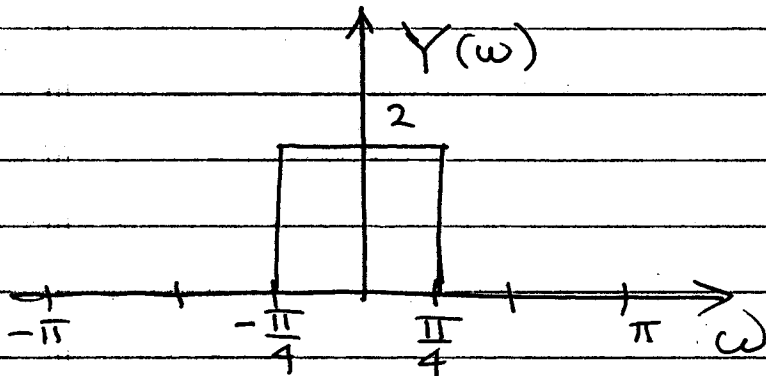
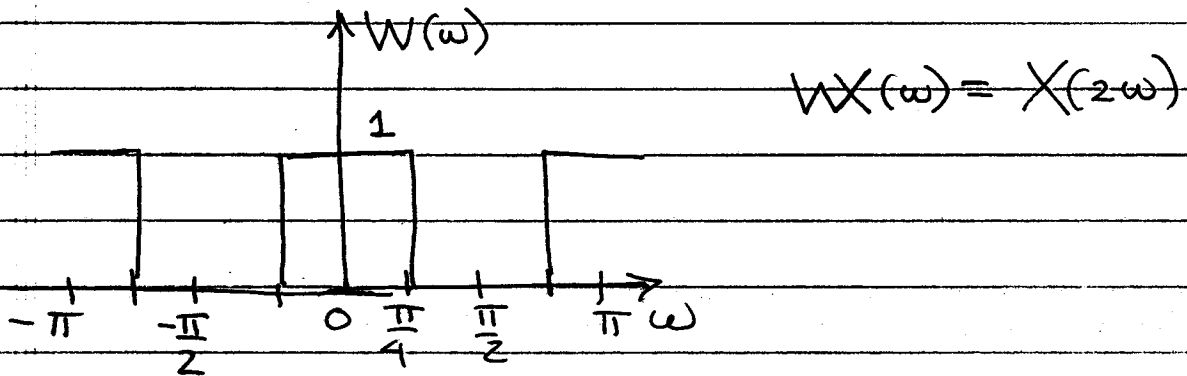
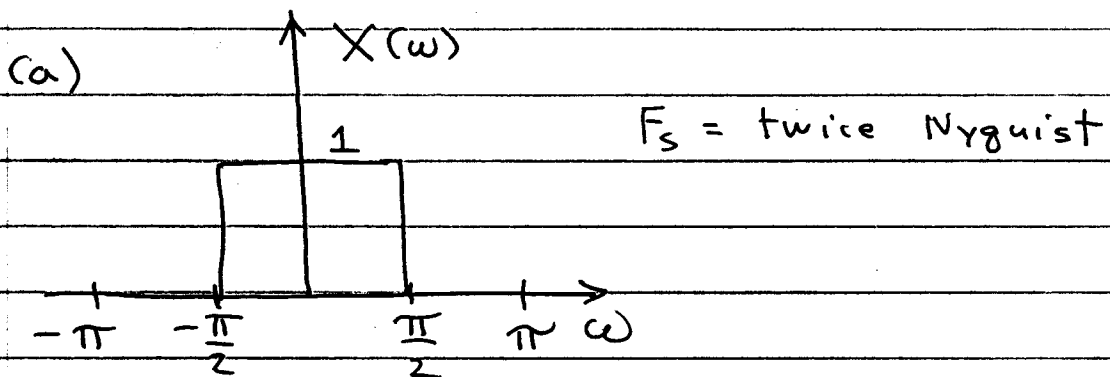


