

1. Papoulis 7-15: n.b. $U(a-X) = \mathbb{1}_{(-\infty, a]}(X)$ and $U(b-Y) = \mathbb{1}_{(-\infty, b]}(Y)$

$$E\{U(a-X)\} = \int_{-\infty}^{\infty} \mathbb{1}_{(-\infty, a]}(x) f_X(x) dx = \int_{-\infty}^a f_X(x) dx = F_X(a). \quad \text{Similarly } E\{U(b-Y)\} = F_Y(b).$$

$$E\{U(a-X)U(b-Y)\} = \iint_{\mathbb{R}^2} \mathbb{1}_{(-\infty, a]}(x) \cdot \mathbb{1}_{(-\infty, b]}(y) dx dy = \iint_{-\infty}^a \int_{-\infty}^b f_{XY}(x,y) dx dy = F_{XY}(a,b)$$

If X and Y are stat indep $\Rightarrow f_{XY}(a,b) = f_X(a)f_Y(b) \Rightarrow F_{XY}(a,b) = F_X(a)F_Y(b)$

$$\Rightarrow E\{U(a-X)U(b-Y)\} = E\{U(a-X)\} \cdot E\{U(b-Y)\}$$

conversely, $E\{U(a-X)U(b-Y)\} = E\{U(a-X)\} \cdot E\{U(b-Y)\} \Rightarrow F_{XY}(a,b) = F_X(a)F_Y(b)$

$$\Rightarrow X \text{ and } Y \text{ stat. indep.}$$

2. Papoulis 7-17: $Z = X+Y$. Let $W=X$ (change of variables) with aux. variable W

Then $f_{XZ}(x,z) = f_{WZ}(w,z) = f_{XY}(x, z(x,y)) \left| \frac{\partial(x,y)}{\partial(x,z)} \right|$, $\left| \frac{\partial(x,y)}{\partial(x,z)} \right| = 1$

$$\Rightarrow f_{XZ}(x,z) = f_{XY}(x, z-x)$$

If X and Y are stat. indep., then $f_{XY}(x,y) = f_X(x)f_Y(y)$

$$\Rightarrow f_{XZ}(x,z) = f_X(x)f_Y(z-x)$$

$$\therefore f_Z(z|x) = \frac{f_{XZ}(x,z)}{f_X(x)} = \frac{f_X(x)f_Y(z-x)}{f_X(x)} = f_Y(z-x)$$

3. We need to find $f_{XY}(x,y) = f(x|y)$. Note that $f_{XY}(x,y)$ is a jointly Gaussian $f_{XY}(x,y)$. You can show this using char. fens. (n.b. $\Phi_{XY}(w_1, w_2) = \Phi_{XN}(w_1, w_1+w_2) = \Phi_X(w_1) \Phi_N(w_1+w_2)$)

$$\bar{X} = 0, \bar{Y} = 0, \text{var}(X) = \sigma_X^2, \text{var}(Y) = \sigma_X^2 + \sigma_N^2$$

$$\Gamma_{XY} = \frac{E\{XY\}}{\sigma_X \sigma_Y} = \frac{E\{X(X+N)\}}{\sigma_X \sigma_Y} = \frac{\sigma_X^2}{\sigma_X \sigma_Y} = \frac{\sigma_X}{\sigma_Y} = \frac{\sigma_X}{\sqrt{\sigma_X^2 + \sigma_N^2}}$$

