ECE 295: Lecture 04 Regression

Spring 2018

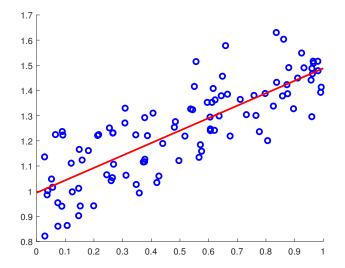
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Data Fitting

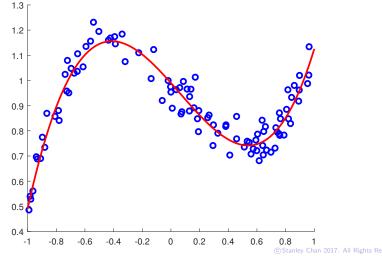
You give me data, I find the trend.



Data Fitting

Once I find the trend, I can

- Predict values where I previously did not measure
- Extrapolate outside the range

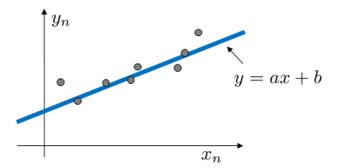


Problem Formulation

First, we need a **model**! Let's start with this:

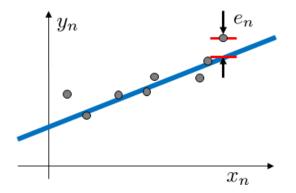
$$y_n = ax_n + b + e_n, \qquad n = 1, \ldots, N$$

This is a linear equation.



What is the error?

- $y_n =$ true measured value
- $ax_n + b = estimated$ value
- e_n measures the difference $y_n (ax_n + b)$



What is "best"?

We need solve this **optimization** problem:

$$\left(\widehat{a},\widehat{b}\right) = \operatorname*{arg\,min}_{(a,b)} \sum_{n=1}^{N} (y_n - (ax_n + b))^2.$$

- argmin = find the values of the variables that can minimize the function.
- $\sum_{n=1}^{N} (y_n (ax_n + b))^2$: sum of all the errors
- You don't have to choose (·)². You can use | · |, or max(·) or whatever.
- ► (·)² is just easier.
- How to solve this optimization?
- Take derivative, set it to zero.

Main Result

Theorem The solution of the problem

$$\left(\widehat{a},\widehat{b}
ight) = \operatorname*{arg\,min}_{(a,b)} \ \sum_{n=1}^{N} (y_n - (ax_n + b))^2$$

is the solution to the following system of linear equations

$$\begin{bmatrix} \sum_{n=1}^{N} x_n^2 & \sum_{n=1}^{N} x_n \\ \sum_{n=1}^{N} x_n & n \end{bmatrix} \begin{bmatrix} \widehat{a} \\ \widehat{b} \end{bmatrix} = \begin{bmatrix} \sum_{n=1}^{N} x_n y_n \\ \sum_{n=1}^{N} y_n \end{bmatrix}$$
(1)

Solution

First, let us define

$$\varphi(a,b) = \sum_{n=1}^{N} (y_n - (ax_n + b))^2.$$

Taking derivatives on both sides with respect to a and b yields

$$\frac{\partial}{\partial a}\varphi(a,b) = 2\left(\sum_{n=1}^{N} x_n y_n - a \sum_{n=1}^{N} x_n^2 - b \sum_{n=1}^{N} x_n\right) = 0$$
$$\frac{\partial}{\partial b}\varphi(a,b) = 2\left(\sum_{n=1}^{N} y_n - a \sum_{n=1}^{N} x_n - nb\right) = 0$$

Rearranging the terms, this is equivalent to

$$\begin{bmatrix} \sum_{n=1}^{N} x_n^2 & \sum_{n=1}^{N} x_n \\ \sum_{n=1}^{N} x_n & n \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \sum_{n=1}^{N} x_n y_n \\ \sum_{n=1}^{N} y_n \end{bmatrix}$$

