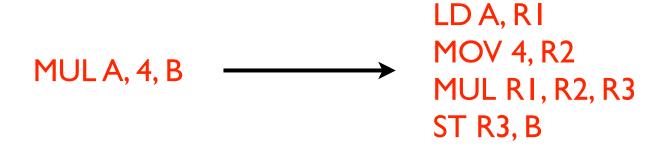
# Code generation and local optimization

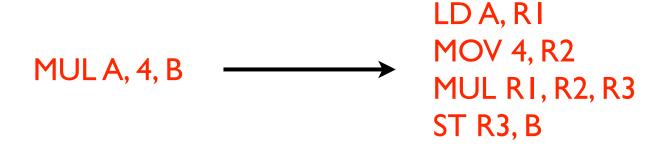
### Generating assembly

- How do we convert from three-address code to assembly?
  - Seems easy! But easy solutions may not be the best option
- What we will cover:
  - Peephole optimizations
  - Address mode selection
  - "Local" common subexpression elimination
  - "Local" register allocation
  - More complex code generation

#### Naïve approach

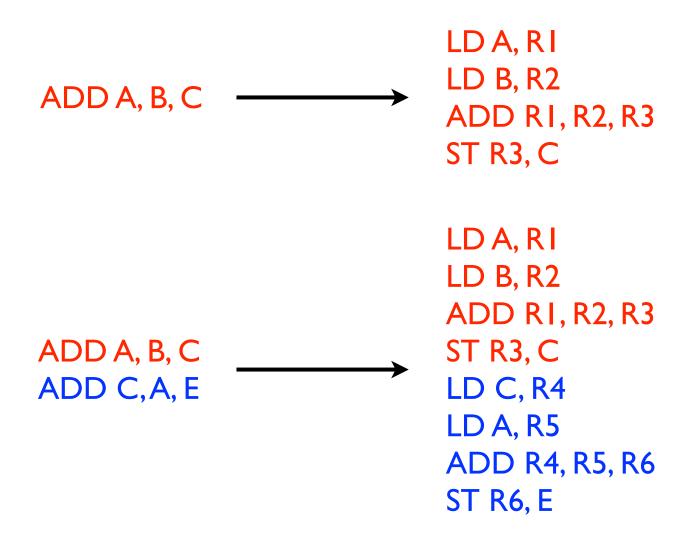
- "Macro-expansion"
  - Treat each 3AC instruction separately, generate code in isolation

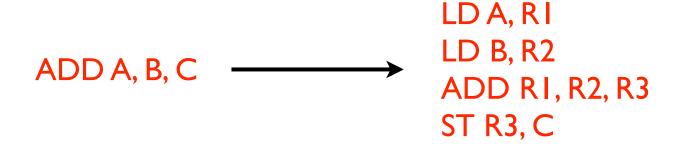




Too many instructions
Should use a different instruction type

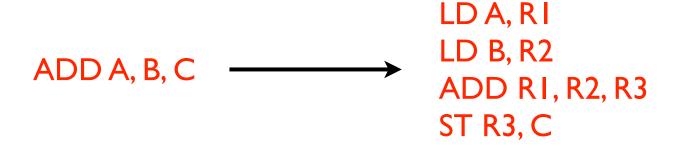
Too many instructions
Should use a different instruction type





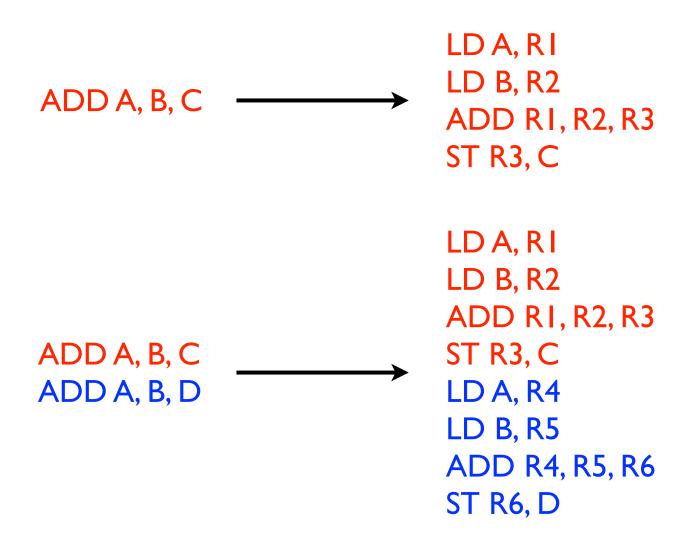
ADD A, B, C
ADD C, A, E

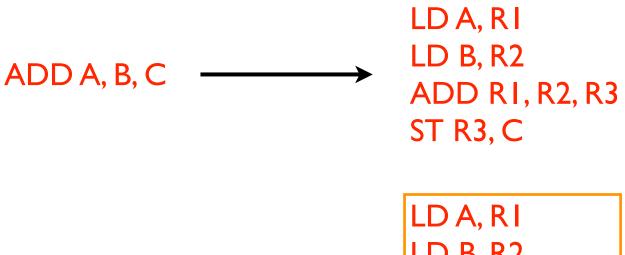
Redundant load of C Redundant load of A Uses a lot of registers LD A, RI LD B, R2 ADD RI, R2, R3 ST R3, C LD C, R4 LD A, R5 ADD R4, R5, R6 ST R6, E



