

Imaging Processing Pipeline for Color Printers & Printing Systems

Session III

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Outline

- ◉ Device Modeling
 - > Analytical Modeling
 - > Empirical Modeling
 - > Model Inversion
- ◉ Gamut Mapping

Device Modeling

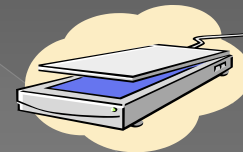
- ◉ How does one build a model of a device?
 - Device Classes
- ◉ Typical device modeling falls into two categories
 - Analytic Modeling
 - Empirical Modeling



◉ Device Classes

Additive Devices

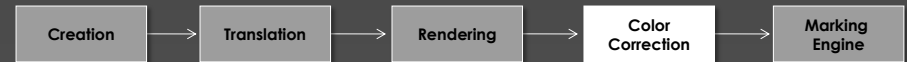
- Displays
- Scanners
- Digital Cameras



Subtractive Devices

- Printers





Common Additive Device Models

> Gain-Offset-Gamma (GOG) Model

$$\{R', G', B'\} = \text{Offset}_{\{R, G, B\}} + (\{R, G, B\} * \text{Gain}_{\{R, G, B\}})^{\text{Gamma}}$$

$$[X, Y, Z]^T = M \cdot [R', G', B']^T$$

> Where M is determined by least squares regression

$$M = (A^T A)^{-1} A^T B$$

Linear Model

$$M = (A^T W A)^{-1} A^T W B$$

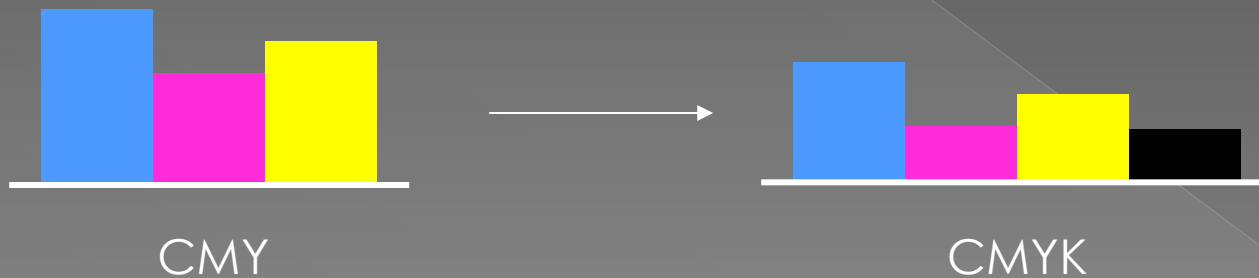
Weighted Linear Model

If higher order coefficients are used (R^2 , G^2 , B^2 , RG , RB , GB , etc.) in A, a higher order polynomial model can be used.

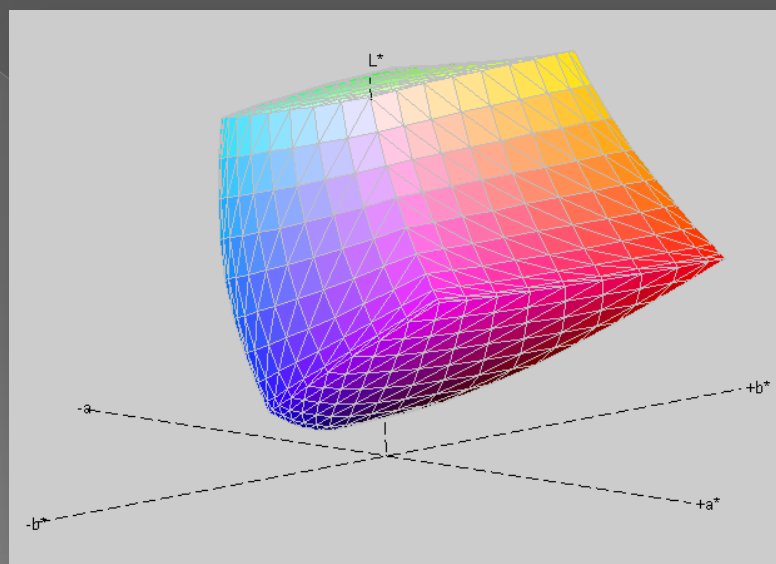
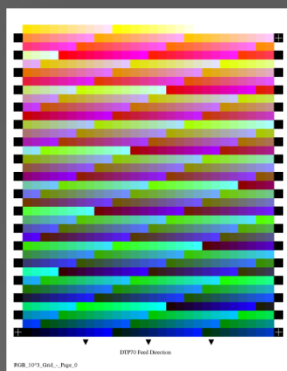


◉ Modeling Subtractive Devices

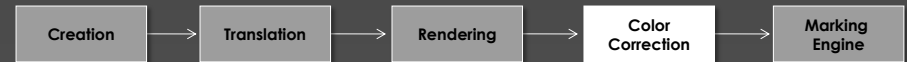
- > To address the full range of colors on a CMYK device would need 256^4 combinations, which is not practical
- > Build a CMY to CMYK transform called a color separation



