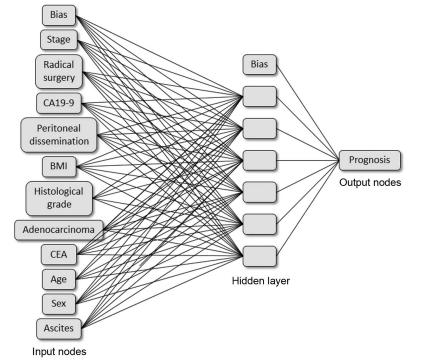
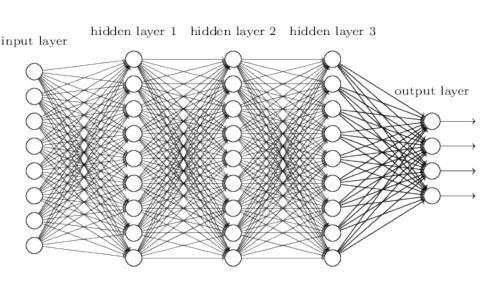
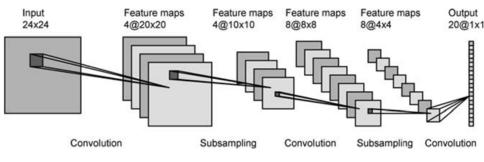
Tricks from Deep Learning

Atılım Güneş Baydin¹ Barak A. Pearlmutter² Jeffrey Mark Siskind³

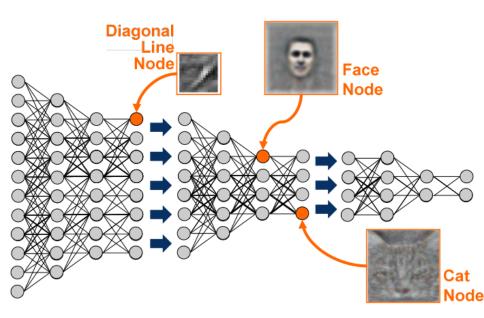
¹Oxford University, \(\langle\)gunes@robots.ox.ac.uk\\
²Maynooth University, \(\langle\)barak@pearlmutter.net\\
³Purdue University, \(\langle\)qobi@purdue.edu\\







Train: reverse AD (Speelpenning, 1980), stochastic ∇ descent (Robbins and Monro, 1951).



Compiling Fast Partial Derivatives of Functions Given by Algorithms (Speelpenning, 1980, PhD thesis)

VS

Learning representations by back-propagating errors (Rumelhart et al., 1986, Nature **323**:533–6)

Compiling Fast Partial Derivatives of Functions Given by Algorithms (Speelpenning, 1980, PhD thesis)

VS

Learning representations by back-propagating errors (Rumelhart et al., 1986, Nature **323**:533–6)



Compiling fast partial derivatives of functions given by algorithms

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[воок] Interval analysis

RE Moore - 1966 - sbras.ru

This book is intended primarily for those not yet familiar with methods for computing with intervals of real numbers and what can be done with these methods. Using a pair [a, b] of computer numbers to represent an interval of real numbers a≤ x≤ b, we define an ... Cited by 5782 Related articles All 6 versions Cite Saved More

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E Hansen, GW Walster - 2003 - books.google.com

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[CITATION] Identification of parametric models from experimental data E Walter, L Pronzato - 1997 - Springer Verlag

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A Griewank, D Juedes, J Utke - ACM Transactions on Mathematical 1996 - dl.acm.org Abstract The C++ package ADOL-C described here facilitates the evaluation of first and higher derivatives of vector functions that are defined by computer programs written in C or C++. The resulting derivative evaluation routines may be called from C/C++, Fortran, or ... Cited by 846 Related articles All 9 versions. Web of Science: 268 Cite. Saved. More

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Support-vector networks

C Cortes, V Vapnik - Machine learning, 1995 - Springer

Abstract The support-vector network is a new learning machine for two-group classification problems. The machine conceptually implements the following idea: input vectors are non-linearly mapped to a very high-dimension feature space. In this feature space a linear ... Cited by 21971 Related articles All 44 versions Web of Science: 8327 Cite Save Moi

Unsupervised learning

<u>T Hastie</u>, <u>R Tibshirani</u>, J Friedman - The elements of statistical learning, 2009 - Springer The previous chapters have been concerned with predicting the values of one or more outputs or response variables Y=(Y1,..., Ym) for a given set of input or predictor variables XT=(X1,..., Xp). Denote by xT i=(xi1,..., xip) the inputs for the ith training case, and let yi be ... Cited by 29291 Related articles All 32 versions Cite Save More

гвоокт Pattern classification

RO Duda, PE Hart, DG Stork - 2012 - books.google.com

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Predicting the secondary structure of globular proteins using neural network models

N Qian, TJ Sejnowski - Journal of molecular biology, 1988 - Elsevier
Abstract We present a new method for predicting the secondary structure of globular proteins based on non-linear neural network models. Network models learn from existing protein structures how to predict the secondary structure of local sequences of amino ...
Cited by 1252 Related articles All 18 versions Web of Science: 687 Cite Save More

Content-based book recommending using learning for text categorization

RJ Mooney, L Roy - Proceedings of the fifth ACM conference on Digital ..., 2000 - dl.acm.org Abstract Recommender systems improve access to relevant products and information by making personalized suggestions based on previous examples of a user's likes and dislikes. Most existing recommender systems use collaborative filtering methods that base ... Cited by 1272 Related articles All 30 versions Cite Save More

Detection, classification, and tracking of targets

<u>D.Li</u>, KD Wong, <u>YH Hu</u>... - IEEE signal processing ..., 2002 - ieeexplore.ieee.org Networks of small, densely distributed wireless sensor nodes are being envisioned and developed for a variety of applications involving monitoring and manipulation of the physical world in a tetherless fashion [1],[16],[17],[22],[23]. Typically, each individual node can ... Cited by 1242 Related articles All 29 versions Web of Science: 444 Cite Save

Improving the learning speed of 2-layer neural networks by choosing initial values of the adaptive weights

D Nguyen, B Widrow - Neural Networks, 1990., 1990 IJCNN ..., 1990 - ieeexplore.ieee.org Abstract A two-layer neural network can be used to approximate any nonlinear function. The behavior of the hidden nodes that allows the network to do this is described. Networks with one input are analyzed first, and the analysis is then extended to networks with multiple ... Cited by 1231 Related articles All 9 versions Cite Save



Yoshua Bengio

Professor, U. Montreal (Computer Sc. & Op. Res.), MILA, CIFAR, CRM, REPARTI, GRSNC

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i10-index	285	234

Title 1–20	Cited by	Year
Gradient-based learning applied to document recognition		
Y LeCun, L Bottou, Y Bengio, P Haffner	5717	1998

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Proceedings of the IEEE 86 (11) 2278-2324

Geoffrey Hinton



Emeritus Professor of Computer Science, University of Toronto & Distinguished Researcher, Google Inc. machine learning, neural networks, artificial intelligence, cognitive science, computer science

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i10-index				288			205
2008 2009	2010	2011	2012	2013	2014	2015	2016

Title 1–20	Cited by	Year
Parallel distributed processing DE Rumelhart, JL McClelland, PDP Research Group IEFET 1.345-365	20676	1988

Yann LeCun



Director of Al Research at Eacebook & Silver Professor at the Courant Institute. New York University

Al. machine learning, computer vision, robotics, image compression Verified email at cs.nvu.edu - Homepage



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Y LeCun. L Bottou. Y Bengio. P Haffner Proceedings of the IEEE 86 (11) 2278-2324 5717 1998

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Title 1-20 Cited by Year Long short-term memory 1997 2421 S Hochreiter, J Schmidhuber





Neural computation 9 (8) 1735-1780

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Citations	24669	19983
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Cited by Title 1-20 A bayesian hierarchical model for learning natural scene categories

Computer Vision and Dattern Decognition, 2005, CVDD 2005, IEEE Computer

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Year

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Citation indices	All	Since 2011
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Alex Krizhevsky

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Citations	10423	10368
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i10-index	11	13

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Imagenet classification with deep convolutional neural networks	
A Krizhevsky, I Sutskever, GE Hinton	6572



Advances in neural information proceeding evetame 1007-1105 Andrej Karpathy

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D Koller, N Friedman MIT press

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Journal of machine Learning research 3 (Jan), 993-1022

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DeCAF: A Deep Convolutional Activation Feature for Generic Visual		
Recognition.	857	2014

















Tianiin Mayor Caught Up

in Xi's Antigraft Campaign

Q. SEARCH





NEWS ANALYSIS Few Expect China to Punish North Korea for Latest Nuclear Test





Boiler Explosion at Bangladesh Factory Kills at Least 23



THE INTERPRETER North Korea, Far From Crazy, Is All Too Rational

ASIA PACIFIC

Google's Computer Program Beats Lee Se-dol in Go Tournament

By CHOE SANG-HUN MARCH 15, 2016



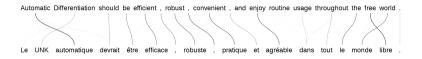
Automatic Differentiation should be efficient, robust, convenient, and enjoy routine usage throughout the free world. Go!