## Solution to Problem 1

1



(b)  $y[n] = 2 \sin\left(\frac{\pi}{4}n\right)$

$\pi n$

$$= \frac{\sin\left(\frac{\pi}{2} \frac{n}{2}\right)}{\pi \frac{n}{2}}$$

$$= X\left[\frac{n}{2}\right]$$

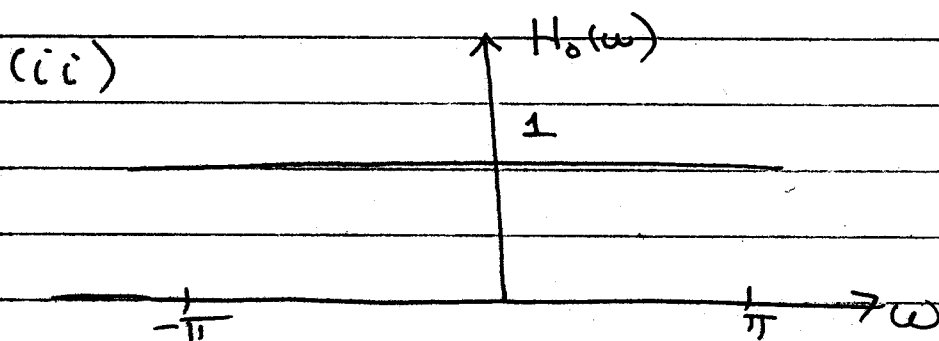
$$-\infty < n < \infty$$

Solution to Prob. 1 (cont.)

(2)

(c)  $h_0[n] = h_{LP}[2n]$

$$\begin{aligned}
 (i) &= \frac{\sin\left(\frac{\pi}{2} 2n\right)}{\frac{\pi}{2} 2n} \cdot \frac{\cos\left(\frac{\pi}{4} 2n\right)}{1 - \frac{(2n)^2}{4}} \\
 &= \frac{\sin(\pi n)}{\pi n} \frac{\cos\left(\frac{\pi}{2} n\right)}{1 - n^2} \\
 &= \delta[n]
 \end{aligned}$$



$$\begin{aligned}
 (iii) \quad y_0[n] &= x[n] * h_0[n] \\
 &= x[n] * \delta[n] \\
 &= x[n] \quad \text{YES}
 \end{aligned}$$

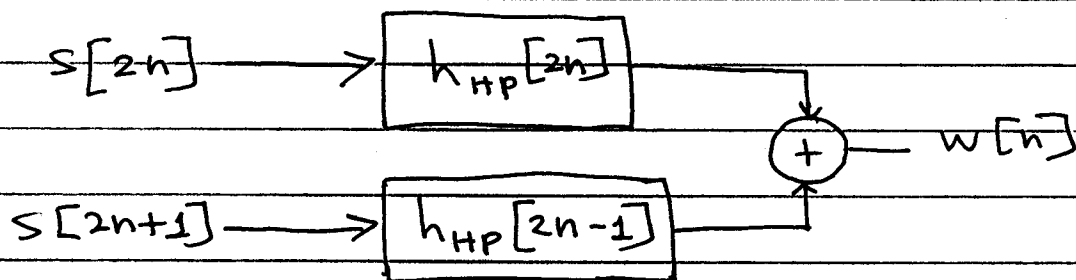
(iv) Don't need to do the convolution of  $x[n]$  with  $h_0[n]$  since  $h_0[n] = \delta[n]$ .  
Need only do convolution of  $x[n]$  with  $h_1[n]$ .

This makes sense since we've upsampled by a factor of 2,  $y[n] = x_a\left(n \frac{T_s}{2}\right)$  where  $T_s = \frac{1}{4W}$ .  
We know  $y_0[n] = y[2n] = x_a\left(2n \frac{T_s}{2}\right) = x[n]$ .  
It's the "in-between" values  $y_1[n] = y[2n+1] = x_a\left(n T_s + \frac{T_s}{2}\right)$  that we need to compute.

