

Lazy Multivariate Higher-Order Forward-Mode AD

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Wengert (1964)

Higher-Order Forward-Mode AD

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$$\mathcal{D}^{[i_1, \dots, i_n]} f \ [c_1, \dots, c_n] \triangleq \left. \frac{\partial^{i_1 + \dots + i_n} f(x_1, \dots, x_n)}{\partial x_1^{i_1} \dots \partial x_n^{i_n}} \right|_{x_1=c_1, \dots, x_n=c_n}$$

Wengert (1964), Karczmarczuk (2001)

The Essence of Forward-Mode AD

Taylor expansion:

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \cdots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \cdots$$

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Key idea: Only need output to be a **finite truncated** power series $a + b\varepsilon$.

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(Analogous to complex numbers $a + bi$ represented as $\langle a, b \rangle$.)

Arithmetic on Truncated Power Series (i.e. Dual Numbers)

$$(x_0 + x_1\varepsilon + \mathcal{O}(\varepsilon^2)) + (y_0 + y_1\varepsilon + \mathcal{O}(\varepsilon^2)) = (x_0 + y_0) + (x_1 + y_1)\varepsilon + \mathcal{O}(\varepsilon^2)$$

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$$\begin{aligned}(x_0 + x_1\varepsilon + \mathcal{O}(\varepsilon^2)) \times (y_0 + y_1\varepsilon + \mathcal{O}(\varepsilon^2)) \\ = (x_0 \times y_0) + (x_0 \times y_1 + x_1 \times y_0)\varepsilon + \mathcal{O}(\varepsilon^2)\end{aligned}$$

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$$u(x_0 + x_1\varepsilon + \mathcal{O}(\varepsilon^2)) = (u x_0) + (x_1 \times (u' x_0))\varepsilon + \mathcal{O}(\varepsilon^2)$$

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Non-truncated is harder: Cannot ignore $\mathcal{O}(\varepsilon^2)$ s.

Higher-Order Derivatives via Iteration

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Need mechanism to support arbitrary nesting of power series.

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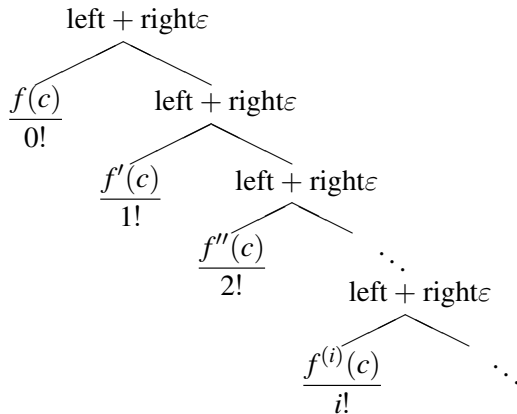
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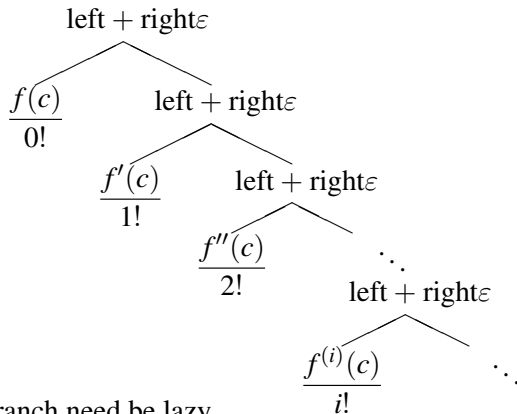
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Bad news: The power series may be **infinite**.