Thus we have

$$f_{XY}(x,y) = \frac{1}{2\pi \sigma_X \sqrt{\sigma_X^2 + \sigma_N^2} \sqrt{1 - \left(\frac{\sigma_X}{\sqrt{\sigma_X^2 + \sigma_N^2}}\right)^2}} \exp \left\{ -\frac{1}{2 \left(1 - \frac{\sigma_X^2}{\sigma_X^2 + \sigma_N^2}\right)} \left[\frac{x^2}{\sigma_X^2} - \frac{2\sigma_X x y}{(\sigma_X^2 + \sigma_N^2)\sigma_X} + \frac{y^2}{\sigma_X^2 + \sigma_N^2} \right] \right\}$$

$$= \frac{1}{2\pi \sigma_X \sigma_N} \exp \left\{ -\frac{(\sigma_X^2 + \sigma_N^2)}{2\sigma_N^2} \left[\frac{x^2}{\sigma_X^2} - \frac{2xy}{\sigma_X^2 + \sigma_N^2} + \frac{y^2}{\sigma_Y^2} \right] \right\}, \quad \text{and } f_Y(y) = \frac{1}{\sqrt{2\pi(\sigma_X^2 + \sigma_N^2)}} \exp \left\{ -\frac{y^2}{2(\sigma_X^2 + \sigma_N^2)} \right\}$$

n.b $f(x|y) = \frac{f(x,y)}{f_Y(y)} = \dots = \frac{1}{\sqrt{2\pi \left(\frac{\sigma_x^2 \sigma_u^2}{\sigma_x^2 + \sigma_u^2}\right)}} \exp \left\{ -\frac{(\sigma_x^2 + \sigma_u^2)}{2\sigma_x^2 \sigma_u^2} \left[x - \left(\frac{\sigma_x^2}{\sigma_x^2 + \sigma_u^2}\right) y \right]^2 \right\}$

$f(x|y) \sim \mathcal{N} \left[\frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2}, \sqrt{\frac{\sigma_x^2 \sigma_u^2}{\sigma_x^2 + \sigma_u^2}} \right]$, a Gaussian with the specified mean and standard deviation

We can now find the MMS and MAP estimators in a straightforward manner

(a) The MMS estimator $\hat{x}_{MMS}(y)$ is given by the conditional expectation

$$\hat{x}_{MMS}(y) = E \{ X | Y=y \} = \int_{-\infty}^{\infty} x f(x|y) dx = \boxed{\frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2}}$$

(b) The MAP estimator is given by

$$\hat{x}_{MAP}(y) = \arg \max_{x \in \mathbb{R}} \{ f(x|y) \}$$

n.b. we can write $f(x|y)$ as

$$f(x|y) = K_1 \exp \left\{ -K_2 \left[x - \frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2} \right]^2 \right\}$$

where $K_1, K_2 > 0$.

Because the exponential is a monotonically increasing function, it takes on its maximum value when its argument takes on its max. value. This happens when $\left[x - \frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2} \right]^2 = 0$

which occurs when $x = \frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2}$

$$\therefore \hat{x}_{MAP}(y) = \frac{\sigma_x^2 y}{\sigma_x^2 + \sigma_u^2}$$

n.b $\hat{x}_{MMS}(y) = \hat{x}_{MAP}(y)$ in this case. Note also that

$\sigma_x^2 \gg \sigma_u^2$ (reliable measurement): $\hat{x}(y) \approx 1 \cdot y = y$ (observed value)
 $\sigma_x^2 \ll \sigma_u^2$ (noisy measurement): $\hat{x}(y) \approx 0 \cdot y = 0$ (prior mean)

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4. Papoulis 7-24: Recall that $E\{g(X, Y)\} = E\{E\{g(X, Y) | X=x\}\}$

Thus if we wish to minimize $E\{[Y - (AX+B)]^2\}$
 $= E\{E\{[Y - (AX+B)]^2 | X=x\}\}$, we should take

$$B = E\{Y\} - A E\{X\} = \mu_Y - A \mu_X$$

We then have that

$$\begin{aligned} Y - (AX+B) &= Y - [AX + \mu_Y - A\mu_X] \\ &= (Y - \mu_Y) - A[X - \mu_X] \end{aligned}$$

where $A = a = \frac{E\{(X - \mu_X)(Y - \mu_Y)\}}{E\{(X - \mu_X)^2\}}$, see Papoulis Eqs. (7-72) and (7-73)

