

Lec 25 Friday March 19

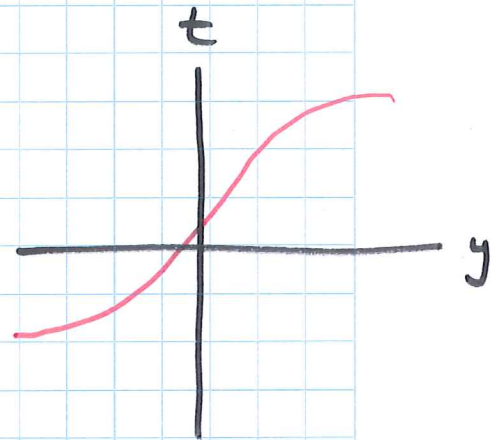
Sufficiency with "The Correct" Notation ...

Y, T jointly distributed with param θ

$$f_{Y|T; \theta}(y|t) = \frac{f_{Y, T; \theta}(y, t)}{f_{T; \theta}(t)}$$

Then interested in case $T = T(Y)$

$$f_{Y, T; \theta}(y, T(y)) = f_{Y; \theta}(y)$$



Generally have

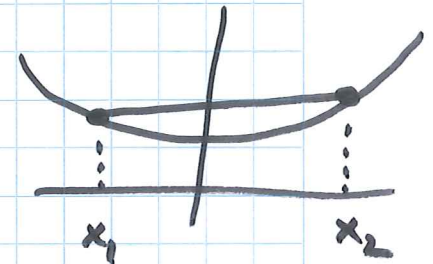
$$f_{Y, T; \theta}(y, T(y)) = f_{Y; \theta}(y) = \underbrace{f_{Y|T; \theta}(y|T(y))}_{\text{circled}} f_{T; \theta}(T(y))$$

This is sufficient if this does not depend on θ

Jensen's Inequality

A function $f(x)$ is convex over (a, b) if for every $x, y \in (a, b)$ and $0 \leq \lambda \leq 1$

$$f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2)$$



Strictly convex if equality holds only for $\lambda = 0$ or $\lambda = 1$.

Jensen: f is a convex function and X is a random variable then

$$f(EX) \leq Ef(X)$$

Moreover, if f is strictly convex then equality implies $X = EX$ with prob. one.

Proof for Discrete Distributions

Go by induction on the # of mass points in dist.

Say $X \in \{x_1, x_2, x_3, \dots\}$

$$p_k = P(X = x_k)$$

Suppose 2 mass points

$$E f(X) = p_1 f(x_1) + p_2 f(x_2)$$

$$f(EX) = f(p_1 x_1 + p_2 x_2)$$

$$\begin{aligned} p_i &\geq 0 \\ p_1 + p_2 &= 1. \end{aligned}$$

Assume J.I. true \forall dists having $n-1$ mass pts.

Consider a case

$$P(X = x_k) = p_k \quad k = 1, 2, \dots, n \quad \sum_{k=1}^n p_k = 1$$

Write $p'_i = \frac{p_i}{1-p_n} \quad 1 \leq i \leq n-1$

$$\sum_{i=1}^n p_i f(x_i) = p_n f(x_n) + (1-p_n) \sum_{i=1}^{n-1} p'_i f(x_i)$$

$$\geq p_n f(x_n) + (1-p_n) f\left(\sum_{i=1}^{n-1} p'_i x_i\right).$$

By
induction

$$\geq f\left(p_n x_n + (1-p_n) \sum_{i=1}^{n-1} p'_i x_i\right)$$

$$\underbrace{\sum_{i=1}^{n-1} p_i x_i}$$

This actually proves
Jensen for any ^{discrete} rv. with
a dist. having finite support

Back to Est. in Classical Setup

Y rand. var. $\in \Gamma$ $Y \sim f_{\theta}(y)$ $\theta \in \Lambda$

θ is merely unknown $\Lambda = \mathbb{R}, \mathbb{R}^m$

Seek a "good" estimate $\hat{\theta}(y)$

↳ try to minimize some average error criterion.

Say squared error ...

Since there is no prior for θ we can only look @ conditional risks ...

$$R_{\theta}(\hat{\theta}) = E_{\theta} \left\{ (\hat{\theta}(Y) - \theta)^2 \right\} \quad \theta \in \Lambda$$

$$E_{Y; \theta}$$

Cannot generally expect to minimize $R_{\theta}(\hat{\theta})$ uniformly for $\theta \in \Lambda$.

Example Let's pick parameter value $\theta_0 \in \Lambda$
define an estimator

$$\hat{\theta}(y) = \theta_0 \quad \forall y \in \mathcal{Y}$$

$$\Rightarrow R_{\theta_0}(\hat{\theta}) = 0$$

but performance could be quite poor for $\theta \neq \theta_0$.

Must come up with a way to exclude estimators such as $\hat{\theta}$ above.

A reasonable restriction:

$$E_{\theta} \{ \hat{\theta}(Y) \} = \theta \quad \forall \theta \in \Lambda$$

such is called unbiased.

and if this holds then

$$\begin{aligned} R_{\theta}(\hat{\theta}) &= E_{\theta} \{ (\hat{\theta}(Y) - \theta)^2 \} \\ &= E_{\theta} \{ (\hat{\theta}(Y) - E_{\theta} \{ \hat{\theta}(Y) \})^2 \} \\ &= \text{Var}_{\theta} \{ \hat{\theta}(Y) \}. \end{aligned}$$

ie MSE is Var.

An unbiased estimator minimizing the MSE for every $\theta \in \Lambda$ is called

minimum variance unbiased estimator (MVUE).

Def.

1) sufficient stat.

2) A function T of Y is said to be minimal sufficient if

* it is sufficient

* it is a function of every other suff. statistic.

\Rightarrow represents the most compression of observations which does not lose any info about θ .

\Rightarrow These sometimes don't exist.

NP Factorization Theorem

A stat. T is suff.

for θ if and only if \exists functions g_θ and h st.

$$f_\theta(y) = g_\theta(T(y)) h(y) \quad \forall y \in \Gamma$$

$$\forall \theta \in \Lambda$$