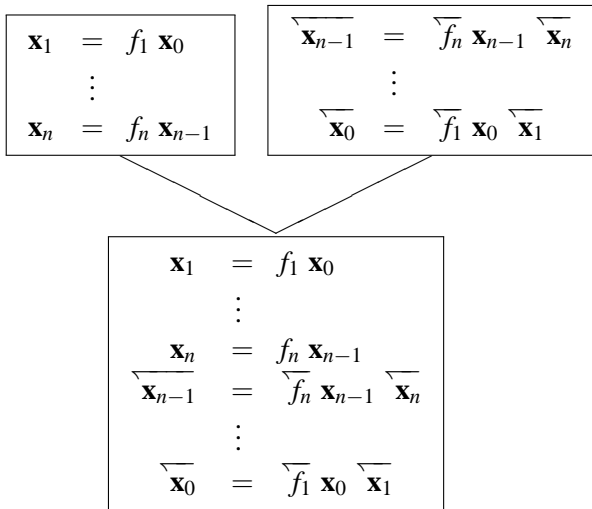
$$\begin{aligned}x_{L_i} &:= u_i x_{R_i} &\rightsquigarrow& \overrightarrow{x_{L_i}} := \overrightarrow{u_i} \overrightarrow{x_{R_i}} \\x_{L_i} &:= b_i (x_{R_i}, x_{S_i}) &\rightsquigarrow& \overrightarrow{x_{L_i}} := \overrightarrow{b_i} (\overrightarrow{x_{R_i}}, \overrightarrow{x_{S_i}})\end{aligned}$$

$$\overrightarrow{x} \equiv (x, \overline{x'})$$

$$\overrightarrow{u} \overrightarrow{x} \equiv ((u x), ((\mathcal{D} u x) \times \overline{x'}))$$

$$\overrightarrow{b} (\overrightarrow{x_1}, \overrightarrow{x_2}) \equiv ((b (x_1, x_2)), ((\mathcal{D}_1 b (x_1, x_2)) \times \overline{x'_1}) + ((\mathcal{D}_2 b (x_1, x_2)) \times \overline{x'_2})))$$

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A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

$$\vdots$$

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

$$\vdots$$

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

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$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

$$\vdots$$

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\vdots$$

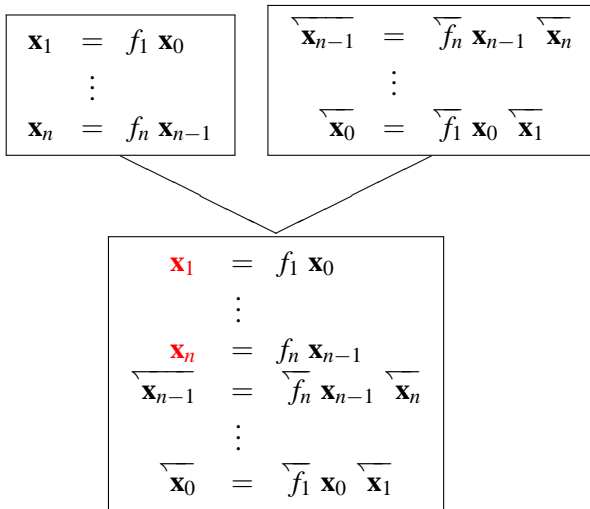
$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

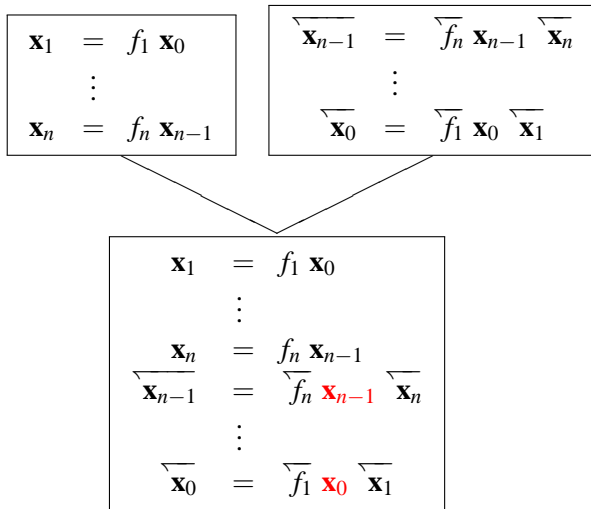
$$\vdots$$

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

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A (Not So) Brief Tutorial on AD



A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\overline{\mathbf{x}}_1 = \lambda \overline{\mathbf{x}} \quad \overline{\mathbf{x}}_0 (\overline{f}_1 \mathbf{x}_0 \overline{\mathbf{x}})$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}}_n = \lambda \overline{\mathbf{x}} \quad \overline{\mathbf{x}}_{n-1} (\overline{f}_1 \mathbf{x}_0 \overline{\mathbf{x}})$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ \overline{\mathbf{x}}_1 &= \lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}}_0 (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}}) \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}}_n &= \lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}}_{n-1} (\overline{f_n} \ \mathbf{x}_0 \ \overline{\mathbf{x}})\end{aligned}$$

$$\begin{aligned}(\mathbf{x}_1, \overline{\mathbf{x}}_1) &= ((f_1 \ \mathbf{x}_0), (\lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}}_0 (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}}))) \\ &\vdots \\ (\mathbf{x}_n, \overline{\mathbf{x}}_n) &= ((f_n \ \mathbf{x}_{n-1}), (\lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}}_{n-1} (\overline{f_n} \ \mathbf{x}_0 \ \overline{\mathbf{x}})))\end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\left. \begin{array}{l} \mathbf{x}_1 = f_1 \mathbf{x}_0 \\ \vdots \\ \mathbf{x}_n = f_n \mathbf{x}_{n-1} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \overleftarrow{\mathbf{x}}_1 = \overleftarrow{f}_1 \overleftarrow{\mathbf{x}}_0 \\ \vdots \\ \overleftarrow{\mathbf{x}}_n = \overleftarrow{f}_n \overleftarrow{\mathbf{x}}_{n-1} \end{array} \right.$$

$$\begin{aligned} \overleftarrow{\mathbf{x}} &\equiv (\mathbf{x}, \overline{\mathbf{x}}) \\ \overleftarrow{f} \overleftarrow{\mathbf{x}} &\equiv ((f \mathbf{x}), (\lambda \overline{\mathbf{x}} \overline{\mathbf{x}} (\overline{f} \mathbf{x} \overline{\mathbf{x}}))) \end{aligned}$$