Solution: Represent Power Series as Lazy Streams

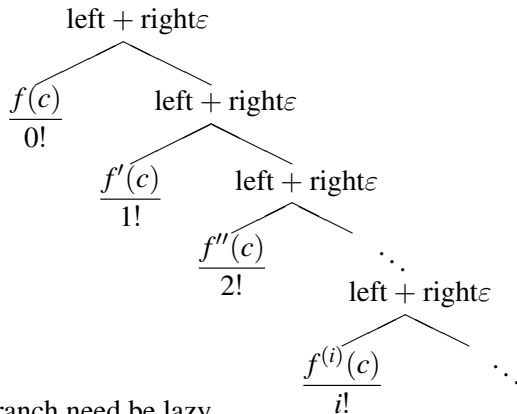


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Only the right branch need be lazy.

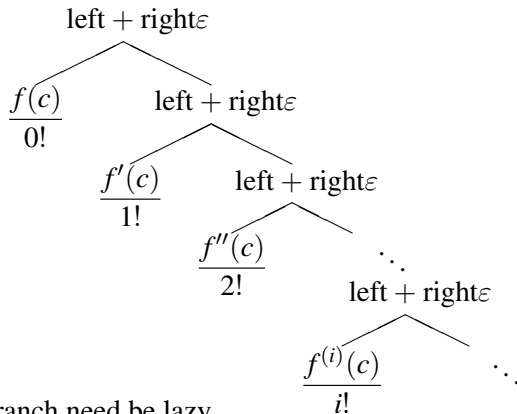
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API: $(Q \varepsilon p)$ computes *quotient* of $\frac{p}{\varepsilon}$, analogous to forcing `cdr`.

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Only the right branch need be lazy.

API: $(Q \varepsilon p)$ computes *quotient* of $\frac{p}{\varepsilon}$, analogous to forcing `cdr`.

$(R \varepsilon p)$ computes *remainder* of $\frac{p}{\varepsilon}$, analogous to `car`.

Higher-Order Multivariate Derivatives

Multivariate Taylor expansion:

$$f((c_1 + \varepsilon_1), \dots, (c_n + \varepsilon_n)) = \sum_{i_1=0}^{\infty} \dots \sum_{i_n=0}^{\infty} \frac{1}{i_1! \dots i_n!} \frac{\partial^{i_1+\dots+i_n} f(x_1, \dots, x_n)}{\partial x_1^{i_1} \dots \partial x_n^{i_n}} \bigg|_{x_1=c_1, \dots, x_n=c_n} \varepsilon_1^{i_1} \dots \varepsilon_n^{i_n}$$

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To compute $\mathcal{D}^{[i_1, \dots, i_n]} f [c_1, \dots, c_n]$:

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Multivariate Taylor expansion:

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To compute $\mathcal{D}^{[i_1, \dots, i_n]} f [c_1, \dots, c_n]$:

- evaluate $\textcolor{red}{f}$

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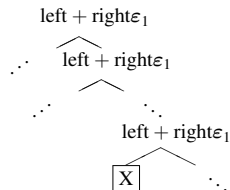
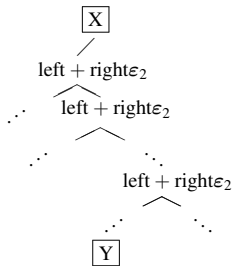
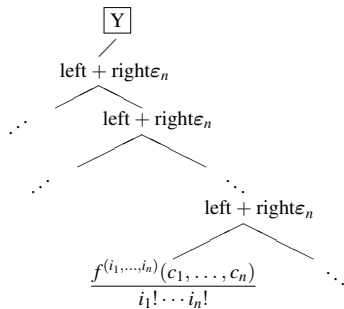
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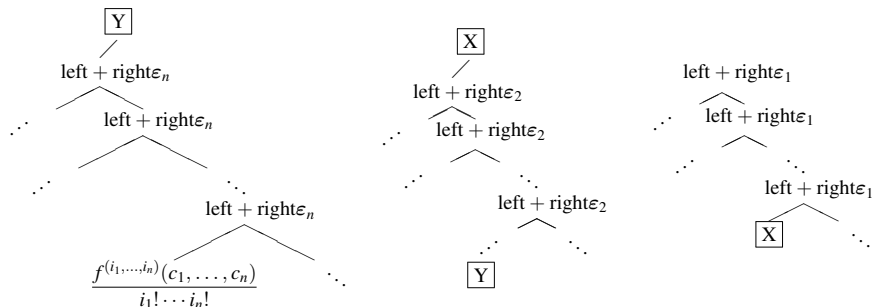
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Multivariate Power Series as Nested Univariate Power Series