Many color separation schemes exist



3D Device Model



◉ Analytic Subtractive models

Murray-Davies Equation

Yule-Nielsen Modification

Kubelka-Munk

Neugebauer

Many of these systems perform poorly for complex non-linear models (like printing)



● Murray Davies Equation

$$R(\lambda) = (1 - a)R_w(\lambda) + aR_s(\lambda) \quad \text{where } a \text{ is fractional area coverage } (0 \leq a \leq 1)$$

$$a = \frac{(R_w - R_N)}{(R_w - R_s)}$$

● Yule Nielsen Modification

$$[R(\lambda)]^{\frac{1}{n}} = (1 - a)[R_w(\lambda)]^{\frac{1}{n}} + a[R_s(\lambda)]^{\frac{1}{n}}$$

The KM and Y-N equations are very simple, single colorant models that attempt to model halftoned response



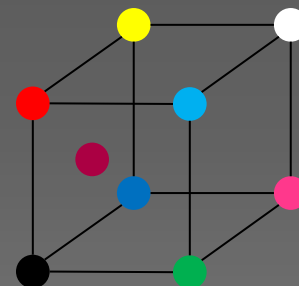
● Neugebauer Equations

- > The Spectral Neugebauer model extends to multiple colorants

$$R(\lambda) = \sum_{j=1}^m a_j R_j(\lambda)$$

Where $m = 2^n$ colorants

$R_j(\lambda)$ = Spectral reflectance of Neugebauer primary



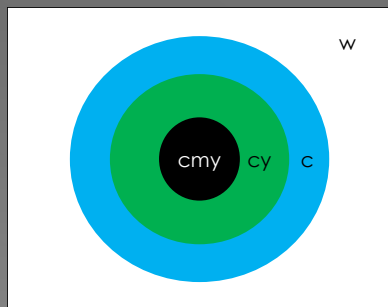
- > The colorant weighting factors (a_j) are computed based on the halftone printing model used



◉ Dot on Dot

Colorants sorted in order of area coverage

White	$a_1 = 1 - c$
1 color	$a_2 = c - y$
2 color	$a_3 = y - m$
3 color	$a_4 = m$



◉ Rotated Screen

Using the Demichel equations, the fractional area coverages are calculated

White	$a_1 = (1-c)(1-m)(1-y)$
Cyan	$a_2 = c(1-m)(1-y)$
Magenta	$a_3 = m(1-c)(1-y)$
Yellow	$a_4 = y(1-c)(1-m)$
Red	$a_5 = my(1-c)$
Green	$a_6 = cy(1-m)$
Blue	$a_7 = cm(1-y)$
Black	$a_8 = cmy$



◉ Empirical Device models

Cellular Neugebauer (Hybrid)

