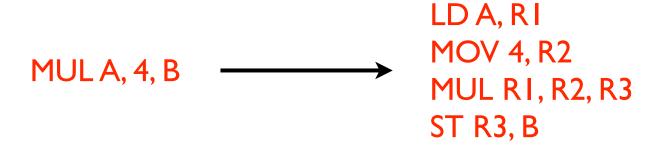
Code generation and local optimization

Generating assembly

- How do we convert from three-address code to assembly?
 - Seems easy! But easy solutions may not be the best option
- What we will cover:
 - Peephole optimizations
 - Address mode selection
 - "Local" common subexpression elimination
 - "Local" register allocation
 - More complex code generation

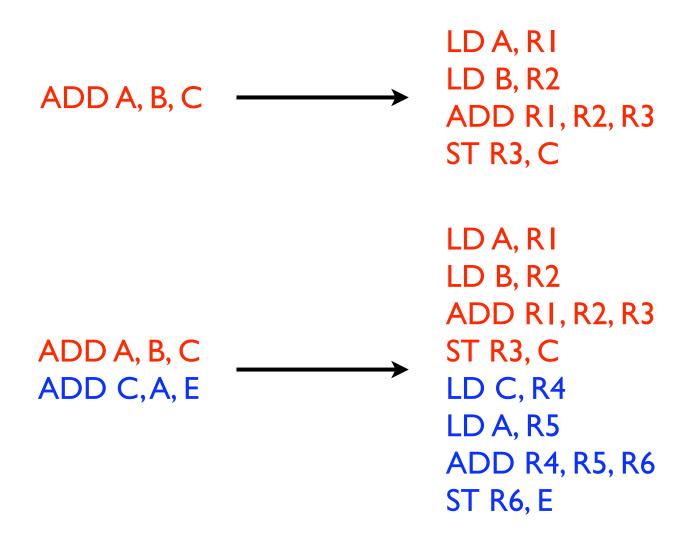
Naïve approach

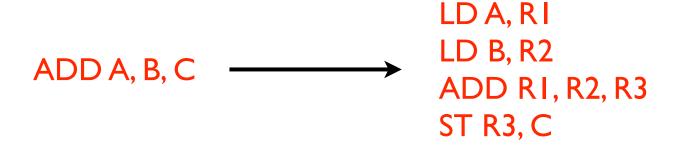
- "Macro-expansion"
 - Treat each 3AC instruction separately, generate code in isolation



Too many instructions
Should use a different instruction type

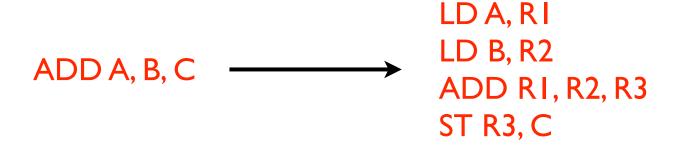
Too many instructions
Should use a different instruction type





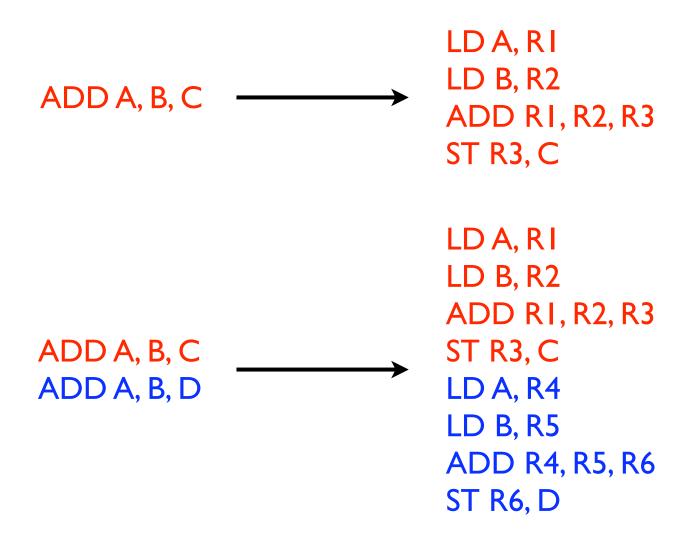
ADD A, B, C
ADD C, A, E

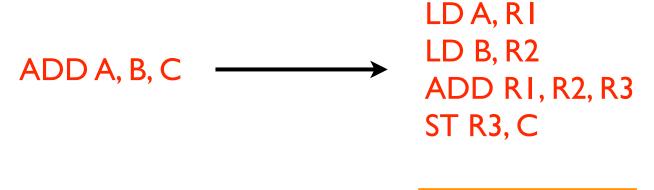
Redundant load of C Redundant load of A Uses a lot of registers LD A, RI LD B, R2 ADD RI, R2, R3 ST R3, C LD C, R4 LD A, R5 ADD R4, R5, R6 ST R6, E



