

## Session 11

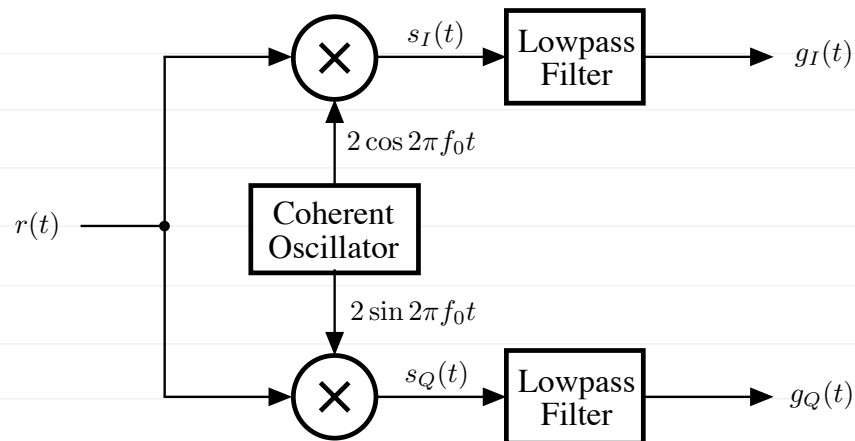
### Radar Signal Models

11.1

- Radar, like most radio systems, modulates a signal of interest onto a high-frequency RF carrier.
- The information bearing signal or pulse typically carries the information of interest.
- In a radar receiver, the received waveform's amplitude, phase and delay must be extracted from the received signal.

- One very common way of doing this is by "beating the signal down to baseband" using a quadrature detector:

11.2



Suppose a pulse  $p(t) = \mathbb{1}_{[0, T]}(t)$  amplitude modulates a carrier with frequency  $f_0$  to produce a signal  $s(t)$ :

11.3

$$s(t) = \cos(2\pi f_0 t) \cdot \mathbb{1}_{[0, T]}(t)$$

Now if the received signal  $r(t)$  is a  $\tau$ -delayed version of  $s(t)$ , we have

$$\begin{aligned} r(t) &= s(t-\tau) = \cos[2\pi f_0 (t-\tau)] \cdot \mathbb{1}_{[0, T]}(t-\tau) \\ &= \cos(2\pi f_0 t - 2\pi f_0 \tau) \cdot \mathbb{1}_{[\tau, T+\tau]}(t) \end{aligned}$$

## Basic Trig. Identities

11.4

$$\cos A \cdot \cos B = \frac{1}{2} (\cos(A+B) + \cos(A-B))$$

$$\cos A \cdot \sin B = \frac{1}{2} (\sin(A+B) - \sin(A-B))$$

$$e^{i\theta} = \cos \theta + i \sin \theta \quad \leftarrow$$

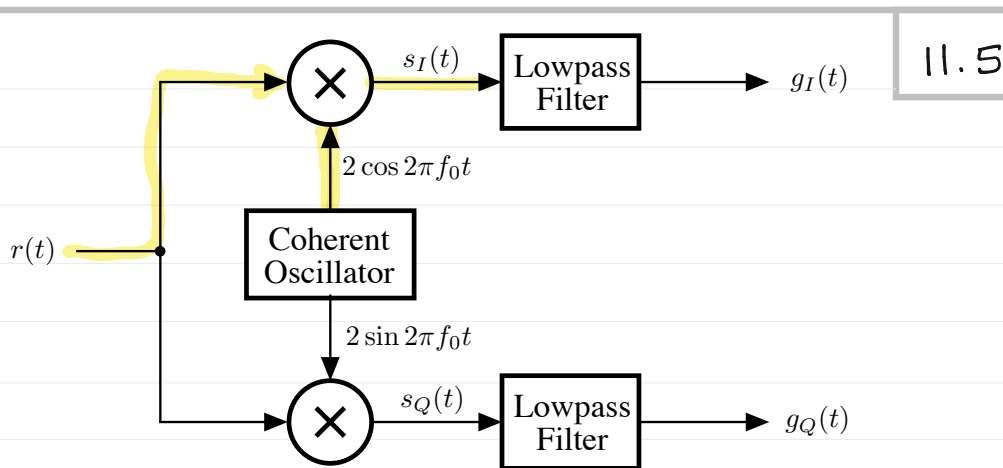
$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

