Loop Parallelization Techniques and dependence analysis

- Data-Dependence Analysis
- Dependence-Removing Techniques
- Parallelizing Transformations
- Performance-enchancing Techniques

When can we run code in parallel?

 Two regions of code can be run in parallel when no dependences exist across statements to be run in parallel

```
a = b + c

x = y + z

u = a + x
```

```
for (i = 0; i < n; i++) {
    c[i] = a[i] * b[i] + c[i]
}
```

Some motivating examples

do i = 1, n

$$a(i) = b(i)$$
 S_1
 $c(i) = a(i-1)$ S_2
end do

Is it legal to

- Run the i loop in parallel?
- Put S₂ first in the loop?

Is it legal to

Fuse the two i loops?

Need to determine if, and in what order, two references access the same memory location

Then can determine if the references might execute in a different order after some transformation.

Dependence, an example

```
do i = 1, n
a(i) = b(i) \quad \mathbf{S_1}
c(i) = a(i-1) \quad \mathbf{S_2}
end do
\mathbf{S_2}
Indicates dependences, i.e.
the statement at the head
of the arc is somehow
dependent on the
statement at the tail
```

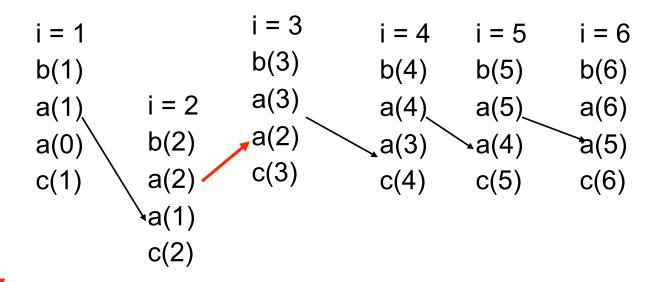
$$i = 1$$
 $i = 2$ $i = 3$ $i = 4$ $i = 5$ $i = 6$ $b(1)$ $b(2)$ $b(3)$ $b(4)$ $b(5)$ $b(6)$ $a(1)$ $a(2)$ $a(3)$ $a(4)$ $a(5)$ $a(6)$ $a(0)$ $a(1)$ $a(2)$ $a(3)$ $a(4)$ $a(5)$ $a(5)$ $a(6)$ $a(1)$ $a(2)$ $a(2)$ $a(3)$ $a(4)$ $a(5)$ $a(5)$ $a(6)$

Can this loop be run in parallel?

do i = 1, n

$$a(i) = b(i)$$
 S_1
 $c(i) = a(i-1)$ S_2
end do

Assume 1 iteration per processor, then if for some reason some iterations execute out of lock-step, bad things can happen In this case, read of a(2) in i=3 will get an invalid value!



time

Can we change the order of the statements?

Access order before statement reordering

```
b(1) a(1) a(0) c(1) || b(2) a(2) a(1) c(2) || b(3) \overline{a(3)} a(2) c(3) || b(4) a(4) a(3) c(4) i=1 i=2 i=3 i=4
```

Access order after statement reordering

$$a(0) c(1) b(1) a(1) \parallel a(1) c(2) b(2) a(2) \parallel a(2) c(3) b(3) a(3) \parallel a(3) c(4) b(4) a(4)$$
 $i=1$
 $i=2$
 $i=3$
 $i=4$

Can we fuse the loop?

- 1. Is ok after fusing, because get a(i-1) from the value assigned in the previous iteration
- 2. No "output" dependence on a(i) or c(i), not overwritten
- 3. No input flow, or true dependence on a b(i), so value comes from outside of the loop nest

In original execution of the unfused loops:

- a(i-1) gets value assigned in a(i)
- Can't overwrite value assigned to a(i) or c(i)
- B(i) value comes from outside the loop

end do

Types of dependence

Flow or true dependence – data for a read comes from a previous write (write/read hazard in hardware terms

Anti-dependence – write to a location cannot occur before a previous read is finished

Output dependence – write a location must wait for a previous write to finish

Dependences always go from earlier in a program execution to later in the execution

Anti and output dependences can be eliminated by using more storage.