A (Not So) Brief Tutorial on AD

$$\overleftarrow{f} \mathbf{x} \equiv \mathbf{begin} \ \bar{x} := \lambda \overleftarrow{\mathbf{x}} \ \bar{x} (\overleftarrow{f} \ \mathbf{x} \ \overleftarrow{\mathbf{x}}); \\ \quad (f \ \mathbf{x}) \ \mathbf{end}$$

A (Not So) Brief Tutorial on AD

$$\begin{array}{l}
 x_{L_i} := u_i x_{R_i} \quad \rightsquigarrow \\
 \\
 x_{L_i} := b_i(x_{R_i}, x_{S_i}) \quad \rightsquigarrow
 \end{array}
 \left\{ \begin{array}{l}
 \bar{x} := \lambda[] \mathbf{begin} \quad \overline{x_{R_i}} += (\mathcal{D} u_i \overleftarrow{x_{R_i}}) \times \overline{x_{L_i}}; \\
 \quad \quad \quad \overline{x_{L_i}} := 0; \\
 \quad \quad \quad \bar{x} [] \mathbf{end} \\
 \\
 \overleftarrow{x_{L_i}} := u_i \overleftarrow{x_{R_i}} \\
 \\
 \bar{x} := \lambda[] \mathbf{begin} \quad \overline{x_{R_i}} += (\mathcal{D}_1 b_i(\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overline{x_{L_i}}; \\
 \quad \quad \quad \overline{x_{S_i}} += (\mathcal{D}_2 b_i(\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overline{x_{L_i}}; \\
 \quad \quad \quad \overline{x_{L_i}} := 0; \\
 \quad \quad \quad \bar{x} [] \mathbf{end} \\
 \\
 \overleftarrow{x_{L_i}} := b_i(\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})
 \end{array} \right.$$

$$\overleftarrow{x} \equiv x$$

A (Not So) Brief Tutorial on AD

$$\begin{aligned} x_{L_i} := u_i x_{R_i} &\rightsquigarrow \left\{ \begin{array}{l} \overleftarrow{x}_{L_i} := u_i \overleftarrow{x}_{R_i} \\ \vdots \\ \overleftarrow{x}_{R_i} + := (\mathcal{D} u_i \overleftarrow{x}_{R_i}) \times \overleftarrow{x}_{L_i}; \\ \overleftarrow{x}_{L_i} := 0 \end{array} \right. \\ x_{L_i} := b_i(x_{R_i}, x_{S_i}) &\rightsquigarrow \left\{ \begin{array}{l} \overleftarrow{x}_{L_i} := b_i(\overleftarrow{x}_{R_i}, \overleftarrow{x}_{S_i}) \\ \vdots \\ \overleftarrow{x}_{R_i} + := (\mathcal{D}_1 b_i(\overleftarrow{x}_{R_i}, \overleftarrow{x}_{S_i})) \times \overleftarrow{x}_{L_i}; \\ \overleftarrow{x}_{S_i} + := (\mathcal{D}_2 b_i(\overleftarrow{x}_{R_i}, \overleftarrow{x}_{S_i})) \times \overleftarrow{x}_{L_i}; \\ \overleftarrow{x}_{L_i} := 0 \end{array} \right. \end{aligned}$$

$$\overleftarrow{x} \equiv x$$

The Functional Reverse-Mode Transformation

$$x_{L_1} := u_1 x_{S_1}$$

$$\vdots$$

$$x_{L_n} := u_n x_{S_n}$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} + := (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} + := (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_{L_1} \quad := \quad u_1 \ x_{S_1} \\ \vdots \\ x_{L_n} \quad := \quad u_n \ x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} \quad := \quad u_1 \ x_{S_1} \\ \vdots \\ x_{L_n} \quad := \quad u_n \ x_{S_n} \\ \overline{x_1} \quad := \quad 0 \\ \vdots \\ \overline{x_m} \quad := \quad 0 \\ \overline{x_{S_n}} \quad +:= \quad (\mathcal{D} \ u_n \ x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} \quad := \quad 0 \\ \vdots \\ \overline{x_{S_1}} \quad +:= \quad (\mathcal{D} \ u_1 \ x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} \quad := \quad 0 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +:=(\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +:=(\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +: = (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +: = (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \\ \overline{x_0} := 0 \\ \vdots \\ \overline{x_{n-1}} := 0 \\ \overline{x_{S_n}} +: = (\mathcal{D} u_n x_{S_n}) \times \overline{x_n} \\ \vdots \\ \overline{x_{S_1}} +: = (\mathcal{D} u_1 x_{S_1}) \times \overline{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \\ \overline{x_0} := 0 \\ \vdots \\ \overline{x_{n-1}} := 0 \\ \overline{x_{S_n}} +:= (\mathcal{D} u_n x_{S_n}) \times \overline{x_n} \\ \vdots \\ \overline{x_{S_1}} +:= (\mathcal{D} u_1 x_{S_1}) \times \overline{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\overline{u_i} \triangleq \lambda \overline{x} (\mathcal{D} u_i x_{S_i}) \times \overline{x}$$