Paul Nahin, Dr. Euler's  
Fabulous Formula

e.g.

$$\cos A \cdot \cos B = \left( \frac{e^{iA} + e^{-iA}}{2} \right) \left( \frac{e^{iB} + e^{-iB}}{2} \right) = \dots \frac{1}{2} [\cos(A+B) + \cos(A-B)]$$

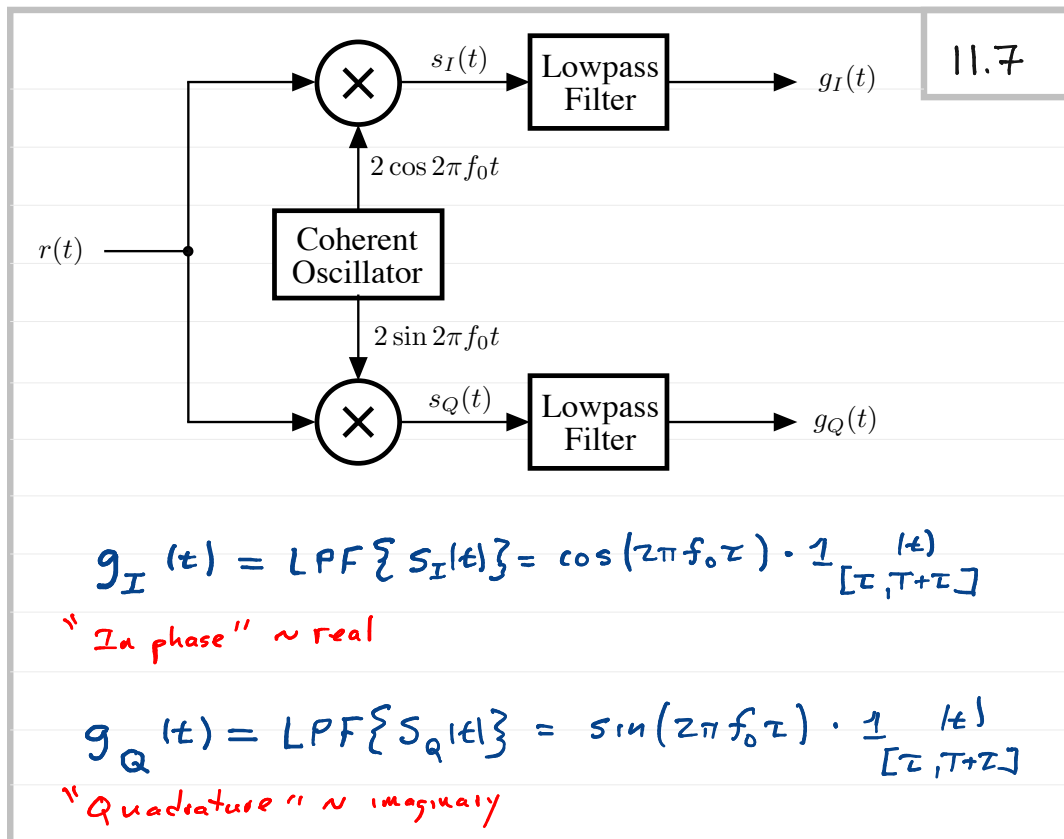
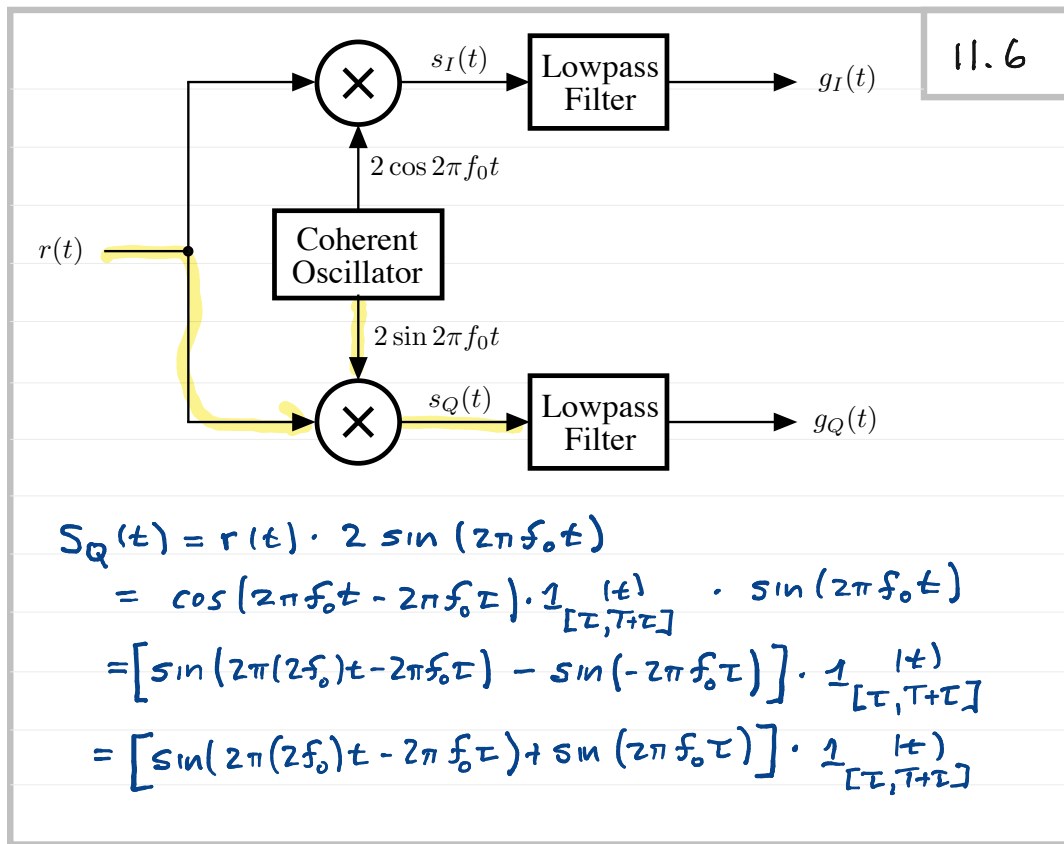