ADD A, B, C ADD C, A, E

Redundant load of C Redundant load of A Uses a lot of registers LD A, R I LD B, R2 ADD R I, R2, R3 ST R3, C LD C, R4 LD A, R5 ADD R4, R5, R6 ST R6, E





ADD A, B, C
ADD A, B, D

Wasting instructions recomputing A + B

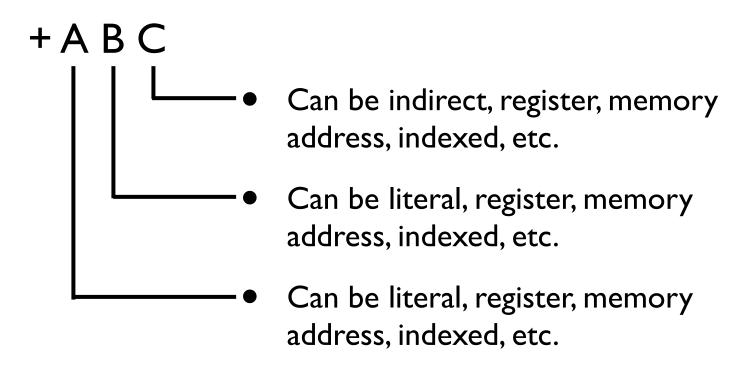
LD A, RI LD B, R2 ADD RI, R2, R3 ST R3, C LD A, R4 LD B, R5 ADD R4, R5, R6 ST R6, D

How do we address this?

- Several techniques to improve performance of generated code
 - Peephole optimizations to remove redundant instructions
 - Address mode selection to choose better instructions
 - Common subexpression elimination to remove redundant computation
 - Register allocation to reduce number of registers used

Address mode selection

 Even a simple instruction may have a large set of possible address modes and combinations



Dozens of potential combinations!

More choices for address mode

- Auto increment/decrement (especially common in embedded processors as in DSPs)
 - e.g., load from this address and increment it
 - Why is this useful?
- Three-address instructions
- Specialized registers (condition registers, floating point registers, etc.)
- "Free" addition in indexed mode
 - MOV (RI)offset R2
 - Why is this useful?

Peephole optimizations

- Simple optimizations that can be performed by pattern matching
 - Intuitively, look through a "peephole" at a small segment of code and replace it with something better
 - Example: if code generator sees ST R X; LD X R, eliminate load
- Can recognize sequences of instructions that can be performed by single instructions

```
LDI R1 R2; ADD R1 4 R1 replaced by
```

LDINC R1 R2 4 //load from address in R1 then inc by 4

Peephole optimizations

Constant folding

```
ADD lit1, lit2, Rx → MOV lit1 + lit2, Rx

MOV lit1, Rx

ADD li2, Rx, Ry → MOV lit1 + lit2, Ry
```

Strength reduction

```
MUL operand, 2, Rx \longrightarrow SHIFTL operand, 1, Rx DIV operand, 4, Rx \longrightarrow SHIFTR operand, 2, Rx
```

Null sequences

```
MUL operand, 1, Rx \longrightarrow MOV operand, Rx ADD operand, 0, Rx \longrightarrow MOV operand, Rx
```

Peephole optimizations

Combine operations

```
JEQ L1

JMP L2

L1: ...
```

Simplifying

```
SUB operand, \emptyset, Rx \longrightarrow NEG Rx
```

Special cases (taking advantage of ++/--)

```
ADD 1, Rx, Rx \longrightarrow INC Rx SUB Rx, 1, Rx \longrightarrow DEC Rx
```

Address mode operations

```
MOV A R1
ADD \emptyset(R1) R2 R3

ADD \emptysetA R2 R3
```

Common subexpression elimination

 Goal: remove redundant computation, don't calculate the same expression multiple times

$$I:A = B + C * D$$

$$2: E = B + C * D$$

Keep the result of statement I in a temporary and reuse for statement 2

 Difficulty: how do we know when the same expression will produce the same result?

$$I:A = B + C * D$$

$$2: B = < new value >$$

$$3: E = B + C * D$$

B is "killed." Any expression using B is no longer "available," so we cannot reuse the result of statement I for statement 3

 This becomes harder with pointers (i.e., how do we know when B is killed?)