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \\ \overline{x_0} := 0 \\ \vdots \\ \overline{x_{n-1}} := 0 \\ \overline{x_{S_n}} + := \overline{u_n} \overline{x_n} \\ \vdots \\ \overline{x_{S_1}} + := \overline{u_1} \overline{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\overleftarrow{u} \ x \triangleq ((u \ x), (\lambda \overleftarrow{x} (\mathcal{D} \ u \ x) \times \overleftarrow{x})))$$

$$\left. \begin{array}{l} x_1 = u_1 \ x_{S_1} \\ \vdots \\ x_n = u_n \ x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (x_1, \overleftarrow{x}_1) = \overleftarrow{u}_1 \ x_{S_1} \\ \vdots \\ (x_n, \overleftarrow{x}_n) = \overleftarrow{u}_n \ x_{S_n} \\ \overleftarrow{x}_0 := 0 \\ \vdots \\ \overleftarrow{x}_{n-1} := 0 \\ \overleftarrow{x}_{S_n} + := \overleftarrow{x}_n \ \overleftarrow{x}_n \\ \vdots \\ \overleftarrow{x}_{S_1} + := \overleftarrow{x}_1 \ \overleftarrow{x}_1 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\overleftarrow{u} \ x \triangleq ((u \ x), (\lambda \overleftarrow{x} (\mathcal{D} \ u \ x) \times \overleftarrow{x}))$$

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (x_1, \overleftarrow{x}_1) = \overleftarrow{u}_1 x_{S_1} \\ \vdots \\ (x_n, \overleftarrow{x}_n) = \overleftarrow{u}_n x_{S_n} \\ \overleftarrow{x}_0 := 0 \\ \vdots \\ \overleftarrow{x}_{n-1} := 0 \\ \overleftarrow{x}_{S_n} + := \overleftarrow{x}_n \ \overleftarrow{x}_n \\ \vdots \\ \overleftarrow{x}_{S_1} + := \overleftarrow{x}_1 \ \overleftarrow{x}_1 \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\overleftarrow{x_1}, \overleftarrow{x_1}) = \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots \\ (\overleftarrow{x_n}, \overleftarrow{x_n}) = \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} := 0 \\ \vdots \\ \overleftarrow{x_{n-1}} := 0 \\ \overleftarrow{x_{S_n}} +: = \overleftarrow{x_n} \overleftarrow{x_n} \\ \vdots \\ \overleftarrow{x_{S_1}} +: = \overleftarrow{x_1} \overleftarrow{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\overleftarrow{x_1}, \overline{x_1}) = \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) = \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overline{x_0} := 0 \\ \vdots \\ \overline{x_{n-1}} := 0 \\ \overline{x_{S_n}} +: = \overline{x_n} \overline{x_n} \\ \vdots \\ \overline{x_{S_1}} +: = \overline{x_1} \overline{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\overleftarrow{x_1}, \overleftarrow{x_1}) = \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots \\ (\overleftarrow{x_n}, \overleftarrow{x_n}) = \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} := 0 \\ \vdots \\ \overleftarrow{x_{n-1}} := 0 \\ \overleftarrow{x_{S_n}} +: = \overleftarrow{x_n} \overleftarrow{x_n} \\ \vdots \\ \overleftarrow{x_{S_1}} +: = \overleftarrow{x_1} \overleftarrow{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\overleftarrow{x_1}, \overleftarrow{x_1}) = \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots \\ (\overleftarrow{x_n}, \overleftarrow{x_n}) = \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} := 0 \\ \vdots \\ \overleftarrow{x_{n-1}} := 0 \\ \overleftarrow{x_{S_n}} \text{ } + := \overleftarrow{x_n} \overleftarrow{x_n} \\ \vdots \\ \overleftarrow{x_{S_1}} \text{ } + := \overleftarrow{x_1} \overleftarrow{x_1} \end{array} \right.$$

The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\overleftarrow{x}_1, \overleftarrow{x}_1) = \overleftarrow{x}_{R_1} \overleftarrow{x}_{S_1} \\ \vdots \\ (\overleftarrow{x}_n, \overleftarrow{x}_n) = \overleftarrow{x}_{R_n} \overleftarrow{x}_{S_n} \\ \overleftarrow{x}_0 := \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x}_0) \\ \vdots \\ \overleftarrow{x}_{n-1} := \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x}_{n-1}) \\ \overleftarrow{x}_{S_n} \oplus := \overleftarrow{x}_n \overleftarrow{x}_n \\ \vdots \\ \overleftarrow{x}_{S_1} \oplus := \overleftarrow{x}_1 \overleftarrow{x}_1 \end{array} \right.$$

Modularity

 $\nabla f \mathbf{x}$

$$\triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

Modularity

$$\nabla f \mathbf{x} \triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

Modularity

$$\nabla f \mathbf{x} \triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

Modularity

$\nabla f \mathbf{x}$	\triangleq	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX r	\triangleq	<i>classified</i>

Modularity

$\nabla f \mathbf{x}$	\triangleq	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX r	\triangleq	<i>classified</i>
DEVIATION r	\triangleq	$((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$

Modularity

$\nabla f \mathbf{x}$	\triangleq	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX r	\triangleq	classified
DEVIATION r	\triangleq	$((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$
r^*	\triangleq	argmin DEVIATION

Fermi, E. (1946). *The Development of the first chain reaction pile*.
Proceedings of the American Philosophy Society, **90**:20–4.

Breaking Modularity

$\nabla f \mathbf{x}$	\triangleq	$(\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX r	\triangleq	classified
DEVIATION r	\triangleq	$((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$
r^*	\triangleq	argmin DEVIATION

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Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \text{argmin DEVIATION}$$

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Proceedings of the American Philosophy Society, **90**:20–4.

Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1^T), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n^T)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \text{argmin DEVIATION}$$

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Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } \vec{f} \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \text{argmin DEVIATION}$$

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Breaking Modularity

$$\nabla \overrightarrow{f} \mathbf{x} \triangleq (\overrightarrow{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}}_1), \dots, (\overrightarrow{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}}_n)$$

$$\text{GRADIENTDESCENT } \overrightarrow{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \overrightarrow{f} \mathbf{x}_i \dots$$

$$\text{argmin } \overrightarrow{f} \triangleq \dots \text{GRADIENTDESCENT } \overrightarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \text{argmin } \overrightarrow{\text{DEVIATION}}$$

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Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } \vec{f} \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION} \xrightarrow{\text{ADIFOR}} \overrightarrow{\text{DEVIATION}}$$

$$r^* \triangleq \text{argmin } \overrightarrow{\text{DEVIATION}}$$

Fermi, E. (1946). *The Development of the first chain reaction pile.*

Proceedings of the American Philosophy Society, **90**:20–4.

Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1^T), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n^T)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } \vec{f} \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \xrightarrow[\rightsquigarrow]{\text{ADIFOR}} \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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$$\text{NEUTRONFLUX } \mathbf{r} \triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \xrightarrow[\rightsquigarrow]{\text{ADIFOR}} \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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Breaking Modularity

$\nabla \vec{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\vec{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$
argmin \vec{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{DEVIATION}}$
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GRADIENTDESCENT $\overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overrightarrow{f} \mathbf{x}_i \dots$
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NEUTRONFLUX	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
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$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H}f \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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$$\text{argmin} \overleftarrow{f} \quad \triangleq \quad \dots \text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$$

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$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	$\dots \overleftarrow{\overleftarrow{f}} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
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NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
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Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
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GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
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GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
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GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin \overleftarrow{f}	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
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NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
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$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	argmin $\overleftarrow{\text{DEVIATION}} \overrightarrow{\text{DEVIATION}}$

Fermi, E. (1946). *The Development of the first chain reaction pile*.
 Proceedings of the American Philosophy Society, **90**:20–4.

Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	\triangleq	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	\triangleq	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
$\operatorname{argmin} \overleftarrow{f} \overrightarrow{f}$	\triangleq	$\dots \operatorname{NEWTNSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
NEUTRONFLUX	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overleftarrow{\text{NEUTRONFLUX}}$
$\overleftarrow{\text{NEUTRONFLUX}}$	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overleftarrow{\text{DEVIATION}}$
$\overleftarrow{\text{DEVIATION}}$	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overrightarrow{\text{DEVIATION}}$
\mathbf{r}^*	\triangleq	$\operatorname{argmin} \overleftarrow{\text{DEVIATION}} \overrightarrow{\text{DEVIATION}}$

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	<i>classified</i>
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_1'), \dots, ((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_n')$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	<i>classified</i>
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	classified
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Restoring Modularity

$\nabla f \mathbf{x}$	\triangleq	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	\triangleq	$\dots (\overrightarrow{\mathcal{J}} (\overleftarrow{\mathcal{J}} f)) \dots \mathbf{x} \dots$
GRADIENTDESCENT $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	\triangleq	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin f	\triangleq	$\dots \text{NEWTONSMETHOD } f \mathbf{x}_0 \dots$
NEUTRONFLUX \mathbf{r}	\triangleq	<div style="border: 1px solid black; padding: 2px; display: inline-block;">classified</div>
DEVIATION \mathbf{r}	\triangleq	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
\mathbf{r}^*	\triangleq	argmin DEVIATION

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Having your cake and eating it too

- Convenient

- Fast

Having your cake and eating it too

- Convenient
 - \mathcal{D} formulated as a higher-order function in the language
 - no arbitrary restrictions
 - applies to all data types and constructs in the language, including code produced by \mathcal{D} and even \mathcal{D} itself

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- higher-order derivatives
 - $(\mathcal{D} (\mathcal{D} f))$

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- higher-order derivatives
 - $(\mathcal{D} (\mathcal{D} f))$
- nesting
 - $(\mathcal{D} (\text{lambda } (...) \dots (\mathcal{D} (\text{lambda } (...) \dots)) \dots))$

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 - $(\mathcal{D} (\mathcal{D} f))$
- nesting
 - $(\mathcal{D} (\text{lambda } (...) \dots (\mathcal{D} (\text{lambda } (...) \dots)) \dots))$

- Fast

- \mathcal{D} implemented by reflective transformation of environments and code associated with closures

Having your cake and eating it too

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- \mathcal{D} formulated as a higher-order function in the language
- no arbitrary restrictions
 - applies to all data types and constructs in the language, including code produced by \mathcal{D} and even \mathcal{D} itself
- higher-order derivatives
 - $(\mathcal{D} (\mathcal{D} f))$
- nesting
 - $(\mathcal{D} (\text{lambda } (...) \dots (\mathcal{D} (\text{lambda } (...) \dots)) \dots))$

- Fast

- \mathcal{D} implemented by reflective transformation of environments and code associated with closures
- compile away reflection with partial evaluation implemented by flow analysis

Monovariant Flow Analysis: 0-CFA

```
(define ( $\mathcal{D}$  f)  
...)
```

Monovariant Flow Analysis: 0-CFA

```
(define ( $\mathcal{D}$  f)  
  ...)
```

```
( $\mathcal{D}$  (lambda (x)  $2x^3$ ))
```


Monovariant Flow Analysis: 0-CFA

```
(define (D f:  $(\lambda x 2x^3)$ )  
  ...)
```

```
(D (lambda (x)  $2x^3$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ ))  
  ...:( $\lambda x 6x^2$ ))  
  
(D (lambda (x)  $2x^3$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ ))  
  ...:( $\lambda x 6x^2$ ))
```

```
(D (lambda (x)  $2x^3$ )):( $\lambda x 6x^2$ )
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3))  
  ...:(λx 6x2))
```

```
(D (lambda (x) 2x3)):(λx 6x2)
```

```
(D (lambda (x) 3x4))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f : ( $\lambda x$   $2x^3$ )  $\cup$  ( $\lambda x$   $3x^4$ ))  
  ... : ( $\lambda x$   $6x^2$ ))
```

```
(D (lambda (x)  $2x^3$ )) : ( $\lambda x$   $6x^2$ )
```

```
(D (lambda (x)  $3x^4$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f : (λx 2x3) ∪ (λx 3x4))  
  ... : (λx 6x2) ∪ (λx 12x3))
```

```
(D (lambda (x) 2x3)) : (λx 6x2)
```

```
(D (lambda (x) 3x4))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f : ( $\lambda x$   $2x^3$ )  $\cup$  ( $\lambda x$   $3x^4$ ))  
  ... : ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ ))
```

```
(D (lambda (x)  $2x^3$ )) : ( $\lambda x$   $6x^2$ )
```

```
(D (lambda (x)  $3x^4$ )) : ( $\lambda x$   $12x^3$ )
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ )  $\cup$  ( $\lambda x 3x^4$ ))  
  ...:( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ ))
```

```
(D (lambda (x) 2x3)) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )
```

```
(D (lambda (x) 3x4)) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )
```