$$s_I(t) = r(t) \cdot 2 \cos 2\pi f_0 t$$

$$= \cos(2\pi f_0 t - 2\pi f_0 \tau) \cdot \frac{1}{\tau} \int_{\tau, \tau+\tau} \cdot 2 \cos 2\pi f_0 t$$

$$= \left[ \cos(2\pi(2f_0)t - 2\pi f_0 \tau) + \cos(-2\pi f_0 \tau) \right] \cdot \frac{1}{\tau} \int_{\tau, \tau+\tau}$$

$$\left[ \cos(2\pi(2f_0)t - 2\pi f_0 \tau) + \cos(2\pi f_0 \tau) \right] \cdot \frac{1}{\tau} \int_{\tau, \tau+\tau}^{(t)}$$



We can construct a complex waveform

11.8

$$z(t) = g_I(t) + i g_Q(t)$$

$$= \cos(2\pi f_0 \tau) \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t) + i \sin(2\pi f_0 \tau) \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t)$$

$$= [\cos(2\pi f_0 \tau) + i \sin(2\pi f_0 \tau)] \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t)$$

$$= e^{i 2\pi f_0 \tau} \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t)$$

This is a rectangular pulse of duration  $\tau$  starting at time  $\tau$ ,

It has phase  $2\pi f_0 \tau$  radians.

