## ECE 5314: Power System Operation & Control

# Lecture 9: Secure Power System Operation

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- R1 A. J. Wood, B. F. Wollenberg, and G. B. Sheble, Power Generation, Operation, and Control, Wiley, 2014, Chapter 7.
- R2 A. Gomez-Exposito, A. J. Conejo, C. Canizares, *Electric Energy Systems: Analysis and Operation*, Chapters 6.

## Power system security

Power system components can experience outages

- generators go offline
- transmission lines trip
- transformers fail

(*N-1*) reliability rule: system should be safely operating even if any single component fails; set by North American Electric Reliability Corp. (NERC)

Major power system security functions:

- 1. power system state estimation (see Lecture 11)
- 2. contingency analysis
- 3. security-constrained OPF (SC-OPF)

# Normal dispatch

Assume double-circuit line with 400 MW limit



Normal dispatch: system is economically optimal, but not necessarily secure



Post-contingency state: due to a single-component failure, operational

constraints are now violated

# Secure dispatch

Assume double-circuit line with 400 MW limit



Secure dispatch: security at the expense of increased cost



Secure post-contingency state: no line overloads

# Contingency (what-if) analysis

Approximate but fast method for checking the effect of outages

Generator outage: if a generator fails, other generators take over

Line outage: cascading failure example

- single line trips (tree contact or insulation failure)
- flows automatically re-distributed over network
- other lines exceed their flow limits and trip
- phenomenon travels fast (few min to an hour for entire ISO footprint)

Linear sensitivity factors: model effect of above events to line flows

- Power Transfer Distribution Factors (PTDF)
- Line Outage Distribution Factors (LODF)

#### Review of DC power flow model

• Branch-bus incidence matrix (bus 1 as reference and slack bus)

$$\tilde{\mathbf{A}} = [\mathbf{a}_1 \ \mathbf{A}]$$

• If line l:(i,j), then the *l*-th row of  $\tilde{\mathbf{A}}$  is  $\mathbf{a}_l = \mathbf{e}_i - \mathbf{e}_j$ 

• Bus reactance matrix 
$$\tilde{\mathbf{B}} = \begin{bmatrix} B_{11} & \mathbf{b}_1^\top \\ \mathbf{b}_1 & \mathbf{B} \end{bmatrix}$$

- Matrices  $(\mathbf{B}, \mathbf{A})$  termed  $(\mathbf{B}_r, \mathbf{A}_r)$  in Lecture 8; simpler notation here
- Flows relate linearly to injections  $\mathbf{f}=\mathbf{S}\mathbf{p}$
- Matrix  ${f S}$  describes how changes in  ${f p}$  reflect on changes in  ${f f}$

$$\Delta \mathbf{f} = \mathbf{S} \Delta \mathbf{p}$$
 where  $\mathbf{S} = [\mathbf{0} \ \mathbf{X}^{-1} \mathbf{A} \mathbf{B}^{-1}]_{L \times N}$ 

#### Power transfer between two buses

Assume GEN<sub>n</sub> goes offline and its power is picked up by GEN<sub>m</sub>

$$\hat{p}_n = p_n + \Delta p_n$$
 and  $\hat{p}_m = p_m - \Delta p_n$ 

with  $\Delta p_n = -p_n$ 

• Change in power injections (e<sub>n</sub>: n-th column of I)

$$\Delta \mathbf{p} = \hat{\mathbf{p}} - \mathbf{p} = \Delta p_n (\mathbf{e}_n - \mathbf{e}_m)$$

· Change in all line flows

$$\Delta \mathbf{f} = \hat{\mathbf{f}} - \mathbf{f} = \mathbf{S} \Delta \mathbf{p} = \Delta p_n (\mathbf{S} \mathbf{e}_n - \mathbf{S} \mathbf{e}_m) = \Delta p_n (\mathbf{S}_{:,n} - \mathbf{S}_{:,m})$$

• Flow on line l changes by  $\Delta f_l = \Delta p_n (S_{l,n} - S_{l,m})$ 

# Finding entry $S_{l,n}$

• Interested in finding the (l, n)-th entry of

$$\mathbf{S} = \mathbf{X}^{-1} [\mathbf{0} \ \mathbf{A} \mathbf{B}^{-1}]$$

• Since 
$$l$$
-th row of  $ilde{\mathbf{A}}$  is  $\mathbf{a}_l = \mathbf{e}_i - \mathbf{e}_j$ , then

$$S_{l,n} = \frac{1}{x_l} (\mathbf{e}_i - \mathbf{e}_j)^\top [\mathbf{B}^{-1}]_{:,n}$$
$$= \frac{[\mathbf{B}^{-1}]_{i,n} - [\mathbf{B}^{-1}]_{j,n}}{x_l}$$

- Exceptions because  ${\bf A}$  has the first column of  $\tilde{{\bf A}}$  removed