5. We know that $\Phi_{X,Y}(\omega_x, \omega_y) = e^{i[\mu_x \omega_x + \mu_y \omega_y]} e^{-\frac{1}{2}[\sigma_x^2 \omega_x^2 + 2r \sigma_x \sigma_y \omega_x \omega_y + \sigma_y^2 \omega_y^2]}$
 and if W and V are jointly Gaussian it has a char. fun. of the form
 $\Phi_{V,W}(\omega_v, \omega_w) = e^{i[\mu_v \omega_v + \mu_w \omega_w]} e^{-\frac{1}{2}[\sigma_v^2 \omega_v^2 + 2\rho \sigma_v \sigma_w \omega_v \omega_w + \sigma_w^2 \omega_w^2]}$ (*)
 We must show that $\Phi_{V,W}(\omega_v, \omega_w)$ has this form. By defn.

$$\begin{aligned} \Phi_{V,W}(\omega_v, \omega_w) &= E\{e^{i[\omega_v (aX+bY) + \omega_w (cX+dY)]}\} = E\{e^{i[(a\omega_v+c\omega_w)X + (b\omega_v+d\omega_w)Y]}\} \\ &= e^{i[(a\omega_v+c\omega_w)\mu_x + (b\omega_v+d\omega_w)\mu_y]} \cdot \exp\left\{-\frac{1}{2}\left[\sigma_x^2(a\omega_v+c\omega_w)^2 + \sigma_y^2(b\omega_v+d\omega_w)^2 + 2r\sigma_x\sigma_y(a\omega_v+c\omega_w)(b\omega_v+d\omega_w)\right]\right\} \\ &= e^{i[(a\mu_x+b\mu_y)\omega_v + (c\mu_x+d\mu_y)\omega_w]} \cdot \exp\left\{-\frac{1}{2}\left[\sigma_x^2(a^2\omega_v^2 + 2ac\omega_v\omega_w + c^2\omega_w^2) + \sigma_y^2(b^2\omega_v^2 + 2bd\omega_v\omega_w + d^2\omega_w^2) + 2r\sigma_x\sigma_y(ab\omega_v^2 + (ad+bc)\omega_v\omega_w + cd\omega_w^2)\right]\right\} \\ &= e^{i[(a\mu_x+b\mu_y)\omega_v + (c\mu_x+d\mu_y)\omega_w]} \cdot \exp\left\{-\frac{1}{2}\left[\omega_v^2(a^2\sigma_x^2 + b^2\sigma_y^2 + 2rab\sigma_x\sigma_y) + \omega_w^2(c^2\sigma_x^2 + d^2\sigma_y^2 + 2rcd\sigma_x\sigma_y) + 2\omega_v\omega_w(ac\sigma_x^2 + bd\sigma_y^2 + r\sigma_x\sigma_y(ad+bc))\right]\right\} \end{aligned}$$

which is the char. fun. of a Gaussian (has the form of (*)).

Here

$$\mu_v = a\mu_x + b\mu_y, \quad \sigma_v^2 = a^2\sigma_x^2 + b^2\sigma_y^2 + 2rab\sigma_x\sigma_y$$

$$\mu_w = c\mu_x + d\mu_y, \quad \sigma_w^2 = c^2\sigma_x^2 + d^2\sigma_y^2 + 2rcd\sigma_x\sigma_y$$

$$\rho = \frac{\rho\sigma_v\sigma_w}{\sqrt{\sigma_v^2\sigma_w^2}} = \frac{ac\sigma_x^2 + bd\sigma_y^2 + (ad+bc)r\sigma_x\sigma_y}{\sqrt{(a^2\sigma_x^2 + b^2\sigma_y^2 + 2rab\sigma_x\sigma_y)(c^2\sigma_x^2 + d^2\sigma_y^2 + 2rcd\sigma_x\sigma_y)}}$$