The form

11.9

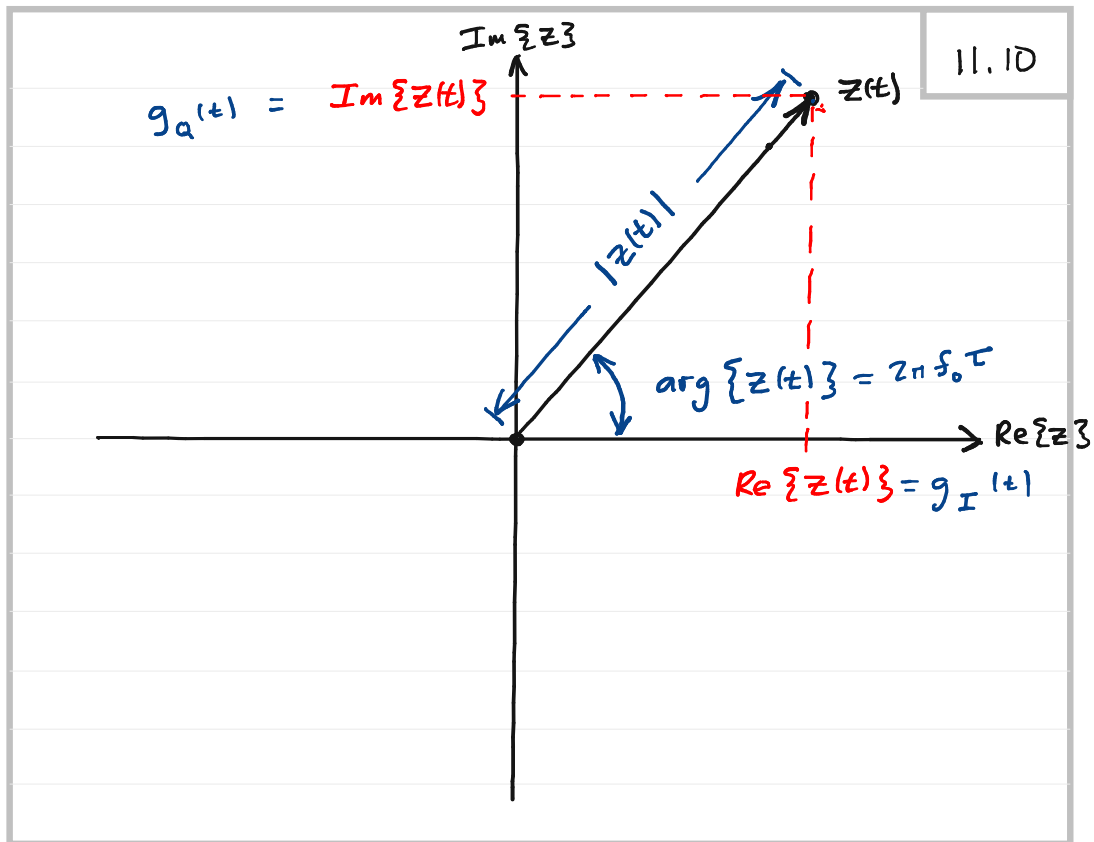
$$z(t) = e^{i 2\pi f_0 \tau} \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t)$$

is called the complex baseband form of real received passband signal

$$r(t) = \cos(2\pi f_0 (t-\tau)) \cdot \mathbb{1}_{[0, \tau]}(t-\tau)$$

$$= \cos(2\pi f_0 t - 2\pi f_0 \tau) \cdot \mathbb{1}_{[\tau, \tau+\tau]}(t)$$

We can represent  $z(t)$  at time  $t$  using a phasor diagram:



### The Narrowband Complex Baseband Signal

11.11

We now generalize the form of the received signal to be

$$r(t) = a(t) \cos(2\pi f_0 t + \theta(t))$$

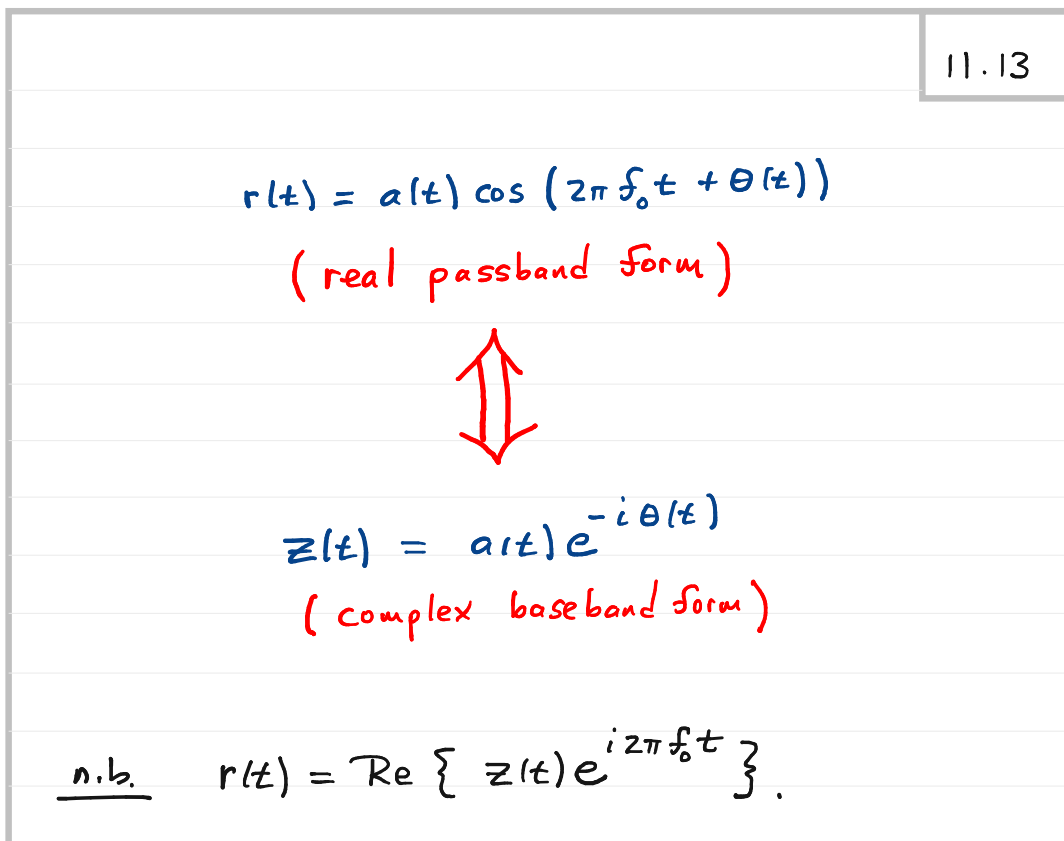
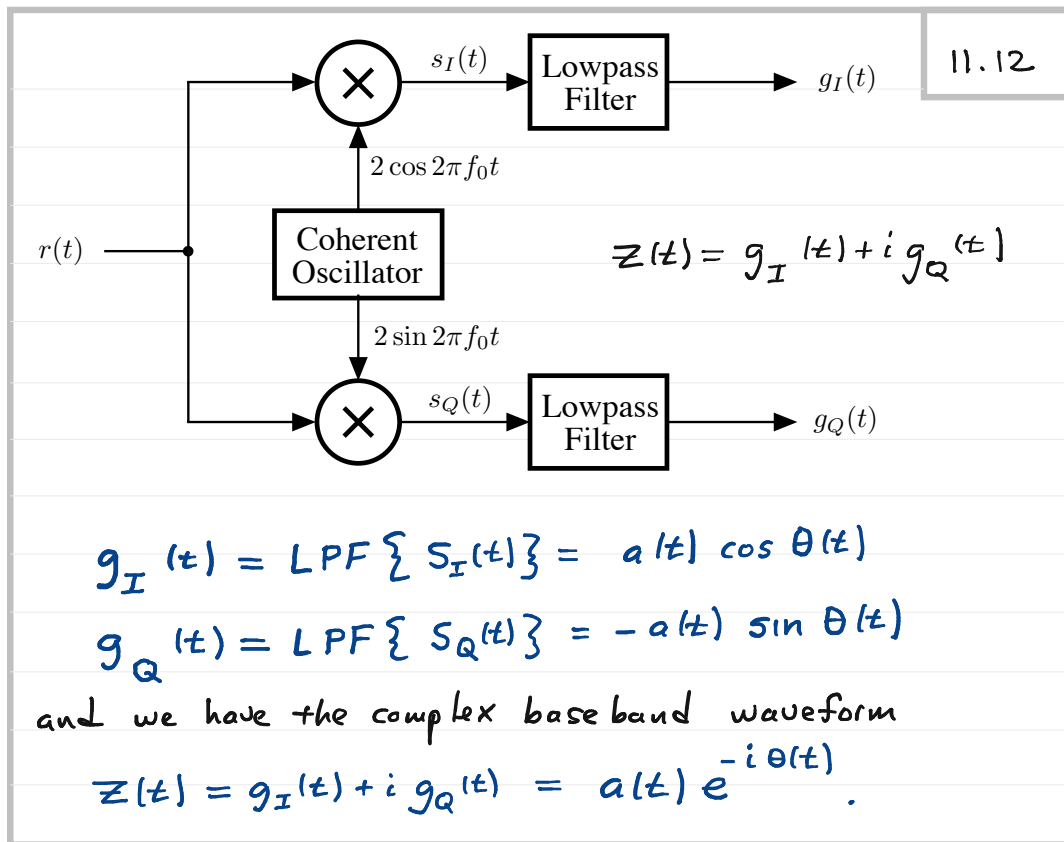
where