Eliminating anti-dependence

$$a(2) = ...$$

Anti-dependence – write to a location cannot occur before a previous read is finished

Let the program in be:

$$= ... a(2)$$

Create additional storage to eliminate the antidependence The new program is:

$$a(2) = ...$$
... = $a(2)$
 $aa(2) = ...$
= ... $aa(2)$

No more anti-dependence!

Similar to register renaming

Getting rid of output dependences

$$a(2) = ...$$

Output dependence – write to a location must wait for a previous write to finish

Let the program be:

$$a(2) = ...$$

... = $a(2)$
 $a(2) = ...$
... = $a(2)$

Again, by creating new storage we can eliminate the output dependence.

The new program is:

Eliminating dependences

- In theory, can always get rid of anti- and output dependences
- Only flow dependences are inherent, i.e. must exist, thus the name "true" dependence.
- In practice, it can be complicated to figure out how to create the new storage
- Storage is not free cost of creating new variables may be greater than the benefit of eliminating the dependence.

An example of when it is messy to create new storage

```
do i = 1, n A(3i) writes locations 2, 5, 8, 11, 14, 17, 20, 23
 a(3i-1) = ...
  a(2i) = ... A(2i) writes locations 2, 4, 6, 8, 10, 12, 14, 16, 18, 20, 22
  = ... a(i)
              A(i) reads from outside the of loop when i = 1, 3, 7, 9, 13,
end do
                 15, 19, 21
              A(i) reads from a(3i-1) when I = 5, 11, 17, 23
              A(i) reads from a(2i) when I = 2, 4, 6, 8, 10, 12, 14, 16, 18,
                 20, 22
```

Data Dependence Tests: Other Motivating Examples

Statement Reordering

can these two statements be swapped?

Loop Parallelization

Can the iterations of this loop be run concurrently?

DO
$$i=1,100,2$$

 $B(2*i) = ...$
 $... = B(2*i) + B(3*i)$
ENDDO

An array data dependence exists between two data references iff:

- both references access the same storage location
- at least one of them is a write access

Dependence sources and sinks

- The sink of a dependence is the statement at the head of the dependence arrow
- The source is the statement at the tail of the dependence arrow
- Dependences always go forward in time in a serial execution

```
for (i=1; i < nl i++) {
  a[i] = ...
   ... = a[i-1]
a[1] =
     = a[0]
```

Data Dependence Tests: Concepts

Terms for data dependences between statements of loop iterations.

- Distance (vector): indicates how many iterations apart the source and sink of a dependence are.
- Direction (vector): is basically the sign of the distance. There are different notations: (<,=,>) or (+1,0,-1) meaning dependence (from earlier to later, within the same, from later to earlier) iteration.
- Loop-carried (or cross-iteration) dependence and non-loop-carried (or loop-independent) dependence: indicates whether or not a dependence exists within one iteration or across iterations.
 - For detecting parallel loops, only cross-iteration dependences matter.
 - equal dependences are relevant for optimizations such as statement reordering and loop distribution.
- Iteration space graphs: the un-abstracted form of a dependence graph with one node per statement instance.

Data Dependence Tests: Iteration space graphs

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 Iteration space graphs: the un-abstracted form of a dependence graph with one node per statement instance.