Tetrahedral

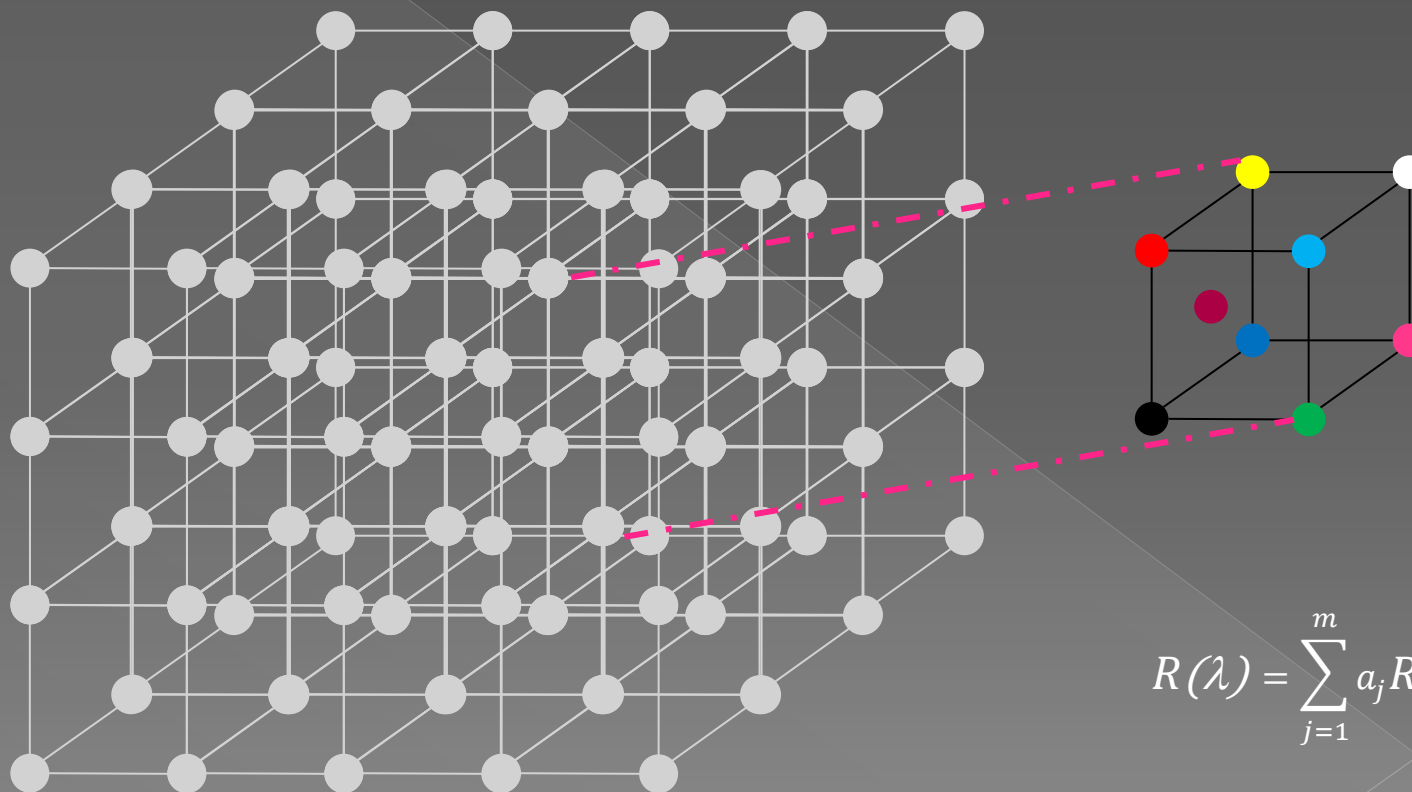
Tri-Linear

Prism

Pyramid



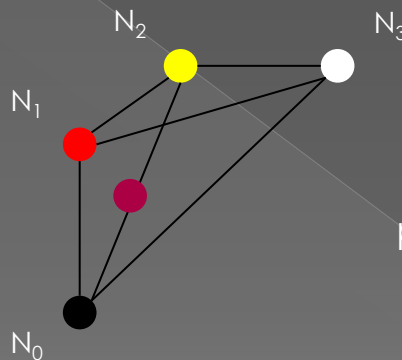
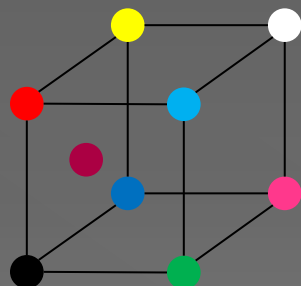
Cellular Neugebauer



$$R(\lambda) = \sum_{j=1}^m a_j R_j(\lambda)$$



Tetrahedral Interpolation

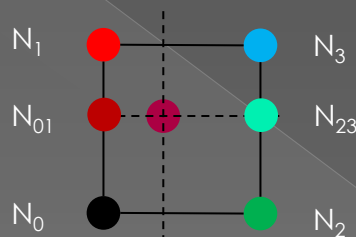
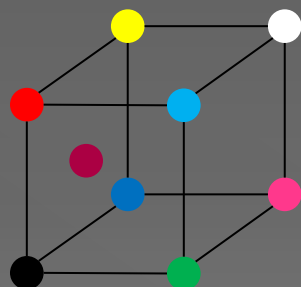


$$p(x,y,z) = N_0 + W_1(N_1 - N_0) + W_2(N_2 - N_0) + W_3(N_3 - N_0)$$

Each interpolation methods has its strengths and weaknesses



Tri-linear Interpolation



$$N_{01} = N_0 + W_1(N_1 - N_0)$$

$$N_{23} = N_2 + W_1(N_3 - N_2)$$

$$p(x,y) = N_{01} + W_2(N_{23} - N_{01})$$

In 2 Dimensions (bi-linear)

Weights W_1 and W_2 are the relative distanced between the nodes
Each interpolation methods has its strengths and weaknesses



○ Interpolation Summary

Method	Strengths	Weaknesses
Cellular Neugebauer	Very accurate multi-dimensional model	Complexity grows quickly as # dimensions increases
Tetrahedral	Preserves color balance for neutral axis interpolation	Identifying tetrahedron is computationally expensive
Tri-Linear	Cannot guarantee neutral axis preservation across diagonal	Computationally efficient

