

## Session 30

### Processing a Coherent Pulse Train

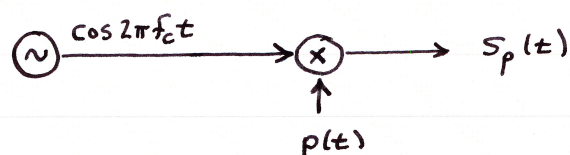
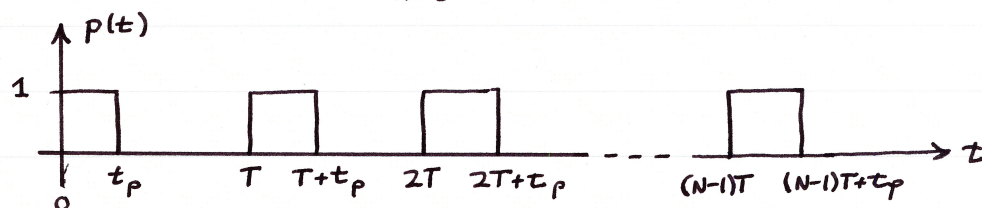
30.1

Assume a radar transmits a passband signal of the form

$$S_p(t) = p(t) \cos 2\pi f_c t$$

where

$$p(t) = \sum_{n=0}^{N-1} 1_{[0, t_p]}(t - nT).$$



The signal reflected back from a point-target with radial velocity  $\dot{R}$  and received by the radar is of the form

$$r(t) = p(t) \cos [2\pi f_c t + \phi(t)].$$

(n.b. we have re-oriented the time origin to account for the round-trip delay)

Here,  $\phi(t)$  is due to the Doppler shift:

$$\phi(t) = +2\pi f_D t = -2\pi \frac{2\dot{R}}{\lambda} t.$$

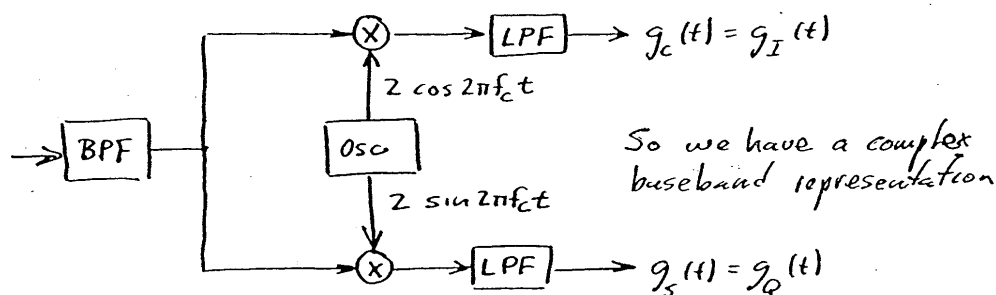
$$f_D = \frac{2v_r}{\lambda}$$

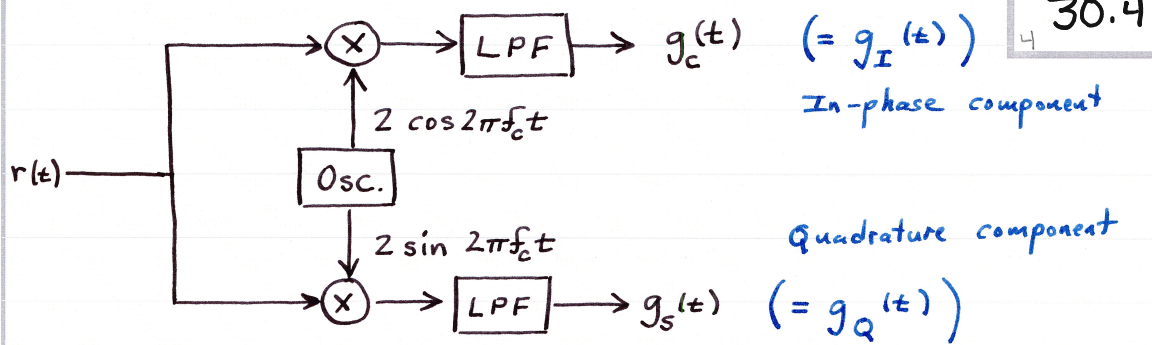
(monostatic)

n.b. We are assuming  $p(t)$  is narrowband w.r.t. carrier  $f_c$  and that time dilation/compression of  $p(t)$  is negligible.  
Narrowband Assumption