$$i_2 = 5 \quad \bigcirc \quad \bigcirc \quad \bigcirc \quad \bigcirc$$

$$do i_1 = 1, n$$

$$do i_2 = 1, n$$

$$a(i_1, i_2) = a(i_1 - 2, i_2 + 3)$$

$$end do$$

$$end do$$

$$end do$$

$$i_2 = 3 \quad \bigcirc \quad \bigcirc \quad \bigcirc$$

$$This is an$$

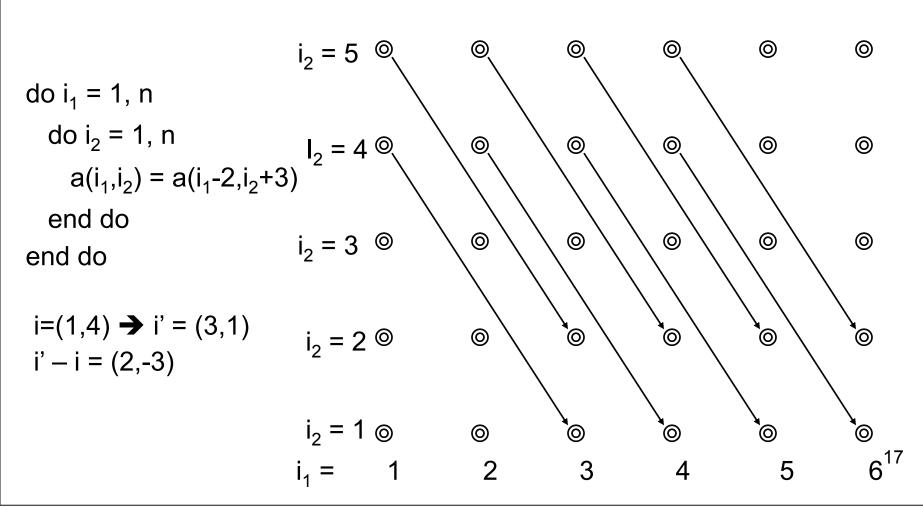
$$iteration \Rightarrow space graph$$

$$(or diagram)$$

$$i_2 = 2 \quad \bigcirc \quad \bigcirc$$

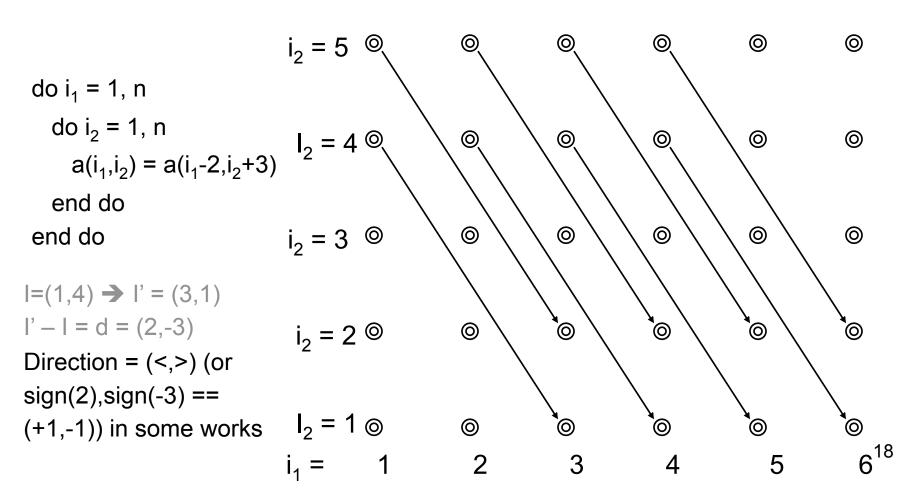
Data Dependence Tests: Distance Vectors

Distance (vector): indicates how many iterations apart are the source and sink of dependence.



Data Dependence Tests: Direction Vectors

Direction (vector): is basically the sign of the distance. There are different notations: (<,=,>) or (1,0,-1) meaning dependence (from earlier to later, within the same, from later to earlier) iteration.



Data Dependence Tests: Loop Carried

 Loop-carried (or cross-iteration) dependence and non-loop-carried (or loop-independent) dependence: indicates whether or not a dependence exists within one iteration or across iterations.

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dependences

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 Loop-carried (or cross-iteration) dependence and non-loop-carried (or loop-independent) dependence: indicates whether or not a dependence exists within one iteration or across iterations.

```
do i_1 = 1, n
                                           i_2 = 5
    dopar i_2 = 1, n
                                                      O¬
                                                                    0
                                                      O¬
                                                                    <del>_</del>
               = a(i_1, i_2-1)
                                          i<sub>2</sub> = 2
                                                      ⊚√
                                                                    <del>_</del>
                                                                                  O-
    end do
                                                      0
                                                                    0
                                                                                  0
                                           i_2 = 1
    dopar i_2 = 1, n
                                           l'<sub>2</sub> = 5
                                                      0
                                                                                  0
                                                                    0
       a(i_1,i_2) =
                                           l'<sub>2</sub> = 4
                                                      0
                                           l'<sub>2</sub> = 3
     end
                                          l'<sub>2</sub> = 2
  end do
This is not legal – turns
                                          l'_{2} = 1
     true into anti
                                                                                                                5
     dependence
```

A quick aside

Can be always be normalized to the loop →

This makes discussing the data-dependence problem easier since we only worry about loops from 1, n, 1

```
More precisely, do i = lower, upper, stride { a(i)} becomes do i' = 0, (upper – lower + stride)/stride – 1, 1 {a(i'*stride + lower)}
```

Data Dependence Tests: Formulation of the Data-dependence problem

```
DO i=1,n

a(4*i) = ...

... = a(2*i+1)

ENDDO
```

the question to answer: can 4*i ever be equal to 2*i+1 within i ∈[1,n]? If so, what is the relation of the i's when they are equal?

