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Derivation of Levinson-Durbin

Algorithm:

• m-th order predictor:

$$\underline{R}_m \underline{a}_m = -\underline{r}_m = - \begin{bmatrix} r[1] \\ \vdots \\ r[m] \end{bmatrix} = - \begin{bmatrix} \underline{r}_{m-1} \\ r[m] \end{bmatrix}$$

• for order m-1:

$$\underline{R}_{m-1} \underline{a}_{m-1} = -\underline{r}_{m-1}$$

$$\underline{R}_m = \begin{bmatrix} r[0] & \underline{r}_{m-1}^T \\ \underline{r}_{m-1} & \underline{R}_{m-1} \end{bmatrix}$$

$$\underline{a}_m = -\underline{R}_m^{-1} \underline{r}_m$$

$$\underline{a}_{m-1} = -\underline{R}_{m-1}^{-1} \underline{r}_{m-1}$$

Partitioned matrix inversion lemma:

If $A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$, then

$$A^{-1} = \begin{bmatrix} E^{-1} & -E^{-1}A_{12}A_{22}^{-1} \\ -A_{22}^{-1}A_{21}E^{-1} & A_{22}^{-1} + A_{22}^{-1}A_{21}E^{-1}A_{12}A_{22}^{-1} \end{bmatrix}$$

• where: $E = A_{11} - A_{12}A_{22}^{-1}A_{21}$

• Here: partition \mathbb{R}^m such that $A_{11} = r \times r$ so that E is $|x|$ scalar
 $E^{-1} = 1/E$

and $A_{22} = \mathbb{R}_{m-1}$

Examine E:

$$E = r[0] - \underline{r}_{m-1}^T R_{m-1}^{-1} \underline{r}_{m-1}$$

$$= r[0] - \underline{r}_{m-1}^T (-\underline{a}_{m-1})$$

$$= r[0] + \underline{r}_{m-1}^T \underline{a}_{m-1}$$

$$= r[0] + \sum_{k=1}^{m-1} a_{m-1}(k) r_{xx}[k]$$

$$= \epsilon_{m-1}^{\min}$$

$$E^{-1} = 1 / \epsilon_{m-1}^{\min}$$

(= r_{xx}^* [k]
 for real-valued
 $x[n]$)

(4)

$$R^{-1} = \frac{1}{\epsilon_{m-1}} \begin{bmatrix} 1 & & & & -r_{m-1}^T R_{m-1}^{-1} \\ \vdots & & & & \vdots \\ \hline -R_{m-1}^{-1} r_{m-1} & \epsilon_{m-1} R_{m-1}^{-1} & & & + R_{m-1}^{-1} r_{m-1}^T \\ \vdots & & & & \vdots \\ \hline \vdots & & & & \vdots \\ \hline \vdots & & & & \vdots \end{bmatrix}$$

$$= \frac{1}{\epsilon_{m-1}} \begin{bmatrix} 1 & & & & a_{m-1}^T \\ \vdots & & & & \vdots \\ \hline + a_{m-1} & \epsilon_{m-1} R_{m-1}^{-1} & & & + a_{m-1} a_{m-1}^T \\ \vdots & & & & \vdots \\ \hline \vdots & & & & \vdots \\ \hline \vdots & & & & \vdots \end{bmatrix}$$

Recall reverse permutation matrix

\tilde{I} satisfies $\tilde{I} \tilde{I} = I$

Also: $\tilde{I} R_m \tilde{I} = R_m$ (for real-valued $X(n)$)

Trick: pre-multiply both sides of (5)

$$\underline{a}_m = -R_m^{-1} r_m \text{ by } \underline{I} :$$

$$\underline{I} \underline{a}_m = -\underline{I} R_m^{-1} \underline{I} \underline{I} r_m$$

Since $(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$ and $\underline{I}^{-1} = \underline{I}$

$$\underline{R}_m^{-1} = (\underline{I} R_m \underline{I})^{-1} = \underline{I} R_m^{-1} \underline{I} = R_m^{-1}$$

$$\underline{I} \underline{a}_m = \begin{bmatrix} \underline{a}_m^{(m)} \\ \underline{I} \underline{a}_m^{(1:m-1)} \end{bmatrix} = -R_m^{-1} \begin{bmatrix} r^{(m)} \\ \underline{I} r_{m-1} \end{bmatrix}$$

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Substituting expression for R_m^{-1} :

$$\begin{bmatrix} a_m(m) \\ \tilde{I}_m a(1:m-1) \end{bmatrix} = \frac{-1}{\epsilon_{m-1}^{\min}} \begin{bmatrix} r[m] + \underline{a}_{m-1}^T \tilde{I} r_{m-1} \\ \dots \\ r[m] \underline{a}_{m-1} + (\underline{a}_{m-1}^T \tilde{I} r_{m-1}) \underline{a}_{m-1} \\ \dots \\ + \epsilon_{m-1}^{\min} R_{m-1}^{-1} \tilde{I} r_{m-1} \\ \dots \end{bmatrix}$$

Thus: $a_m(m) = - \frac{\{ r[m] + \underline{a}_{m-1}^T \tilde{I} r_{m-1} \}}{\epsilon_{m-1}^{\min}}$

and:

$$\begin{aligned} \underline{a}_m(1:m-1) &= + a_m(m) \tilde{I} \underline{a}_{m-1} - \tilde{I} R_{m-1}^{-1} \tilde{I} r_{m-1} \\ &= a_m(m) \tilde{I} \underline{a}_{m-1} - \underline{a}_{m-1} \end{aligned}$$

• End of Derivation