

Session 29

Recall...

Stochastic Processes

29.1

Defn⁽¹⁾: A random process defined on a random experiment $(\mathcal{S}, \mathcal{F}, P)$ is a family $\{X(t); t \in \mathbb{R}\}$ of random variables defined on $(\mathcal{S}, \mathcal{F}, P)$ and indexed by t .

Recall: A RV $X: \mathcal{S} \rightarrow \mathbb{R}$ for a particular outcome $\omega_0 \in \mathcal{S}$ is just a real number $X(\omega_0)$.

A random process $X(t, \omega)$ is a function of two variables: time and the outcome $\omega \in \mathcal{S}$.

Recall...

29.2

Defn : For a fixed outcome $w_0 \in \Omega$, the time function $X(\cdot) = X(\cdot, w_0)$ is called the sample path of the random process $X(t)$ corresponding to w_0 . Each $w \in \Omega$ has a sample path $X(\cdot) = X(\cdot, w)$. The set of all sample paths
$$\mathcal{E} = \{X(\cdot) : X(\cdot) = X(\cdot, w), \text{ for } w \in \Omega\}$$
 is called the ensemble of the R.P. $X(t)$.

Having established these ideas, we can give the following equivalent definition of a random process ...

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Recall...

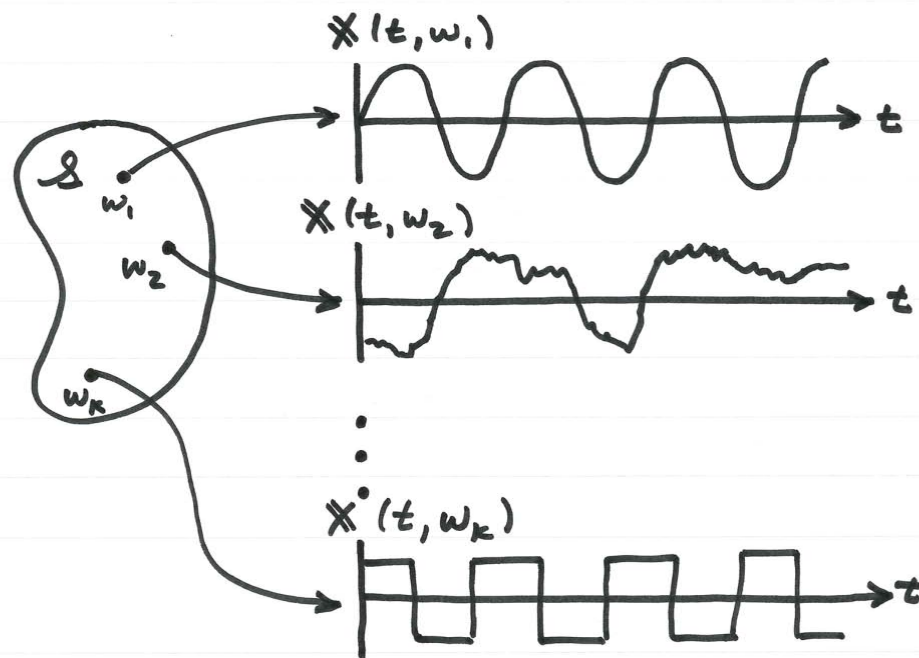
29.3

Defn⁽²⁾ : Consider a random experiment $(\Omega, \mathcal{F}, P)$. A function $X : \Omega \rightarrow \mathcal{E}$, where $\mathcal{E}$ is a set of functions of time (sample paths) is called a random process. That is, X is a mapping assigning a function of time $X(\cdot, w)$ to each $w \in \Omega$.

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A picture appears as follows:

29.4



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Note that once we know the particular $w_k \in S$ that is the outcome of the experiment, there is nothing random about the random process.

29.5

Randomness only enters into the random process through the selection of $w \in S$ in the random experiment.

Note: A random process is completely analogous to a Random variable:

Random Variable $X: S \rightarrow \mathbb{R}$ (real line)

Random Process: $X(t): S \rightarrow \mathcal{E}$ (set of functions of time)

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Example: I flip a coin three times (once a second) and construct a random process by making a waveform take on the value during that second corresponding to the outcome of the coin during that second:

29.6

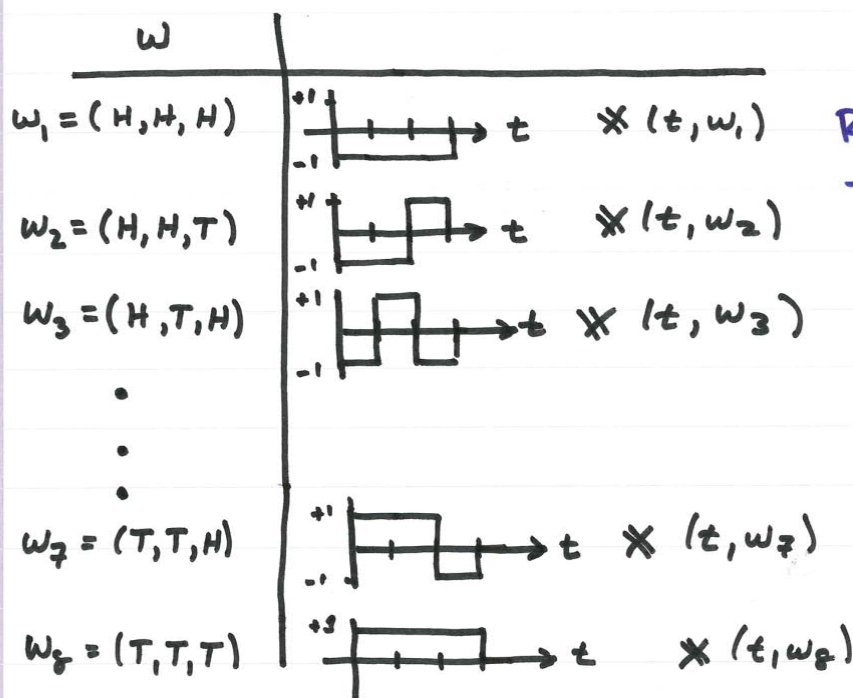
$$H \rightarrow -1 \quad (*)$$

$$T \rightarrow +1$$

I can consider this to be a combined experiment with $2^3 = 8$ possible outcomes:

$$\mathcal{S} = \{w_1, \dots, w_8\}$$

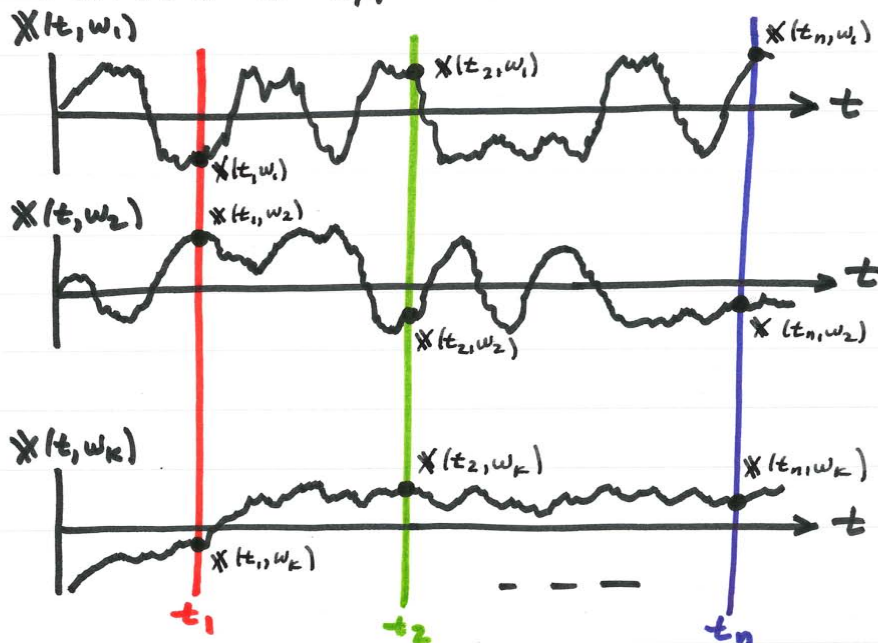
29.7



Randomness enters in only in the determination of w by flipping the coin 3 times. Once you know w , $x(t, w)$ is specified by relation $(*)$ non-randomly.

Note: If we evaluate a random process at time t , we get a random variable $X(t)$:

29.8



If we sample the random process $X(t)$ at n points in time, we get n j-dist RVs $X(t_1), X(t_2), \dots, X(t_n)$.