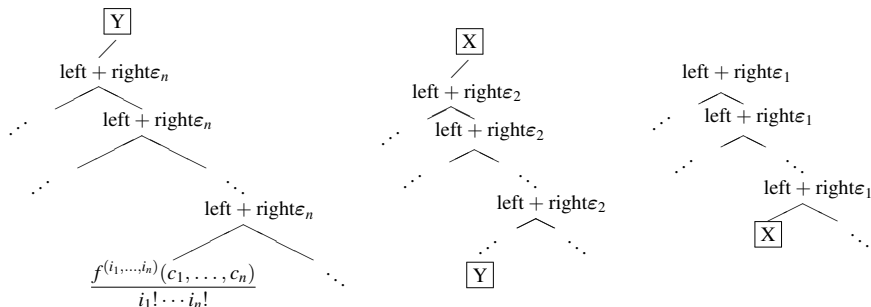


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The left-branching depth is limited by the number of distinct ϵ_i .

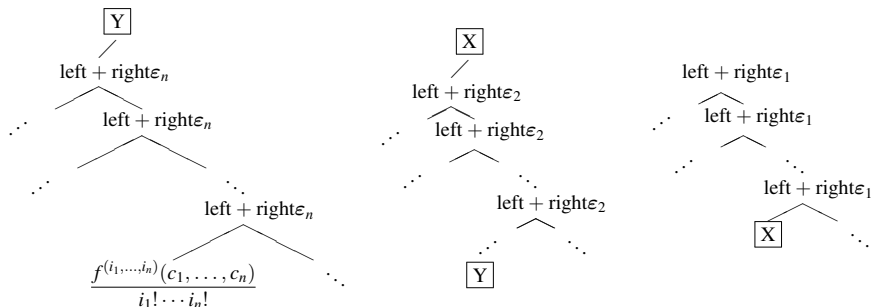
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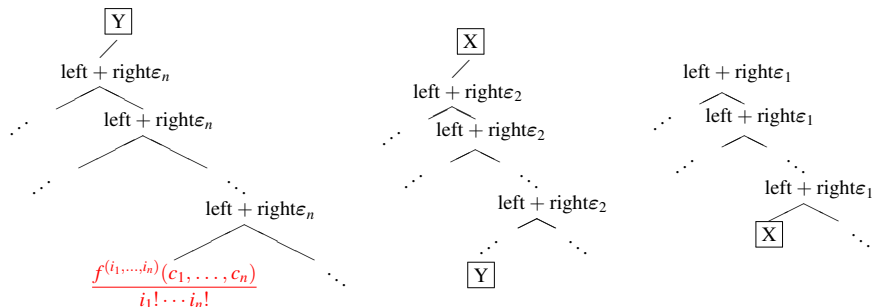