Monovariant Flow Analysis: 0-CFA

```
(define (D f: ( $\lambda x$   $2x^3$ )  $\cup$  ( $\lambda x$   $3x^4$ ))  
  ...: ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ ))
```

```
(D (lambda (x)  $2x^3$ )) : ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ )
```

```
(D (lambda (x)  $3x^4$ )) : ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ )
```

Monovariant Flow Analysis: 0-CFA

```
(define ( $\mathcal{D}$  f)  
  ...)
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f)  
  ...)
```

```
(D (D (lambda (x) e2x)))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ ))  
  ...)
```

```
(D (D (lambda (x)  $e^{2x}$ )))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ ))  
  
(D (D (lambda (x)  $e^{2x}$ )))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ ))):( $\lambda x 2e^{2x}$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ )):( $\lambda x 2e^{2x}$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ )):( $\lambda x 2e^{2x}$ ))
```


Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ ))):(  $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))  
...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ ))):(  $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
```

```
(D (D (lambda (x) e2x))):( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
```

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}$  f) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}$  f) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}_g$  f) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

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Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}_g$  f:( $\lambda x$   $2x^3$ )) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

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Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

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```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
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(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

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```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define (Dg f : (λx 2x3)) ... : (λx 6x2))
```

```
(define (Dh f) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)) : (λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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(define (Dg f:(λx 2x3) ...:(λx 6x2))
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```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (Dh f:(λx 3x4) ...:(λx 12x3))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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Polyvariant Flow Analysis: k -CFA

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(define (Dg f:(λx 2x3) ...:(λx 6x2))
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```

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```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))

((compose k  $\mathcal{D}$ ) g)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

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  (if (zero? n) x ((compose (- n 1) f) (f x))))
```

```
((compose k  $\mathcal{D}$ ) g)
```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

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```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))
```

```
((compose k  $\mathcal{D}$ ) g)
```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose}}$  f:g') ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))
```

```
((compose k  $\mathcal{D}$ ) g)
```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose}}$  f:g') ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose:compose}}$  f:g'') ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis: k -CFA