Matrix-Vector Representation

This is a 2×2 system of linear equations

$$\begin{bmatrix} \sum_{n=1}^{N} x_n^2 & \sum_{n=1}^{N} x_n \\ \sum_{n=1}^{N} x_n & n \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \sum_{n=1}^{N} x_n y_n \\ \sum_{n=1}^{N} y_n \end{bmatrix}$$

This is equivalent to

$$\boldsymbol{X}^{T}\boldsymbol{X}\boldsymbol{\beta} = \boldsymbol{X}^{T}\boldsymbol{y}, \qquad (2)$$

where

$$\boldsymbol{X} = \begin{bmatrix} x_1 & 1 \\ \vdots & \vdots \\ x_N & 1 \end{bmatrix}, \quad \boldsymbol{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} a \\ b \end{bmatrix}, \quad (3)$$

Solution in Matrix-Vector Representation

The equation

$$\boldsymbol{X}^{T}\boldsymbol{X}\boldsymbol{\beta} = \boldsymbol{X}^{T}\boldsymbol{y} \tag{4}$$

is called the **normal equation** of a linear system $Xx = \beta$.

To determine the vector β, we take inverse (assuming X^TX is invertible):

$$\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^{\mathsf{T}} \boldsymbol{X})^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}$$
 (5)

- ► The matrix X^TX is invertible when there is no dependent columns of X^TX, which in turn holds when there is no dependent columns of X.
- ► If the matrix X^TX is close to non-invertible (i.e., having a very large condition number), then we can perturb the solution as

$$\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^{T}\boldsymbol{X} + \lambda \boldsymbol{I})^{-1}\boldsymbol{X}^{T}\boldsymbol{y}$$
(6)

where $\lambda > 0$ is a constant.

General Least Squares Minimization

The normal equation can also be derived from an optimization:

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{arg\,min}} \|\boldsymbol{X}\boldsymbol{\beta} - \boldsymbol{y}\|^2 \tag{7}$$

Here, $\|\boldsymbol{u}\|^2$ denotes the ℓ_2 -norm square of a vector \boldsymbol{u} :

$$\|\boldsymbol{u}\|^2 = \sum_{i=1}^n u_i^2.$$

Derivation of the optimal solution: (Need some matrix-calculus)

$$\frac{d}{d\beta} \| \boldsymbol{X} \boldsymbol{\beta} - \boldsymbol{y} \|^2 = 0 \quad \Rightarrow \quad \boldsymbol{X}^T (\boldsymbol{X} \boldsymbol{\beta} - \boldsymbol{y}) = 0$$
$$\Rightarrow \quad \boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\beta} = \boldsymbol{X}^T \boldsymbol{\beta},$$

so we obtain the same normal equation.

Example 1: Quadratic Fitting

Problem: Find the linear least squares solution for

$$y_n = ax_n^2 + bx_n + c$$

Extension: This idea can be extended high order polynomials.

Solution:

$$\boldsymbol{X} = \begin{bmatrix} x_1^2 & x_1 & 1 \\ \vdots & \vdots & \vdots \\ x_N^2 & x_N & 1 \end{bmatrix}, \quad \boldsymbol{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} \boldsymbol{a} \\ \boldsymbol{b} \\ \boldsymbol{c} \end{bmatrix},$$

The solution is

$$\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{y}.$$

Example 2: Auto-Regressive Model

Problem: Find the linear least squares solution for

$$y_n = ay_{n-1} + by_{n-2}$$

Application: Stock-prediction: We have sample y_{n-1} and y_{n-2} , we want to predict y_n .

Solution:

$$\boldsymbol{X} = \begin{bmatrix} y_2 & y_1 \\ y_3 & y_2 \\ \vdots & \vdots \\ y_{N-1} & y_{N-2} \end{bmatrix}, \quad \boldsymbol{y} = \begin{bmatrix} y_3 \\ y_4 \\ \vdots \\ y_N \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} a \\ b \end{bmatrix},$$

The solution is

$$\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^{\mathsf{T}} \boldsymbol{X})^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}$$

