

EE538

DSPI

Module 29

Outline

- Unconstrained Least Squares AR Spectral Estimation: Sect. 12.3.4
 - Refinement: backward prediction - Sect. 11.2.2
- Two-Step ARMA Spectral Estimation
 - Sect. 12.3.8 - see demo
ARMA2stepest.m

• consider $m = p+1$ with $x[n]$ an AR(p) process

$$\cdot a_{p+1}(p+1) = K_{p+1} =$$

$$- \left[r_{xx}[p+1] + \sum_{k=1}^p a_p(k) r_{xx}(p+1-k) \right]$$

• thus, for $m > p$, if $x[n]$ is AR(p):

$$a_m(k) = a_p(k), \quad k = 1, 2, \dots, p$$

$$a_m(k) = 0, \quad k = p+1, \dots, m$$

• ϵ_p^{\min} monotonically decreases until $\epsilon_p^{\min} = \sigma_w^2$ and $\epsilon_m^{\min} = \sigma_w^2$ for $m > p$

- Unconstrained Least Squares (LS) Method for Estimating AR Model Parameters

- showed that AR spectral estimation is inherently related to linear prediction

- consider replacing expected value of prediction error by a time-averaged estimate of prediction error

$$\hat{\epsilon} = \frac{1}{N-p} \sum_{n=p}^{N-1} \left| x[n] + \sum_{k=1}^p a_k x[n-k] \right|^2$$

- recall: $x[n] \neq 0$ for $0 \leq n \leq N-1$
- rationale for limits on summation:
- lower limit: $n=p$. require P nonzero past values to predict $x[n]$ or have larger than "normal" error
- upper limit: $n=N-1$. nonsensical to $\hat{0}$ from P past values $N-1 < n < N+p-1$
Predict

- assume $x[n]$ is real-valued for sake of simplicity

- take partial wrt a_l , $l=1, \dots, P$ and set equal to 0 to obtain P equations in P unknowns

$$\frac{\partial \hat{\epsilon}}{\partial a_l} = \frac{1}{N-P} \sum_{n=p}^{N-1} 2 \left\{ x[n] + \sum_{k=1}^P a_k x[n-k] \right\} x[n-l] = 0$$

- rearranging:

$$\sum_{k=1}^P a_k \frac{1}{N-P} \sum_{n=p}^{N-1} x[n-k] x[n-l] = - \sum_{n=p}^{N-1} x[n] x[n-l]$$

• in matrix form: $\hat{\underline{R}}^{LS} \hat{\underline{a}} = -\hat{\underline{r}}^{LS}$

$P \times P$ $P \times 1$ $P \times 1$

• where:

$$\hat{R}_{k,l}^{LS} = \frac{1}{N-P} \sum_{n=p}^{N-1} x[n-k] x^*[n-l]$$

$$\hat{r}_l^{LS} = \frac{1}{N-P} \sum_{n=p}^{N-1} x[n] x^*[n-l]$$

$k = 1, \dots, P$
 $l = 1, \dots, P$

• Note: $\hat{\underline{R}}^{LS}$ is not Toeplitz \Rightarrow
can't use Levinson-Durbin algorithm

- P+M Text Terminology:
- Yule-Walker Method: solve $\underline{R} \underline{a} = -\underline{r}$
 where \underline{R} is Toeplitz-Hermitian
 formed from biased time-avg'd
 estimates of autocorrelation sequence
- Unconstrained LS: solve $\underline{\hat{R}}^{LS} \underline{\hat{a}} = -\underline{\hat{r}}^{LS}$
 where $\underline{\hat{R}}^{LS}$ has elements as
 prescribed previously - not Toeplitz!