• if 
$$n = 1$$
, then  $S_{l,n} = 0$   
• if  $j = 1$  and  $n \neq 1$ , then  $S_{l,n} = \frac{[\mathbf{B}^{-1}]_{i,n}}{x_l}$   
• if  $i = 1$  and  $n \neq 1$ , then  $S_{l,n} = -\frac{[\mathbf{B}^{-1}]_{j,n}}{x_l}$ 

#### Power Transfer Distribution Factors

• How a power transfer from bus n to bus m affects flow on line l

$$\mathsf{PTDF}_{n,m,l} = \frac{\text{flow change on line } l}{\text{power transfer from bus } n \text{ to } m}$$
$$= \frac{\Delta f_l}{\Delta p_n}$$
$$= S_{l,n} - S_{l,m}$$

- It can be shown that  $|\mathsf{PTDF}_{n,m,l}| \leq 1$
- Typically the outage of generator n is shared by multiple generators (AGC)

$$\Delta f_l = \sum_{m \neq n} \gamma_m \Delta p_n \mathsf{PTDF}_{n,m,l}$$

for participation factors  $\gamma_m \geq 0$  and  $\sum_{m \neq n} \gamma_m = 1$ 

#### Power transfers through reference bus

• Recall that  $\mathsf{PTDF}_{n,1,l} = S_{l,n}$  because  $S_{l,1} = 0$ 

· Power transfer between two buses through the reference bus

$$\mathsf{PTDF}_{n,m,l} = \mathsf{PTDF}_{n,1,l} - \mathsf{PTDF}_{m,1,l} = S_{l,n} - S_{l,m}$$

- Hence, no need to compute all PTDF<sub>n,m,l</sub>
- Need only to compute  $PTDF_{n,1,l}$ ; that is the entries of S
- Power sharing after generator outage

$$\Delta f_l = \Delta p_n S_{l,n} - \sum_{m \neq n} \gamma_m \Delta p_n S_{l,m}$$

## Line Outage Distribution Factors

- How flows change when a single line  $k : (n \rightarrow m)$  is removed?
- How are flows redistributed under a transmission topology change?
- If line k was originally carrying  $f_k$ , the post-contingency flow on line l is

$$\hat{f}_l = f_l + \mathsf{LODF}_{l,k} f_k$$

- Two ways for finding LODF<sub>1,k</sub>
  - 1. compensation trick
  - 2. matrix inversion lemma

#### LODFs via the compensation trick

Pretend no line outage has happened

Modify  $(p_n,p_m)$  by  $(\hat{f}_k,-\hat{f}_k)$  such that the new flow on line k:(n,m) is  $\hat{f}_k$ 



This implies that line k has no effect for the rest of the grid

Line outage has been interpreted as a power transfer  $f_k$  from bus n to m

$$\Delta f_l = \mathsf{PTDF}_{n,m,l} \hat{f}_k = \frac{\mathsf{PTDF}_{n,m,l}}{1 - \mathsf{PTDF}_{n,m,k}} f_k$$

**Result**:  $\text{LODF}_{l,k} = \frac{\text{PTDF}_{n,m,l}}{1-\text{PTDF}_{n,m,k}}$  for  $l \neq k$ ; and  $\text{LODF}_{k,k} = -1$ 

# LODFs via the matrix inversion lemma

• Applying the matrix inversion lemma

$$(\mathbf{A} + \mathbf{B}\mathbf{C}\mathbf{D})^{-1} = \mathbf{A}^{-1} - \mathbf{A}^{-1}\mathbf{B}(\mathbf{C}^{-1} + \mathbf{D}\mathbf{A}^{-1}\mathbf{B})^{-1}\mathbf{D}\mathbf{A}^{-1}$$

· yields the inverse of the modified bus-reactance matrix

$$\hat{\mathbf{B}}^{-1} = \left(\mathbf{B} - \frac{1}{x_k} \mathbf{a}_k \mathbf{a}_k^{\mathsf{T}}\right)^{-1} = \mathbf{B}^{-1} + \frac{\mathbf{B}^{-1} \mathbf{a}_k \mathbf{a}_k^{\mathsf{T}} \mathbf{B}^{-1}}{x_k - \mathbf{a}_k^{\mathsf{T}} \mathbf{B}^{-1} \mathbf{a}_k}$$

• the post-outage flows are then

$$\hat{\mathbf{f}} = \mathbf{f} + \frac{\mathbf{X}^{-1}\mathbf{A}\mathbf{B}^{-1}\mathbf{a}_k\mathbf{a}_k^{\top}\mathbf{B}^{-1}\mathbf{p}_r}{x_k - \mathbf{a}_k^{\top}\mathbf{B}^{-1}\mathbf{a}_k}$$

• focusing on the *l*-th entry

$$\Delta f_l = \hat{f}_l - f_l = \left(\frac{\mathbf{a}_l^\top \mathbf{B}^{-1} \mathbf{a}_k}{x_l}\right) \left(\frac{1}{1 - \mathbf{a}_k^\top \mathbf{B}^{-1} \mathbf{a}_k/x_k}\right) \left(\frac{\mathbf{a}_k^\top \mathbf{B}^{-1} \mathbf{p}_r}{x_k}\right)$$
$$= \frac{\mathsf{PTDF}_{n,m,l}}{1 - \mathsf{PTDF}_{n,m,k}} f_k$$