Go!





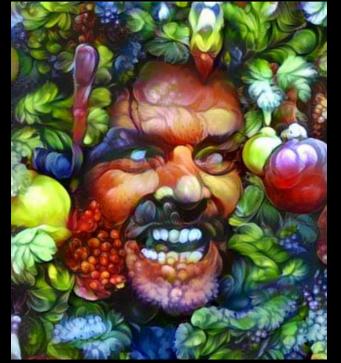
Le **UNK** automatique devrait être efficace, robuste, pratique et agréable dans tout le monde libre.

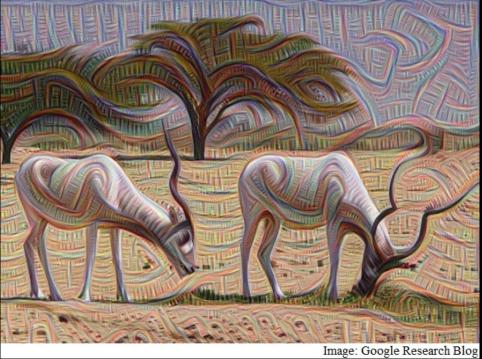


Unknown words! The following words are unknown to the model: Differentiation

Our network was trained on a lot of data from the United Nations and the European Parliament, so these are the kind of sentences that it does well on. Give them a try!

(see http://lisa.iro.umontreal.ca/mt-demo)









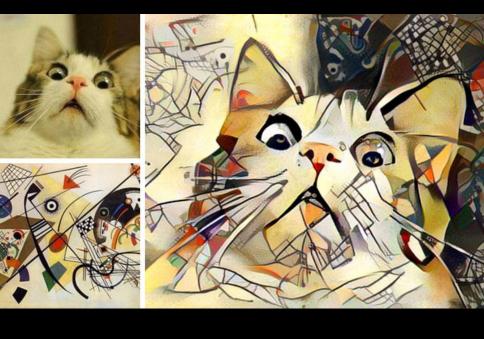




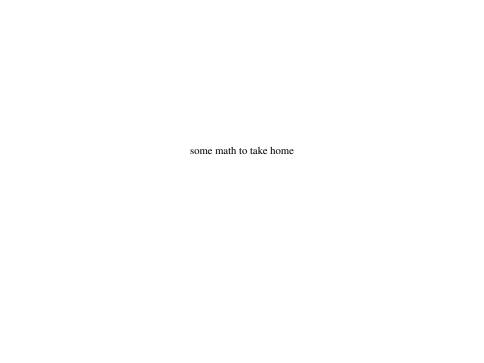








big programs vs big data



Stochastic Gradient Descent (Robbins and Monro, 1951)

Define the stochastic hat: $\mathbf{E}[\hat{\cdot}] = \cdot$

Stochastic Gradient Descent (Robbins and Monro, 1951)

Define the stochastic hat: $\mathbf{E}[\hat{\cdot}] = \cdot$

Find the minimizer w^* of

$$E(w) = \frac{1}{n} \sum_{i=1}^{n} E_i(w)$$

by iterating

$$w(t+1) = w(t) - \eta_t \nabla_w \widehat{E}(w(t)) = w(t) - \eta_t \nabla_w E_i(w(t))$$

where *i* is chosen randomly and $\eta_t > 0$ is gradually decreased, $O(t^{-2}) < \eta_t \le O(t^{-1})$.

Stochastic Gradient Descent (Robbins and Monro, 1951)

Define the stochastic hat: $\mathbf{E}[\hat{\cdot}] = \cdot$

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where *i* is chosen randomly and $\eta_t > 0$ is gradually decreased, $O(t^{-2}) < \eta_t \le O(t^{-1})$.

Nowadays: choose *i* sequentially, mini-batches, $\eta_t = O(1)$, momentum.

