

Session 33

Recall...

33.1

Constant False Alarm Rate  
(CFAR)  
Detection

Recall...

33.2

Assume that we must decide between two simple hypotheses

$$\begin{aligned} H_0 : X &\sim \exp(\mu_0), \\ H_1 : X &\sim \exp(\mu_1). \end{aligned} \quad (\text{assume } \mu_1 > \mu_0.)$$

The resulting test will be a threshold test of the form

$$\phi(X) = \begin{cases} 1, & \text{for } X \geq x_0; \\ 0, & \text{for } X < x_0. \end{cases}$$

The threshold  $x_0$  that yields a probability of false alarm  $\alpha$  is

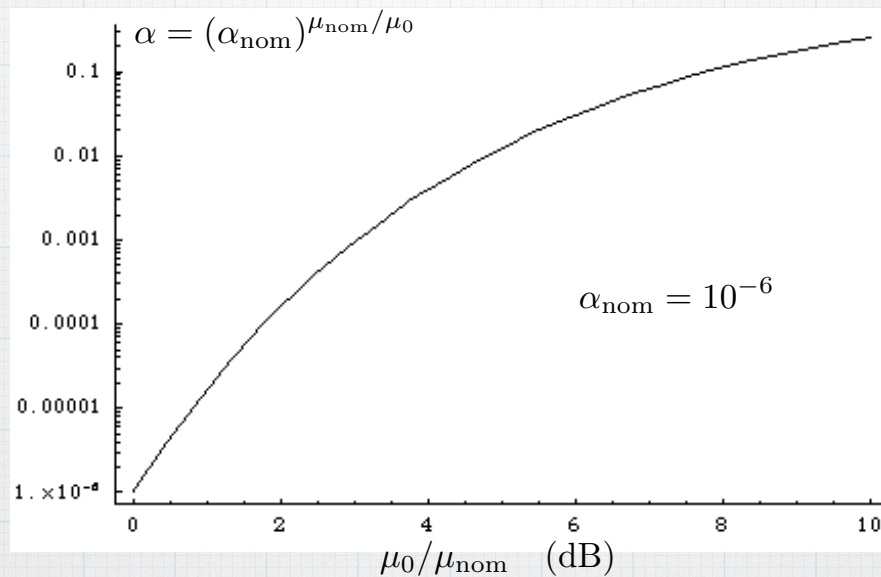
$$x_0 = -\mu_0 \ln \alpha.$$

If we have an error in  $\mu_0$ , we will have a significantly different false alarm probability:

$$\alpha = (\alpha_{\text{nom}})^{\mu_{\text{nom}}/\mu_0}.$$

33.3

### The effects of inaccurate noise estimates





Recall...

## The exponential Detection Problem Revisited

33.4

Assume that we must decide between two simple hypotheses

$$H_0 : Y \sim \exp(\mu_0),$$

$$H_1 : Y \sim \exp(\mu_1).$$

$$\mu_1 > \mu_0$$

Now if we think of

$$\mu_1 = \mu_0 + \mu_s,$$

where

$$\mu_s = \text{signal component of } \mu_1,$$

then if we define the *signal-to-noise ratio* as

$$S = \mu_s / \mu_0,$$

we can rewrite  $\mu_1$  as

$$\mu_1 = \mu_0(1 + S),$$

and our simple hypotheses can be rewritten as

$$H_0 : Y \sim \exp(\mu_0) \quad \text{versus} \quad H_1 : Y \sim \exp(\mu_0(1 + S)).$$

Recall...

33.5

The most powerful test of size  $\alpha$  is given by

$$\phi(Y) = \begin{cases} 1, & \text{for } Y > Y_0, \\ 0, & \text{for } Y \leq Y_0, \end{cases}$$

where the threshold  $Y_0$  is given by

$$Y_0 = -\mu_0 \ln \alpha.$$

The power of the test is given by

$$\beta = P(Y > Y_0 | H_1) = \dots = \alpha^{1/(1+S)}.$$

*n.b.* The threshold  $Y_0$  is a function of  $\mu_0$  and the probability of false alarm  $\alpha$ .



If we don't know the value of  $\mu_0$ , we cannot set the threshold  $Y_0$  that will yield our size  $\alpha$  test. How should we proceed?

In principle,  $\mu_0$  could take on a broad range of positive values.

We could view  $H_0$  as a the composite hypothesis that  $\mu_0 \in (0, \infty)$ .

We could then use a generalized likelihood ratio test to solve the problem.

Under hypothesis  $H_0$ , this would correspond to finding the maximum likelihood estimate  $\hat{\mu}_0$  and using it in place of  $\mu_0$ . But for one sample measurement, this does not yield a good estimate.