ADD A, B, C ADD C, A, E

Redundant load of C Redundant load of A Uses a lot of registers LD A, RI LD B, R2 ADD RI, R2, R3 ST R3, C LD C, R4 LD A, R5 ADD R4, R5, R6 ST R6, E





ADD A, B, C
ADD A, B, D

Wasting instructions recomputing A + B

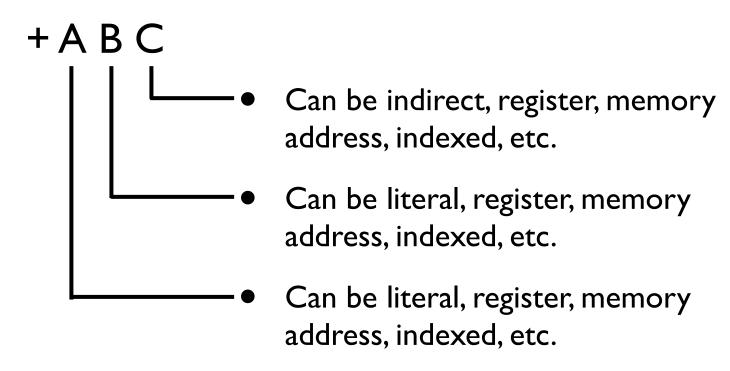
LD A, RI LD B, R2 ADD RI, R2, R3 ST R3, C LD A, R4 LD B, R5 ADD R4, R5, R6 ST R6, D

#### How do we address this?

- Several techniques to improve performance of generated code
  - Address mode selection to choose better instructions
  - Peephole optimizations to remove redundant instructions
  - Common subexpression elimination to remove redundant computation
  - Register allocation to reduce number of registers used

#### Address mode selection

 Even a simple instruction may have a large set of possible address modes and combinations



Dozens of potential combinations!

#### More choices for address mode

- Auto increment/decrement (especially common in embedded processors as in DSPs)
  - e.g., load from this address and increment it
  - Why is this useful?
- Three-address instructions
- Specialized registers (condition registers, floating point registers, etc.)
- "Free" addition in indexed mode
  - MOV (RI)offset R2
  - Why is this useful?

#### Peephole optimizations

- Simple optimizations that can be performed by pattern matching
  - Intuitively, look through a "peephole" at a small segment of code and replace it with something better
  - Example: if code generator sees ST R X; LD X R, eliminate load
- Can recognize sequences of instructions that can be performed by single instructions

```
LDI R1 R2; ADD R1 4 R1 replaced by
```

LDINC R1 R2 4 //load from address in R1 then inc by 4

#### Peephole optimizations

Constant folding

```
ADD lit1, lit2, Rx \longrightarrow MOV lit1 + lit2, Rx MOV lit1, Rx ADD li2, Rx, Ry \longrightarrow MOV lit1 + lit2, Ry
```

Strength reduction

```
MUL operand, 2, Rx \longrightarrow SHIFTL operand, 1, Rx DIV operand, 4, Rx \longrightarrow SHIFTR operand, 2, Rx
```

Null sequences

```
MUL operand, 1, Rx \longrightarrow MOV operand, Rx ADD operand, 0, Rx \longrightarrow MOV operand, Rx
```

#### Peephole optimizations

Combine operations

```
JEQ L1

JMP L2

L1: ...
```

Simplifying

```
SUB operand, \emptyset, Rx \longrightarrow NEG Rx
```

Special cases (taking advantage of ++/--)

```
ADD 1, Rx, Rx \longrightarrow INC Rx SUB Rx, 1, Rx \longrightarrow DEC Rx
```

Address mode operations

```
MOV A R1
ADD \emptyset(R1) R2 R3

ADD \emptysetA R2 R3
```

# Common subexpression elimination

 Goal: remove redundant computation, don't calculate the same expression multiple times

$$I:A = B + C * D$$

$$2: E = B + C * D$$

Keep the result of statement I in a temporary and reuse for statement 2

• Difficulty: how do we know when the same expression will produce the same result?

$$I:A = B + C * D$$

$$2: B = < new value >$$

$$3: E = B + C * D$$

B is "killed." Any expression using B is no longer "available," so we cannot reuse the result of statement I for statement 3

• This becomes harder with pointers (i.e., how do we know when B is killed?)