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6. Papoulis 8-2: Define the zero-one RVs

$$X_A = \mathbb{1}_A(\omega), X_B = \mathbb{1}_B(\omega), X_C = \mathbb{1}_C(\omega), \omega \in \Omega.$$

$$P(\{X_A=1\} \cap \{X_B=1\} \cap \{X_C=1\}) = P(A \cap B \cap C) = \frac{1}{4}$$

$$\left. \begin{aligned} P(\{X_A=1\}) &= P(A) = \frac{1}{2} \\ P(\{X_B=1\}) &= P(B) = \frac{1}{2} \\ P(\{X_C=1\}) &= P(C) = \frac{1}{2} \end{aligned} \right\} \Rightarrow P(\{X_A=1\})P(\{X_B=1\})P(\{X_C=1\}) = \frac{1}{8}$$

thus $P(\{X_A=1\} \cap \{X_B=1\} \cap \{X_C=1\}) \neq P(\{X_A=1\})P(\{X_B=1\})P(\{X_C=1\})$

$\Rightarrow X_A, X_B, X_C$ are not stat. indep.

However $P(\{X_A=1\} \cap \{X_B=1\}) = P(A \cap B) = \frac{1}{4} = P(\{X_A=1\})P(\{X_B=1\})$

and this will be true for all combinations of the form $P(\{X_Q=b_Q\} \cap \{X_R=b_R\}) = \frac{1}{4}$, for $Q, R \in \{A, B, C\}$ and $b_Q, b_R \in \{0, 1\}$.

7. Papoulis 8-3: If $X, Y,$ and Z are independent in pairs, then

$$r_{XY} = 0, r_{XZ} = 0, r_{YZ} = 0$$

and the char. fun. $\Phi_{XYZ}(\omega_1, \omega_2, \omega_3)$ is given by

$$\Phi_{XYZ}(\omega_1, \omega_2, \omega_3) = \exp\{i[\omega_1 \eta_X + \omega_2 \eta_Y + \omega_3 \eta_Z]\} \cdot \exp\left\{-\frac{1}{2}[\sigma_X^2 \omega_1^2 + \sigma_Y^2 \omega_2^2 + \sigma_Z^2 \omega_3^2]\right\}$$

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Addendum
on Page 4(b)

$$= \exp\left\{i\omega_1 \eta_X - \frac{1}{2}\omega_1^2 \sigma_X^2\right\} \cdot \exp\left\{i\omega_2 \eta_Y - \frac{1}{2}\omega_2^2 \sigma_Y^2\right\}$$

$$\cdot \exp\left\{i\omega_3 \eta_Z - \frac{1}{2}\omega_3^2 \sigma_Z^2\right\}$$

$$= \Phi_X(\omega_1) \Phi_Y(\omega_2) \Phi_Z(\omega_3)$$

$$\Rightarrow f_{XYZ}(x, y, z) = f_X(x) f_Y(y) f_Z(z)$$

$\Rightarrow X, Y,$ and Z are stat. indep. Successes,

Problem 7 Addendum:

From the discussion in section 8-2 of Papoulis, we have that the joint char. fn. of the jointly Gaussian RVs X_1, \dots, X_n is

$$\Phi_{X_1, \dots, X_n}(w_1, \dots, w_n) = e^{i \sum_{j=1}^n \eta_j w_j} \cdot \exp \left\{ -\frac{1}{2} \sum_{j=1}^n \sum_{k=1}^n w_j w_k C_{jk} \right\}$$

$$\text{where } C_{jk} = \text{cov}(X_j, X_k) = r_{X_j X_k} \sigma_{X_j} \sigma_{X_k}$$

$$\eta_j = E\{X_j\}$$

In problem 7 we have three joint Gaussians X , Y , and Z . Hence we have (noting that $r_{XY} = r_{XZ} = r_{YZ} = 0$)

