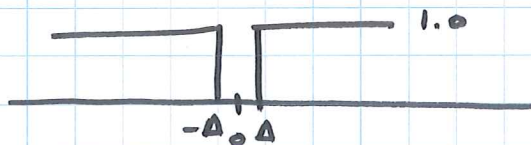


Wednesday
March 10

Lect. 21
FORM C
APPROVED FOR USE IN
PURDUE UNIVERSITY

* No Live Class Monday 3/15 \rightarrow Owe you 2 recorded classes.

Last Time: MAP Estimation



\Rightarrow A reas. approach is to find max of posterior dist of Θ given $Y=y$.

$$w(\theta|y)$$

$$\Rightarrow \underset{\theta}{\operatorname{argmax}} w(\theta|y) \stackrel{\Delta}{=} \hat{\theta}_{\text{MAP}}(y)$$

$$\Rightarrow \frac{\partial}{\partial \theta} w(\theta|y) = 0 \quad \text{solve for } \theta = \hat{\theta}_{\text{MAP}}(y).$$

In all the cases: MMSE, MMAE, MAP our approach in all cases is find cond. dist. of Θ given $Y=y$.

$$w(\theta|y)$$

Our model is

- $\{f_{\theta} : \theta \in \Lambda\}$ of the cond. pdfs. $Y | \Theta = \theta$ $\left. \vphantom{\{f_{\theta} : \theta \in \Lambda\}} \right\} f_{Y|\Theta}(y|\theta)$
- prior dist. on Θ .

To get $w(\theta|y)$ from the given model we use Bayes.

$$w(\theta|y) = \frac{f_{\theta}(y) w(\theta)}{\int_{\Lambda} f_{\theta}(y) w(\theta) d\theta}$$

$$\int_{\Lambda} f_{\theta}(y) w(\theta) d\theta$$

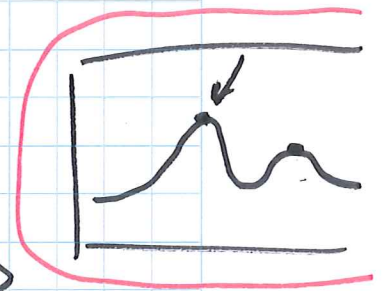
$f_Y(y)$

If interested in MAP don't need to comp. denom.

$$\hat{\theta}_{\text{MAP}}(y) = \underset{\theta}{\operatorname{argmax}} w(\theta|y) = \underset{\theta}{\operatorname{argmax}} f_{\theta}(y) w(\theta)$$

$$\ln = \underset{\theta}{\operatorname{argmax}} \log (f_{\theta}(y) w(\theta))$$

$$= \underset{\theta}{\operatorname{argmax}} \left\{ \log f_{\theta}(y) + \log w(\theta) \right\}$$



Subject to smoothness, a necc. condition for max is

$$\left. \frac{\partial}{\partial \theta} \log f_{\theta}(y) \right|_{\theta = \hat{\theta}_{\text{MAP}}(y)} = - \left. \frac{\partial}{\partial \theta} \log w(\theta) \right|_{\theta = \hat{\theta}_{\text{MAP}}(y)}$$

Called the
MAP Equation

Estimation of Signal Amplitude

$$\Gamma = \mathbb{R}^n \quad \Lambda = \mathbb{R}$$

$$N \sim N(0, \Sigma)$$

$$N \perp \Theta$$

$$Y_k = N_k + \Theta s_k \quad 1 \leq k \leq n$$

$$\Theta \sim N(\mu, \nu^2)$$

s is known.

For all cases want $w(\theta|y)$.