We would like to find the complex baseband representation of the received signal  $r(t)$  via processing:

- Pass the signal through a bandpass filter that passes virtually all of the signal, but little outside of the signal's frequency band.
- Use an I/Q demodulator to get the in-phase and quadrature components.





$$g_c(t) = p(t) \cos \phi(t)$$

$$g_s(t) = p(t) \sin \phi(t)$$

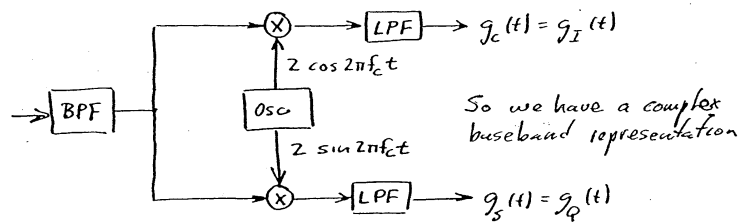
Now consider the complex envelope function

$$u(t) = g_c(t) + i g_s(t) = p(t) \cos \phi(t) + i p(t) \sin \phi(t)$$

$$= p(t) [\cos \phi(t) + i \sin \phi(t)]$$

$$= p(t) e^{i \phi(t)}. \quad (\text{By Euler's identity})$$

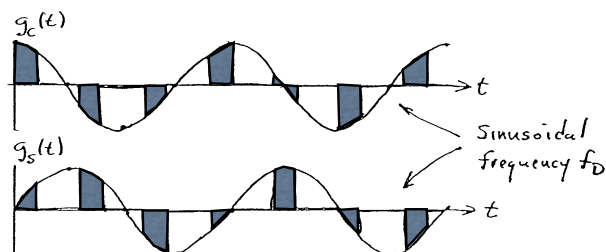
30.5

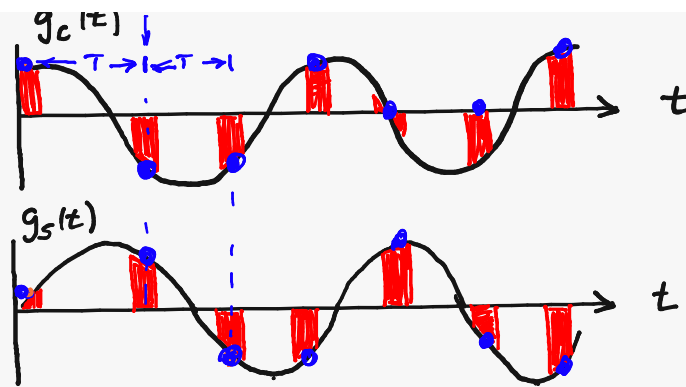


$$g_c(t) = p(t) \cos \phi(t)$$

$$g_s(t) = p(t) \sin \phi(t)$$

For  $\phi(t) = 2\pi f_D t$  as in our case, the two signals appear as follows:





30.6

Now we can form the complex envelope function

$$u(t) = g_c(t) + i g_s(t)$$

If we sample  $u(t)$  at sampling instants  $t_0, t_1, \dots, t_{N-1}$  such that

$$t_n - t_{n-1} = T, \quad n = 1, \dots, N-1$$

with  $t_0$  selected within the first pulse ( $0 < t_0 < t_p$ ) we get one complex sample from each pulse return