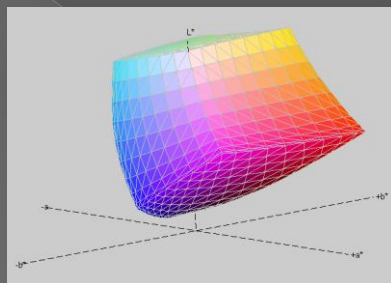


◉ Color Table Inversion

- > One must be able to “round-trip” with a high degree of accuracy



FWD



INV



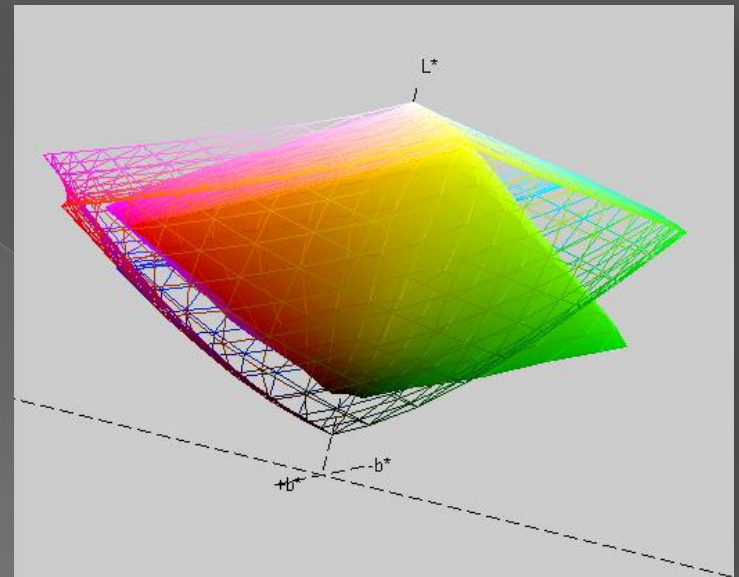
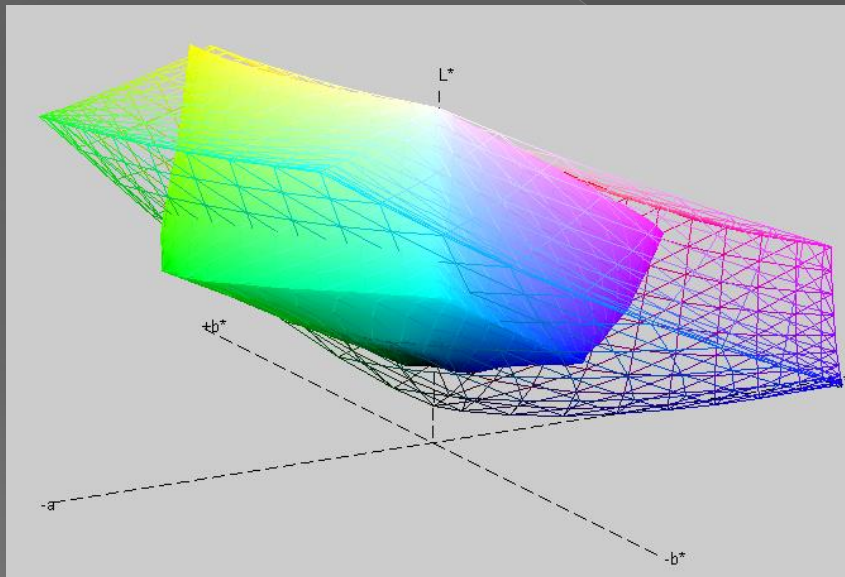
- > The process of building the inverse map is non-trivial, with many-to-one mappings possible
- > Common methods : “Brute force” tetrahedral inversion
Thin-plate splines

Gamut Mapping

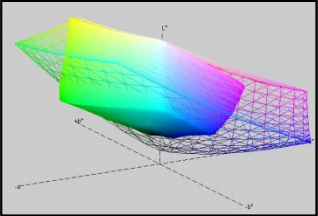
- > Attempting to fit the color gamut of one device into another devices gamut
- > Color appearance models are used to help preserve appearance attributes
- > Different GM algorithms trade the errors in Lightness, Chroma and Hue differently
- > Overall objective is to render a pleasant reproduction