In general, given:

- two subscript functions f(I) and g(I) and
- upper and lower loop bounds

```
Question to answer: Does f(I) = g(I') have an integer solution such that lower \le I, I' \le upper?
```

Diophantine equations

- An equation whose coefficients and solutions are all integers is a Diophantine equation
- Determining if a Diophantine equation has a solution requires a slight detour into elementary number theory
- Let $f(i) = a_1^*i + c_1$ and $g(i') = b_1^*i' + c_2$, then

$$f(i) = g(i') \Rightarrow a_1^*i - b_1^*i' = c_2 - c_1$$

❖ fits general form of Diophantine equation of $a_1*i_1 + a_2*i_2 = c$

Does f(i) = g(i') have a solution?

The Diophantine equation

$$a_1^*i_2 + a_2^*i_2 = c$$

has no solution if $gcd(a_1,a_2)$ does not evenly divide c

```
Examples: 15*i +6*j -9*k = 12 has a solution gcd=3 2*i + 7*j = 3 has a solution gcd=1 9*i + 3*j + 6*k = 5 has no solution gcd=3
```

```
Euclid Algorithm: find gcd(a,b)

Repeat
a \leftarrow a \mod b

swap a,b

Until b=0

For more than two numbers: gcd(a,b,c) = (gcd(a,gcd(b,c)))
```

Finding GCDs

```
Euclid Algorithm: find gcd(a,b)

Repeat
a \leftarrow a \mod b

swap a,b

Until b=0

The resulting a is the gcd

for more than two numbers: gcd(a,b,c) = (gcd(a,gcd(b,c)))
```

```
a = 16, b = 6
```

Determining if a Diophantine equation has a solution

Let $g = gcd(a_1,a_2)$, then can rewrite the equation as:

$$g^*a'_1^*i_1 + g^*a'_2^*i_2 = c \rightarrow g^*(a'_1^*i_1 + a'_2^*i_2) = c$$

Because a'₁ and a'₂ are relatively prime, all integers can be expressed as a *linear combination* of a'₁ and a'₂.

- a'₁*i₁+a'₂*i₂ is just such a linear combination and therefore a'₁*i₁-a'₂*i₂ generates all integers, (assuming a'₁,a'₂ can range over the integers.)
- If remainder(c/g) = 0, c is a solution since c = g*c', and $g*(a'_1*i_1-a'_2*i_2)$ generates all multiples of g.
- If remainder(c/g) != 0, c cannot be a solution, since all values generated by g*(a'₁*i₁-a'₂*i₂) are (trivially) divisible by g, and cannot equal any c that is not divisible by g.

More information on gcd's and dependence analysis

- General books on number theory for info on Diophantine equations
- Books by Utpal Banerjee (Kluwer Academic Publishers), (Illinois, now Intel) who developed the GCD test in late 70's, Mike Wolfe, (Illinois, now Portland Group) "High Performance Compilers for Parallel Computing
- Randy Allen's thesis, Rice University
- Work by Eigenman & Blume Purdue (range test)
- Work by Pugh (Omega test) Maryland
- Work by Hoeflinger, etc. Illinois (LMAD)

Other DD Tests

- The GCD test is simple but by itself not very useful
 - Most subscript coefficients are 1, gcd(1,i) = 1
- Other tests
 - Banerjee test: accurate state-of-the-art test, takes direction and loop bounds into account
 - Omega test: "precise" test, most accurate for linear subscripts (See Bill Pugh publications for details). Worst case complexity is bad.
 - Range test: handles non-linear and symbolic subscripts (Blume and Eigenmann)
 - many variants of these tests
- Compilers tend to perform simple to complex tests in an attempt to disprove dependence

What do dependence tests do?