Stochastic Hessian-Vector Product

Stochastic Hessian-Vector Product

(same as stochastic gradient: sample data)

Stochastic Hessian-Vector Product

(same as stochastic gradient: sample data)

$$\widehat{H}v = \nabla^2 \widehat{E}v$$

Stochastic Hessian-Inverse-Vector Product

Stochastic Hessian-Inverse-Vector Product

$$H^{-1} = \sum_{i=0}^{\infty} (I - H)^{i}$$

choose $i \sim p(i)$ and

$$\widehat{H^{-1}}v = p(i)^{-1} \underbrace{(I - \widehat{H})(\cdots ((I - \widehat{H})}_{i \text{ times}} v))$$

(Assume in radius of convergence. See Agarwal et al., 2016)

Reversible Learning

Desire: perform reverse AD on $f: x \mapsto y(t_F)$ where $y(t_f)$ is the result of numeric integration of an ode with time-dependent x-dependent driving term,

$$y(t + \Delta t) = y(t) + \Delta t g(t, y(t), x)$$

Naïve reverse AD: store $y(t_0), y(t_0 + \Delta t), \dots, t(t_F)$.

Idea: this ode is time reversible; run it backwards during reverse pass.

Problems: (a) the ode is stable, so its time-reversal is unstable; (b) $\Delta t > 0$ and limited precision cause time reversal to diverge from primal.

Solution: store info during primal to correct time-reversal so it never diverges from primal (Maclaurin et al., 2015).

DrMAD: Distilling Reverse-Mode Automatic Differentiation for Optimizing Hyperparameters of Deep Neural Networks

Jie Fu* Hongyin Luo^ Jiashi Feng* Kian Hsiang Low* Tat-Seng Chua*

* National University of Singapore, Singapore

^ Tsinghua University, China

Abstract

The performance of deep neural networks is wellknown to be sensitive to the setting of their hyperparameters. Recent advances in reverse-mode automatic differentiation allow for optimizing hyperparameters with gradients. The standard way of computing these gradients involves a forward and backward pass of computations. However, the backward pass usually needs to consume unaffordable memory to store all the intermediate variables to exactly reverse the forward training procedure. In this work we propose a simple but effective method. DrMAD, to distill the knowledge of the forward pass into a shortcut path, through which we approximately reverse the training trajectory. Experiments on two image benchmark datasets show that DrMAD is at least 45 times faster and consumes 100 times less memory compared to statedeep neural networks in a variety of benchmark datasets [Shahriari et al., 2016; Snoek et al., 2012].

A common choice for hyperparameter optimization is gradient-free Bayesian optimization [Wang et al., 2013]. Bayesian optimization builds a probability model to describe the distribution of validation loss conditioned on specific hyperparameters, which is obtained by multiple observations over the pairs of hyperparameter and validation loss. This probability model is then used to optimize the validation loss after complete training of the model's elementary1 parameters. Although those techniques have been shown to achieve good performance with a variety of models on benchmark datasets [Shahriari et al., 2016], they can hardly scale up to handle more than 20 hyperparameters [Maclaurin et al., 2015; Shahriari et al., 2016]. Here we mean effective hyperparameters. It has been shown in [Wang et al., 2013] that Bayesian optimization can handle high-dimensional inputs only if the number of effective hyperparameters is small. Due to this inability hyperparameters are often considered nui-

deep learning tools

Deep Learning



What society thinks I do



What my friends think I do



What other computer scientists think I do



What mathematicians think I do



What I think I do

from theano import

What I actually do

Theano is a Python library for efficiently handling mathematical expressions involving multi-dimensional arrays (also known as tensors). It is a common choice for implementing neural network models. Theano has been developed in University of Montreal, in a group led by Yoshua Bengio, since 2008.

Some of the features include:

automatic differentiation – you only have to implement the forward (prediction) part of the model, and
 Theano will automatically figure out how to calculate the gradients at various points, allowing you to
 perform gradient descent for model training.

transparent use of a GPU – you can write the same code and run it either on CPU or GPU. More specifically, Theano will figure out which parts of the computation should be moved to the GPU.
 speed and stability optimisations – Theano will internally reorganise and optimise your computations in order to make them run faster and be more numerically stable. It will also try to compile some operations into C code, in order to speed up the computation.

Technically, Theano isn't actually a machine learning library, as it doesn't provide you with pre-built models that you can train on your dataset. Instead, it is a mathematical library that provides you with

(from What is Theano? http://www.marekrei.com/blog/theano-tutorial/)

Gradient-based Optimization of MLP in Lua/Torch7

(runs on real FMRI data)