Note that if we define the complex sequence

30.7

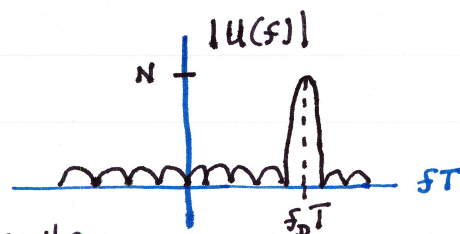
$$u_n = u(t_n) = u(t_0 + nT), \quad n = 0, 1, \dots, N-1$$

and compute the DTFT of  $\{u_n\}$ , we get

$$\begin{aligned} U(f) &= \sum_{n=0}^{N-1} u_n e^{-i2\pi nTf} = \sum_{n=0}^{N-1} e^{i2\pi f_0(t_0 + nT)} e^{-i2\pi nTf} \\ &= e^{i2\pi f_0 t_0} \sum_{n=0}^{N-1} e^{-i2\pi(f - f_0)nT} \end{aligned}$$

$$\text{For } f = f_0 \Rightarrow |U(f)| = N,$$

$$\text{For } f \neq f_0 \Rightarrow |U(f)| \approx 0.$$



n.b where we pick  $t_0$  determines the delay to the target. ( $t_0$  = delay to first pulse return.)

30.8

We could calculate the DFT of the sequence  $u_n$ :

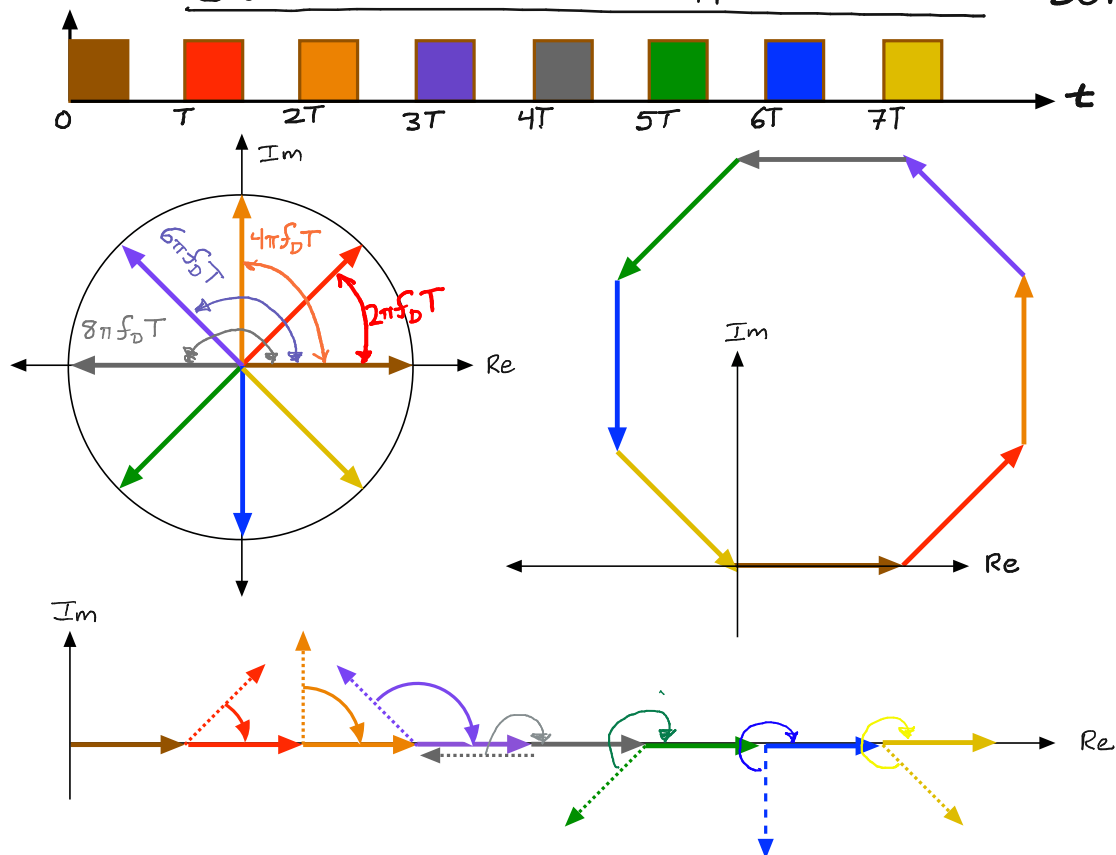
$$U_k = \sum_{n=0}^{N-1} u_n e^{-i \frac{2\pi nk}{N}}, \quad k=0, 1, \dots, N-1.$$