## Combining sensitivity factors

Study simultaneous power transfer of  $\delta_{ij}$  between  $i \rightarrow j$  and outage of line k

• First, model the power transfer on line k and any other line l

$$\hat{f}_k = f_k + \delta_{ij} \cdot \mathsf{PTDF}_{i,j,k}$$
  
 $\hat{f}_l = f_l + \delta_{ij} \cdot \mathsf{PTDF}_{i,j,l}$ 

• Secondly, capture the line outage

 $\hat{f}_{l} = \hat{f}_{l} + \mathsf{LODF}_{l,k} \hat{f}_{k}$  $= (f_{l} + \mathsf{LODF}_{l,k} f_{k}) + (\mathsf{PTDF}_{i,j,l} + \mathsf{LODF}_{l,k} \mathsf{PTDF}_{i,j,k}) \delta_{ij}$ 

• Why not implement the changes in reverse order?

Sensitivity factors can be used to simplify: *i*) monitoring security of current system state; and also *ii*) security-constrained OPF (SC-OPF)

#### Preventive SC-OPF

Recall network-constrained DC-OPF:

$$\min_{\mathbf{p} \le \mathbf{p} \le \overline{\mathbf{p}}} \sum_{m=1}^{N} C_m(p_m)$$
(P1)  
s.to  $\mathbf{1}^{\top} \mathbf{p} = 0$   
 $-\overline{\mathbf{f}} \le \mathbf{S} \mathbf{p} \le \overline{\mathbf{f}}$ 

To ensure flows remain safe even after any single-line outage, add constraints

for each line  $l: -\overline{\mathbf{f}}^l \leq \mathbf{S}^l \mathbf{p} \leq \overline{\mathbf{f}}^l$  where  $\mathbf{S}^l$  relates to each line outage

How to compute  $S^l$  from LODFs?

Note that power injections remain unchanged after line outage

## Preventive SC-OPF

In a power system with L lines, we need L sets of constraints  $-\overline{\mathbf{f}}^l \leq \mathbf{S}^l \mathbf{p} \leq \overline{\mathbf{f}}^l$ ; hence total of  $\mathcal{O}(L^2)$  linear inequality constraints

With L in the order of thousands, we end up with millions of constraints...

Successively adding credible contingencies

- solve base DC-OPF in (P1) to find  $\mathbf{p}^*$  and  $\mathbf{f}^*$
- apply LODFs on  $\mathbf{f}^*$  to find flows under contingencies
- if contingency flows are safe, output dispatch  $\mathbf{p}^{*}$
- else, rank outages or individual constraints based on severity of violation
- add only credible contingencies to (P1), resolve, and iterate ...

#### Reserves

With preventive SC-OPF, we assumed there was no time to react

Reserves: generation available to be deployed under contingencies

Categorized as regulating (real-time); spinning (10'); and non-spinning (30'); Enforced system-wide and regionally.

Scheduling of reserves: up-spinning  $R_m^{up}$ ; down-spinning  $R_m^{down}$ 



Available reserves depend on generation; co-optimized with energy schedules

# Corrective SC-OPF

Decides reserves and plans  $\mathbf{p}^k$  for each contingency (AC-OPF versions exist!)

$$\min_{\mathbf{p},\mathbf{r}^{\mathrm{up}},\mathbf{r}^{\mathrm{down}},\{\mathbf{p}^k\}} \quad \sum_{m=1}^{N} C_m(p_m) + C_m^{\mathrm{up}}(r_m^{\mathrm{up}}) + C_m^{\mathrm{down}}(r_m^{\mathrm{down}})$$
(1)

s.to 
$$\underline{\mathbf{p}} \leq \mathbf{p} \leq \overline{\mathbf{p}}; \mathbf{1}^{\top} \mathbf{p} = 0; -\overline{\mathbf{f}} \leq \mathbf{S} \mathbf{p} \leq \overline{\mathbf{f}}$$
 (2)

$$\underline{\mathbf{p}} \le \mathbf{p} - \mathbf{r}^{\text{down}}; \ \mathbf{p} + \mathbf{r}^{\text{up}} \le \overline{\mathbf{p}}$$
(3)

$$\underline{\mathbf{p}}^{k} \leq \mathbf{p}^{k} \leq \overline{\mathbf{p}}^{k}; \mathbf{1}^{\top} \mathbf{p}^{k} = 0; -\overline{\mathbf{f}}^{k} \leq \mathbf{S}^{k} \mathbf{p}^{k} \leq \overline{\mathbf{f}}^{k}$$
(4)

$$\mathbf{p} - \mathbf{r}^{\text{down}} \le \mathbf{p}^k \le \mathbf{p} + \mathbf{r}^{\text{up}}$$
(5)

- (1): generation and reserve cost
- (2): network constraints for base case
- (3): reserve levels
- (4)–(5): network constraints and adjustments for credible contingency k