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```
(define ((compose n f) x)
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```

```
((compose k  $\mathcal{D}$ ) g)
```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose}}$  f:g') ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose:compose}}$  f:g'') ...)
```

⋮

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

$$v ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (v_1, v_2) \mid \langle \sigma, e \rangle$$

$$\sigma ::= \{x_1 \mapsto v_1, \dots\}$$

Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

$$v ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (v_1, v_2) \mid \langle \sigma, e \rangle$$

$$\sigma ::= \{x_1 \mapsto v_1, \dots\}$$

$$\bar{v} ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (\bar{v}_1, \bar{v}_2) \mid \langle \bar{\sigma}, e \rangle \mid \overline{\mathbb{R}}$$

$$\bar{\sigma} ::= \{x_1 \mapsto \bar{v}_1, \dots\}$$

Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

$$v ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (v_1, v_2) \mid \langle \sigma, e \rangle$$

$$\sigma ::= \{x_1 \mapsto v_1, \dots\}$$

$$\bar{\mathcal{E}} : e \times \bar{\sigma} \rightarrow \bar{v}$$

$$\bar{v} ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (\bar{v}_1, \bar{v}_2) \mid \langle \bar{\sigma}, e \rangle \mid \bar{\mathbb{R}}$$

$$\bar{\sigma} ::= \{x_1 \mapsto \bar{v}_1, \dots\}$$

Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

$$v ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (v_1, v_2) \mid \langle \sigma, e \rangle$$

$$\sigma ::= \{x_1 \mapsto v_1, \dots\}$$

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Memoize $\bar{\mathcal{E}}$ indexed (by suitable equivalence relations on) e and $\bar{\sigma}$.

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Necessary for migrating reflective source-code transformation to compile time.

Side benefits: union-free, no cyclic abstract values

No tags, tag checking, tag dispatching, indirect calls

Allows complete unboxing: no allocation, reclamation, indirection

Game Theory

			B			
		b_1	\dots	b_j	\dots	b_n
	a_1					
	\vdots		\ddots	\vdots		
A	a_i	\dots	$\text{PAYOFF}(a_i, b_j)$	\dots		
	\vdots		\vdots		\ddots	
	a_m					

von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

			B		
	b_1	\dots	b_j	\dots	b_n
a_1					
\vdots		\ddots	\vdots		
A	a_i	\dots	PAYOFF(a_i, b_j)	\dots	
\vdots			\vdots		\ddots
a_m					

$$\max_{a \in A} \min_{b \in B} \text{PAYOFF}(a, b)$$

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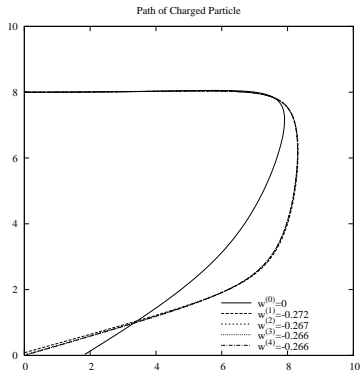
Game Theory

		\mathbb{R}^n		
		...	b	...
		<hr/>		
	\vdots	\ddots	\vdots	
\mathbb{R}^m	a	...	PAYOFF(a, b)	...
	\vdots		\vdots	\ddots

$$\max_{\mathbf{a} \in \mathbb{R}^m} \min_{\mathbf{b} \in \mathbb{R}^n} \text{PAYOFF}(\mathbf{a}, \mathbf{b})$$

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Cathode Ray Tubes



$$\text{potential: } p(\mathbf{x}; w) = \|\mathbf{x} - (10, 10 - w)\|^{-1} + \|\mathbf{x} - (10, 0)\|^{-1}$$

$$\ddot{\mathbf{x}}(t) = -\nabla_{\mathbf{x}} p(\mathbf{x})|_{\mathbf{x}=\mathbf{x}(t)}$$

$$\dot{\mathbf{x}}(t + \Delta t) = \dot{\mathbf{x}}(t) + \Delta t \ddot{\mathbf{x}}(t)$$

$$\mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \Delta t \dot{\mathbf{x}}(t)$$

$$\text{When: } x_1(t + \Delta t) \leq 0$$

$$\text{let: } \Delta t_f = -x_1(t) / \dot{x}_1(t)$$

$$t_f = t + \Delta t_f$$

$$\mathbf{x}(t_f) = \mathbf{x}(t) + \Delta t_f \dot{\mathbf{x}}(t)$$

$$\text{Error: } E(w) = x_0(t_f)^2$$

$$\text{Find: } \underset{w}{\operatorname{argmin}} E(w)$$

Sprague, C. S. and George, R. H. (1939). *Cathode Ray Deflecting Electrode*. US Patent 2,161,437.

George, R. H. (1940). *Cathode Ray Tube*. US Patent 2,222,942.

Performance Comparison

		particle				saddle			
		FF	FR	RF	RR	FF	FR	RF	RR
VLAD	STALIN ∇	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
FORTRAN	ADIFOR	1.52	■	■	■	2.07	■	■	■
	TAPENADE	3.40	■	■	■	2.56	■	■	■
C++	FADBAD++	65.69	■	■	■	22.44	■	■	■
ML	MLTON	53.89	88.88	16.08	28.06	40.39	51.21	1.86	2.67
	OCAML	160.50	340.35	147.91	263.66	107.71	156.33	6.75	13.51
	SML/NJ	106.21	182.45	105.04	185.15	84.38	106.01	3.55	6.31
HASKELL	GHC	165.22	■	■	■	121.18	■	■	■
SCHEME	BIGLOO	505.90	761.40	104.81	228.56	423.69	440.25	15.77	24.59
	CHICKEN	1120.37	2026.31	425.60	1872.85	889.58	1144.65	35.73	68.94
	GAMBIT	444.13	752.63	138.34	256.30	362.65	420.48	14.08	23.87
	IKARUS	192.07	312.28	61.79	114.87	158.88	205.97	6.75	11.40
	LARCENY	726.59	1108.18	144.55	270.14	571.81	613.65	19.14	29.77
	MIT SCHEME	1472.26	2500.00	309.66	591.36	1243.26	1428.57	51.36	79.10
	MzC	2073.26	3434.64	340.30	655.83	2436.26	1996.40	72.45	150.02
	MzSCHEME	2344.70	4076.16	409.95	843.68	2000.89	2332.43	80.78	134.00
	SCHEME->C	391.42	605.26	109.77	198.43	324.95	328.84	12.74	18.28
	SCMUTILS	3321.20	■	■	■	2800.71	■	■	■
	STALIN	208.10	366.08	51.84	91.86	166.96	212.93	7.68	11.40

- not implemented but could implement
- not implemented in existing tool
- can't implement

Gradient-Based Optimization

```
(define (e i n)
  (if (zero? n)
      '()
      (cons (if (zero? i) 1.0 0.0)
            (e (- i 1) (- n 1)))))
```

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(define (e i n)
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            (e (- i 1) (- n 1)))))

(define ((gradient f) x)
  (let ((n (length x)))
    (map (lambda (i) (tangent ((j* f) (bundle x (e i n))))
         (iota n)))))
```

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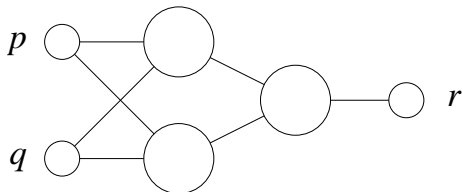
(define ((gradient f) x)
  (let ((n (length x)))
    (map (lambda (i) (tangent ((j* f) (bundle x (e i n))))
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(define (gradient-ascent f x0 n eta)
  (if (zero? n)
      (list x0 (f x0) ((gradient f) x0))
      (gradient-ascent f
                       (zip (lambda (xi gi) (+ xi (* eta gi)))
                            x0
                            ((gradient f) x0))
                       (- n 1)
                       eta)))
```


Gradient-Based Optimization

```
(define ((gradient f) x) (cdr ((cdr ((*j f) (*j x))) 1.0)))
```

```
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  (if (zero? n)
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      (gradient-ascent f
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                            x0
                            ((gradient f) x0))
                        (- n 1)
                        eta)))
```



p	q	r
0	0	0
0	1	1
1	0	1
1	1	0

Rumelhart, D. E., Hinton, G. E., and Williams, R. J. (1986). *Learning representations by back-propagating errors*. Nature, **323**:533–6.

Neural Networks in VLAD

```
(define ((sum-activities activities) bias ws)
  ((fold + bias) (zip * ws activities)))
```

Neural Networks in VLAD

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(define (sum-layer activities ws-layer)
  (map (sum-activities activities) ws-layer))
```

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(define (sigmoid x) (/ 1 (+ (exp (- 0 x)) 1)))

(define ((forward-pass ws-layers) in)
  (if (null? ws-layers)
      in
      ((forward-pass (cdr ws-layers))
       (map sigmoid (sum-layer in (car ws-layers))))))
```

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```
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(define ((error-on-dataset dataset) ws-layers)
  ((fold + 0)
   (map (lambda ((list in target))
         (* 0.5 (magnitude-squared (v- ((forward-pass ws-layers) in) target)))
        dataset)))
```