## Common subexpression elimination

- Two varieties of common subexpression elimination (CSE)
- Local: within a single basic block
  - Easier problem to solve (why?)
- Global: within a single procedure or across the whole program
  - Intra- vs. inter-procedural
  - More powerful, but harder (why?)
  - Will come back to these sorts of "global" optimizations later

#### CSE in practice

- Idea: keep track of which expressions are "available" during the execution of a basic block
  - Which expressions have we already computed?
  - Issue: determining when an expression is no longer available
    - This happens when one of its components is assigned to, or "killed."
- Idea: when we see an expression that is already available, rather than generating code, copy the temporary
  - Issue: determining when two expressions are the same

### Maintaining available expressions

- For each 3AC operation in a basic block
  - Create name for expression (based on lexical representation)
  - If name not in available expression set, generate code, add it to set
    - Track temporary that holds expression and any variables used to compute expression
  - If name in available expression set, generate move instruction
  - If operation assigns to a variable, kill all dependent expressions

#### Three address code

- + A B T1
- + T1 C T2
- + A B T3
- + T1 T2 C
- + T1 C T4
- + T3 T2 D

Generated code

Available expressions:

#### Three address code

```
+ A B T1
```

- + T1 C T2
- + A B T3
- + T1 T2 C
- + T1 C T4
- + T3 T2 D

Generated code

ADD A B R1

Available expressions: "A+B"

#### Three address code

```
+ A B T1
```

#### Generated code

Available expressions: "A+B" "T1+C"

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
```

+ T3 T2 D

#### Generated code

ADD A B R1 ADD R1 C R2 MOV R1 R3

Available expressions: "A+B" "T1+C"

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

#### Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
```

Available expressions: "A+B" "T1+C" "T1+T2"

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

#### Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
```

Available expressions: "A+B" "T1+T2" "T1+C"

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

#### Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
ADD R3 R2 R6; ST R6 D
```

Available expressions: "A+B" "T1+T2" "T1+C" "T3+T2"

#### **Downsides**

 What are some downsides to this approach? Consider the two highlighted operations

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

#### Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
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```

#### **Downsides**

 What are some downsides to this approach? Consider the two highlighted operations

#### Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

#### Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
ST R5 D
```

 This can be handled by an optimization called value numbering, which we will not cover now (although we may get to it later)

#### Aliasing

- One of the biggest problems in compiler analysis is to recognize aliases – different names for the same location in memory
- Aliases can occur for many reasons
  - Pointers referring to same location, arrays referencing the same element, function calls passing the same reference in two arguments, explicit storage overlapping (unions)
- Upshot: when talking about "live" and "killed" values in optimizations like CSE, we're talking about particular variable names
- In the presence of aliasing, we may not know which variables get killed when a location is written to

### Memory disambiguation

- Most compiler analyses rely on memory disambiguation
  - Otherwise, they need to be too conservative and are not useful
- Memory disambiguation is the problem of determining whether two references point to the same memory location
  - Points-to and alias analyses try to solve this
  - Will cover basic pointer analyses in a later lecture

#### Register allocation

- Simple code generation: use a register for each temporary, load from a variable on each read, store to a variable at each write
- Problems
  - Real machines have a limited number of registers one register per temporary may be too many
  - Loading from and storing to variables on each use may produce a lot of redundant loads and stores
- Goal: allocate temporaries and variables to registers to:
  - Use only as many registers as machine supports
  - Minimize loading and storing variables to memory (keep variables in registers when possible)
  - Minimize putting temporaries on stack

#### Global vs. local

- Same distinction as global vs. local CSE
  - Local register allocation is for a single basic block
  - Global register allocation is for an entire function (but not interprocedural – why?)

Will cover some local allocation strategies now, global allocation later

### Top-down register allocation

- For each basic block
  - Find the number of references of each variable
  - Assign registers to variables with the most references
- Details
  - Keep some registers free for operations on unassigned variables and spilling
  - Store dirty registers at the end of BB (i.e., registers which have variables assigned to them)
    - Do not need to do this for temporaries (why?)

#### Bottom-up register allocation

- Smarter approach:
  - Free registers once the data in them isn't used anymore
- Requires calculating liveness
- Easy to calculate within a BB:
  - Start at end of block, all variables marked dead
  - When a variable is used, mark as live, record use
  - When a variable is defined, record def, variable dead above this
  - Creates chains linking uses of variables to where they were defined
- We will discuss how to calculate this across BBs later

### Liveness example

• What is live in this code?

