ECE678 Radar Engineering Fall 2024

## Homework Assignment #4

Due Monday, October 21, 2024

Reading Assignment: Read the Bayesian Detection section in Chapter 5 and Chapter 6 on Matched Filters of the course notes.

- 1. Consider the following detection problem defined in the Bayesian context:
  - (a) Call  $f(\underline{\theta}, \underline{x})$  the joint probability mass function-probability density function of  $\underline{\theta}$  and  $\underline{x}$ :

$$f(\underline{\theta}, \underline{x}) = \begin{cases} p_0 f_{\underline{\theta}_0}(\underline{x}), & \underline{\theta} = \underline{\theta}_0; \\ p_1 f_{\underline{\theta}_1}(\underline{x}), & \underline{\theta} = \underline{\theta}_1. \end{cases}$$

Find the conditional probability mass function of  $\underline{\theta}$  given  $\underline{X}$ .

- (b) One criterion for testing  $H_0$  versus  $H_1$  would be to evaluate the posterior conditioal pmf (part (a)) at  $\underline{\theta}$  for the measurement  $\underline{X}$ —call the result the *posterior likelihood*— and select  $H_1$  when the posterior likelihood of  $H_1$  exceeds the posterior likelihood of  $H_0$ . Show that the resulting test is a likelihood ratio test, and find the threshold to which the likelihood ratio L(X) must be compared.
- 2. (Binary Optical Communication): A laser transmits a binary digit ("0" or "1") by transmitting  $N_T$  photons in the time interval [0, T], where the number of photons transmitted is a Poisson random variable with pmf

$$p_i(n) = P(\{N_T = n\}) = \frac{(\lambda_i T)^n e^{-\lambda_i T}}{n!}, \quad n = 0, 1, 2, \dots, \quad i = 0, 1.$$

Here the rate parameter  $\lambda_i$  is  $\lambda_0$  under  $H_0$  and  $\lambda_1$  under  $H_1$ , where  $\lambda_1 > \lambda_0 \ge 0$ . Now assume that each transmitted photon has a probability p of being detected. Furthurmore, assume that the digits "0" and "1" have prior probabilities  $p_0$  and  $p_1$ , respectively. You are to decide whether a "0" or "1" was sent based on the observed number of detected photons  $M_T$  in the interval [0, T].

- (a) Find the probability mass function of  $M_T$ .
- (b) Find the decision rule that minimizes the probability of error, and express it as a function of  $\lambda_0$ ,  $\lambda_1$ , p,  $p_0$ ,  $p_1$  and T.
- (c) Write an expression for the resulting probability of error.
- 3. Assume that  $H_0$  is the hypothesis that no target is present and  $H_1$  is the hypothesis that a target is present. The prior probability of  $H_1$  is  $p_1$ . Assume that the loss associated with a type I error is  $L_{01}$  and with a type II error is  $L_{10}$ ; also assume that  $L_{00} = L_{11} = 0$ . We observe a scalar random variable X, which under  $H_0$  has pdf

$$f_0(x) = \frac{1}{\sqrt{2\pi\sigma}} \exp\left\{\frac{-x^2}{2\sigma^2}\right\},$$

and under  $H_1$  has pdf

$$f_1(x) = \frac{1}{\sqrt{2\pi\sigma}} \exp\left\{\frac{-(x-A)^2}{2\sigma^2}\right\},\,$$

where A is a positive constant.

- (a) Find a threshold test on X yielding the Bayes decision rule, and specify the threshold  $x_0$  to which X must be compared.
- (b) Compute the value for the threshold  $x_0$  as a function of  $p_1$  when A = 1,  $\sigma = 1$ ,  $L_{01} = 1$ , and  $L_{10} = 2$ .
- (c) Compute  $\alpha$ , the probability of type I error, and  $1 \beta$ , the probability of type II error, as a function of  $p_1$  for the numerical values given in part (b). Plot these for  $0 < p_1 < 0.9$ .
- (d) Compute the Bayes risk for the values given in part (b) and plot it for  $0.1 < p_1 < 0.9$ .
- (e) The minimax test is the test that minimizes the Bayes risk over all possible priors  $p_1$ . Consider the result of part (d), and find the minimanx test corresponding to the values given in part (b).
- 4. Consider the signal

$$s(t) = A \cdot 1_{[0,T]}(t)$$

in additive white Gaussian noise with power spectral density

$$S_{nn}(f) = N_o/2,$$

where A is a positive constant and T is the duration of the pulse.

- (a) Find the impulse response of the matched filter whose output is sampled at time T.
- (b) Find the peak SNR at the output of the matched filter in this case.
- 5. Consider the signal

$$s(t) = Ae^{i\pi\alpha t^2} \cdot \mathbf{1}_{[0,T]}(t)$$

in additive white Gaussian noise with power spectral density

$$S_{nn}(f) = N_o/2,$$

where A is a positive constant, T is he duration of the pulse, and  $\alpha > 0$  is the "chirp rate" of this linear FM pulse.

- (a) Find the impulse response of the matched filter whose output is sampled at time T.
- (b) Find the peak SNR at the output of the matched filter in this case.