ECE 438 Exam No. 1 Spring 2018

- You have 50 minutes to work the following four problems.
- Be sure to show all your work to obtain full credit.
- The exam is closed book and closed notes.
- Calculators are **not** permitted.
- 1. (25 pts.) Consider the linear, time-invariant system defined by the difference equation

$$y[n] = x[n] - x[n-1] - y[n-1]$$
.

a. (9) Find the response of this system to the input

$$x[n] = \begin{cases} 1, & 0 \le n \le 2 \\ 0, & \text{else} \end{cases}.$$

Assume that the system is initially at rest. So y[n] = 0, n < 0.

- b. (9) Find a simple expression for the frequency response $H(\omega)$ of this system.
- c. (7) Based on your answer to part (b), find simple expressions for the magnitude $|H(\omega)|$ and phase $|H(\omega)|$ of the frequency response of this system.

2. (25 pts.) Perform the convolution w[n] of the following two signals, and carefully sketch the output signal w[n].

$$x[n] = \left(\frac{1}{2}\right)^n u[n], \text{ and } y[n] = \begin{cases} 1, & 0 \le n \le 9 \\ 0, & \text{else} \end{cases}.$$

- 3. (25) Consider the continuous-time signal $x(t) = \cos(2\pi(3000)t) + \cos(2\pi(7000)t)$.
 - a. (8) Find a simple expression for the CTFT X(f) of x(t), and sketch it.

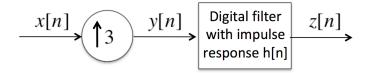
Suppose that we sample x(t) at an 8 kHz sampling rate to generate the continuous-time sampled signal $x_s(t) = \text{comb}_T[x(t)]$, where T = 1/8000 sec. is the sampling interval.

b. (9) Find a simple expression for the CTFT $X_s(f)$ of $x_s(t)$, and sketch it. Your final answer should not contain any operators.

Now, suppose that we input $x_s(t)$ to an ideal low-pass reconstruction filter with frequency response $H_r(f) = T \cdot \text{rect}(Tf)$.

c. (8) Find a simple expression for the output $x_r(t)$ from the reconstruction filter. Your final answer should not contain any operators.

4. (25 pts) Consider the system shown below:

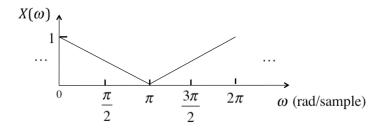


The impulse response of the filter is given by:

$$h[n] = \begin{cases} 1, & 0 \le n \le 2 \\ 0, & \text{else} \end{cases}.$$

a) (6) Find the response z[n] of this system to the input x[n] given below:

- b) (13) Find a simple closed-form expression for the DTFT $Z(\omega)$ of the output z[n] in terms of the DTFT $X(\omega)$ of the input x[n]. (Note that this expression should be valid for any input x[n].) Your answer should not contain any operators.
- c) (6) Sketch $Z(\omega)$, when $X(\omega)$ is given as below:



Be sure to dimension all important quantities.

(b)
$$Y_{(w)} = X_{(w)} - X_{(w)} e^{jw} - Y_{(w)} e^{-jw}$$

$$Y_{(w)} (1 + e^{-jw}) = X_{(w)} (1 - e^{-jw})$$

$$\frac{Y_{(w)}}{X_{(w)}} = \frac{1 - e^{-jw}}{1 + e^{-jw}}$$

$$= \frac{e^{-jw}}{e^{-jw}_{2}} (e^{jw}_{2} - e^{-jw}_{2})$$

$$= \frac{e^{-jw}_{2}}{e^{-jw}_{2}} (e^{jw}_{2} + e^{-jw}_{2})$$

$$= \frac{e^{-jw}_{2}}{e^{-jw}_{2}} = j \tan(w/2) = 2pts$$

$$\cos(w/2)$$

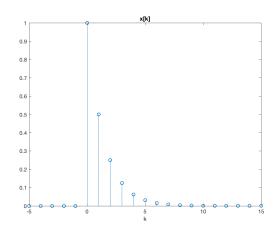
(c)
$$\Phi |H(w)| = |\int tan(\frac{w}{2})| = |tan(\frac{w}{2})|$$
 $\angle H(w) = \angle \int + \angle tan\frac{w}{2}$
 $= \begin{cases} \frac{\pi}{2} + 0 & ocwell \\ \frac{\pi}{2} - \pi & -\pi < w < 0 \end{cases}$
 $= \begin{cases} \frac{\pi}{2} & ocwell \\ -\frac{\pi}{2} & -\pi < w < 0 \end{cases}$
 $\geq pts$