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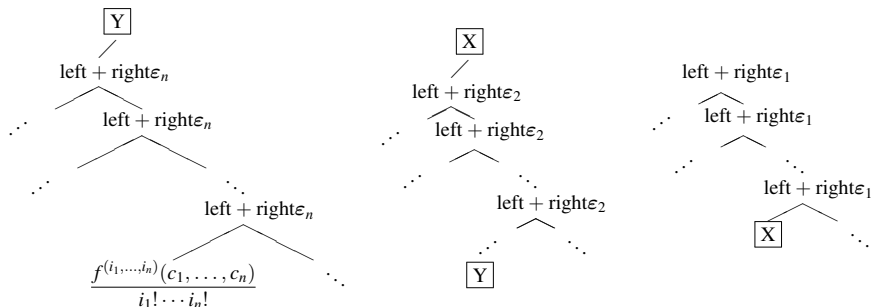
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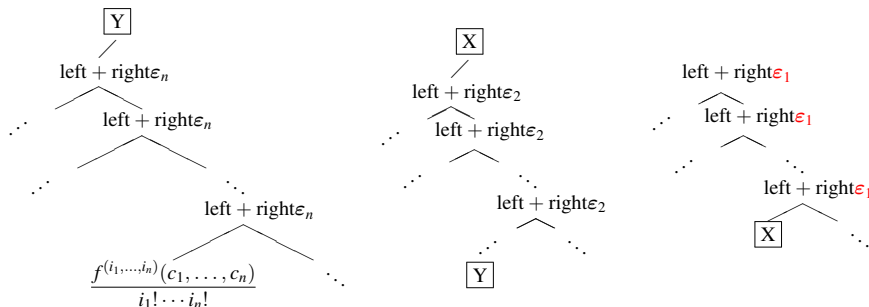
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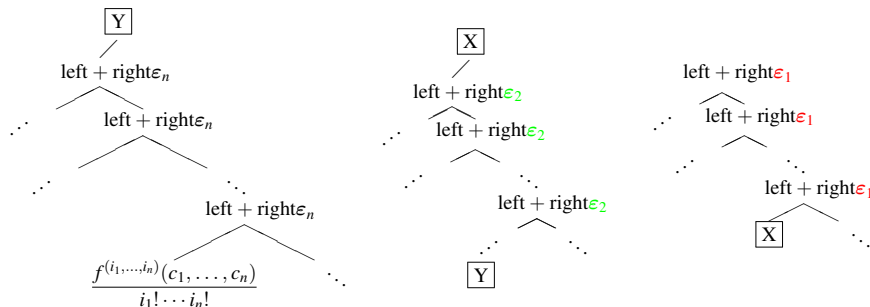
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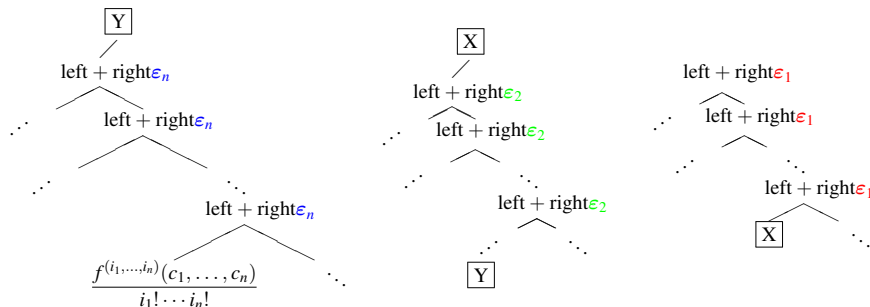
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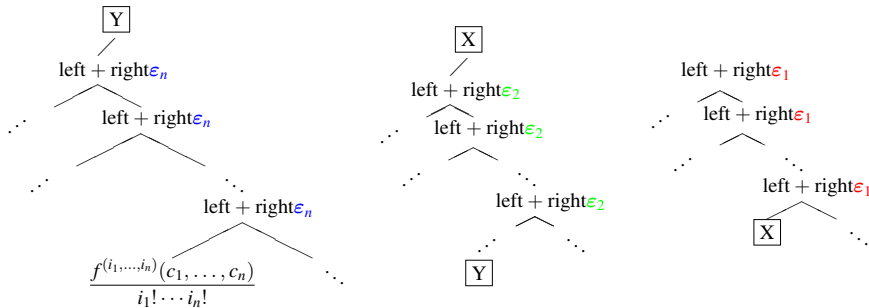
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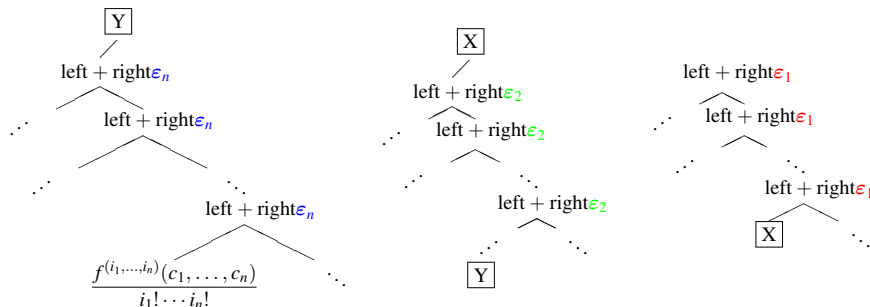
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Painfully ironic: Cannot *implement* \mathcal{D} in a referentially transparent language even though \mathcal{D} itself *is* referentially transparent!