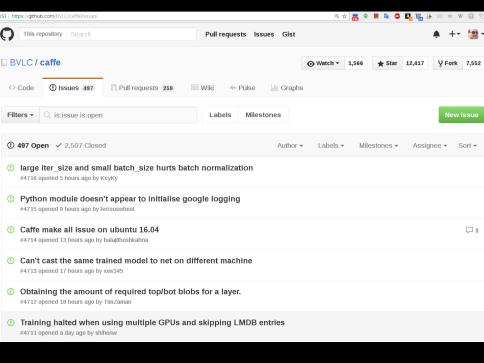
```
function classify_net(number_of_voxels, number_of_classes)
   local mlp = nn.Sequential()
   mlp:add(nn.Dropout(0.5))
   mlp:add(nn.Linear(number of voxels, number of voxels))
   mlp:add(nn.ReLU(true))
   mlp:add(nn.Dropout(0.5))
   mlp:add(nn.Linear(number_of_voxels, number of classes))
   mlp:add(nn.LogSoftMax())
   return mlp
end
function train classifier (net, criterion, iterations, learning rate,
                          training set)
   for i = 1, iterations do
      net:training()
      local class = net:forward(training set.fmri)
      criterion:forward(class, training_set.labels)
      net:zeroGradParameters()
      net:backward(fmri, criterion:backward(class, training_set.labels))
      net:updateParameters(learning rate)
   end
end
```

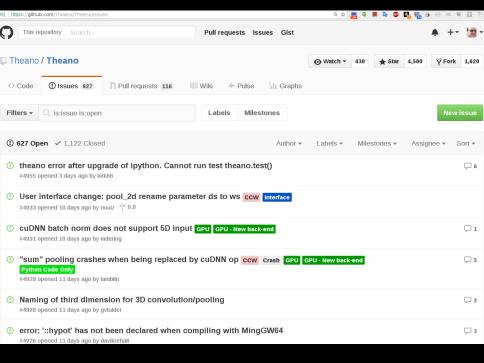
Gradient-based Optimization of MLP in Julia/ReverseDiffSource

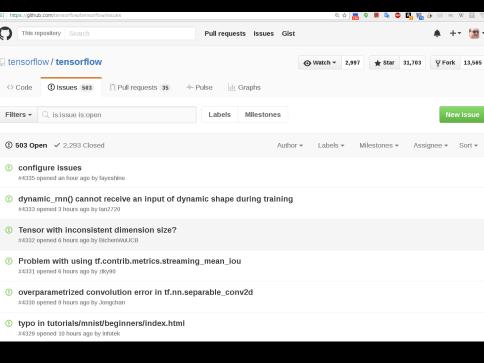
```
function classify net(d1, d2, w1, w2, x1)
   x1 = d1 \cdot x1
   x2 = w1 * x1
   x2 = log1p(exp(x2))
   x2 = d2.*x2
   x3 = w2 * x2
   x3 = log1p(exp(x3))
   log(1/(sum(exp(x))*exp(x)))
end
function train classifier (criterion, iterations, learning rate, training set)
   d1, d2 = 0.5*rand(4096), 0.5*rand(4096)
   w1, w2 = randn(4096, 4096), randn(4096, 12)
   dnet = rdiff(classify net, (d1, d2, w1, w2, training set))
   for i in 1:iterations
       d1, d2 = 0.5 \times rand(4096), 0.5 \times rand(4096)
       _, _, _, dedw1, dedw2, _ = dnet(d1, d2, w1, w2, training_set)
       w1 = w1-learning rate*dedw1
       w2 = w2-learning rate*dedw2
   and
end
```

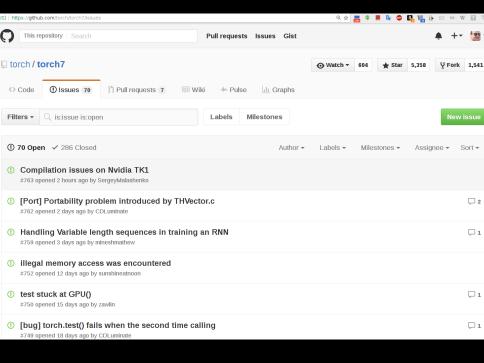
Gradient-based Optimization of MLP in Python/autograd

