

Friday 2/19 L13

## Discrete Time Detection

$$H_0: Y_k = N_k + S_{0k} \quad 1 \leq k \leq n$$

vs

$$H_1: Y_k = N_k + S_{1k} \quad 1 \leq k \leq n$$

$$Y = [Y_1 \dots Y_n]^T$$
$$N = [N_1 \dots N_n]^T$$

$$S_0 = \dots$$
$$S_1 = \dots$$

Signal characterization is one of 3 types:

- 1)  $S_0$  &  $S_1$  known (deterministic)
- 2)  $S_0$  &  $S_1$  known except for some params.
- 3)  $S_0$  &  $S_1$  random and only know prob. distributions

Noise characterization

- 1) Noise indep of sigs under either hyp.
- 2) Noise distribution does not dep. on hyp.
- 3) Noise dist. given by a density or pmf

$$f_N(\cdot) \quad \text{domain } \mathbb{R}^n$$

## Likelihood Ratio

$$H_0: \text{pdf of } Y \text{ given } S_0 = s_0 \quad f_0(y | S_0 = s_0) \\ = f_N(y - s_0)$$

$\Rightarrow$  uncond. dist. of  $Y$  is

$$f_0(y) = E\{f_N(y - S_0)\}$$

$$\text{Similarly under } H_1, \Rightarrow f_1(y | S_1 = s_1) = f_N(y - s_1)$$

$$f_1(y) = E\{f_N(y - S_1)\}$$

$\Rightarrow$  Likelihood Ratio

$$L(y) = \frac{f_1(y)}{f_0(y)} = \frac{E\{f_N(y - S_1)\}}{E\{f_N(y - S_0)\}}$$

Thresholds still found from

$$\bar{L} = \frac{\pi_0}{\pi_1} \frac{c_{10} - c_{00}}{c_{01} - c_{11}} \quad \text{for Bayes}$$

or

$\gamma \rightarrow$  found from  $P_{FA} = \alpha$  for NP.

Adding Assumptions to Get more specific detectors

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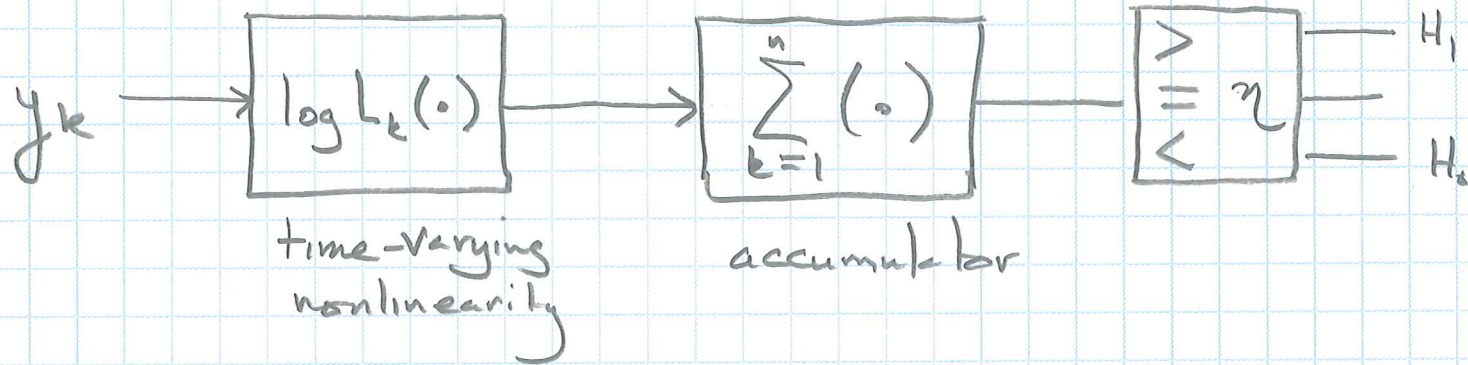
### Det. Sigs in Indep Noise

$$L(y) = \frac{f_N(y - s_1)}{f_N(y - s_0)} = \frac{f_N(y_1 - s_{11}, y_2 - s_{12}, \dots, y_n - s_{1n})}{f_N(y_1 - s_{01}, y_2 - s_{02}, \dots, y_n - s_{0n})}$$

If indep. then factors  $\rightarrow$

$$= \prod_{k=1}^n \frac{f_{N_k}(y_k - s_{1k})}{f_{N_k}(y_k - s_{0k})} \rightarrow L_k(y_k)$$