- Some tests, and Banerjee's in some situations (affine subscripts, rectangular loops) are precise
 - Definitively proves existence or lack of a dependence
- Most of the time tests are conservative
 - Always indicate a dependence if one may exist
 - May indicate a dependence if it does not exist
- In the case of "may" dependence, run-time test or speculation can prove or disprove the existence of a dependence
- Short answer: tests disprove dependences for some dependences

Banerjee's Inequalities

If $a^*i_1 - b^*i_1' = c$ has a solution, does it have a solution within the loop bounds, and for a given direction vector?

By the mean value theorem, c can be a solution to the equation
$$f(i) = c$$
, $i \in [lb, ub]$ iff

do
$$i = 1, 100$$

$$x(i) =$$

$$= x(i-1)$$

end do

Note: there is a (<) dependence.

Let's test for (=) and (<) dependence.

•
$$f(lb) \leq c$$

•
$$f(ub) >= c$$

(assumes *f*(*i*) is monotonically increasing over the range *[lb,ub]*)

The idea behind *Banerjee's Inequalities* is to find the maximum and minimum values the dependence equation can take on for a given direction vector, and see if these bound *c*. *This is done in the real domain since integer solution requires integer programming (in NP)*

Banerjee test

If $a^*i_1 - b^*i_1' = c$ has a solution, does it have a solution within the loop bounds for a given direction vector (<) or (=) in this case)?

For our problem, does $i_1 - i'_1 = -1$ have a solution?

- For $i_1 = i'_1$, then it does not (no (=) dependence).
- For $i_1 < i'_1$, then it does ((<) dependence).

Example of where the direction vector makes a difference

```
do i = 1, 100
x(i) = 
= x(i-1)
end do
Note: there is a (<)
dependence.
Let's test for (=) and
(<) dependence.
```

Dependence equation is i-i' = -1

If i = i' (i.e. "=" direction vector), then i-i' = 0, \forall i, i'

If i < i', then $i-i' \neq 0$, and when i=i'-1, the equation has a solution.

Cannot parallelize the loop, but can reorder x(i) and x(i-1) within the loop.

Program Transformations

 Applying data dependence tests to untransformed loops would determine that most loops are not parallel.

Reason #1: there are many anti and output

dependences

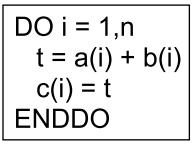
anti dependence (cross-iter.) DO i=1,n t = a(i)+b(I) c(i) = t c(i) =

Dependence Classification:

- flow dependence: read-write dependence
- anti dependence:
 write-read dependence
- output dependence:
 write-write dependence

Solution: scalar and array privatization

Scalar Expansion/Privatization



Private creates one copy per parallel loop iteration.

privatization

expansion

```
PARALLEL DO i = 1,n

t1(i) = a(i) + b(i)

c(i) = t1(i)

ENDDO
```

Analysis and Transformation for Scalar Expansion/Privatization

Loop Analysis:

- find variables that are used in the loop body but dead on entry. i.e., the variables are written (on all paths) through the loop before being used.
- determine if the variables are live out of the loop (make sure the variable is defined in the last loop iteration).

Transformation (variable *t*)

- Privatization:
 - put t on private list. Mark as last-value if necessary.
- Expansion:
 - declare an array t0(n), with n=#loop_iterations.
 - replace all occurrences of t in the loop body with tO(i), where i is the loop variable.
 - live-out variables: create the assignment t=tO(n) after the loop.

Parallelization of Reduction Operations

```
DO i = 1,n
sum = sum + a(i)
ENDDO
```

```
PARALLEL DO i = 1,n
Private s = 0
s = s + a(i)
POSTAMBLE
Lock
sum = sum + s
Unlock
ENDDO
```

```
PARALLEL DO i = 1,n
ATOMIC:
sum = sum + a(i)
ENDDO
```

```
DIMENSION s(#processors)

DO j = 1,#processors

s(j) = 0

ENDDO

PARALLEL DO i = 1,n/#processors

s(myproc) = s(myproc) + a(i)

ENDDO

DO j = 1,#processors

sum = sum + s(j)

ENDDO
```

Analysis and Transformation for (Sum) Reduction Operations

Loop Analysis:

- find reduction statements
 of the form s = s + expr
 where expr does not use s.
- discard s as a reduction variable if it is used in nonreduction statements.