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         dataset)))

(gradient-descent (error-on-dataset '((0 0) (0))
                                       ((0 1) (1))
                                       ((1 0) (1))
                                       ((1 1) (0))))
'(((0 -0.284227 1.16054) (0 0.617194 1.30467))
  ((0 -0.084395 0.648461)))
1000.0
0.3)
```


Performance Comparison

		backprop		
		Fs	Fv	R
VLAD	STALIN ∇	1.00	■	1.00
FORTRAN	ADIFOR	11.84	2.68	■
	TAPENADE	11.35	4.33	6.24
C	ADIC	16.33	3.93	■
C++	ADOL-C	12.34	3.89	35.53
	CPPAD	42.15	■	23.69
	FADBAD++	98.96	33.15	53.03
ML	MLTON	73.94	■	37.94
	OCAML	157.75	■	149.14
	SML/NJ	142.71	■	94.97
HASKELL	GHC	■	■	■
SCHEME	BIGLOO	577.45	■	306.60
	CHICKEN	1391.75	■	971.91
	GAMBIT	545.20	■	341.73
	IKARUS	216.42	■	147.49
	LARCENY	955.98	■	486.64
	MIT SCHEME	1900.04	■	1141.22
	MzC	2439.93	■	1571.52
	MzSCHEME	3477.86	■	1866.28
	SCHEME->C	484.24	■	233.75
	SCMUTILS	4544.48	■	■
	STALIN	832.68	■	367.84

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$P = \mathbf{if } x_0 \mathbf{ then } 0 \mathbf{ else if } x_1 \mathbf{ then } 1 \mathbf{ else } 2$

Koller, D., McAllester, D. , and Pfeffer, A. (1997). *Effective Bayesian Inference for Stochastic Programs*. Proceedings of the 14th National Conference on Artificial Intelligence (AAAI), pp. 740–7.

Probabilistic Lambda Calculus

$P = \mathbf{if } x_0 \mathbf{ then } 0 \mathbf{ else if } x_1 \mathbf{ then } 1 \mathbf{ else } 2$

$$\Pr(x_0 \mapsto \mathbf{true}) = p_0$$

$$\Pr(x_0 \mapsto \mathbf{false}) = 1 - p_0$$

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$$\Pr(\mathcal{E}(P) = 1 | p_0, p_1) = (1 - p_0)p_1$$

$$\Pr(\mathcal{E}(P) = 2 | p_0, p_1) = (1 - p_0)(1 - p_1)$$

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$$\prod_{v \in \{0,1,2,2\}} \Pr(\mathcal{E}(P) = v | p_0, p_1) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

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$$\operatorname{argmax}_{p_0, p_1} \prod_{v \in \{0,1,2,2\}} \Pr(\mathcal{E}(P) = v | p_0, p_1) = \left\langle \frac{1}{4}, \frac{1}{3} \right\rangle$$

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Probabilistic Prolog

$p(0).$

$p(X) :- q(X).$

$q(1).$

$q(2).$

Probabilistic Prolog

$$\Pr(\mathbf{p}(0) \text{ .}) = p_0$$

$$\Pr(\mathbf{p}(X) : \neg \mathbf{q}(X) \text{ .}) = 1 - p_0$$

$$\Pr(\mathbf{q}(1) \text{ .}) = p_1$$

$$\Pr(\mathbf{q}(2) \text{ .}) = 1 - p_1$$

Probabilistic Prolog

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$$\Pr(\mathbf{q}(2) \text{ .}) = 1 - p_1$$

$$\Pr(\text{?-}\mathbf{p}(0) \text{ .}) = p_0$$

$$\Pr(\text{?-}\mathbf{p}(1) \text{ .}) = (1 - p_0)p_1$$

$$\Pr(\text{?-}\mathbf{p}(2) \text{ .}) = (1 - p_0)(1 - p_1)$$

Probabilistic Prolog

$$\Pr(\mathbf{p}(0) \text{ .}) = p_0$$

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$$\Pr(\mathbf{q}(1) \text{ .}) = p_1$$

$$\Pr(\mathbf{q}(2) \text{ .}) = 1 - p_1$$

$$\Pr(?-\mathbf{p}(0) \text{ .}) = p_0$$

$$\Pr(?-\mathbf{p}(1) \text{ .}) = (1 - p_0)p_1$$

$$\Pr(?-\mathbf{p}(2) \text{ .}) = (1 - p_0)(1 - p_1)$$

$$\prod_{q \in \{\mathbf{p}(0), \mathbf{p}(1), \mathbf{p}(2), \mathbf{p}(2)\}} \Pr(?-q \text{ .}) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

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$$\Pr(?-\mathbf{p}(0) \text{ .}) = p_0$$

$$\Pr(?-\mathbf{p}(1) \text{ .}) = (1 - p_0)p_1$$

$$\Pr(?-\mathbf{p}(2) \text{ .}) = (1 - p_0)(1 - p_1)$$

$$\prod_{q \in \{\mathbf{p}(0), \mathbf{p}(1), \mathbf{p}(2), \mathbf{p}(2)\}} \Pr(?-q \text{ .}) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

$$\operatorname{argmax}_{p_0, p_1} \prod_{q \in \{\mathbf{p}(0), \mathbf{p}(1), \mathbf{p}(2), \mathbf{p}(2)\}} \Pr(?-q \text{ .}) = \left\langle \frac{1}{4}, \frac{1}{3} \right\rangle$$

Probabilistic Lambda Calculus