However, if we had  $N$  i.i.d. measurements  $X_1, \dots, X_N$  of the noise, we could use the maximum likelihood (and minimum variance unbiased) estimate

$$\hat{\mu}_0 = \frac{1}{N} \sum_{i=1}^N X_i$$

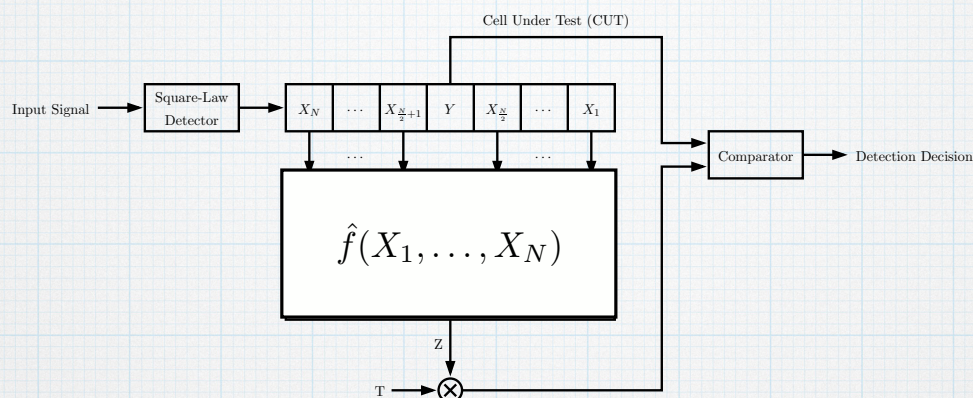
in place of  $\mu_0$ .

- In a “typical” radar scenario, targets are sparsely located against a background of noise and clutter.
- There tends to be regions of local statistical homogeneity in this noise/clutter background because the physical environment giving rise to it often has homogeneous statistics.
- However, there can be significant changes in the local scattering characteristics as you move through the scattering environment.
- There can be sharp boundaries between scattering regions.



- This suggests that one approach to estimating the background noise power for target detection in a particular resolution cell is to average the measured noise power in surrounding resolution cells.
- This is an example of a class of detection techniques called *Constant False Alarm Rate* (CFAR) techniques.
- We will see where the term *Constant False Alarm Rate* comes from, but more important than the constant false alarm rate is a robustness to changes in the average noise power.

### A Generic CFAR Processor



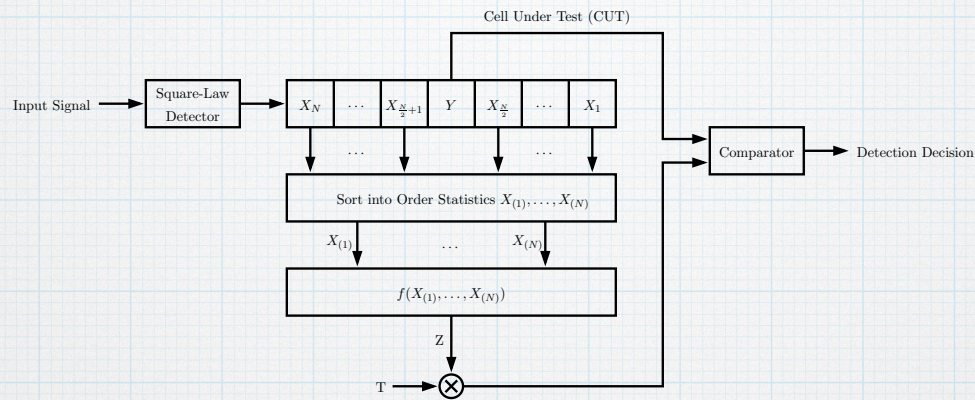
The resolution *cell under test* (CUT) with measurement  $Y$  is tested for the presence of the target using a threshold computed using neighboring resolution cell measurements  $X_1, \dots, X_N$ .

The statistic  $Z = \hat{f}(X_1, \dots, X_N)$  is an estimate of the noise power.

The threshold scaling factor  $T$  sets the threshold level by scaling the statistic the statistic  $Z$ . This works because the threshold is the product of a constant and the average noise power.