Model $\Theta \sim N(\mu, \nu^2)$

$$Y \sim N(\Theta s, \Sigma) \quad \text{conditioned on } \Theta = \theta.$$

$$w(\theta|y) = \frac{f_{\theta}(y) w(\theta)}{\int_{\Lambda} f_{\theta}(y) w(\theta) d\theta} = \frac{\frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (y - \theta s)^T \Sigma^{-1} (y - \theta s)\right\}}{\frac{1}{\sqrt{2\pi\nu}} \exp\left\{-\frac{(\theta - \mu)^2}{2\nu^2}\right\}} \times$$

denom.

$$= K(y) \exp\left\{-\frac{1}{2} y^T \Sigma^{-1} y + \frac{\theta}{2} s^T \Sigma^{-1} y + \frac{\theta}{2} y^T \Sigma^{-1} s - \frac{1}{2} \theta^2 s^T \Sigma^{-1} s\right\} \times$$

$$\exp\left\{-\frac{1}{2\nu^2} [\theta^2 - 2\theta\mu + \mu^2]\right\}.$$

With a new def. for $K(y) \dots$

$$w(\theta|y) = K'(y) \exp \left\{ -\frac{\theta^2}{2} \left(d^2 + \frac{1}{v^2} \right) + \theta \left(s^T \Sigma^{-1} y + \frac{\mu}{v^2} \right) \right\}$$

$$d^2 = s^T \Sigma^{-1} s$$

Know $w(\theta|y)$ is Gaussian ... exponential of a quadratic
in θ so

$$w(\theta|y) \sim N(m, q^2)$$

$$= \frac{1}{\sqrt{2\pi} q} e^{-\frac{(\theta - m)^2}{2q^2}}$$

$$= \frac{e^{-m^2/2q^2}}{\sqrt{2\pi} q} e^{-\frac{\theta^2}{2} q^{-2} + \theta m q^{-2}}$$

Equate terms

$$q^2 = \left(d^2 + \frac{1}{v^2} \right)^{-1} \quad m = \left(d^2 + \frac{1}{v^2} \right)^{-1} \left(s^T \Sigma^{-1} y + \frac{\mu}{v^2} \right)$$

$$K'(y) = \frac{e^{-m^2/2q^2}}{\sqrt{2\pi} q}$$

Immediately ...

$$\hat{\Theta}_{\text{MMSE}}(y) = \frac{s^T \Sigma^{-1} y + \frac{\mu}{\nu^2}}{d^2 + \frac{1}{\nu^2}} = \frac{\nu^2 d^2 \hat{\Theta}_1(y) + \mu}{\nu^2 d^2 + 1}$$

having defined $\hat{\Theta}_1(y) = s^T \Sigma^{-1} y / d^2$.

Also follows ...

$$\text{MMSE} = E\{\text{Var}\{\Theta | Y\}\} = \frac{1}{d^2 + \frac{1}{\nu^2}} = \frac{\nu^2}{\nu^2 d^2 + 1}.$$

where note $\text{Var}\{\Theta | Y\}$ does not dep. on Y .

Turns out ... also have $\hat{\Theta}_{\text{ABS}}(y) = \hat{\Theta}_{\text{MAP}}(y) = \hat{\Theta}_{\text{MMSE}}(y)$.

Interpretation: $\hat{\Theta}_{\text{MMSE}}(y) = \frac{v^2 d^2 \hat{\Theta}_1(y) + \mu}{v^2 d^2 + 1}$

v^2 determines accuracy of prior knowledge about Θ

d^2 is a meas. of quality with which s can be distinguished from $N(0, \Sigma)$ noise.

① $v^2 d^2$ is small. $\Rightarrow \hat{\Theta}_{\text{MMSE}}(y) \approx \mu$

② $v^2 d^2$ is large $\Rightarrow \hat{\Theta}_{\text{MMSE}}(y) \approx \hat{\Theta}_1(y)$ estimate driven by obs. of not prior model.
MSE $\approx 1/d^2$

Special Case:

$$\Sigma = \sigma^2 \mathbf{I} \quad s = [1, 1, 1, \dots, 1] \quad v^2 d^2 = n v^2 / \sigma^2$$

$$\hat{\Theta}_1(y) = \frac{1}{n} \sum_{k=1}^n y_k.$$