Defn: Fix n time instants

29.9

$t_1, \dots, t_n$. Then the n -th order cdf of $X(t)$ at times $t_1, t_2, \dots, t_n$ is the joint cdf of the n j-dist RVs $X(t_1), X(t_2), \dots, X(t_n)$:

$$F_{X(t_1) \dots X(t_n)}(x_1, \dots, x_n) = P(\{X(t_1) \leq x_1\} \cap \dots \cap \{X(t_n) \leq x_n\})$$

$$= "F_{X(t)}(x_1, \dots, x_n; t_1, \dots, t_n)"$$

and the corresponding n -th order pdf of $X(t)$ is

$$f_{X(t_1) \dots X(t_n)}(x_1, \dots, x_n) = \frac{\partial^n F_{X(t_1) \dots X(t_n)}(x_1, \dots, x_n)}{\partial x_1 \partial x_2 \dots \partial x_n}$$

$$= "f_{X(t)}(x_1, \dots, x_n; t_1, \dots, t_n)"$$

Theorem: The probabilistic behavior of a random process $X(t)$ is completely characterized by the collection of all n -th order cdfs or pdfs, for all $t_1, t_2, \dots, t_n$, and all $n = 1, 2, 3, \dots$ (all $n \in \mathbb{N}$.)

29.10

Proof: (Kolmogorov) Way beyond this course
But we can use the fact.

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Stationary Random Processes

29.11

"Stationary" $\triangleq$ staying in one place throughout time.

What if the n -th order distributions don't change with a shift in the time origin?

"Probabilistic behavior is the same yesterday, today and tomorrow."

15 Probabilistic description "stays in one place" throughout time.

Defn: A random process $X(t)$ is called n-th order stationary if all n-th order cdfs or pdfs are invariant to time shifts in the origin: 29.12

$$f_{X(t_1) \dots X(t_n)}(x_1, \dots, x_n) = f_{X(t_1+c) \dots X(t_n+c)}(x_1, \dots, x_n)$$

for all $c \in \mathbb{R}$ and for any n time instants $t_1, \dots, t_n$.

Defn: A random process $X(t)$ is called stationary, or strict sense stationary (SSS), if $X(t)$ is n-th order stationary for all $n=1, 2, 3, \dots$

Note: If $X(t)$ is stationary, it is first-order ($n=1$) stationary. 29.13

$$\begin{aligned} \Rightarrow f_{X(t_1)}(x) &= f_{X(t_1+c)}(x), \forall c \in \mathbb{R} \\ &= f_{X(t_2)}(x), \text{ for any } t_2 \in \mathbb{R} \\ &= f(x) \quad (\text{not a function of time}) \end{aligned}$$

$$\begin{aligned} \therefore E[X(t)] &= \int_{-\infty}^{\infty} x f_{X(t)}(x) dx \\ &= \int_{-\infty}^{\infty} x f(x) dx = \text{constant} \end{aligned} \quad \left(\begin{array}{l} \text{Not a} \\ \text{function} \\ \text{of} \\ \text{time.} \end{array} \right)$$

Similarly

$$\begin{aligned} \text{var}(X(t)) &= E[X^2(t)] - (E[X(t)])^2 \\ &= \sigma^2 = \text{constant} \quad (\text{Not a function of time.}) \end{aligned}$$

Example: non-stationary random process.

29.14

$$\text{Let } X(t) \triangleq e^{-\lambda t} \cdot 1_{[0, \infty)}(t)$$

where λ is a uniformly distributed RV on $[0, 1]$.

$X(t)$ is a random process.

At $t = t_1$, we have that $X(t_1)$ is a RV:

$$\begin{aligned} X(t_1) &= e^{-\lambda t_1} \cdot 1_{[0, \infty)}(t_1) = g(\lambda, t_1) \\ &= g_{t_1}(\lambda). \end{aligned}$$

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So

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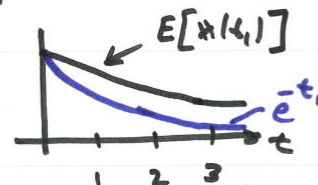
$$E[X(t_1)] = E[g_{t_1}(\lambda)]$$

$$= \int_{-\infty}^{\infty} g_{t_1}(a) f_{\lambda}(a) da$$

$$= \int_0^1 g_{t_1}(a) \cdot 1 da = \int_0^1 e^{-at_1} da \cdot 1_{[0, \infty)}(t_1)$$

$$= 1_{[0, \infty)}(t_1) \left. \frac{e^{-at_1}}{-t_1} \right|_{a=0}^1 = \frac{1 - e^{-t_1}}{t_1} \cdot 1_{[0, \infty)}(t_1)$$

$$\therefore E[X(t_1)] = \frac{1 - e^{-t_1}}{t_1} \cdot 1_{[0, \infty)}(t_1)$$



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Because $E[X(t)]$ is a function of t , it follows that $f_{X(t)}(x)$ must also be a function of t (you can find $f_{X(t)}(x)$ as an exercise)

29.16

$\Rightarrow X(t)$ is not first order stationary

$\Rightarrow X(t)$ is not stationary

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78.21

In the special case of 2nd order ($n=2$) stationary processes, we have

29.17

$$f_{X(t_1), X(t_2)}(x_1, x_2) = f_{X(t_1+c), X(t_2+c)}(x_1, x_2), \forall c \in \mathbb{R}.$$

This means that the second-order pdf

$$f_{X(t_1), X(t_2)}(x_1, x_2) = "f_X(x_1, x_2; t_1, t_2)"$$

can depend on t_1 and t_2 only through the time difference $t_1 - t_2$.