Arithmetic on Non-Truncated Power Series

- Unary primitives:

$$u(x + x'\varepsilon) = (u x) + ((\mathcal{C}_{\varepsilon^0} (u' (x + x'\varepsilon)[\varepsilon \mapsto \xi]))[\xi \mapsto \varepsilon] \times x')\varepsilon$$

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- Read the paper for the details.

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- Many important numeric concepts are higher-order functions.
- For functional programming to interest numerical computing, it should provide useful numeric constructs.
- For instance: *exact efficient derivatives!*
- We have shown how to implement an unrestricted multivariate higher-order derivative operator using forward-mode AD.

Contingency Slides

Forward AD of Non-Scalar Functions

Discussed scalar functions for expository simplicity

- Can generalize higher-order scalar derivative

$$\mathcal{D} : \mathbb{N} \times (\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$$

to higher-order vector directional derivative

$$\mathcal{J} : \mathbb{N} \times (\mathbb{R}^n \rightarrow \mathbb{R}^m) \rightarrow (\mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^m)$$

- using same mechanisms: find directional i -th derivative $\mathcal{J} \text{ if } \mathbf{c} \mathbf{c}'$ of $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ at $\mathbf{c} : \mathbb{R}^n$ in direction $\mathbf{c}' : \mathbb{R}^n$ by calculating

$$\mathbf{y} = f [c_1 + c'_1 \varepsilon, \dots, c_n + c'_n \varepsilon]$$

and extracting

$$[y'_1, \dots, y'_m] = [\mathcal{C}_{\varepsilon^i} y_1, \dots, \mathcal{C}_{\varepsilon^i} y_m]$$

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Two alternatives for representing

$$x(\varepsilon) = x_0 + x_1\varepsilon + x_2\varepsilon^2 + x_3\varepsilon^3 + \dots$$

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$$\begin{aligned} & \langle x(0), \langle x'(0), \langle x''(0), \langle x'''(0), \dots \rangle \rangle \rangle \rangle \\ &= \langle 0! \times x_0, \langle 1! \times x_1, \langle 2! \times x_2, \langle 3! \times x_3, \dots \rangle \rangle \rangle \rangle \\ &= \langle x_0, \langle x_1, \langle 2 \times x_2, \langle 6 \times x_3, \dots \rangle \rangle \rangle \rangle \end{aligned}$$

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- Identical in truncated case
- Fungible: trade off which “left shift” is fast,

$$Q \varepsilon x(\varepsilon) = \frac{1}{\varepsilon}(x(\varepsilon) - x(0)) \quad \text{or} \quad \frac{d}{d\varepsilon}x(\varepsilon)$$

Implementation of \mathcal{D} vs. Referential Transparency

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$$\mathcal{D} (\lambda x \dots \boxed{x} \dots) c$$
$$\mathcal{D} (\lambda y \dots \boxed{y} \dots) c$$

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(Oops)