Higher Order Functions

Recall that in Python, functions that we define are just objects like anything else:

```
In [1]: def meaningOfLife(x):
    return 42 * x

type(meaningOfLife)
Out[1]: function
```

This means that we can assign functions to variables, and then treat those variables as functions

```
In [2]: f = meaningOfLife
print f(2)
```

This is sort of like function pointers in C, but much cleaner (because Python doesn't force you to be super precise about types). Note that in the same way that we can bind functions to variables, we can pass functions in to other functions. For example, the function myApply below takes a function as its first argument, and calls that function on its second argument:

```
In [3]: def myApply(fun, x) :
    return fun(x)

myApply(meaningOfLife, 3)
Out[3]: 126
```

A function that takes other functions as arguments (or *returns* a function) is called a *higher order function*. Note that we called our example myApply above, because Python already *has* a higher order function called apply that does basically the same thing, but in a more robust way:

```
In [4]: apply(meaningOfLife, [3])
Out[4]: 126
```

So why are higher order functions useful? Let's take a simple example, where we want to filter an input list, say to discard values that are too high or too low:

```
In [5]: import numpy as np
    data = np.loadtxt('math_scores.txt')
    print len(data), data[:10]

50000 [67.2 42.3 33.1 59. 41.3 38.3 44.3 50.4 53.5 43.5]

In [6]: def simpleFilter(data):
    res = []
    for d in data:
        if d >= 40 and d <= 60:
            res.append(d)
    return res

filtered1 = simpleFilter(data)
    print len(filtered1), filtered1[:10]

31582 [42.3, 59.0, 41.3, 44.3, 50.4, 53.5, 43.5, 53.4, 52.2, 56.3]</pre>
```

But now if we want to change the range we filter out, we have to write a *new* filter function to do it. Instead, we can turn filter into a higher order function that takes as an argument a new function p that returns True if we want to keep the datum, and False if we don't:

```
In [7]: def myFilter(p, data) :
    res = []
    for d in data :
        if p(d) :
            res.append(d)
    return res
```

Two things to note: First, we calling the test p for "predicate." Second, our filtering function is called myFilter because Python has a built-in function called filter that does more or less the same thing.

Now all we need to do is define a new function to find things in range, then pass it to myFilter:

```
In [8]: def inRange(d):
    return True if d >= 40 and d <= 60 else False

filtered2 = myFilter(inRange, data)

print len(filtered2), filtered2[:10]

31582 [42.3, 59.0, 41.3, 44.3, 50.4, 53.5, 43.5, 53.4, 52.2, 56.3]</pre>
```

Great! Now we can write arbitrary filter functions. Here's one that filters out any element where floor(element) is odd:

```
In [9]: def isEven(d):
    return True if (int(d) % 2 == 0) else False

onlyEven = myFilter(isEven, data)

print len(onlyEven), onlyEven[:10]

24936 [42.3, 38.3, 44.3, 50.4, 52.2, 56.3, 44.4, 58.8, 90.1, 52.0]
```

But let's go back to our range function. It's annoying that we have to write a brand new predicate function p every time we want a new range to filter. So we can take advantage of another trick of higher order functions: the ability to *return* functions from other functions.

Returning Functions and Closures

Python lets you define *nested* functions: functions that are defined inside of other functions. Because function definitions are just objects, these newly defined functions can be returned. The trick to these functions is that variables you use inside the nested functions take on their values from the enclosing function. In programming languages terminology, this is a *closure*: a function that "captures" the values of its surrounding environment, and "keeps them around" for the next time you call the function.

Let's define a function that *creates* a predicate function for filtering out a range:

```
In [10]: def createRangeP(minimum, maximum) :
    def p(d) :
        return True if d >= float(minimum) and d <= maximum else False
    return p

p1 = createRangeP(45, 55)
p2 = createRangeP(45, 60)
print p1(40)
print p1(50)
print p1(60)
print p2(40)
print p2(50)
print p2(60)</pre>
```

True False False True Let's unpack what happened here. The function p is declared as an inner function. It takes one argument, d. Inside this definition, it uses two variables minimum and maximum that don't exist inside p's local scope. Instead, p captures those variables from its enclosing scope: the values of minimum and maximum passed in to createRangeP. Importantly, p "remembers" these values even after it has been returned, for when it is called later!

This new function, in combination with myFilter lets us easily filter arbitrary ranges:

```
In [11]: filtered3 = myFilter(createRangeP(20, 80), data)
    print len(filtered3), filtered3[:10]
41051 [67.2, 42.3, 33.1, 59.0, 41.3, 38.3, 44.3, 50.4, 53.5, 43.5]
```

Lambdas

Python provides a shortcut for quickly defining functions that compute an expression and return it, called *lambdas* (called this because *lambda* is the symbol used for functions in lambda calculus). We can use this anywhere we need to define and use a function just once, but don't need to assign this function to a variable/name so we can use it again later (for this reason, these functions are often called *anonymous functions*)

```
In [12]: filtered4 = myFilter(lambda x : True if x >= 20 and x <= 80 else False
    , data)
print len(filtered4), filtered4[:10]

41051 [67.2, 42.3, 33.1, 59.0, 41.3, 38.3, 44.3, 50.4, 53.5, 43.5]</pre>
```

We could have also written createRange using lambdas:

```
In [13]: def createRangeP_lambda(minimum, maximum) :
    return lambda d : True if d >= float(minimum) and d <= maximum els
    e False
    filtered5 = myFilter(createRangeP_lambda(20, 80), data)
    print len(filtered5), filtered5[:10]

41051 [67.2, 42.3, 33.1, 59.0, 41.3, 38.3, 44.3, 50.4, 53.5, 43.5]</pre>
```

Map and Reduce

Two of the most common higher order functions are map and reduce (sometimes called fold). map takes an input list and a function f of one argument, and returns a new list. The ith element of the output list is f applied to the ith element of the input list.

reduce takes a list and a function of two arguments, and returns a single value. That value is computed by applying the function f to the first two elements of the list, then applying the result of that to the third element, then the result of that to the fourth element, and so on: f(f(f(inp[0], inp[1]), inp[2]), inp[3]) ...

These are built in functions in Python, but we'll write our own versions using higher order functions:

```
In [27]: def myMap(f, inp) :
    res = []
    for i in inp :
        res.append(f(i))
    return res

def myReduce(f, inp, init = None) :
    if (init == None) :
        res = inp[0]
    else :
        res = f(init, inp[0])
    for i in range(1, len(inp)) :
        res = f(res, inp[i])
    return res
```

Let's use myReduce to compute the average of our input data:

```
In [28]: total = myReduce(lambda x, y : x + y, data)
    count = myReduce(lambda x, y : x + 1, data, 0)
    avg = total / count

print total, count, avg

2850713.8999999915 50000 57.014277999999834
```

We can then use myMap and myReduce together to compute the variance:

```
In [29]: sqerr = myMap(lambda x : (x - avg) ** 2, data)
var = myReduce(lambda x, y : y + x, sqerr) / count
print var
```

250.58829593871462

We can compare these to the average and variance computed by the NumPy functions: