

1. For each signal below, do the following:

- i. Sketch $x(t)$ by hand, i.e. don't use Matlab
- ii. State whether it is right-sided, left-sided, or two-sided.
- iii. State whether it is causal, anti-causal, or neither.
- iv. Calculate the metrics E_x , P_x , x_{rms} , M_x , A_x , and x_{avg} by hand.

a. $x(t) = e^t u(-t - 1)$

b. $x[n] = \sum_{k=-\infty}^{\infty} \cos(\pi(n-6k)/6) \{u[n-6k] - u[n-6k-3]\}$

c. $x[n] = e^{(-j-1)\pi n/6} \{u[n] - u[n-12]\}$

2. For each signal $x[n]$ below, do the following:

- i. Use MATLAB to compute the result of the following two filtering operations:

$$y_1[n] = \{x[n] + x[n-1] + x[n-2]\} / 3$$

$$y_2[n] = \{x[n] - x[n-1]\}$$

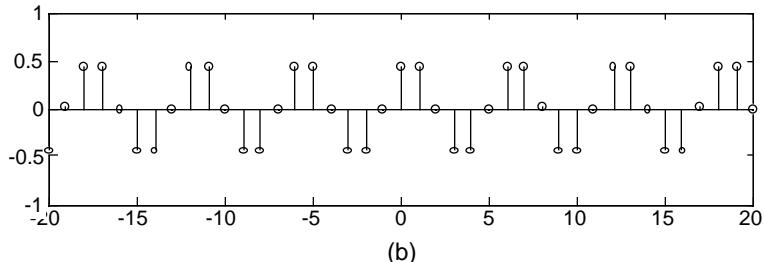
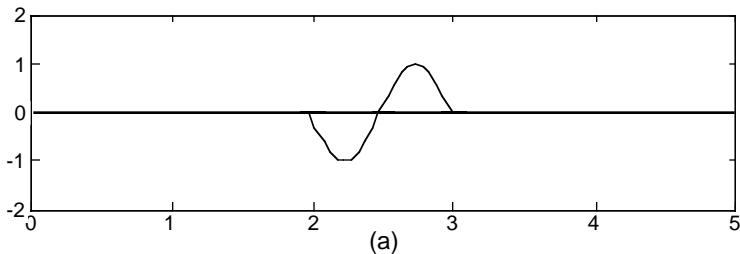
- ii. Use MATLAB to generate stem plots for $x[n]$, $y_1[n]$, and $y_2[n]$ for $-20 \leq n \leq 20$. Plot all three signals on the same page, using the subplot command.

Note: Be sure to turn in printouts of all MATLAB code.

a. $x[n] = \sin(\pi n) / \sin(\pi n / 10)$

b. $x[n] = (1.2)^{-n} \sin(\pi n / 4) u[n]$

3. Express each signal shown below in terms of standard functions. Note that the signal for part (b) is a sinusoid, and should be expressed as such.



4. For each system below, determine whether or not it is:

- i. linear,
- ii. time-invariant,
- iii. causal,
- iv. stable,
- v. memoryless

For each of the above properties, if you think it holds, prove it. Otherwise, find a counter-example. In addition, find the response to an impulse.

a. $y[n] = \begin{cases} x[n], & n \text{ even} \\ -x[n], & \text{else} \end{cases}$

b. $y[n] = \sum_{k=-1}^1 x[n-k]$

c. $y(t) = x(2t)$

5. For the LTI systems below,

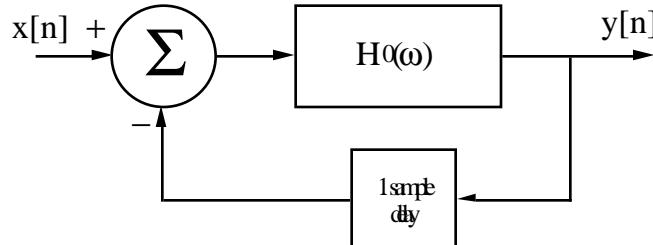
- i. find the impulse response,
- ii. find an expression for the frequency response (simplify as much as possible),
- iii. sketch the magnitude and phase of the frequency response,
- iv. describe in general terms the effect that the filter has on a signal.

a. $y[n] = (x[n] + x[n-1]) / 2$

b. $y[n] = (x[n] - x[n-3]) / 2$

c. $y[n] = (x[n] - 2x[n-1] + x[n-2]) / 4$

6. Consider the system shown below where the filter is described by the difference equation $y[n] = (x[n] + y[n-1]) / 2$:



- a. Find a difference equation that describes the overall system.
- b. Find an expression for the frequency response $H(\omega)$ of the overall system in terms of $H_0(\omega)$, the frequency response of the filter.
- c. Find the actual frequency response $H(\omega)$ from your answer to part a. and also using your answer to part b. Verify that the two approaches lead to the same answer.