Take Log get a detector structure

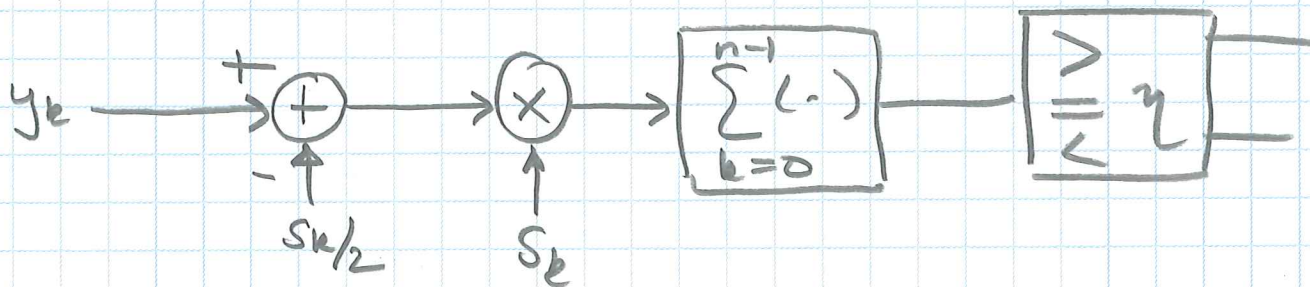


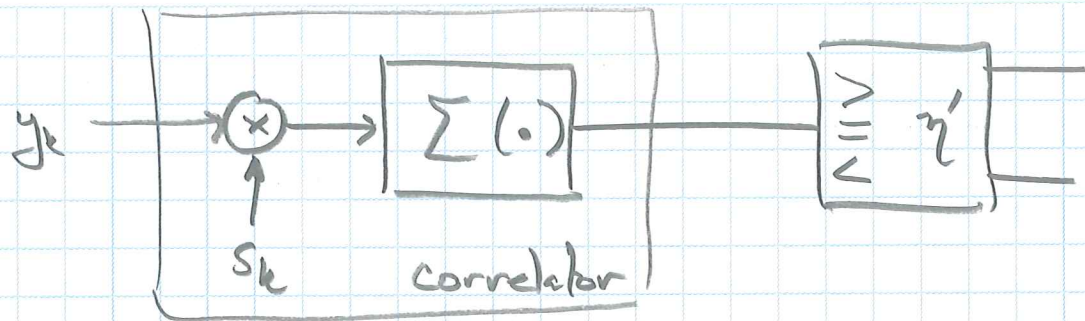
Coherent Detection in IID Noise  $\rightarrow H_0: Y_k = N_k + S_k \quad k=0,1,2,\dots,n-1$

$$N_k \sim \mathcal{N}(0, \sigma^2) \quad \text{iid}$$

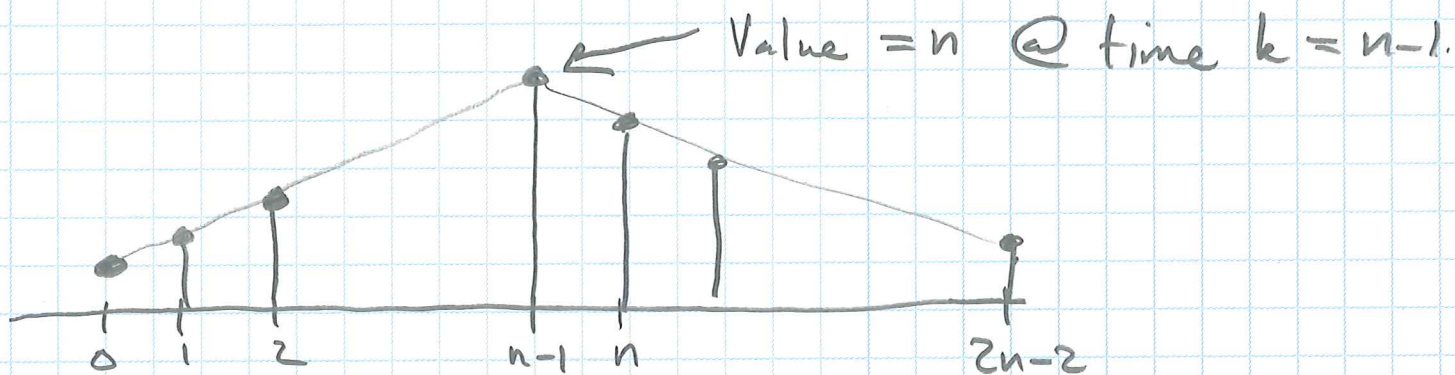
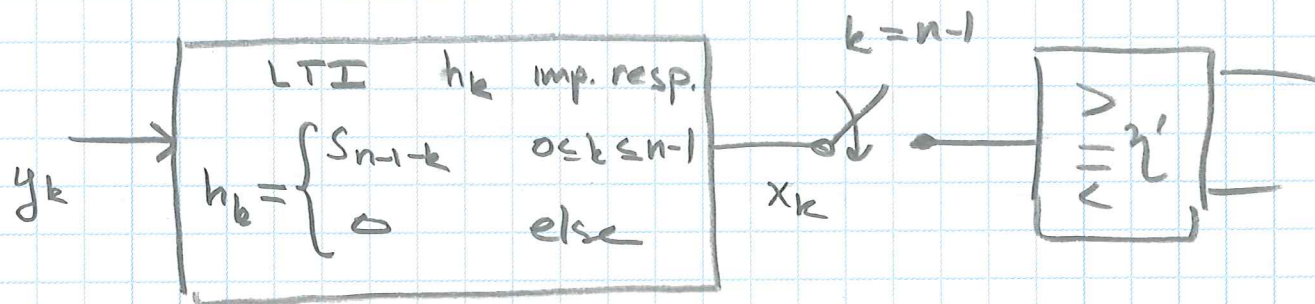
$$s_0 = 0 \quad s_1 = s$$