```
1: A = B + C

2: C = A + B

3: T1 = B + C

4: T2 = T1 + C

5: D = T2

6: E = A + B

7: B = E + D

8: A = C + D

9: T3 = A + B

10: F = T3
```

#### Liveness example

• What is live in this code?

```
1: {A, B}
1: A = B + C
2: C = A + B
                            2: {A, B, C}
3: T1 = B + C
                           3: {A, B, C, T1}
4: T2 = T1 + C
                           4: {A, B, C, T2}
5: D = T2
                            5: {A, B, C, D}
6: E = A + B
                            6: {C, D, E}
7: B = E + D
                            7: {B, C, D}
8: A = C + D
                            8: {A, B}
9: T3 = A + B
                            9: {T3}
10: F = T3
                            10: {}
```

#### Bottom-up register allocation

```
For each tuple op A B C in a BB, do

R<sub>x</sub> = ensure(A)

R<sub>y</sub> = ensure(B)

if A dead after this tuple, free(R<sub>x</sub>)

if B dead after this tuple, free(R<sub>y</sub>)

R<sub>z</sub> = allocate(C) //could use R<sub>x</sub> or R<sub>y</sub>

mark R<sub>z</sub> dirty

At end of BB, for each dirty register

generate code to store register into appropriate variable
```

We will present this as if A, B, C are variables in memory.
 Can be modified to assume that A, B and C are in virtual registers, instead

#### Bottom-up register allocation

```
ensure(opr)

if opr is already in register r

return r

else

r = allocate(opr)

generate load from opr into r

return r
```

```
free(r)

if r is marked dirty

generate store

mark r as free
```

```
allocate(opr)

if there is a free r

choose r

else

choose r with most distant use

free(r)

mark r associated with opr

return r
```

• Perform register allocation for this code:

```
1: A = B + C

2: C = A + B

3: T1 = B + C

4: T2 = T1 + C

5: D = T2

6: E = A + B

7: B = E + D

8: A = C + D

9: T3 = A + B

10: F = T3
```

```
A = B + C
              1: {A, B}
2:
   C = A + B \qquad 2:
                    \{A, B, C\}
                     {A, B, C, T1}
3:
   T1 = B + C 3:
                4: {A, B, C, T2}
4:
   T2 = T1 + C
   D = T2
5:
                 5:
                    \{A, B, C, D\}
6: E = A + B
                 6: {C, D, E}
                     {B, C, D}
   B = E + D
                 7:
7:
8:
   A = C + D
                8:
                    {A, B}
   T3 = A + B
                     {T3}
                 9:
10: F = T3
                 10: {}
```

Inst	R1	R2	R3
1			
2			
3			
4			
5			
6			
7			
8			
9			
10			

```
A = B + C
             1: {A, B}
2:
  C = A + B \qquad 2:
                   \{A, B, C\}
                   \{A, B, C, T1\}
3:
   T1 = B + C 3:
               4: {A, B, C, T2}
4:
   T2 = T1 + C
   D = T2
5:
                 5: {A, B, C, D}
6: E = A + B
                 6: {C, D, E}
                    {B, C, D}
  B = E + D
                7:
7:
8:
   A = C + D
               8:
                   {A, B}
   T3 = A + B
                    {T3}
              9:
10: F = T3
                 10: {}
```

Inst	R1	R2	R3
1	В		Α
2	В	С	Α
3	В	O	T1
4	В	С	T2
5	В	С	D
6	E		D
7	В		D
8	В		Α
9	Т3		
10	F		

### Aliasing, as usual, is a problem

What happens with this code?

```
//a and b are aliased

LD a R1

LD b R2

ADD R1 R2 R3

ST R3 c // c = a + b

R1 = 7 //a = 7

ADD R1 R2 R4

ST R4 d // d = a + b
```

### Dealing with aliasing

- Immediately before loading a variable x
  - For each variable aliased to x that is already in a register, save it to memory (i.e., perform a store)
  - This ensures that we load the right value
- Immediately before storing a variable x
  - For each register associated with a variable aliased to x, mark it as invalid
  - So next time we use the variable, we will reload it
- Conservative approach: assume all variables are aliased (in other words, reload from memory on each read, store to memory on each write)
  - Better alias analysis can improve this
  - At subroutine boundaries, still often use conservative analysis

#### Allocation considerations

- Use register coloring to perform global register allocation
  - Will see this next
- Find right order of optimizations and register allocation
  - Peephole optimizations can reduce register pressure, can make allocation better
  - CSE can actually increase register pressure
  - Different orders of optimization produce different results
- Register allocation still an open research area
  - For example, how to do allocation for JIT compilers