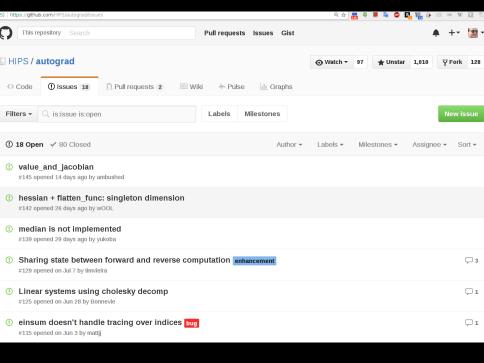
```
def neural net predict (parameters, inputs):
    for W, b in parameters:
        outputs = np.dot(inputs, W) + b
        inputs = np.tanh(outputs)
    return outputs - logsumexp(outputs, axis=1, keepdims=True)
def 12 norm(parameters):
    flattened, _ = flatten(parameters)
    return np.dot(flattened, flattened)
def log posterior(parameters, inputs, targets):
    log_prior = -12_norm(parameters)
    log_likelihood = np.sum(neural_net_predict(parameters, inputs) * targets)
    return log prior + log likelihood
def objective (parameters, iter):
    return -log posterior(parameters, training set, training labels)
optimized parameters = adam(grad(objective), init parameters,
                            step size=step size.
                            num iters=num epochs * num batches)
```

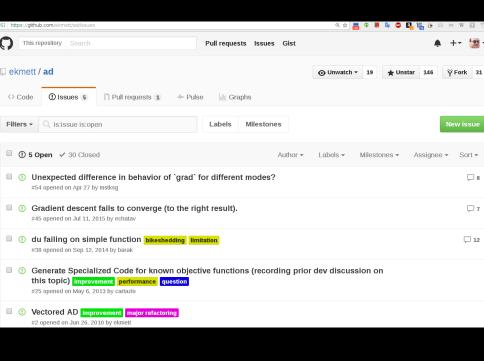


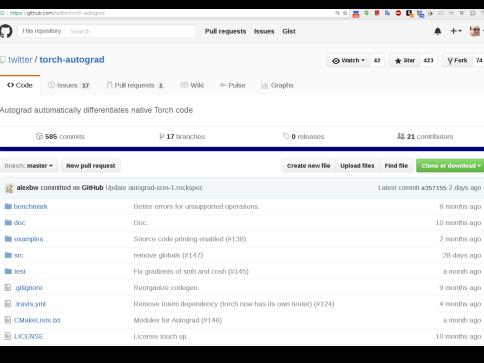












Autograd

build passing

Autograd automatically differentiates native Torch code. Inspired by the original Python version.

Scope

Autograd has multiple goals:

- provide automatic differentiation of Torch expressions
- support arbitrary Torch types (e.g. transparent and full support for CUDA-backed computations)
- full integration with nn modules: mix and match auto-differentiation with user-provided gradients
- full integration with nn modules: mix and match auto-differentiation with user-provided gradients
- the ability to define any new nn compliant Module with automatic differentiation
- represent complex evaluation graphs, which is very useful to describe models with multiple loss functions and/or inputs
- graphs are dynamic, i.e. can be different at each function call: for loops, or conditional, can depend
 on intermediate results, or on input parameters
- enable gradients of gradients for transparent computation of Hessians

Undates

Black-Box Stochastic Variational Inference in Five Lines of Python

David Duvenaud

dduvenaud@seas.harvard.edu
Harvard University

Ryan P. Adams

rpa@seas.harvard.edu Harvard University

Abstract

Several large software engineering projects have been undertaken to support black-box inference methods. In contrast, we emphasize how easy it is to construct scalable and easy-to-use automatic inference methods using only automatic differentiation. We present a small function which computes stochastic gradients of the evidence lower bound for any differentiable posterior. As an example, we perform stochastic variational inference in a deep Bayesian neural network.

Black-box stochastic variational inference in five lines of Python (Duvenaud and Adams, 2015, NIPS Workshop on Black-box Learning and Inference)

```
def lower bound(variational params, logprob func, D, num samples):
    # variational params: the mean and covariance of approximate posterior.
    # loaprob_func:
                         the unnormalized log-probability of the model.
                         the number of parameters in the model.
    # D •
    # num samples: the number of Monte Carlo samples to use.
    # Unpack mean and covariance of diagonal Gaussian.
   mu, cov = variational params[:D], np.exp(variational params[D:])
    # Sample from multivariate normal using the reparameterization trick.
    samples = npr.randn(num samples, D) * np.sqrt(cov) + mu
    # Lower bound is the exact entropy plus a Monte Carlo estimate of energy.
    return mvn.entropy(mu, np.diag(cov)) + np.mean(logprob(samples))
# Get gradient with respect to variational params using autograd.
gradient = grad(lower bound)
```

Black-box stochastic variational inference in five lines of Python (Duvenaud and Adams, 2015, NIPS Workshop on Black-box Learning and Inference)