Transformation:

(as shown on previous slide)

- create private or expanded variable and replace all occurrences of reduction variable in loop body.
- update original variable
 with sum over all partial
 sums, using a critical
 section in a loop postamble
 or a summation after the
 loop, respectively.

Induction Variable Substitution

```
ind = ind0
DO j = 1,n
    a(ind) = b(j)
    ind = ind+k
ENDDO
```

ind = ind0

PARALLEL DO j = 1,n

a(ind0+k*(j-1)) = b(j)

ENDDO

```
Example: string concat

j = eosA

do i = 1, b.length

a(j) = b(i)

j = j + 1;

end
```

Gives k*j – k + indo

This is of the form

a*j + c, which is good

for dependence analysis. j is the

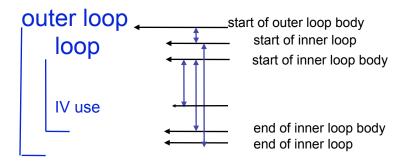
loop canonical induction

variable.

Induction Variable Analysis and Transformation

- Loop Analyis:
 - find induction
 statements of the form
 s = s + expr where
 expr is a loop-invariant
 term or another
 induction variable.
 - discard variables that are modified in noninduction statements.

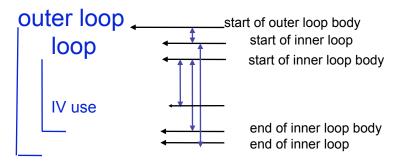
- Transformation:
 - find the following increments



- for each use of IV:
 - compute the increment inc with respect to the start of the outermost loop in which it is an induction sequence
 - Replace IV by inc+ind0

Induction Variable Analysis and Transformation

- Transformation:
 - find the following increments



- for each use of IV:
 - compute the increment inc with respect to the start of the outermost loop in which it is an induction sequence in
 - Replace IV by inc+ind0.

```
ind = ind0
PARALLEL DO j = 1,n
   a(ind0+k*(j-1)) = b(j)
ENDDO
```

Thus in the above

- ind0 is obvious;
- inc is k*(j-1)
 - inc is an induction sequence within the loop DO j
 - The inner loop body is empty

Loop Fusion and Distribution

DO j = 1,n

$$a(j) = b(j)$$

ENDDO

fusion

$$DO j = 1,n$$

$$a(j) = b(j)$$

$$c(j) = a(j)$$
ENDDO

distribution

ENDDO

- necessary form for vectorization
- can provide synchronization necessary for "forward" dependences
- can create perfectly nested loops

- less parallel loop startup overhead
- can increase *affinity* (better locality of reference)

Both transformations change the statement execution order. Data dependences need to be considered!

Loop Fusion and Distribution

DO j = 1,n

$$a(j) = b(j)$$

ENDDO

fusion

 $DO j = 1,n$
 $a(j) = b(j)$
 $c(k) = a(k)$
ENDDO

distribution

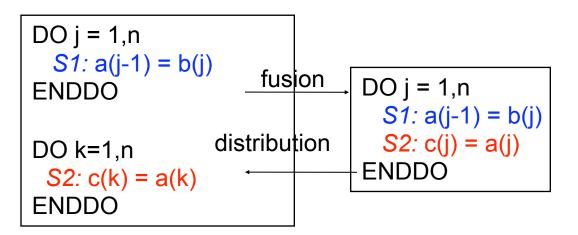
ENDDO

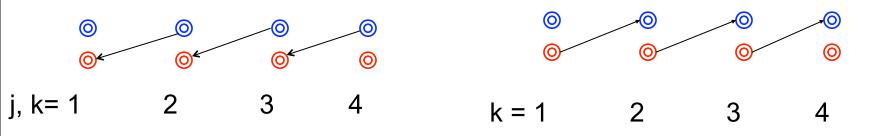
ENDDO

Dependence analysis needed:

- Determine uses/def and def/use chains across unfused loops
- Every def ⇒use link should have a flow dependence in the fused loop
 - Every use ⇒def link should have an anti-dependence in the fused loop
 - No dependence not associated with a use ⇒def or def ⇒use should be present in the fused loop