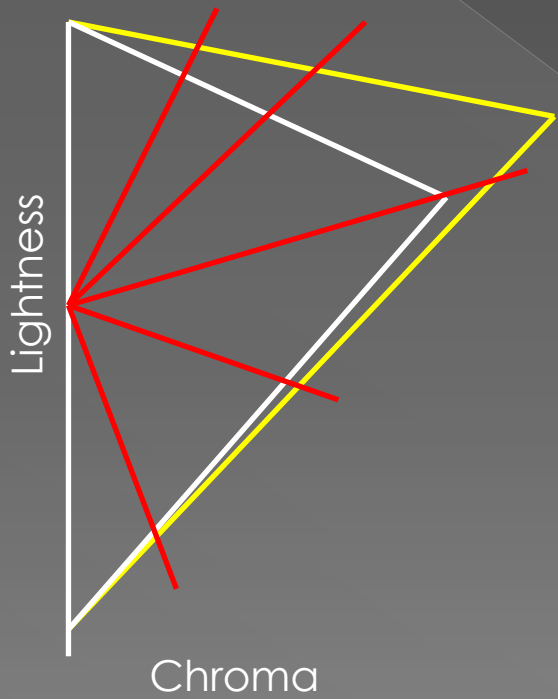
◉ Comparing Device Gamut's



The process of mapping colors from one device to another - **Gamut Mapping**

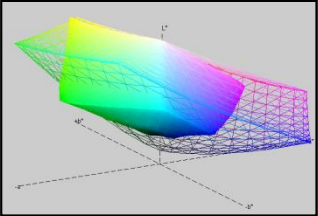


• Centroid

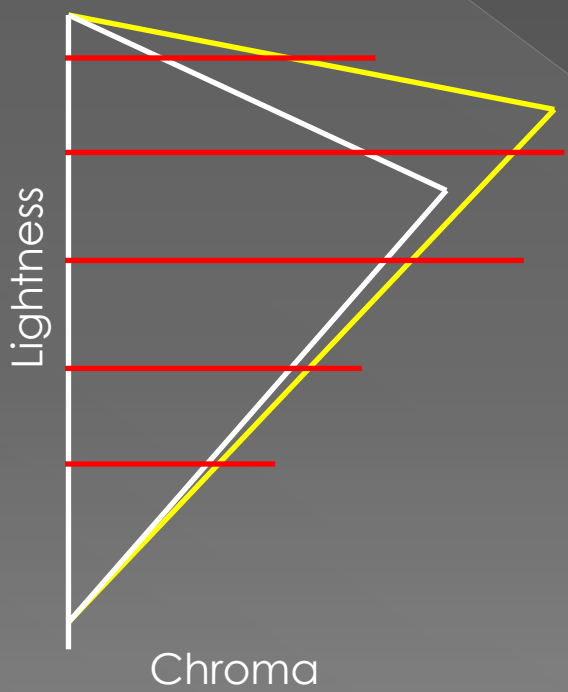


— Source Gamut
— Destination Gamut

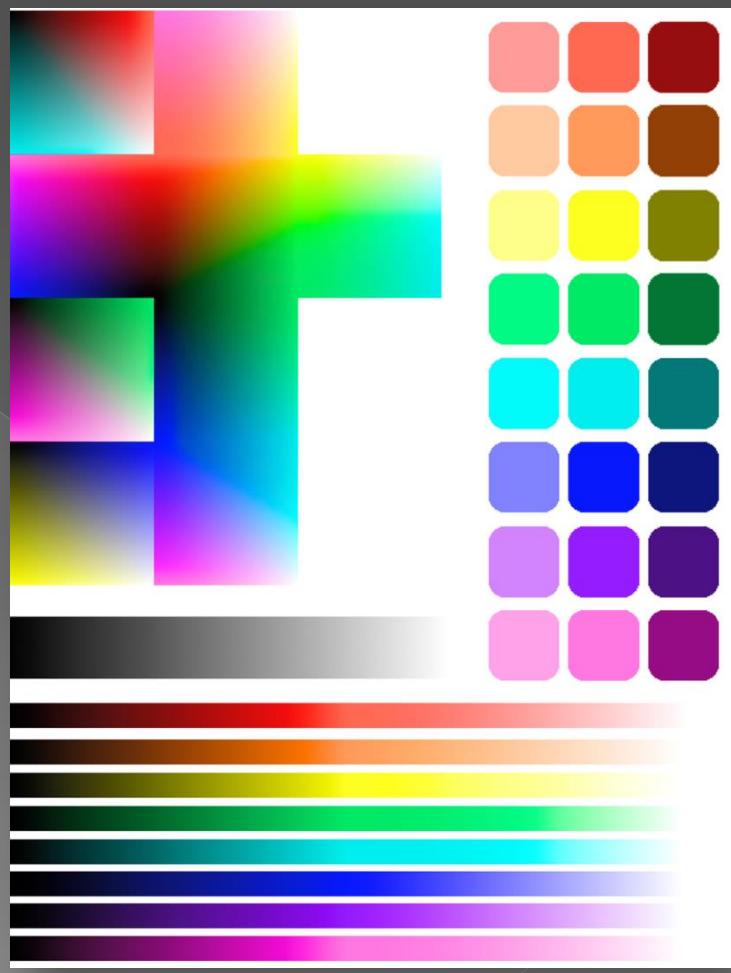


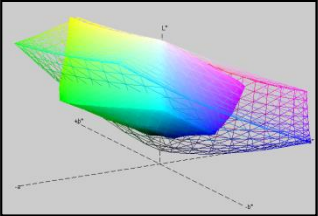


• Constant L^*

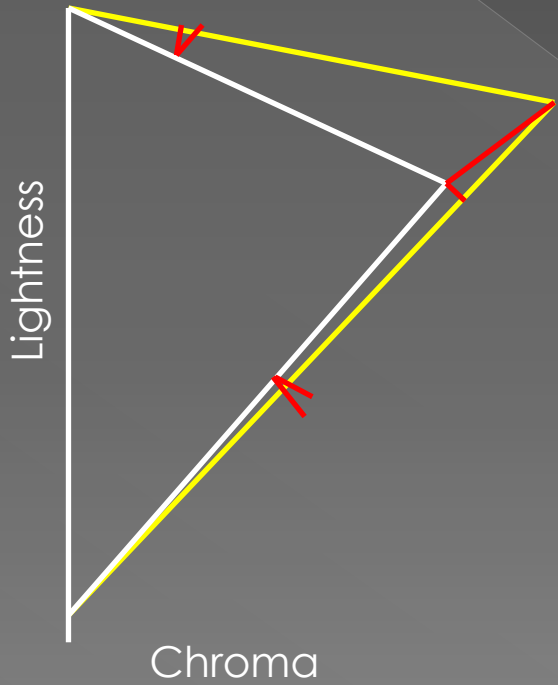


— Source Gamut
