# More Dataflow Analysis

Saturday, December 6, 14

#### Steps to building analysis

- Step I: Choose lattice
- Step 2: Choose direction of dataflow (forward or backward)
- Step 3: Create transfer function
- Step 4: Choose confluence operator (i.e., what to do at merges)
  - Either join or meet in the lattice
- Let's walk through these steps for a new analysis

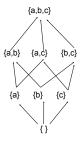
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# Liveness analysis

- Which variables are live at a particular program point?
- Used all over the place in compilers
  - Register allocation
  - Loop optimizations

Choose lattice

- What do we want to know?
  - At each program point, want to maintain the set of variables that are live
  - Lattice elements: sets of variables
  - Natural choice for lattice: powerset of variables!



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#### Choose dataflow direction

- A variable is *live* if it is used later in the program without being redefined
  - At a given program point, we want to know information about what happens later in the program
  - This means that liveness is a backwards analysis
    - Recall that we did liveness backwards when we looked at single basic blocks

#### Create x-fer functions

• What do we do for a statement like:

x = y + z

- If x was live "before" (i.e., live after the statement), it isn't now (i.e., is not live before the statement)
- If y and z were not live "before," they are now
- What about:

x = x

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#### Create x-fer functions

- Let's generalize
- For any statement s, we can look at which live variables are killed, and which new variables are made live (generated)
- Which variables are killed in s?
  - The variables that are defined in s: DEF(s)
- Which variables are made live in s?
  - The variables that are used in s: USE(s)
- If the set of variables that are live after s is X, what is the set of variables live before s?

$$T_s(X) = \mathbf{use}(s) \cup (X - \mathbf{def}(s))$$

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# Dealing with aliases

- Aliases, as usual, cause problems
- Consider

```
int x, y, r, s
int *z, *w;
if (...) z = &y else z = &x
if (...) w = &r else w = &s
*z = *w; //which variable is defined? which is used?
```

- What should USE(\*z = \*w) and DEF(\*z = \*w) be?
  - Keep in mind: the goal is to get a list of variables that may be live at a program point
- For now, assume there is no aliasing

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# Dealing with function calls

• Similar problem as aliases:

```
int foo(int &x, int &y); //pass by reference!
void main() {
 int x, y, z;
 z = foo(x, y);
```

- Simple solution: functions can do anything redefine variables, use variables
  - So DEF(foo()) is { } and USE(foo()) is V
- Real solution: interprocedural analysis, which determines what variables are used and defined in foo

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# Choose confluence operator

y = x

y = w

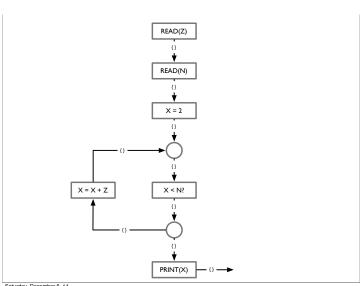
- What happens at a merge point?
  - The variables live in to a merge point are the variables that are live along either branch
  - Confluence operator: Set union (1) of all live sets of outgoing edges

$$T_{merge} = \bigcup_{X \in succ(merge)} X$$

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# How to initialize analysis?

- At the end of the program, we know no variables are live → value at exit point is { }
  - What about if we're analyzing a single function? Need to make conservative assumption about what may be live
- What about elsewhere in the program?
  - We should initialize other sets to { }



# An alternate approach

- Dataflow analyses like live-variable analysis are bit-vector analyses: are even more structured than regular dataflow analysis
  - Consistent lattice: powerset
  - Consistent transfer functions
- Many sources only talk about bitvector dataflow

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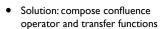
#### Bit-vector lattices

- Consider a single element, V, of the powerset(S) lattice
- Each item in S either appears in V or does not: can represent using a single bit
  - Can represent V as a bit vector
    - $\{a, b, c\} = \langle I, I, I \rangle$
    - {} = <0,0,0>
  - {b, c} = <0, 1, 1>
- □ and □ (which are just ∪ and ∩) are simply bitwise ∨ and ∧, respectively

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# Eliminating merge nodes

- Many dataflow presentations do not use explicit merge nodes in CFG
- How do we handle this?
- Problem: now a node may be a statement and a merge point







 $T(s) = \mathbf{use}(s) \cup ((\bigcup_{X \in succ(s)} X) - \mathbf{def}(s))$ 

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# Simplifying matters

$$T(s) = \mathbf{use}(s) \cup ((\bigcup_{X \in succ(s)} X) - \mathbf{def}(s))$$

- Lets split this up into two different sets
  - OUT(s): the set of variables that are live immediately after a statement is executed
  - IN(s): the set of variables that are live immediately before a statement is executed

$$IN(s) = \mathbf{use}(s) \cup (OUT(s) - \mathbf{def}(s))$$
  
 $OUT(s) = \bigcup_{t \in succ(s)} IN(t)$ 

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# Generalizing

- USE(s) are the variables that become live due to a statement—they are generated by this statement
- DEF(s) are the variables that stop being live due to a statement—they are killed by this statement

$$\begin{array}{lcl} IN(s) & = & \mathbf{gen}(s) \cup (OUT(s) - \mathbf{kill}(s)) \\ OUT(s) & = & \bigcup_{t \in succ(s)} IN(t) \end{array}$$