$$\begin{aligned} \Phi_{XYZ}(w_1, w_2, w_3) &= e^{i(\eta_X w_1 + \eta_Y w_2 + \eta_Z w_3)} \cdot \exp \left\{ -\frac{1}{2} \left[w_1^2 \sigma_X^2 + w_1 w_2 \cancel{r_{XZ} \sigma_X \sigma_Z} + w_1 w_3 \cancel{r_{XZ} \sigma_X \sigma_Z} \right. \right. \\ &\quad \left. \left. + w_2 w_3 \cancel{r_{YZ} \sigma_Y \sigma_Z} + w_2 w_1 \cancel{r_{XZ} \sigma_X \sigma_Z} + w_2^2 \sigma_Y^2 + w_3^2 \sigma_Z^2 + w_3 w_1 \cancel{r_{XZ} \sigma_X \sigma_Z} \right. \right. \\ &\quad \left. \left. + w_3 w_2 \cancel{r_{YZ} \sigma_Y \sigma_Z} + w_3^2 \sigma_Z^2 \right] \right\} \\ &= e^{i(\eta_X w_1 + \eta_Y w_2 + \eta_Z w_3)} \cdot e^{-\frac{1}{2} [\sigma_X^2 w_1^2 + \sigma_Y^2 w_2^2 + \sigma_Z^2 w_3^2]} \\ &= \left[e^{i \eta_X w_1} e^{-\frac{1}{2} \sigma_X^2 w_1^2} \right] \cdot \left[e^{i \eta_Y w_2} e^{-\frac{1}{2} \sigma_Y^2 w_2^2} \right] \cdot \left[e^{i \eta_Z w_3} e^{-\frac{1}{2} \sigma_Z^2 w_3^2} \right] \\ &= \Phi_X(w_1) \Phi_Y(w_2) \Phi_Z(w_3) \end{aligned}$$

$$\Rightarrow f_{XYZ}(x, y, z) = f_X(x) f_Y(y) f_Z(z)$$

$$\Rightarrow X, Y, \text{ and } Z \text{ are stat. indep.}$$

8. (Papoulis 7-4)

Define $Z = X_1 + X_2 + X_3$, where X_1, X_2 and X_3 are i.i.d. RVs with pdf

$$f_{X_i}(x) = \begin{cases} 1 & (x) \\ [-1/2, 1/2] \end{cases}, \quad i=1, 2, 3.$$

The characteristic function for each X_i is

$$\begin{aligned} \underline{\Phi}_{X_i}(\omega) &= E[e^{i\omega X_i}] = \int f_{X_i}(x) e^{i\omega x} dx \\ &= \int_{-1/2}^{1/2} e^{i\omega x} dx = \left. \frac{e^{i\omega x}}{i\omega} \right|_{-1/2}^{1/2} = \frac{e^{i\omega/2} - e^{-i\omega/2}}{i\omega} \\ &= \frac{\sin(\omega/2)}{(\omega/2)} = \frac{2 \sin(\omega/2)}{\omega}, \quad i=1, 2, 3. \end{aligned}$$

Thus it follows that since X_1, X_2 and X_3 are statistically independent

$$\underline{\Phi}_Z(\omega) = \underline{\Phi}_{X_1}(\omega) \cdot \underline{\Phi}_{X_2}(\omega) \cdot \underline{\Phi}_{X_3}(\omega) = \left[\frac{2 \sin(\omega/2)}{\omega} \right]^3$$

$$\begin{aligned} \text{Now } \underline{\Phi}_Z(\omega) &= E[e^{i\omega Z}] = E\left[\sum_{k=0}^{\infty} \frac{(i\omega Z)^k}{k!} \right] = \sum_{k=0}^{\infty} \frac{(i\omega)^k}{k!} E[Z^k] \\ &= \sum_{k=0}^{\infty} \frac{i^k \omega^k}{k!} m_k = \sum_{k=0}^{\infty} a_k \omega^k, \end{aligned}$$

where $m_k = E[X^k]$ is the k -th moment of Z ,

and $a_k = \frac{i^k m_k}{k!}$. Thus we have $E[X^k] = m_k = \frac{a_k \cdot k!}{i^k}$.