Loop Fusion and Distribution

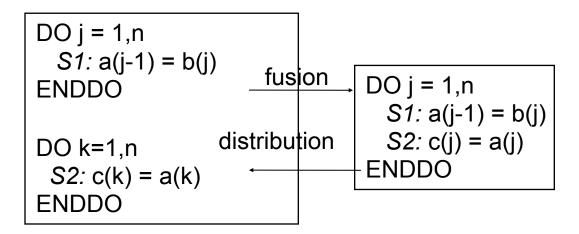


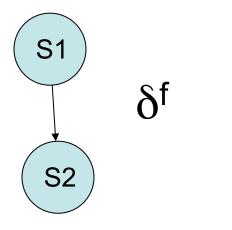


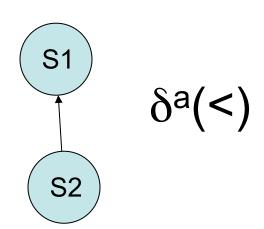
Flow dependence from S1 to S2

Anti-dependence from S2 to S2

Dependence graphs







Loop Interchange

Loop Interchange

$$\begin{array}{c|c} \mathsf{PDO} \ \mathsf{i} = \mathsf{1}, \mathsf{n} \\ \mathsf{DO} \ \mathsf{j} = \mathsf{1}, \mathsf{m} \\ \mathsf{a}(\mathsf{i}, \mathsf{j}) = \mathsf{b}(\mathsf{i}, \mathsf{j}) \\ \mathsf{ENDDO} \\ \mathsf{ENDDO} \\ \mathsf{ENDDO} \\ \end{array} \begin{array}{c} \mathsf{PDO} \ \mathsf{j} = \mathsf{1}, \mathsf{m} \\ \mathsf{DO} \ \mathsf{i} = \mathsf{1}, \mathsf{n} \\ \mathsf{a}(\mathsf{i}, \mathsf{j}) = \mathsf{b}(\mathsf{i}, \mathsf{j}) \\ \mathsf{ENDDO} \\ \mathsf{ENDDO} \\ \mathsf{ENDDO} \\ \end{array}$$

- loop interchanging alters the data reference order
 - > significantly affects locality-of reference
 - data dependences determine the legality of the transformation: dependence structure should stay the same
- loop interchanging may also impact the granularity of the parallel computation (inner loop may become parallel instead of outer)

Loop interchange legality

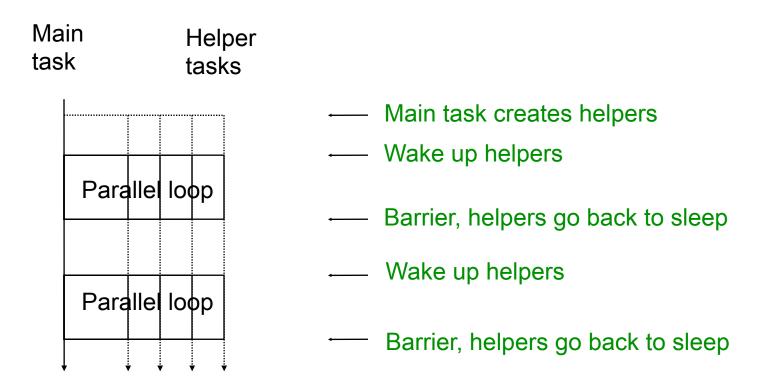
```
(=,=): after interchange still loop indepent dependences (=,<): after interchange, is (<,=), still carried on the j loop (<,=): after interchange is (=,<), still carried on the i loop (<.<): after interchange still positive in both directions
```

(>,*), (=,>): not possible – dependences must move forward in Iteration space

(<,>): after interchange is (>,<), except cannot have a (>,<) dependence. The source and sink of the dependence change, changing the dependence. Not legal.

Parallel ExecutionScheme

Most widely used: Microtasking scheme



Program Translation for

```
Subroutine x
...
C$OMP PARALLEL DO
DO j=1,n
a(j)=b(j)
ENDDO
...
END
```

```
Subroutine x
...
call scheduler(1,n,a,b,loopsub)
...
END
```

```
Subroutine loopsub(lb,ub,a,b)
integer lb,ub
DO jj=lb,ub
a(jj)=b(jj)
ENDDO
END
```