-
- Unconstrained LS generally performs better than Yule-Walker
 - especially true when the actual spectrum has closely-spaced sharp spectral peaks
 - See Figures 12.6 & 12.7 in P&M Text
 - See demo - matlab file at course web site \Rightarrow YWvsULS.m

• Refinement to Unconstrained LS

• motivation: $\hat{R}^{LS} \xrightarrow{N \rightarrow \infty} \underline{R}$

• where: \underline{R} is Toeplitz-Hermitian

• \underline{R} satisfies: $\underline{I} \underline{R} \underline{I}^* = \underline{R}$

• \underline{I} : reverse permutation matrix
one's along anti-diagonal & zeros elsewhere

$$\underline{I} = \begin{bmatrix} 0 & 0 & \dots & 1 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & \dots & 0 \end{bmatrix}$$

• action of $\underline{\underline{I}}$ on a vector:

$$\underline{\underline{I}} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \quad [1 \ 2 \ 3] \underline{\underline{I}} = [3 \ 2 \ 1]$$

• consider 3×3 example Toeplitz matrix

$$\underline{\underline{R}} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 2 \\ 3 & 2 & 1 \end{bmatrix}; \quad \underline{\underline{I}} \underline{\underline{R}} = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 1 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

$$\underline{\underline{(\underline{\underline{I}} \underline{\underline{R}}) \underline{\underline{I}}}} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 2 \\ 3 & 2 & 1 \end{bmatrix} = \underline{\underline{R}} \quad \checkmark$$

• viewer can verify \textcircled{w} complex example

$$\underline{\underline{I}} \underline{\underline{R}}^* \underline{\underline{I}} = \underline{\underline{R}}$$

• conjugate centro-Hermitian property

• since $\underline{\underline{\hat{R}}}^{LS}$ is asymptotically Toeplitz,

replace $\underline{\underline{\hat{R}}}^{LS}$ by

$$\underline{\underline{\hat{R}}}^{fb} = \frac{1}{2} \left\{ \underline{\underline{\hat{R}}}^{LS} + \underline{\underline{I}} \underline{\underline{\hat{R}}}^{LS*} \underline{\underline{I}} \right\}$$

$$\hat{R}^{fb} = \hat{I} \hat{R}^{fb*} \hat{I}$$

• to prove this, need to use $\hat{I} \hat{I} = \hat{I}$

• show by example:

$$\hat{I} \hat{R}^{fb*} \hat{I} = \hat{I} \left\{ \hat{R}^{ls*} + \hat{I} \hat{R}^{ls} \right\} \hat{I} = \hat{R}^{fb}$$

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \underbrace{\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}}_{\hat{I}}$$

- viewer can see Sect. 11.2.2 for relationship to backward prediction
- note: no computation involved in forming $\underline{\hat{\mathbf{I}}} \hat{\mathbf{R}}^{LS*} \underline{\hat{\mathbf{I}}}$
 - just simple reordering of matrix elements plus conjugation
- thus, formula (12.3.7) in P&M text is deceptive

- again: Unconstrained LS generally outperforms Yule-Walker
 - offers better resolution when power spectrum has closely-spaced sharp spectral peaks

- computational trade-off: can't use Levinson-Durbin algorithm to solve

$$\underline{\hat{R}}^{\text{fb}} \underline{\hat{a}} = \underline{\hat{r}}^{\text{fb}}$$

- However, if we do backward avg. as well as forward-avg. (very little added comp.)