$$\Rightarrow \log L_k(y_k) = s_k (y_k - s_k/2) / \sigma^2$$





This can be seen as a matched filter.



Max SNR Prop

$$X_{n-1} = \sum_{l=0}^{n-1} h_{n-1-l} Y_l$$

$\underbrace{\hspace{10em}}_{S_e + N_e}$

SNR @ filter @ Sampling Time

$$= \frac{(E\{X_{n-1}\})^2}{\text{Var}\{X_{n-1}\}} = \frac{\left(\sum_{l=0}^{n-1} h_{n-1-l} S_e\right)^2}{\text{Var}\left\{\sum_{l=0}^{n-1} h_{n-1-l} N_e\right\}}$$

Can show:  $SNR_{\max} = \frac{\sum_{l=0}^{n-1} S_e^2}{\sigma^2}$

is achieved for  $h_m = S_{n-1-m}$   $m=0, 1, \dots, n-1$ .

## LMP Detection in IID Noise $\longrightarrow$ HW?

(To fill in yet.)

### Deterministic Signals in Gaussian Noise

- Model:

$$H_0 : Y_k = N_k + s_{0k} \quad 1 \leq k \leq n$$

vs.

$$H_1 : Y_k = N_k + s_{1k} \quad 1 \leq k \leq n$$

where:

- $s_0$  and  $s_1$  are known  $n \times 1$  deterministic vectors
- $N \sim \mathcal{N}(0, \Sigma)$  is a zero mean Gaussian noise of dimension  $n \times 1$ .

- Likelihood ratio is

$$\begin{aligned} L(y) &= \frac{\frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (y - s_1)^T \Sigma^{-1} (y - s_1) \right\}}{\frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (y - s_0)^T \Sigma^{-1} (y - s_0) \right\}} \\ &= \exp \left\{ (s_1 - s_0)^T \Sigma^{-1} \left( y - \frac{s_0 + s_1}{2} \right) \right\} \end{aligned}$$

for  $y \in \mathcal{R}^n$ .

- Detector structure is the same as for the i.i.d. noise case since the decision rule is of the form

$$\delta(y) = \begin{cases} 1 & > \\ \gamma \overset{\zeta^T}{(s_1 - s_0)^T \Sigma^{-1} y} & = \eta \\ 0 & < \end{cases}$$

where  $\eta$  is picked either to satisfy a false alarm constraint or via the Bayes formulation<sup>2</sup>.

- If define *pseudo signal*  $\tilde{s}_k$  via  $\tilde{s} = \Sigma^{-1}(s_1 - s_0)$  then have same correlator as in i.i.d. case (but for a modified signal).

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<sup>2</sup>For Bayes  $\eta$  would be chosen

$$\eta = \log \left[ \frac{\pi_0(c_{10} - c_{00})}{\pi_1(c_{01} - c_{11})} \right] + (s_1 - s_0)^T \Sigma^{-1} \left( \frac{s_1 + s_0}{2} \right).$$