Figure 1: Black-box stochastic variational inference in five lines of Python, using automatic differentiation. The variational objective gradient can be used with any stochastic-gradient-based optimizer.

```
def lower bound(variational params, logprob func, D, num samples):
    # variational_params: the mean and covariance of approximate posterior.
    # logprob_func:
                           the unnormalized log-probability of the model.
                           the number of parameters in the model.
    # D •
    # num samples:
                           the number of Monte Carlo samples to use.
    # Unpack mean and covariance of diagonal Gaussian.
    mu, cov = variational params[:D], np.exp(variational params[D:])
    # Sample from multivariate normal using the reparameterization trick.
    samples = npr.randn(num samples, D) * np.sqrt(cov) + mu
    # Lower bound is the exact entropy plus a Monte Carlo estimate of energy.
    return mvn.entropy(mu, np.diag(cov)) + np.mean(logprob(samples))
# Get gradient with respect to variational params using autograd.
gradient = grad(lower bound)
Figure 1: Black-box stochastic variational inference in five lines of Python, using automatic differen-
tiation. The variational objective gradient can be used with any stochastic-gradient-based optimizer.
```

Black-box stochastic variational inference in five lines of Python (Duvenaud and Adams, 2015, NIPS Workshop on Black-box Learning and Inference)

The Machine Learning community cares about the AD API.

Automatic differentiation for machine learning in Julia

Automatic differentiation is a term I first heard of while working on (as it turns out now, a bit cumbersome) implementation of backpropagation algorithm – after all it caused lots of headaches as I had to handle all derivatives myself with almost pen-and-paper like approach. Obviously I made many mistakes until I got my final solution working.

At that time, I was aware some libraries like Theano or Tensorflow handle derivatives in a certain "magical" way for free. I never knew exactly what happens deep in the guts of these libraries though and I somehow suspected it is rather painful than fun to grasp (apparently, I was wrong!).

I decided to take a shot and directed my first steps towards TensorFlow official documentation to quickly find out what the magic is. The term I was looking for was **automatic differentiation**.

Contents [hide]

- 1 Introduction Why do we care at all?
- 2 Input functions our scope limits
- 3 Forward mode automatic differentiation
 - 3.1 Dual Numbers
 - 3.2 Dual Numbers in Iulia
- 4 Reverse mode automatic differentiation
 - 4.1 Reverse mode automatic differentiation basic bits

Justin Domke's Weblog



← Hessian-Vector products

The Stalin Compiler →

Automatic Differentiation: The most criminally underused tool in the potential machine learning toolbox?

Posted on February 17, 2009

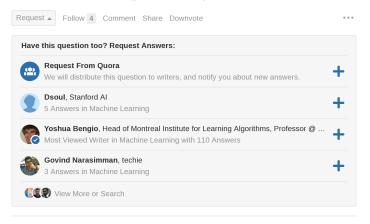
Update: (November 2015) In the almost seven years since writing this, there has been an explosion of great tools for automatic differentiation and a corresponding upsurge in its use. Thus, happily, this post is more or less obsolete.

I recently got back reviews of a paper in which I used <u>automatic differentiation</u>. Therein, a reviewer clearly thought I was using finite difference, or "numerical" differentiation. This has led me to wondering: Why don't machine learning people use automatic differentiation more? Why don't they use it...constantly? Before recklessly speculating on the answer, let me

Archives

- September 2015
- December 2014
- February 2014
- January 2014
- September 2013
- September 2012
- January 2012
- November 2011
- October 2011
- July 2011
- May 2011
- March 2011November 2009
 - Ootobox 2000
- October 2009
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Why isn't automatic differentiation more widely used in the machine learning community?





Can you answer this question?

Answer

Why isn't automatic differentiation more widely used in the machine learning community?

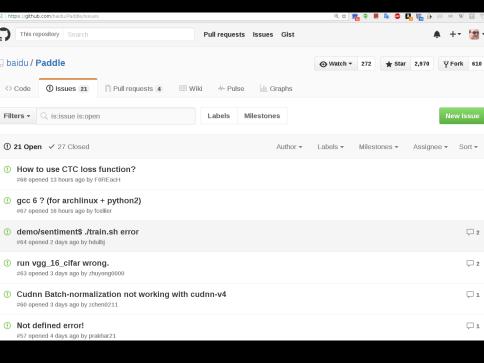
- 1. the ML community doesn't use Fortran
 - ▶ it doesn't even use C much anymore, and hasn't for a while
 - ▶ it never used C++ or Java very much
 - it uses Matlab a lot, and has for a long time
 - it uses Python a lot
- 2. it typically doesn't write big programs
 - ▶ instead it writes small programs that express complicated mathematical ideas (nuggets) in a dense fashion
 - relies a lot on reuse through libraries widely used in the community
- 3. it doesn't need to support legacy code
- 4. it needs to be nimble
 - code written by individuals and small teams
 - but shared a lot with other groups that fork the code and build on it can't tolerate large build infrastructures that come with preprocessors
- 5. it processes huge amounts of data
- 6. recently, it relies heavily on GPUs
- 7. it uses idioms that are conveniently formulated with data-parallel constructs