$a(t)$  = real-valued amplitude function

and

$\theta(t)$  = real-valued phase function.

Assume  $a(t)$  and  $\theta(t)$  vary slowly compared to  $\cos 2\pi f_0 t$ .



## Narrowband Complex Baseband Noise

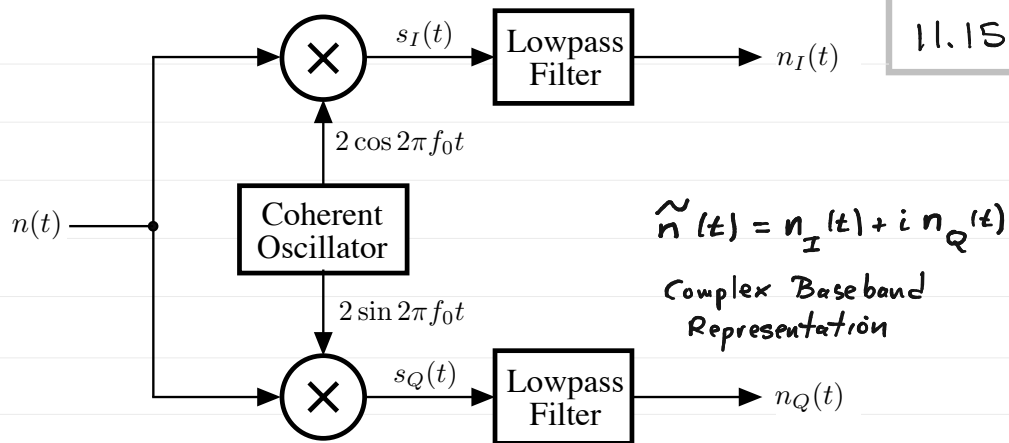
11.14

Consider a real, wide-sense stationary random process  $n(t)$ .

Assume that  $n(t)$  is wide-sense stationary white Gaussian noise.

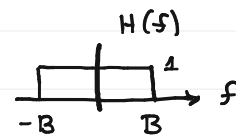
If we beat  $n(t)$  down to baseband, we get a corresponding complex baseband waveform

$$\tilde{n}(t) = n_I(t) + i n_Q(t).$$



If we have ideal low-pass filters

$$H(f) = \begin{cases} 1 & (f) \\ [-B, B] \end{cases},$$



then

$$S_{n_I n_I}(f) = S_{n_Q n_Q}(f) = \frac{N_0}{2} \mathbb{1}_{[-B, B]}(f).$$



Recall...