Now expanding $\underline{\Phi}_{X_i}(\omega)$ about $\omega=0$ as a Taylor series yields

$$\underline{\Phi}_{X_i}(\omega) = \frac{2 \sin(\omega/2)}{\omega} = 1 - \frac{\omega^2}{24} + \frac{\omega^4}{1920} - \dots$$

Thus we have

$$\begin{aligned} \underline{\Phi}_Z(\omega) &= \left[\frac{2 \sin(\omega/2)}{\omega} \right]^3 = \left[1 - \frac{\omega^2}{24} + \frac{\omega^4}{1920} - \dots \right]^3 \\ &= 1 - \frac{\omega^2}{8} + \frac{13}{1920} \omega^4 - \dots \end{aligned}$$

The coefficient on $\frac{\omega^4}{8}$ in this expansion is $a_k = \frac{13}{1920}$

$$\therefore E[Z^4] = \frac{a_4 \cdot 4!}{i^4} = \frac{13(4!)}{1920} \cdot \frac{1}{(i)^4} = \boxed{\frac{11}{80}}$$

9. Papoulis 7-7 (8-7 in 2nd edition)

We wish to show that

$$\begin{aligned} E[X_1 \cdot X_2 | X_3] &= E \left[E[X_1 \cdot X_2 | X_2, X_3] | X_3 \right] \\ &= E \left[X_2 \cdot E[X_1 | X_2, X_3] | X_3 \right] \end{aligned}$$

We start by noting that

$$E[X_1 \cdot X_2 | X_3 = x_3] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 x_2 f_{X_1, X_2}(x_1, x_2 | X_3 = x_3) dx_1 dx_2$$

$$= \int_{-\infty}^{\infty} x_1 x_2 f_{X_1}(x_1 | X_2 = x_2, X_3 = x_3) f_{X_2}(x_2 | X_3 = x_3) dx_1 dx_2$$

(because $f_{X_1, X_2}(x_1, x_2 | X_3 = x_3) = f_{X_1}(x_1 | X_2 = x_2, X_3 = x_3) \cdot f_{X_2}(x_2 | X_3 = x_3)$)

$$= \int_{-\infty}^{\infty} f_{X_2}(x_2 | X_3 = x_3) \int_{-\infty}^{\infty} x_1 x_2 f_{X_1}(x_1 | X_2 = x_2, X_3 = x_3) dx_1 dx_2 \quad \dots (*)$$

$$= \int_{-\infty}^{\infty} f_{X_2}(x_2 | X_3 = x_3) \cdot E[X_1 \cdot X_2 | X_2 = x_2, X_3 = x_3] dx_2 = \varphi_1(x_3)$$

$$\Rightarrow E[X_1 \cdot X_2 | X_3] = \int_{-\infty}^{\infty} f_{X_2}(x_2 | X_3) \cdot E[X_1 \cdot X_2 | X_2 = x_2, X_3] dx_2$$

$$= \varphi_1(X_3) = E \left[E[X_1 \cdot X_2 | X_2, X_3] | X_3 \right]$$

(proving first result)

Also from (*)

$$E[X_1 \cdot X_2 | X_3 = x_3] = \int_{-\infty}^{\infty} x_2 f_{X_2}(x_2 | X_3 = x_3) \int_{-\infty}^{\infty} x_1 f_{X_1}(x_1 | X_2 = x_2, X_3 = x_3) dx_1 dx_2$$

$$= \int_{-\infty}^{\infty} x_2 f_{X_2}(x_2 | X_3 = x_3) \cdot E[X_1 | X_2 = x_2, X_3 = x_3] dx_2$$

$$= E \left[X_2 \cdot E[X_1 | X_2, X_3 = x_3] | X_3 = x_3 \right] = \varphi_2(x_3)$$

from which it follows from substituting the RV X_3 for x_3 , we have

$$E[X_1 \cdot X_2 | X_3] = \varphi_2(X_3) = E \left[X_2 \cdot E[X_1 | X_2, X_3] | X_3 \right]$$

(proving second result)