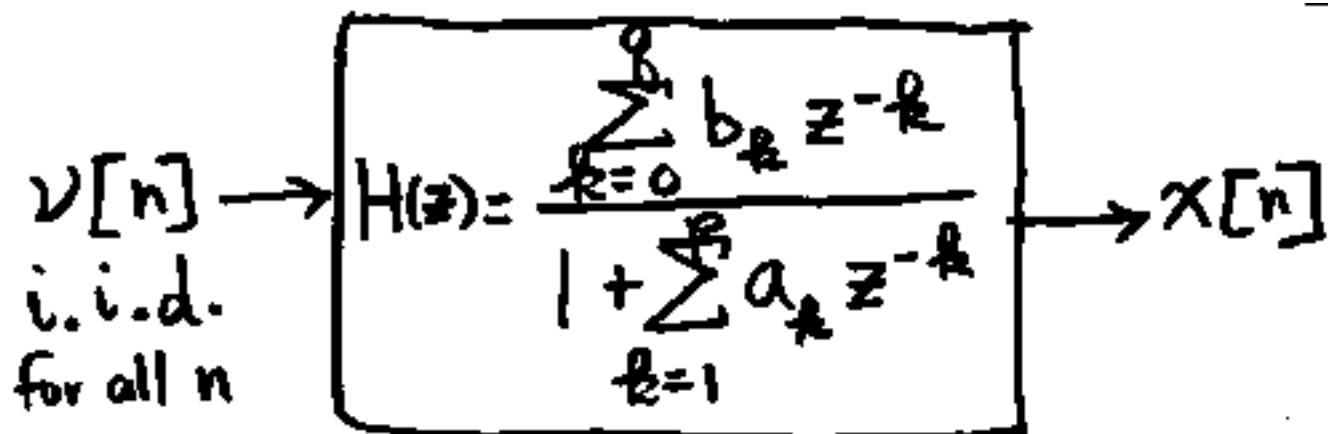
- exploiting this "centro-Hermitian" property, Larry Marple developed a method for solving $\hat{R}^{fb} \hat{a} = \hat{r}^{fb}$ that is similar in complexity to the Levinson-Durbin algorithm

- Reference: "Digital Spectral Analysis" by Larry Marple, Prentice-Hall, ~1991.
- backward avg. offers almost negligible performance improvement \Rightarrow mostly useful for computational reduction

- ARMA Spectral Estimation
- more generally applicable than AR
- power spectrum modeled as rationale:

$$S_{xx}(\omega) = \sigma_w^2 \frac{\left| 1 + \sum_{k=1}^Q b_k e^{-jk\omega} \right|^2}{\left| 1 + \sum_{k=1}^P a_k e^{-jk\omega} \right|^2}$$

- again, for power spectrum estimation, only trying to "match" the power spectrum of a stationary random process



$E\{v[n]v^*[n-m]\} = \sigma_w^2 \delta[m] \quad **$

• in contrast to AR model, there is a nonlinear relationship between

$\Gamma_{xx}[m] = E\{x[n]x^*[n-m]\}$ and

the MA model parameters

$\{b_k, k=1, \dots, p\}$

See Eqn. 12.3.4

- Yet, the AR parameters $\{a_k, k=1, \dots, P\}$ may be solved for via a linear system of equations using $r_{xx}[0], \dots, r_{xx}[P], \dots, r_{xx}[q+P]$
- let's examine $r_{xx}[m]$ for $m > q$

$$E\{x[n]x^*[n-m]\} = E\left\{\left[-\sum_{k=1}^P a_k x[n-k] + \sum_{k=0}^q b_k v[n-k]\right]x^*[n-m]\right\}$$

$$\bullet r_{xx}[m] = - \sum_{k=1}^p a_k r_{xx}[m-k] +$$

$$\sum_{k=0}^q b_k E \left\{ v[n-k] x^*[n-m] \right\}$$

$v[n], \dots, v[n-q]$

contribute

$v[n-m],$
 $v[n-m-1],$
 \vdots

contribute

• for $m > q$, second term is zero. Thus:

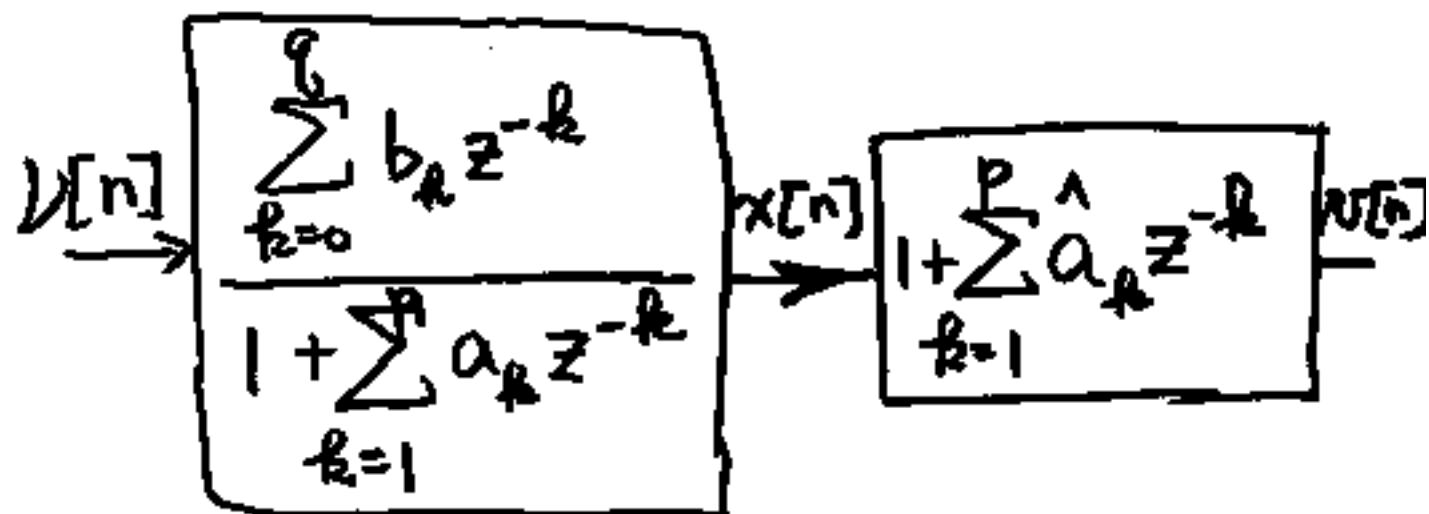
$$r_{xx}[m] = - \sum_{k=1}^p a_k r_{xx}[m-k] \left. \vphantom{\sum_{k=1}^p} \right\} \begin{array}{l} \text{"pee":} \\ \text{upper} \\ \text{limit} \end{array}$$

$$\begin{bmatrix}
 r_{xx}[q] & r_{xx}[q-1] & \dots & r_{xx}[q-p] \\
 r_{xx}[q+1] & r_{xx}[q] & \dots & r_{xx}[q-p+1] \\
 \vdots & \vdots & \dots & \vdots \\
 r_{xx}[q+p-1] & \dots & & r_{xx}[q]
 \end{bmatrix}
 \begin{bmatrix}
 a_1 \\
 a_2 \\
 \vdots \\
 a_p
 \end{bmatrix}
 =
 \begin{bmatrix}
 r_{xx}[q+1] \\
 r_{xx}[q+2] \\
 \vdots \\
 r_{xx}[q+p]
 \end{bmatrix}$$

Toeplitz \Rightarrow but NOT symmetric

• Text states create overdetermined

system of equations - compute LS
 error sol'n. - see p. 935 (12.3.46)



• if $\hat{a}_k = a_k$, then

$$V[n] = \sum_{k=0}^q b_k V[n-k] \quad \left. \begin{array}{l} \text{MA}(q) \\ \text{process} \end{array} \right\}$$

$$\cdot r_{VV}[m] = \sigma_w^2 \sum_{k=0}^q b_k b_{k-m}^*$$

$$\bullet N[n] = \sum_{k=0}^q b_k v[n-k]$$

$$\bullet r_{NN}[m] = E\{N[n] N^*[n-m]\}$$

$$= \sum_{k=0}^q \sum_{l=0}^q b_k b_l^* \underbrace{E\{v[n-k] v^*[n-m-l]\}}_{\sigma_w^2 \delta[k-m-l]}$$

$$= \sum_{k=0}^q b_k b_{k-m}^* \Rightarrow \text{deterministic autocorrelation of } \{b_0, b_1, \dots, b_q\}$$

- thus, $r_{NN}[m] \neq 0$ only
for $|m| \leq q$

$$\hat{S}_{xx}^{ARMA}(\omega) = \frac{\sum_{m=-q}^q \hat{r}_{NN}[m] e^{-j\omega m}}{\left| 1 + \sum_{k=1}^p \hat{a}_k e^{-jk\omega} \right|^2}$$

- See demo: ARMA 2 step est. m