```
(define (evaluate expression environment)
  (cond
    ((constant-expression? expression)
     (singleton-tagged-distribution
      (constant-expression-value expression)))
    ((variable-access-expression? expression)
     (lookup-value
      (variable-access-expression-variable expression) environment))
    ((lambda-expression? expression)
     (singleton-tagged-distribution
      (lambda (tagged-distribution)
        (evaluate
         (lambda-expression-body expression)
         (cons (make-binding (lambda-expression-variable expression)
                             tagged-distribution)
               environment))))))
    (else (let ((tagged-distribution
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Probabilistic Lambda Calculus

```
(gradient-ascent
 (lambda (p)
  (let ((tagged-distribution
        (evaluate if  $x_0$  then 0 else if  $x_1$  then 1 else 2
              (list  $\Pr(x_0 \mapsto \mathbf{true}) = p_0$   $\Pr(x_0 \mapsto \mathbf{false}) = 1 - p_0$ 
                     $\Pr(x_1 \mapsto \mathbf{true}) = p_1$   $\Pr(x_1 \mapsto \mathbf{false}) = 1 - p_1$ 
                    ...)))
    (map-reduce
     *
     1.0
     (lambda (value)
      (likelihood value tagged-distribution))
     '(0 1 2 2))))
 '(0.5 0.5)
 1000.0
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Probabilistic Prolog

```
(define (proof-distribution term clauses)
  (let ((offset ...))
    (map-reduce
      append
      '()
      (lambda (clause)
        (let ((clause (alpha-rename clause offset)))
          (let loop ((p (clause-p clause))
                     (substitution (unify term (clause-term clause)))
                     (terms (clause-terms clause)))
            (if (boolean? substitution)
                '()
                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
                      '()
                      (lambda (double)
                        (loop (* p (double-p double))
                              (append substitution (double-substitution double))
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Probabilistic Prolog

```
(gradient-ascent
 (lambda (p)
  (let ((clauses (list Pr(p(0).) = p0
                       Pr(p(X):-q(X).) = 1 - p0
                       Pr(q(1).) = p1
                       Pr(q(2).) = 1 - p1))))
    (map-reduce
     *
     1.0
     (lambda (query)
      (likelihood (proof-distribution query clauses)))
     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
 1000.0
 0.1)
```

Probabilistic Prolog

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 (lambda (p)
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     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
 1000.0
 0.1)
```

Probabilistic Prolog

```
(gradient-ascent
 (lambda (p)
  (let ((clauses (list Pr(p(0).) = p0
                       Pr(p(X):-q(X).) = 1 - p0
                       Pr(q(1).) = p1
                       Pr(q(2).) = 1 - p1))))
    (map-reduce
     *
     1.0
     (lambda (query)
      (likelihood (proof-distribution query clauses)))
     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
 1000.0
 0.1)
```

Probabilistic Prolog

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     *
     1.0
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Probabilistic Prolog

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    (map-reduce
     *
     1.0
     (lambda (query)
      (likelihood (proof-distribution query clauses)))
     '(p(0) p(1) p(2) p(2))))))
'(0.5 0.5)
1000.0
0.1)
```

Generated Code

```
static void f2679(double a_f2679_0,double a_f2679_1,double a_f2679_2,double a_f2679_3){
    int t272381=((a_f2679_2==0.)?0:1);
    double t272406;
    double t272405;
    double t272404;
    double t272403;
    double t272402;
    if((t272381==0)){
        double t272480=(1.-a_f2679_0);
        double t272572=(1.-a_f2679_1);
        double t273043=(a_f2679_0+0.);
        double t274185=(t272480*a_f2679_1);
        double t274426=(t274185+0.);
        double t275653=(t272480*t272572);
        double t275894=(t275653+0.);
        double t277121=(t272480*t272572);
        double t277362=(t277121+0.);
        double t277431=(t277362*1.);
        double t277436=(t275894*t277431);
        double t277441=(t274426*t277436);
        double t277446=(t273043*t277441);
        ...
        double t1777107=(t1774696+t1715394);
        double t1777194=(0.-t1745420);
        double t1778533=(t1777194+t1419700);
        t272406=a_f2679_0;
        t272405=a_f2679_1;
        t272404=t277446;
        t272403=t1778533;
        t272402=t1777107;}
    else {...}
    r_f2679_0=t272406;
    r_f2679_1=t272405;
    r_f2679_2=t272404;
    r_f2679_3=t272403;
    r_f2679_4=t272402;}
```

Performance Comparison

		probabilistic-lambda-calculus		probabilistic-prolog	
		F	R	F	R
VLAD	STALIN ∇	1.00	1.00	1.00	1.00
ML	MLTON	106.45	124.95	789.41	483.47
	OCAML	215.73	538.68	1207.13	1534.61
	SML/NJ	197.75	272.45	2448.02	1471.94
HASKELL	GHC	■	■	■	■
SCHEME	BIGLOO	832.92	1048.11	14422.16	8286.06
	CHICKEN	2305.98	3283.00	66948.70	37792.84
	GAMBIT	879.88	1153.86	24316.03	13649.81
	IKARUS	437.46	531.10	8242.92	4845.86
	LARCENY	1651.01	1673.22	25589.62	14833.53
	MIT SCHEME	3491.10	4130.19	85819.57	48335.38
	MzC	5289.17	5929.14	154206.95	83480.27
	MzSCHEME	6235.78	7134.71	166129.12	91630.70
	SCHEME->C	682.15	794.31	10530.66	5980.27
	SCMUTILS	6456.99	■	80100.23	■
	STALIN	1240.73	1137.41	22511.79	10986.43

- not implemented but could implement, including FORTRAN, C, and C++
- not implemented in existing tool
- can't implement

It is, of course, not excluded that the range of arguments or range of values of a function should consist wholly or partly of functions. The derivative, as this notion appears in the elementary differential calculus, is a familiar mathematical example of a function for which both ranges consist of functions.

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(¶4)

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Gottfried Leibniz
|
Jacob Bernoulli
|
Johann Bernoulli
|
Leonhard Euler
|
Joseph Louis Lagrange
|
Simeon Poisson
|
Michel Chasles
|
Hubert Anson Newton
|
Eliakim Hastings Moore
|
Oswald Veblen
|
Alonzo Church