Here again, we would get a large magnitude when  $\frac{k}{N} \simeq T f_D$ :

$$U_k = \begin{cases} N \cdot e^{i 2\pi f_D t_0}, & k \simeq N T f_D \\ 0, & \text{elsewhere.} \end{cases}$$

Successive pulses with Doppler shift  $f_D$ .

30.9



So for ease of implementation, the DFT (computed using an FFT algorithm) is commonly used to determine the Doppler of a target located at delay  $t_0$  corresponding to the initial sampling time  $t_0$ .

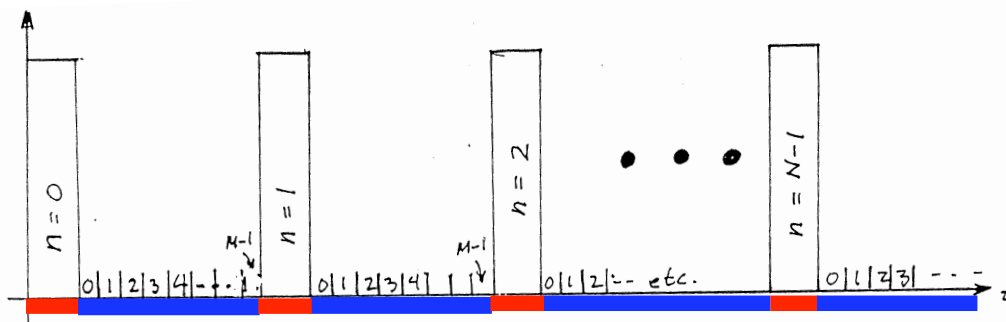
This is the beginning (and main idea) on which we build the delay-Doppler processor.

## The Pulse Waveform Delay-Doppler Processor

30.12

In general, we are interested in looking at the returns from all possible ranges (delays).

The situation appears as follows:



Because we transmit finite-bandwidth signals, we only have limited range or delay resolution.

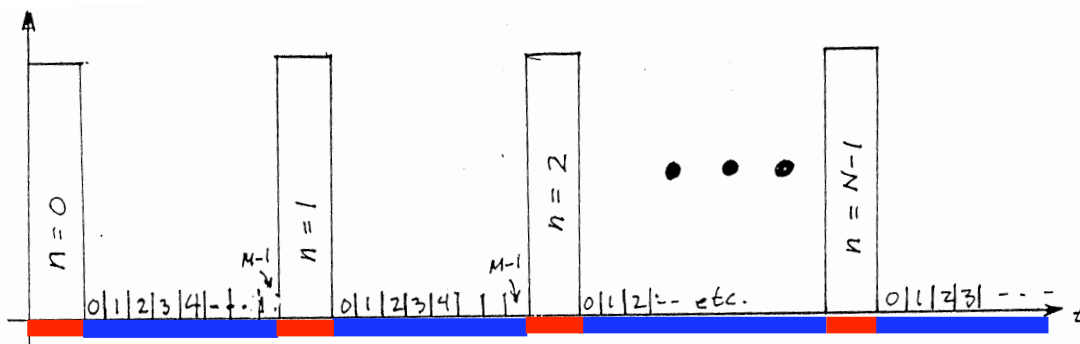
Recall what  $\beta_s(\tau, \nu)$  looks like.