Common subexpression elimination

- Two varieties of common subexpression elimination (CSE)
- Local: within a single basic block
 - Easier problem to solve (why?)
- Global: within a single procedure or across the whole program
 - Intra- vs. inter-procedural
 - More powerful, but harder (why?)
 - Will come back to these sorts of "global" optimizations later

CSE in practice

- Idea: keep track of which expressions are "available" during the execution of a basic block
 - Which expressions have we already computed?
 - Issue: determining when an expression is no longer available
 - This happens when one of its components is assigned to, or "killed."
- Idea: when we see an expression that is already available, rather than generating code, copy the temporary
 - Issue: determining when two expressions are the same

Maintaining available expressions

- For each 3AC operation in a basic block
 - Create name for expression (based on lexical representation)
 - If name not in available expression set, generate code, add it to set
 - Track temporary that holds expression and any variables used to compute expression
 - If name in available expression set, generate move instruction
 - If operation assigns to a variable, kill all dependent expressions

Three address code

- + A B T1
- + T1 C T2
- + A B T3
- + T1 T2 C
- + T1 C T4
- + T3 T2 D

Generated code

Available expressions:

Three address code

```
+ A B T1
```

- + T1 C T2
- + A B T3
- + T1 T2 C
- + T1 C T4
- + T3 T2 D

Generated code

ADD A B R1

Available expressions: "A+B"

Three address code

```
+ A B T1
```

Generated code

Available expressions: "A+B" "T1+C"

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
```

+ T1 C T4

+ T3 T2 D

Available expressions: "A+B" "T1+C"

Generated code

ADD A B R1 ADD R1 C R2 MOV R1 R3

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
```

Available expressions: "A+B" "T1+C" "T1+T2"

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
```

Available expressions: "A+B" "T1+T2" "T1+C"

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
ADD R3 R2 R6; ST R6 D
```

Available expressions: "A+B" "T1+T2" "T1+C" "T3+T2"

Downsides

 What are some downsides to this approach? Consider the two highlighted operations

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

Generated code

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ADD A B R1
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Downsides

 What are some downsides to this approach? Consider the two highlighted operations

Three address code

```
+ A B T1
+ T1 C T2
+ A B T3
+ T1 T2 C
+ T1 C T4
+ T3 T2 D
```

Generated code

```
ADD A B R1
ADD R1 C R2
MOV R1 R3
ADD R1 R2 R5; ST R5 C
ADD R1 C R4
ST R5 D
```

 This can be handled by an optimization called value numbering, which we will not cover now (although we may get to it later)

Aliasing

- One of the biggest problems in compiler analysis is to recognize aliases – different names for the same location in memory
- Aliases can occur for many reasons
 - Pointers referring to same location, arrays referencing the same element, function calls passing the same reference in two arguments, explicit storage overlapping (unions)
- Upshot: when talking about "live" and "killed" values in optimizations like CSE, we're talking about particular variable names
- In the presence of aliasing, we may not know which variables get killed when a location is written to

Memory disambiguation

- Most compiler analyses rely on memory disambiguation
 - Otherwise, they need to be too conservative and are not useful
- Memory disambiguation is the problem of determining whether two references point to the same memory location
 - Points-to and alias analyses try to solve this
 - Will cover basic pointer analyses in a later lecture

Register allocation

- Simple code generation: use a register for each temporary variable, load from a variable on each read, store to a variable at each write
- Problems
 - Real machines have a limited number of registers one register per temporary may be too many
 - Loading from and storing to variables on each use may produce a lot of redundant loads and stores
- Goal: allocate registers to variables and temporaries to do two things
 - Eliminate loads and stores
 - Minimize register spills

Register allocation basics

- One approach: assume all variables are in memory, load into registers as needed
- Alternate approach: start with unlimited pool of virtual registers
 - Whenever a new register is needed (e.g., a new temporary is created, a variables is loaded, etc.) create a new virtual register
 - No re-use of registers
- Need to worry about aliasing

//a and b are aliased

LD a R1

LD b R2

Dealing with aliasing

- Immediately before loading a variable x
 - For each variable aliased to x that is already in a register, save it to memory (i.e., perform a store)
 - This ensures that we load the right value
- Immediately before storing a variable x
 - For each register associated with a variable aliased to x, mark it as invalid
 - So next time we use the variable, we will reload it
- Conservative approach: assume all variables are aliased (in other words, reload from memory on each read, store to memory on each write)
 - Better alias analysis can improve this
 - At subroutine boundaries, still often use conservative analysis

Global vs. local

- Same distinction as global vs. local CSE
 - Local register allocation is for a single basic block
 - Global register allocation is for an entire function (but not interprocedural – why?)

Will cover some local allocation strategies now, global allocation later

Top-down register allocation

- For each basic block
 - Find the number of references of each variable
 - Assign registers to variables with the most references
- Details
 - Keep some registers free for operations on unassigned variables and spilling
 - Store dirty registers at the end of BB (i.e., registers which have variables assigned to them)
 - Do not need to do this for temporaries (why?)