Interpreting the Results

| city | funding | hs | not-hs | college | college4 | crime rate |
|------|---------|----|--------|---------|----------|------------|
| 1 | 40 | 74 | 11 | 31 | 20 | 478 |
| 2 | 32 | 72 | 11 | 43 | 18 | 494 |
| 3 | 57 | 70 | 18 | 16 | 16 | 643 |
| 4 | 31 | 71 | 11 | 25 | 19 | 341 |
| 5 | 67 | 72 | 9 | 29 | 24 | 773 |
| : | : | : | : | : | | |
| 50 | 66 | 67 | 26 | 18 | 16 | 940 |

https://web.stanford.edu/~hastie/StatLearnSparsity/data.html

$$\boldsymbol{X} = \begin{bmatrix} 1 & 40 & 74 & 11 & 31 & 20 \\ 1 & 32 & 72 & 11 & 43 & 18 \\ & \vdots & & & \\ 1 & 66 & 67 & 26 & 18 & 16 \end{bmatrix}, \quad \boldsymbol{y} = \begin{bmatrix} 478 \\ 494 \\ \vdots \\ 940 \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_5 \end{bmatrix},$$

Interpreting the Results

Run regression analysis (with $\lambda = 1000$). Here is the result:

- $\beta_1 = 10.9934$: police funding
- $\beta_2 = 1.1451$: high school
- $\beta_3 = 10.1812$: no high school
- ▶ β₄ = 2.7386: college
- $\beta_5 = -0.7781$: college at least 4 years

That means:

- Crime rate is more influenced by police funding
- and number of residents without high school
- Other factors are not quite relevant

The term β_0 is known as the bias, or the DC term in circuit terminology.

Solution Trajectory Recall that $\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$ is equivalent to

$$\widehat{oldsymbol{eta}} = rgmin_{oldsymbol{eta}} \ \|oldsymbol{X}oldsymbol{eta} - oldsymbol{y}\|^2.$$

We can show that $\widehat{\boldsymbol{\beta}} = (\boldsymbol{X}^T \boldsymbol{X} + \lambda \boldsymbol{I})^{-1} \boldsymbol{X}^T \boldsymbol{y}$ is equivalent to

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{arg\,min}} \quad \|\boldsymbol{X}\boldsymbol{\beta} - \boldsymbol{y}\|^2 + \lambda \|\boldsymbol{\beta}\|^2.$$
(8)

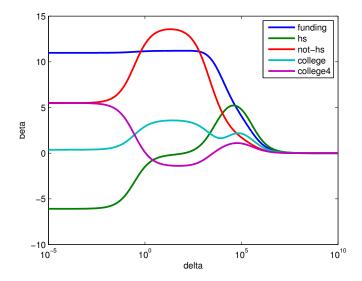
Why?

$$\frac{d}{d\beta}(\cdot) = 0 \implies \mathbf{X}^{\mathsf{T}}(\mathbf{X}\beta - \mathbf{y}) + \lambda\beta = 0$$
$$\implies (\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda\mathbf{I})\beta = \mathbf{X}^{\mathsf{T}}\mathbf{y}.$$

Now, consider $\widehat{\beta}$ as a function of λ :

$$\widehat{\boldsymbol{\beta}}_{\lambda} = (\boldsymbol{X}^{T}\boldsymbol{X} + \lambda \boldsymbol{I})^{-1} \boldsymbol{X}^{T} \boldsymbol{y}$$

Solution Trajectory



Beyond Least Squares

It is possible to use other forms of optimization, e.g.,

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{arg\,min}} \|\boldsymbol{X}\boldsymbol{\beta} - \boldsymbol{y}\|^2 + \lambda \|\boldsymbol{\beta}\|_1, \tag{9}$$

where $\|\cdot\|_1$ is called the ℓ_1 -norm:

$$\|\boldsymbol{u}\|_1 = \sum_{i=1}^n |u_i|.$$

This is called the Least Absolute Shrinkage and Selection Operation (LASSO).

- Solving the LASSO problem is beyond the scope of this course. (See ECE 695 Sparse Modeling and Algorithms)
- It requires convex optimization algorithms.
- LASSO makes $\widehat{\boldsymbol{\beta}}$ sparse.
- Essential if X is short and fat. (X^TX is not invertible.)