So we will divide the listening period into bins of duration  $\tau_{RB}$ .

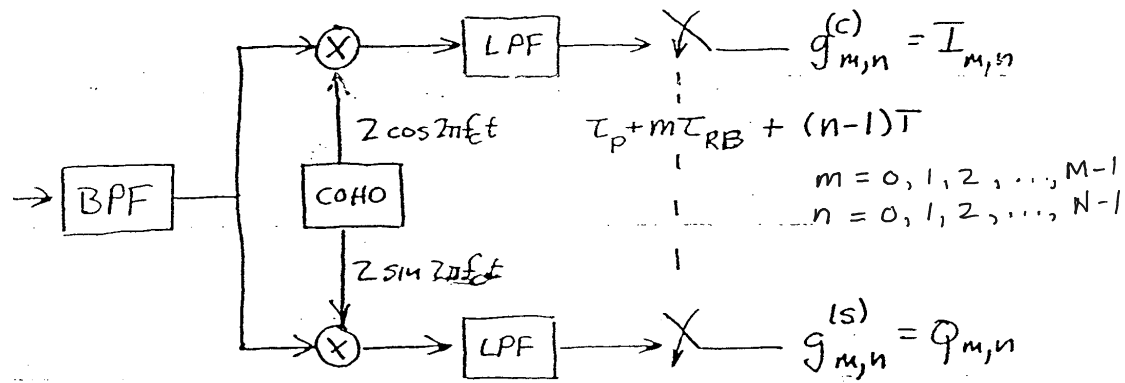
30.13

So we will divide the listening period into time bins of width  $\tau_{RB}$  and sample the signal once per bin for each range bin of interest.

Label the range bins  $0, 1, \dots, M-1$ .



We can get the sample returns from each of the range bins (both I and Q components to represent the complex baseband signal) by processing the received signal as follows:



*n.b.*,  $\tau_p$  is the transmitted pulse duration.

Once we have carried out this procedure, we can think of the I and Q samples  $\{I_{m,n}, Q_{m,n}\}$  as being arranged in an array as follows:

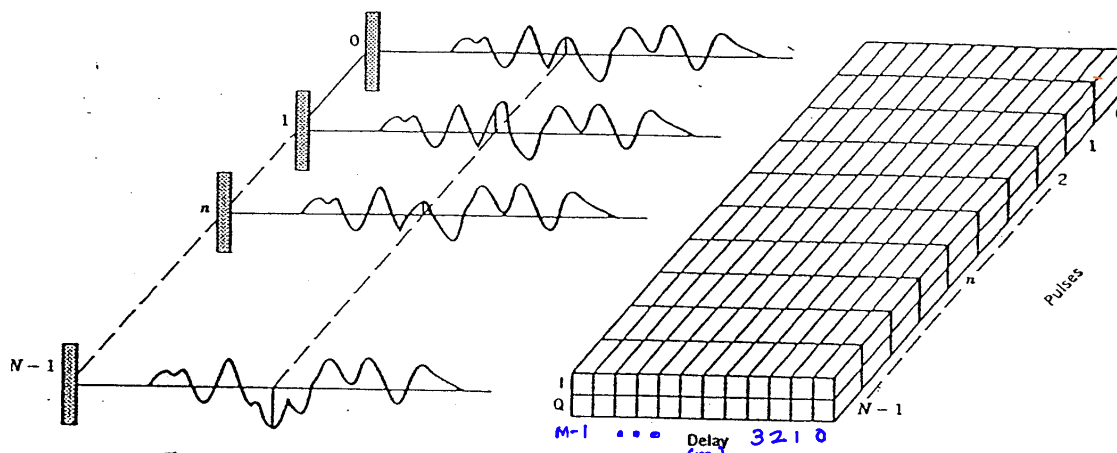


Figure 10.3 A conceptual diagram of the accumulation of I & Q samples at various delays, from N consecutive pulses.

(From: N. Levanon, *Radar Principles*, Wiley, 1987)