## Narrowband Complex Baseband Noise

11.16

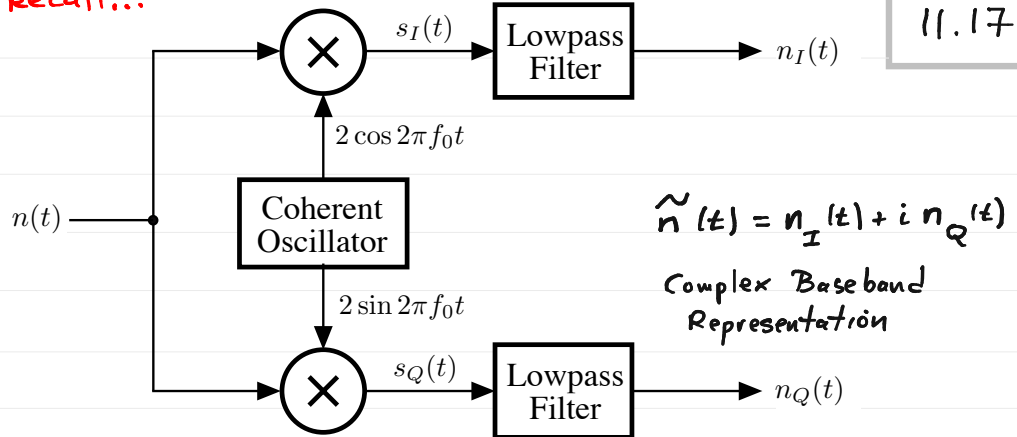
Consider a real, wide-sense stationary random process  $n(t)$ .

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If we beat  $n(t)$  down to baseband, we get a corresponding complex baseband waveform

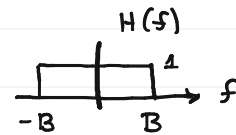
$$\tilde{n}(t) = n_I(t) + i n_Q(t).$$

Recall...



If we have ideal low-pass filters

$$H(f) = \begin{cases} 1 & (f) \\ [-B, B] \end{cases},$$



then

$$S_{n_I n_I}(f) = S_{n_Q n_Q}(f) = \frac{N_0}{2} \mathbb{1}_{[-B, B]}(f).$$

Furthermore,  $n_I(t)$  and  $n_Q(t)$  have identical autocorrelation functions.

11.18

$$\begin{aligned} R_{n_I}(\tau) &= R_{n_Q}(\tau) = \int_{-B}^B \frac{N_0}{2} e^{i2\pi f\tau} df \\ &= N_0 B \left( \frac{\sin 2\pi B\tau}{2\pi B\tau} \right) \\ &= N_0 B \operatorname{sinc}(2B\tau) \end{aligned}$$

where

$$\operatorname{sinc}(x) \triangleq \frac{\sin \pi x}{\pi x}.$$

Furthermore, it can be shown that

11.19

$$\begin{aligned} E[n_I(t+\tau)n_Q(t)] &= -E[n_Q(t+\tau)n_I(t)] \\ \Rightarrow R_{n_I n_Q}(\tau) &= -R_{n_Q n_I}(\tau) \end{aligned}$$

It follows that

$$\begin{aligned} R_{\tilde{n}}(\tau) &= E[\tilde{n}(t+\tau)\tilde{n}^*(t)] \\ &= E[(n_I(t+\tau) + in_Q(t+\tau))(n_I(t) - in_Q(t))] \\ &= R_{n_I}(\tau) + R_{n_Q}(\tau) + i(E[n_Q(t+\tau)n_I(t)] - E[n_I(t+\tau)n_Q(t)]) \\ &= 2(R_{n_I}(\tau) + R_{n_Q n_I}(\tau)). \end{aligned}$$

From this, we make the following observations...