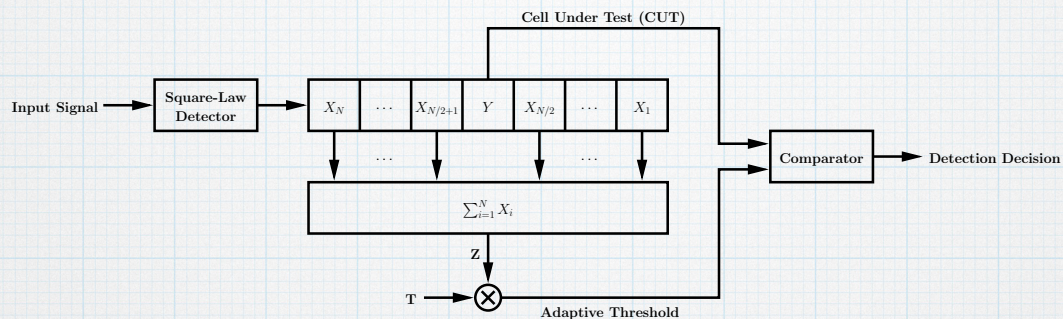
## A More Specific Class of CFAR Processors



This processor can compute

- Mean
- Median
- Arbitrary Order Statistics
- Linear Combination of Order Statistics.

## Cell-Averaging CFAR (CA-CFAR)



In CA-CFAR, we have that the statistic  $Z/N$  is just the sample mean.

It can be shown that  $Z/N$  is the maximum-likelihood estimate of  $\mu_0$ . (It is also the *minimum variance unbiased estimate* (MVUE) of  $\mu_0$  and an *efficient estimate*—satisfying the Cramer-Rao lower bound.)



If we assume that  $X_1, \dots, X_N$  are i.i.d exponential with mean  $\mu$  (drop subscript for simplicity) we have

$$f_{X_i}(x) = \frac{1}{\mu} e^{-x/\mu} \cdot 1_{[0, \infty)}(x).$$

The moment generating function of each  $X_i$  is

$$\Phi_{X_i}(s) = \left( \frac{1}{1 - \mu s} \right).$$

$\Phi_{X_i}(s) = E[e^{sX}]$ , where  $s \in \mathbb{R}$  (or  $s \in \mathbb{C}$ ). Closely related to char. fcn  $\phi_X(\omega) = E[e^{i\omega X}]$ ,  $\omega \in \mathbb{R}$ .

The moment generating function of  $Z$  is

$$\Phi_Z(s) = \left( \frac{1}{1 - \mu s} \right)^N.$$

Because the test is a threshold test comparing the CUT  $Y$  to the threshold  $TZ$ , the probability of false alarm is

$$\begin{aligned} \alpha &= E_Z [P[Y > TZ | H_0]] \\ &= E_Z \left[ \int_{TZ}^{\infty} \frac{1}{\mu} e^{-y/\mu} dy \right] \\ &= E_Z [\exp(-TZ/\mu)] \\ &= \int_{-\infty}^{\infty} e^{-\frac{Tz}{\mu}} f_Z(z) dz \\ &= \Phi_Z \left( -\frac{T}{\mu} \right), \end{aligned}$$

$\Phi_Z(s) = E[e^{sZ}]$   
= moment generating function of  $Z$

where  $E_Z[\cdot]$  denotes expectation w.r.t.  $Z$ .

Substituting this into the expression for  $\Phi_Z(s)$ , the false alarm probability is

$$\alpha = (1 + T)^{-N}.$$

Note that the false alarm rate is not a function of the mean noise power  $\mu$ . Hence the term *constant false-alarm rate*.



The threshold scaling factor yielding a size  $\alpha$  test is

$$T = (\alpha)^{-1/N} - 1.$$

Similarly, the detection probability can be calculated under the alternative hypothesis  $H_1$  and given by

$$\begin{aligned}\beta &= E_Z [P[Y > TZ|H_1]] \\ &= E_Z \left[ \int_{TZ}^{\infty} \frac{1}{\mu(1+S)} e^{-y/\mu(1+S)} dy \right] \\ &= E_Z [\exp(-TZ/\mu)] \\ &= \Phi_Z \left( -\frac{T}{\mu(1+S)} \right) \\ &= \left[ 1 + \frac{T}{(1+S)} \right]^{-N} \\ &= \left( \frac{1+S}{1+T+S} \right)^N.\end{aligned}$$