— Destination Gamut

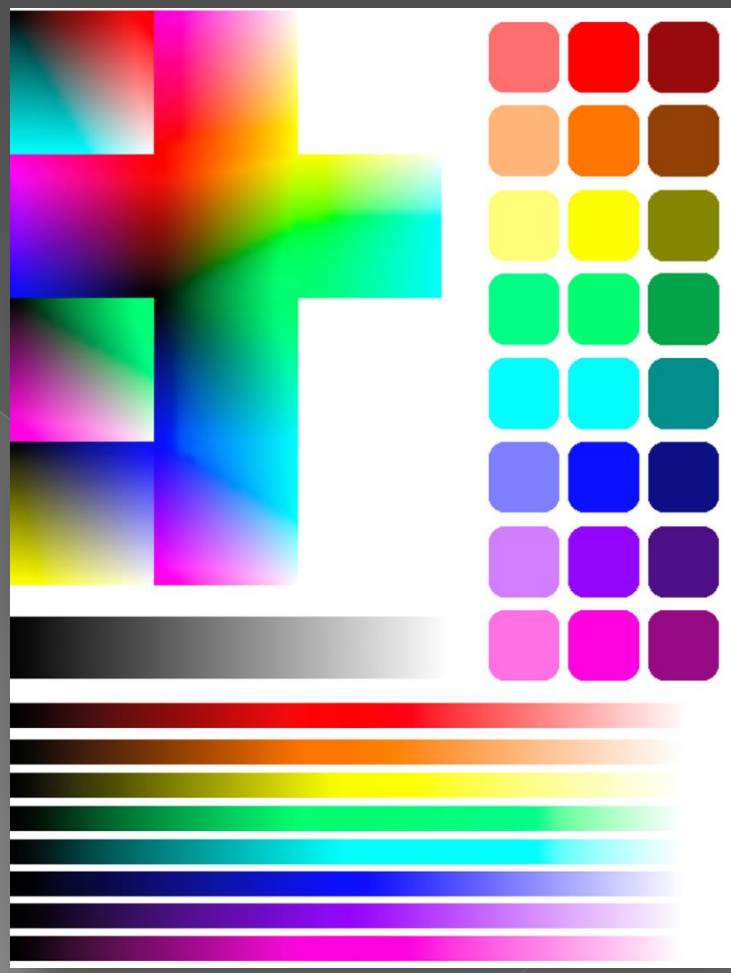




• Min DE



— Source Gamut
— Destination Gamut





Centroid



Constant L^*



Min DE



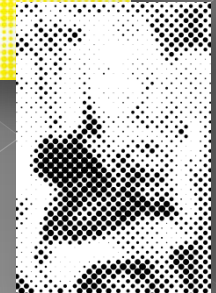
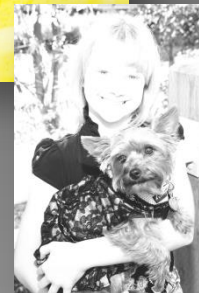
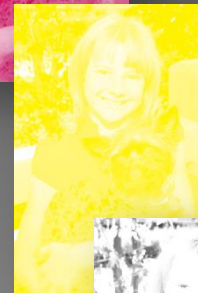
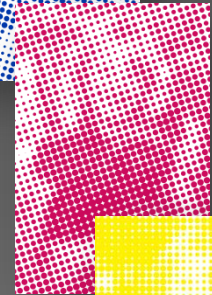
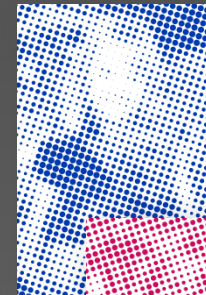
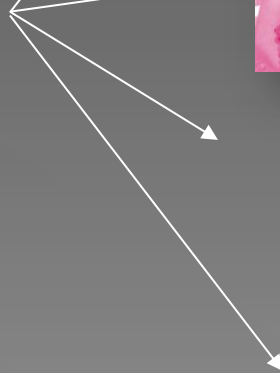
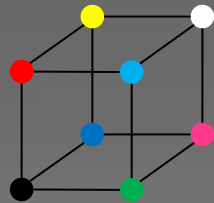