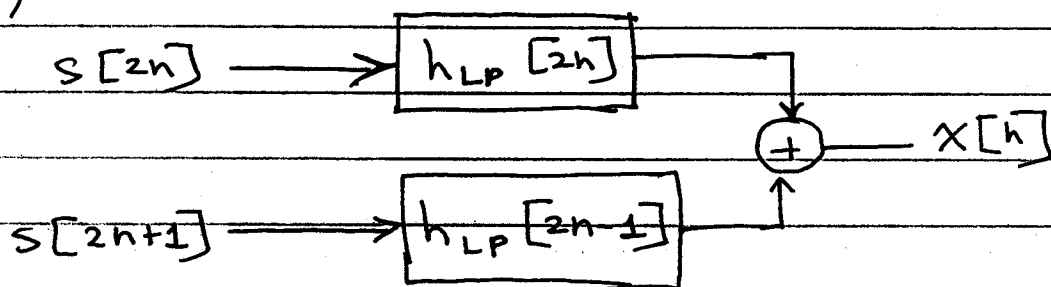
Solution to Problem 2

3

(a)



(b)

Solution to Problem 3

$$(a) \quad \omega_{p0} = 2\pi \frac{20 \text{ K}}{50 \text{ K}} = \frac{4\pi}{5}$$

$$\text{Stage 1} \left\{ \begin{aligned} \omega_{p1} &= \frac{\omega_{p0}}{4} = \frac{\pi}{5} \\ \omega_{s1} &= \frac{2\pi}{4} - \omega_{p1} = \frac{4\pi}{4} - \frac{\pi}{5} = \frac{5\pi}{10} - \frac{2\pi}{10} = \frac{3\pi}{10} \end{aligned} \right.$$

$$\text{Stage 2} \left\{ \begin{aligned} \omega_{p2} &= \frac{\omega_{p1}}{4} = \frac{\pi}{20} \\ \omega_{s2} &= \frac{2\pi}{4} - \omega_{p2} = \frac{\pi}{2} - \frac{\pi}{20} = \frac{10\pi}{20} - \frac{\pi}{20} = \frac{9\pi}{20} \end{aligned} \right.$$

(a) choose  $c=1 \Rightarrow$  then do pre-warping

$$\Omega_c = \tan\left(\frac{\omega_c}{2}\right) = \tan\left(\frac{1}{2} \frac{\pi}{2}\right) \\ = \tan\left(\frac{\pi}{4}\right) = 1$$

$$(b) H(z) = H_a(s) \Big|_{s = \frac{z-1}{z+1}} = \frac{1}{s+1} \Big|_{s = \frac{z-1}{z+1}} \\ = \frac{1}{\frac{z-1}{z+1} + 1} = \frac{z+1}{z-1+z+1} = \frac{z+1}{2z} \\ = \frac{1+z^{-1}}{2}$$

(c) Yes  $\Rightarrow$  bilinear transform maps stable Butterworth analog filter to stable digital filter

$$(d) H(0) = \frac{z+1}{2z} \Big|_{z=1} = \frac{1+1}{2} = 1 \\ H(\omega) \Big|_{\omega=0}$$

$$H(\omega) \Big|_{\omega = \frac{\pi}{2}} = H(z) \Big|_{z = e^{j\frac{\pi}{2}} = j} = \frac{j+1}{2j} = \frac{1-j}{2} = \frac{1}{\sqrt{2}} e^{-j\frac{\pi}{4}}$$

$$H(\omega) \Big|_{\omega = \pi} = H(z) \Big|_{z = -1} = \frac{-1+1}{2(-1)} = 0$$

$$(e) y[n] = \frac{1}{2} x[n] + \frac{1}{2} x[n-1]$$