Combining these results, we find that

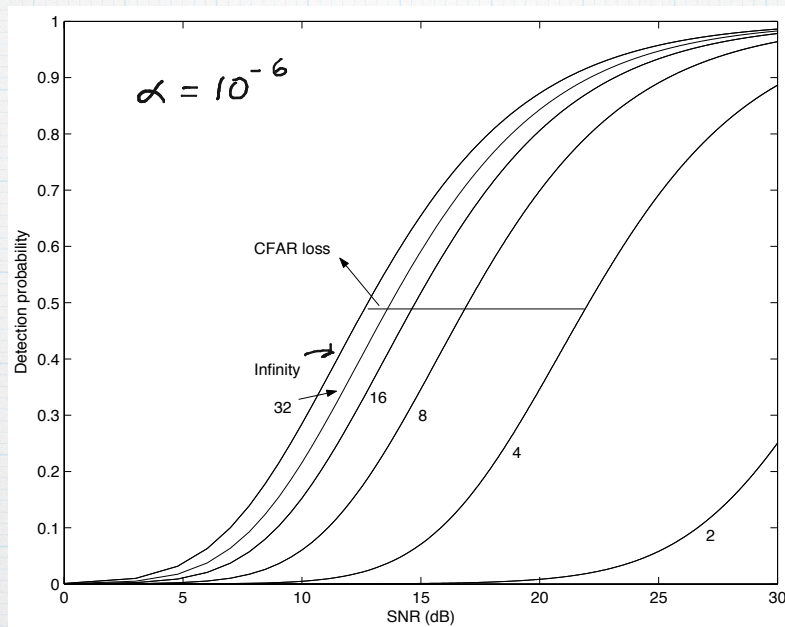
$$\beta = \left( \frac{1+S}{\alpha^{-1/N} + S} \right)^N.$$

In the limit, as  $N \rightarrow \infty$ , we have

$$\begin{aligned}\lim_{N \rightarrow \infty} \alpha &= \lim_{N \rightarrow \infty} (1 + \epsilon/N)^{-N} \\ &= \exp\{-\epsilon\} \\ \lim_{N \rightarrow \infty} \beta &= \lim_{N \rightarrow \infty} (1 + \epsilon/N(1+S))^{-N} \\ &= \exp\{-\epsilon/(1+S)\} \\ \Rightarrow \beta &\rightarrow \alpha^{1/(1+S)}, \text{ as } N \rightarrow \infty\end{aligned}$$



## CA-CFAR Detection Performance



CA-CFAR  $P_d$  versus  $N$  and  $SNR$  (dB) for a desired  $P_{fa} = 1 \times 10^{-6}$

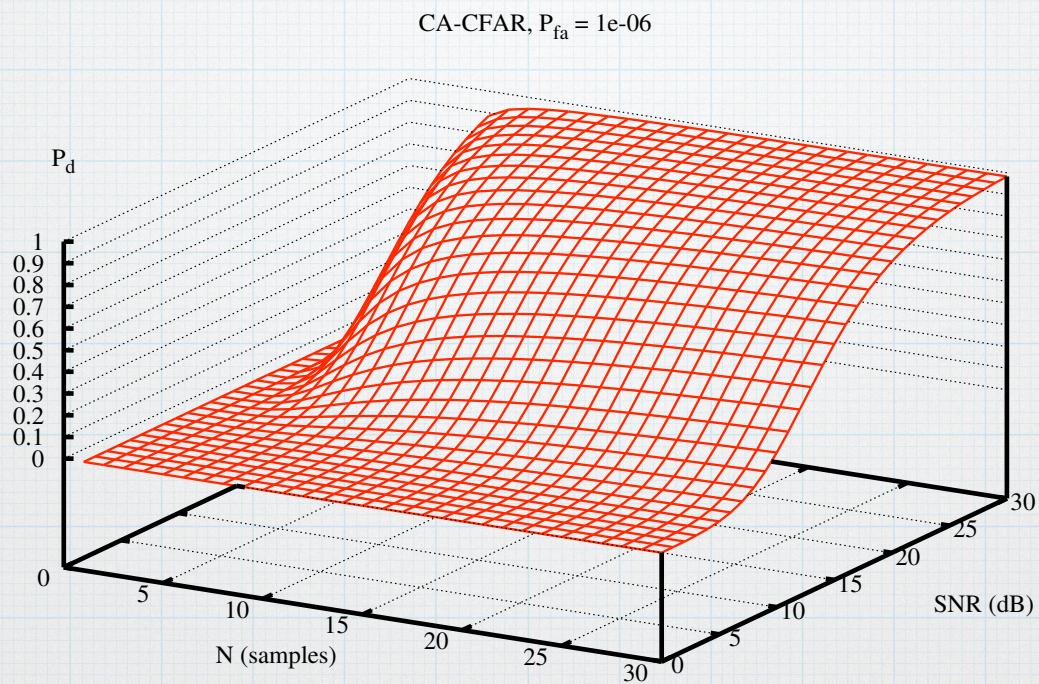


Figure from: Michael F. Rimbert, *Constant False Alarm Rate Detection Techniques Based on Empirical Distribution Function Statistics*, Ph.D Thesis, School of Electrical and Computer Engineering, Purdue University, August 2005.