In such cases, the correlations between $X(t_1)$ and $X(t_2)$ can depend only on the time difference $t_1 - t_2$.

28.22

This motivates the following weaker form of stationarity:

29.18

Defn: A random process $X(t)$ is called wide-sense stationary (WSS) if

$$(i) E[X(t)] = \bar{X} = \text{constant}$$

and

$$(ii) E[X(t_1) \cdot X(t_2)] = R(t_1 - t_2)$$

i.e., it depends on t_1 and t_2 only through the time difference $t_1 - t_2$.

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Note:

1. If a random process $X(t)$ is first and second order ($n=1, 2$) stationary, and if $E[X(t)]$ and $E[X(t_1)X(t_2)]$ exist, then $X(t)$ is wide-sense stationary. The converse is not true.
2. If a R.P. $X(t)$ is stationary (S.S.S), it is also wide-sense stationary (W.S.S) if $E[X(t)]$ and $E[X(t_1)X(t_2)]$ exist.
3. If $X(t)$ is a W.S.S R.P., $E[X(t_1)X(t_2)]$, $\text{cov}(X(t_1), X(t_2))$, and the correlation coefficient $r_{X(t_1)X(t_2)}$ will depend only on the time difference $t_1 - t_2$.

29.19

Example: Consider a R.P.

29.20

$$X(t) = \cos(\omega_0 t + \Theta)$$

← radian freq.

where Θ is a R.V. uniformly distributed on $[0, 2\pi]$:

$$f_{\Theta}(\theta) = \begin{cases} \frac{1}{2\pi} & 0 \leq \theta < 2\pi \\ 0 & \text{elsewhere} \end{cases}, \omega_0 = \text{constant}$$

(radian frequency)
not outcome

Is $X(t)$ W.S.S? Let's check the two defining conditions

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(i) $E[X(t)] = E[\cos \omega_0 t + \Theta]$

29.21

$$\begin{aligned} &= E[\cos(\omega_0 t) \cos(\Theta) - \sin(\omega_0 t) \sin(\Theta)] \\ &= \int_{-\infty}^{\infty} (\cos \omega_0 t \cdot \cos(\theta) - \sin \omega_0 t \cdot \sin(\theta)) f_{\Theta}(\theta) d\theta \\ &= \frac{\cos \omega_0 t}{2\pi} \int_0^{2\pi} \cos \theta d\theta - \frac{\sin \omega_0 t}{2\pi} \int_0^{2\pi} \sin \theta d\theta \\ &= 0 \therefore E[X(t)] = 0 = \text{constant} \quad \checkmark \end{aligned}$$

n.b. Even easier

$$E[X(t)] = E[\cos(\omega_0 t + \Theta)] = \frac{1}{2\pi} \int_0^{2\pi} \cos(\omega_0 t + \theta) d\theta$$

$= 0$

integral over one period is 0.

$$\cos A \cdot \cos B = \frac{1}{2} [\cos(A+B) + \cos(A-B)] \quad 29.22$$

$$E[X(t_1)X(t_2)]$$

$$= E[\cos(\omega_0 t_1 + \Theta) \cdot \cos(\omega_0 t_2 + \Theta)]$$

$$= E\left[\frac{1}{2} (\cos(\omega_0(t_1+t_2) + 2\Theta) + \cos(\omega_0(t_1-t_2)))\right]$$

$$= \frac{1}{2} E[\cos(\omega_0(t_1+t_2) + 2\Theta) + \cos(\omega_0(t_1-t_2))]$$

$$= \frac{1}{2} \cos \omega_0(t_1 - t_2) \quad \square$$

$$\therefore (i) \quad E[X(t)] = 0 = \text{constant}$$

$$(ii) \quad E[X(t_1)X(t_2)] = \frac{1}{2} \cos \omega_0(t_1 - t_2)$$

a function of t_1 and t_2 through the difference $t_1 - t_2$

$\therefore X(t)$ is wide sense stationary.