Bottom-up register allocation

```
For each tuple op A B C in a BB, do

R<sub>x</sub> = ensure(A)

R<sub>y</sub> = ensure(B)

if A dead after this tuple, free(R<sub>x</sub>)

if B dead after this tuple, free(R<sub>y</sub>)

R<sub>z</sub> = allocate(C) //could use R<sub>x</sub> or R<sub>y</sub>

mark R<sub>z</sub> dirty

At end of BB, for each dirty register

generate code to store register into appropriate variable
```

We will present this as if A, B, C are variables in memory.
 Can be modified to assume that A, B and C are in virtual registers, instead

Bottom-up register allocation

```
ensure(opr)
  if opr is already in register r
    return r
  else
    r = allocate(opr)
    generate load from opr into r
    return r
```

```
free(r)

if r is marked dirty

generate store

mark r as free
```

```
allocate(opr)

if there is a free r

choose r

else

choose r with most distant use

free(r)

mark r associated with opr

return r
```

- Requires calculating def-use chains
- Easy to calculate within a BB:
 - Start at end of block, all variables marked dead
 - When a variable is used, mark as live, record use
 - When a variable is defined, record def, variable dead above this
 - Creates chains linking uses of variables to where they were defined
- We will discuss how to calculate this across BBs later

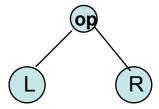
Allocation considerations

- Use register coloring to perform global register allocation
 - Will see this next
- Find right order of optimizations and register allocation
 - Peephole optimizations can reduce register pressure, can make allocation better
 - CSE can actually increase register pressure
 - Different orders of optimization produce different results
- Register allocation still an open research area
 - For example, how to do allocation for JIT compilers

Context-sensitive Code Generation

Generating code from IR trees.

Idea:



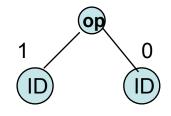
if evaluating R takes more registers than L, it is better to

- evaluate R
- save result in a register
- evaluate L
- do the (binary) operation

This is because result of R takes a register

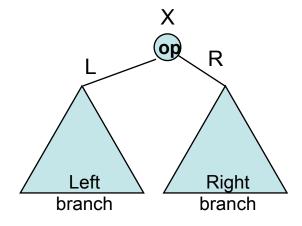
Determining Register Needs

Assuming both register-to-register and storage-to register instructions



For ID nodes (these are leaf nodes):

- left: 1 register
- right: 0 registers (use op from memory)



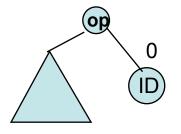
Register need of the combined tree:

$$X =$$

- L+1, if R = L
- max(R,L), if $R \neq L$

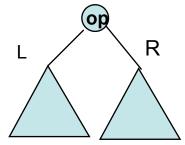
Algorithm for Code Generation Using Register-Need Annotations

Recursive tree algorithm. Each step leaves result in R1 (R1 is the first register in the list of available registers)



Case 1: right branch is an ID:

- generate code for left branch
- generate OP ID,R1 (op,R1,ID,R1)

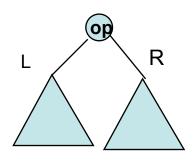


Case 2: min(L,R) >= max available registers:

- generate code for right branch
- spill R1 into a temporary T
- generate code for left branch
- generate OP T,R1

Tree Code Generation continued

Remaining cases: at least one branch needs fewer registers than available



min(R,L) < available regs Case 3: R < max available registers:

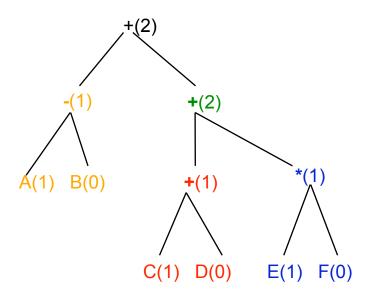
- generate code for left branch
- remove first register (R1) from available register list
- generate code for right branch (result in R2)
- generate OP R2,R1

Case 4: L < max available registers:

- temporarily swap R1 and R2
- generate code for right branch
- remove first register (R2) from available register list
- generate code for left branch (result in R1)
- generate OP R2,R1

Example Tree Code Generation

$$(A-B)+((C+D)+(E*F))$$



	R1 holds	R2 holds	
Load C,R2		С	
Add D,R2		C+D	
Load E,R1	E	C+D	
Mult F,R1	E*F	C+D	
Add R1,R2		C+D+E*F	
Load A,R1	Α	C+D+E*F	
Sub B,R1	A-B	C+D+E*F	
Add R2,R1	A-B+C+D+E*F		

Note: life gets more interesting if some of the leaves are reused/across trees