### Bit-vector analyses

- A bit-vector analysis is any analysis that
  - Operates over the powerset lattice, ordered by  $\subseteq$  and with  $\cup$  and  $\cap$  as its meet and join
  - Has transfer functions that can be written in the form:

$$\begin{array}{rcl} IN(s) & = & \mathbf{gen}(s) \cup (OUT(s) - \mathbf{kill}(s)) \\ OUT(s) & = & \bigcup_{t \in succ(s)} IN(t) \end{array}$$

- Are these transfer functions monotonic? (Hint: if f and g are monotonic, is f · g monotonic?)
- gen and kill are dependent on the statement, but not on IN or OUT
- $\bullet$  Things are a little different for forward analyses, and some analyses use n instead of  $\cup$

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### Reaching definitions

- What definitions of a variable reach a particular program point
  - A definition of variable x from statement s reaches a statement t if there is a path from s to t where x is not redefined
- Especially important if x is used in t
  - Used to build def-use chains and use-def chains, which are key building blocks of other analyses
    - Used to determine dependences: if x is defined in s and that definition reaches t then there is a flow dependence from s
  - We used this to determine if statements were loop invaraint
    - All definitions that reach an expression must originate from outside the loop, or themselves be invariant

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# Creating a reaching-def analysis

- Can we use a powerset lattice?
- At each program point, we want to know which definitions have reached a particular point
  - Can use powerset of set of definitions in the program
    - V is set of variables, S is set of program statements
    - Definition:  $d \in V \times S$ 
      - Use a tuple, <v, s>
  - How big is this set?
    - At most |V × S| definitions

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#### Forward or backward?

• What do you think?

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### Choose confluence operator

- Remember: we want to know if a definition may reach a program point
- What happens if we are at a merge point and a definition reaches from one branch but not the other?
  - We don't know which branch is taken!
  - We should union the two sets any of those definitions can reach
- $\bullet$  We want to avoid getting too many reaching definitions  $\rightarrow$  should start sets at  $\bot$

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# Transfer functions for RD

- Forward analysis, so need a slightly different formulation
  - Merged data flowing into a statement

$$IN(s) = \bigcup_{t \in pred(s)} OUT(t)$$
  
 $OUT(s) = \mathbf{gen}(s) \cup (IN(s) - \mathbf{kill}(s))$ 

- What are gen and kill?
  - gen(s): the set of definitions that may occur at s
    - e.g.,  $gen(s_1: x = e)$  is  $\langle x, s_1 \rangle$
  - kill(s): all previous definitions of variables that are definitely redefined by s
    - e.g., kill(s<sub>1</sub>: x = e) is <x, \*>

# Available expressions

- We've seen this one before
- What is the lattice? powerset of all expressions appearing in a procedure
- Forward or backward?
- Confluence operator?

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#### Transfer functions for meet

• What do the transfer functions look like if we are doing a meet?

$$IN(S) = \bigcap_{t \in pred(s)} OUT(t)$$
  
 $OUT(S) = \mathbf{gen}(s) \cup (IN(S) - \mathbf{kill}(s))$ 

- gen(s): expressions that must be computed in this statement
- kill(s): expressions that use variables that may be defined in this statement
  - Note difference between these sets and the sets for reaching definitions or liveness.
- Insight: gen and kill must never lead to incorrect results
- Must not decide an expression is available when it isn't, but OK to be safe and say it isn't
- Must not decide a definition doesn't reach, but OK to overestimate and say it does

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# Analysis initialization (II)

- The set at the entry of a program (for forward analyses) or exit of a program (for backward analyses) may be different
  - One way of looking at this: start statement and end statement have their own transfer functions
- General rule for bitvector analyses: no information at beginning of analysis, so first set is always { }

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# Very busy expressions

- Lattice?
- Direction?
- Confluence operator?
- Initialization?
- Transfer functions?
  - Gen? Kill?

### Analysis initialization

- Remember our formalization
  - If we start with everything initialized to  $\bot$ , we compute the least fixpoint
  - If we start with everything initialized to ⊤, we compute the greatest fixpoint
- Which do we want? It depends!
  - Reaching definitions: a definition that may reach this point
  - We want to have as few reaching definitions as possible → use least fixpoint
  - Available expressions: an expression that was definitely computed earlier
    - We want to have as many available expressions as possible → use greatest fixpoint
  - Rule of thumb: if confluence operator is  $\sqcup$ , start with  $\bot$ , otherwise start with  $\top$

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# Very busy expressions

- An expression is very busy if it is computed on every path that leads from a program point
  - Why does this matter?
  - Can calculate very busy expressions early without wasting computation (since the expression is used at least once on every outgoing path) – this can save space
  - Good candidates for loop invariant code motion

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