Color Separation

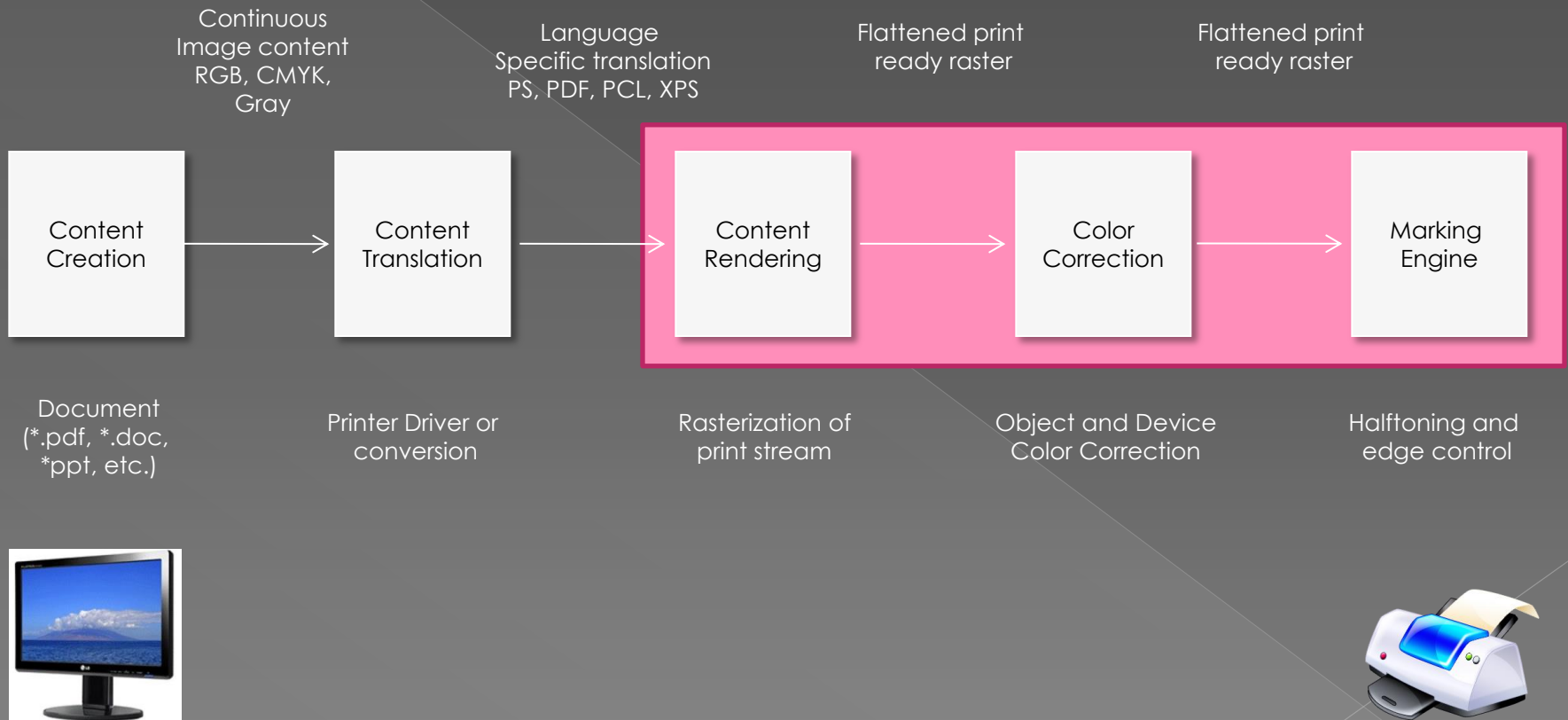
Halftoning and
edge control

Rendering

Color
Management

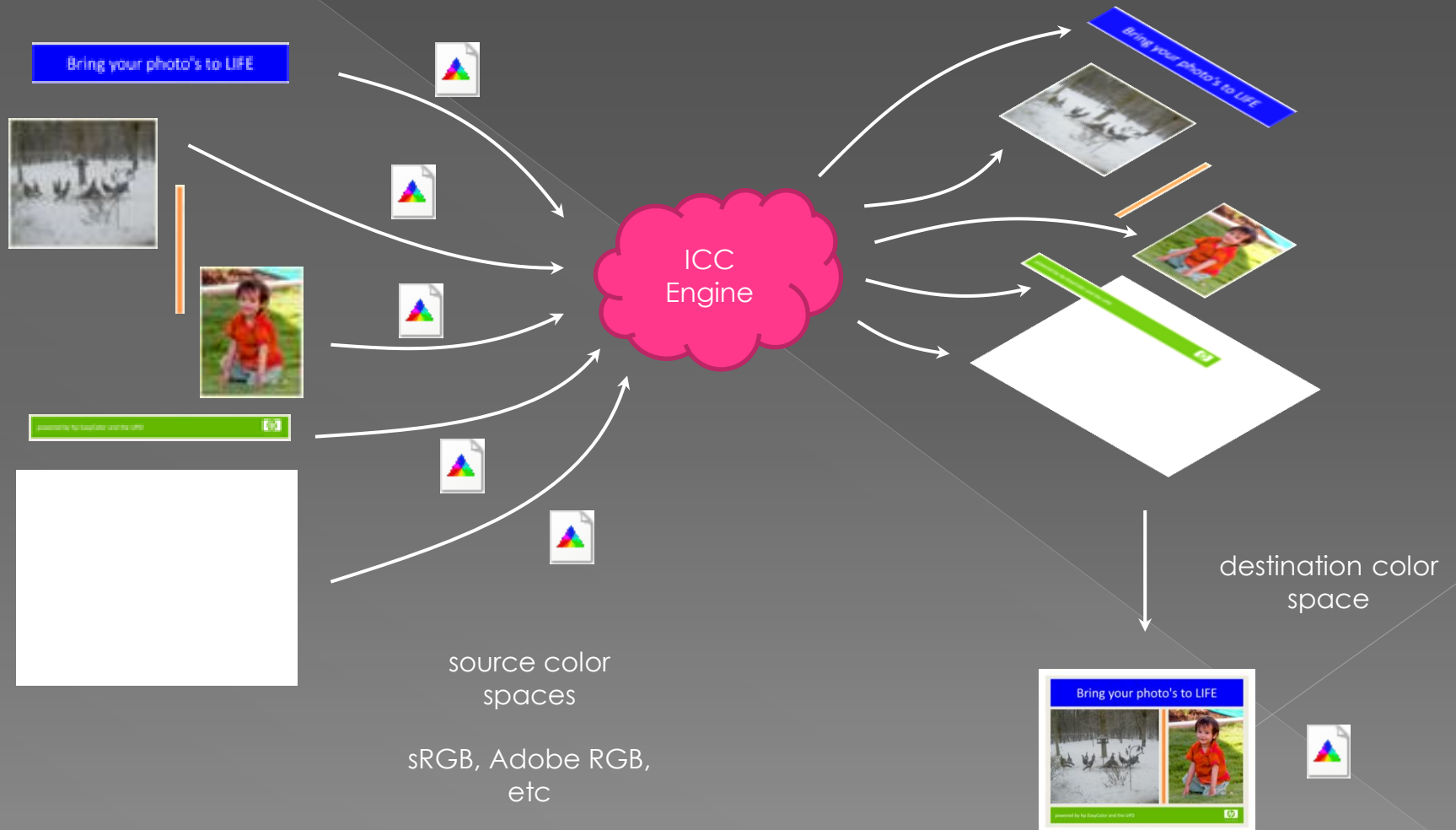
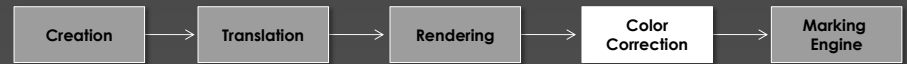


Embedded Systems

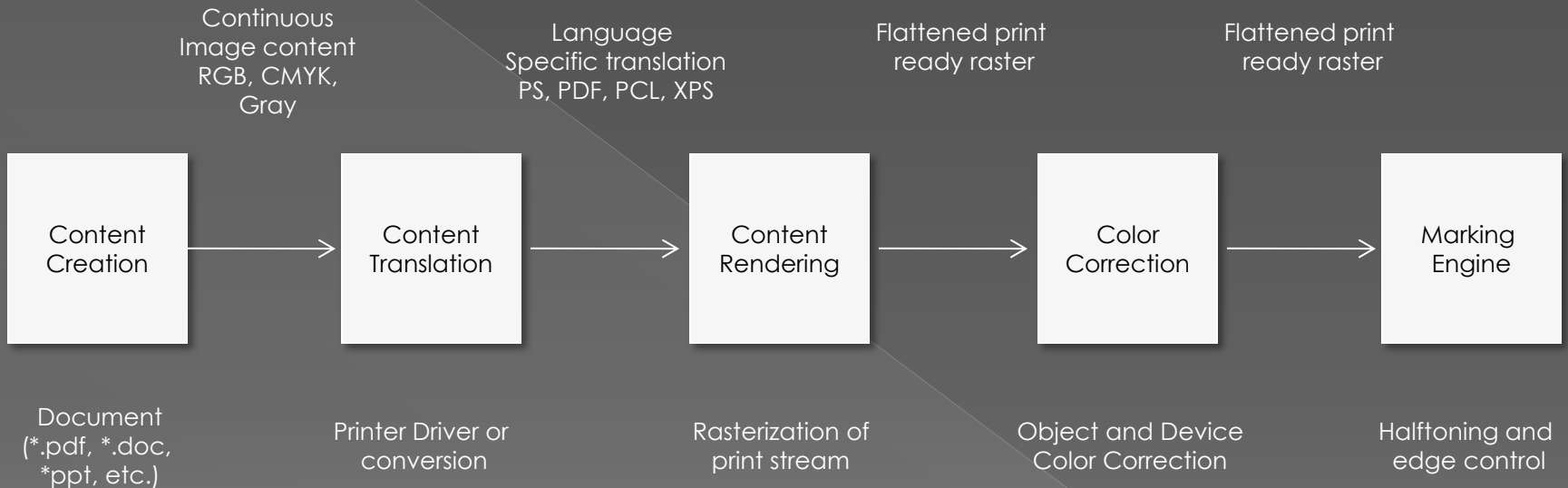


Summary

- End-to-end document imaging workflow
- Content Creation
- Document Translation
- Rendering Stream
- Color Management
- Device Modeling
- Gamut Mapping



Summary



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