Deep Learning Tool Uptake Requirements

In order for the Deep Learning community to embrace a tool it must provide them:

- AD
- High speed on large datasets
- Expressive power for algorithms of interest
- High speed on large datasets
- Open source
- High speed on large datasets

Baidu open-sourced **paddlepaddle** on 12-Sep-2016



Take-Home Message

- ► The AD community has spent a lot of time developing
 - sophisticated methods for taking gradients (forward mode, reverse mode, checkpointing, ...)
 - that apply to programs
- ► The ML community has spent a lot of time developing
 - specialized methods for taking gradients
 - ▶ that apply to *neural nets* (feed forward data-flow graphs constructed out of a small number of node types)
 - but has made them *fast* (GPU implementations)
 - ▶ to run on *huge* datasets (ImageNet, MSCOCO, Sports1M, ...)
- ▶ The AD community is *tiny* (\approx 50)
- ▶ The ML community is *huge* (\approx 15000)
- ▶ The ML community is rediscovering AD
- ► There is a window of opportunity for the AD community to have impact in the ML community

ML and AD

opportunity for ideas to flow back and forth

Good News

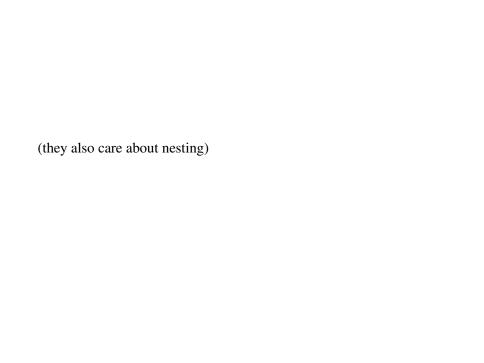
Bad News

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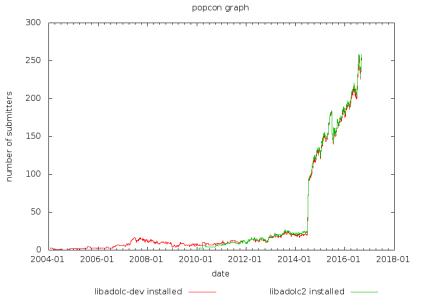
Editors' note: bibliometrics and the curators of orthodoxy

MSCS Editorial Board

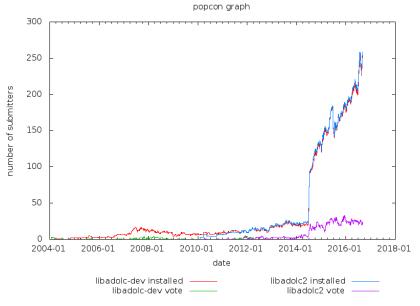
Received 1 December 2008

Have you ever seen the Citation Indexes (CIs) for the year 1600? At that time, a very active community was working on the reconstruction of planetary movements by means of epicycles. In principle, any ellipse around the Sun may be approximated by sufficiently many epicycles around the Earth. This is a non-trivial geometrical task, especially given the lack of analytical tools (sums of series). And the books and papers of many talented geometers quoted one another. Scientific knowledge, however, was already taking other directions. Science has a certain 'inertia', it is prudent (at times, it has been exceedingly so, mostly for political or metaphysical reasons), but even under the best of conditions, we all know how difficult it is to accept new ideas, to let them blossom in time, away from short-term pressures.

At best, CIs transform this slowness into a tool for judgement. If used unwisely, as is increasingly the case, they discourage people (young ones in particular) right from the



Debian package population count



Debian package population count (with usage)

Outline

1. beginning (ML rocks)

- because they're smart
- and generous
- and work on important stuff
- count their citations
- look at their pretty pictures
- follow the money

2. middle (technical gobbledygook)

- caffe, theano, torch, tensorflow, grad, autograd, robust first class verbiage
- reverse mode by reversing a reversible ode leaving bread crumbs
- from stochastic gradient descent to stochastic hessian inverse product
- limited by their tools but they're working hard
- 3. end (take home message)
 - ▶ if we don't service the ML community they will eat AD for lunch