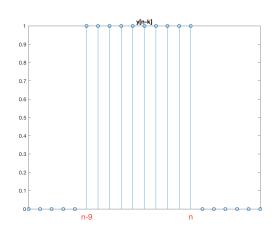
Question 2

$$x[n] = (\frac{1}{2})^n u[n]$$

$$y[n] = \begin{cases} 1 & 0 \le n \le 9 \\ 0 & else \end{cases}$$

$$\text{let } w[n] = \sum_{k=-\infty}^{\infty} x[k]y[n-k]$$





 $\underline{n < 0:}$ 2 pts - condition w[n] = 0 3 pts - result

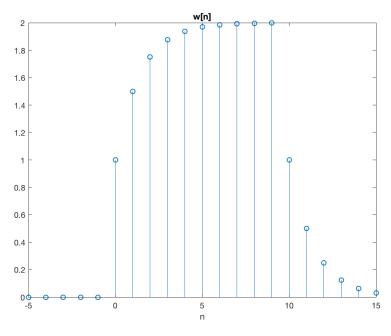
 $\underline{n-9} < 0, n \geqslant 0 \Longrightarrow 0 \leqslant n < 9$: 3 pts - condition

$$w[n] = \sum_{k=0}^{n} (\frac{1}{2})^k = \frac{1 - (\frac{1}{2})^{n+1}}{\frac{1}{2}} = 2 - (\frac{1}{2})^n$$
 2 pts - correct form (sum of (1/2)^k) 2 pts - boundary 1 pt - result

 $\underline{n \geqslant 9}$: 3 pts - condition

$$w[n] = \sum_{k=n-9}^{n} (\frac{1}{2})^k = \sum_{k=0}^{n} (\frac{1}{2})^k - \sum_{k=0}^{n-10} (\frac{1}{2})^k = \frac{1 - (\frac{1}{2})^{n+1}}{\frac{1}{2}} - \frac{1 - (\frac{1}{2})^{n-9}}{\frac{1}{2}} = (\frac{1}{2})^{n-10} - (\frac{1}{2})^n$$

2 pts - correct form (sum of (1/2)^k) 2 pts - boundary 3 pts - result

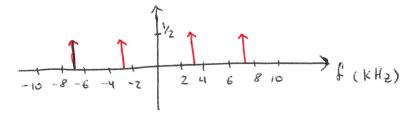


1 pt - graph based on student's answer

1 pt - correct result

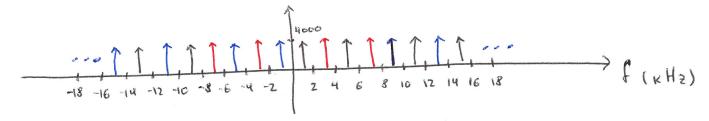
x(t) = cos(211 (3000)t) + cos(271 (7000)t)

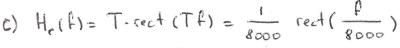
a) Using CTFT pairs:

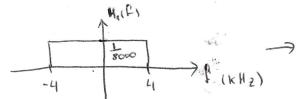


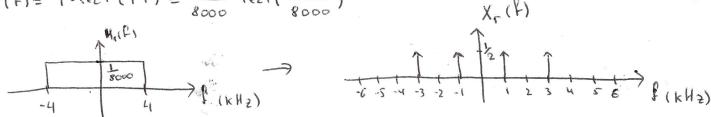
$$X_s(l) = \frac{1}{T} \exp_{\frac{1}{2}} \left[x(l) \right] = 8000 \exp_{8000} \left[x(l) \right] = \sum_{k=-\infty}^{\infty} 4000 \left[s(l-3000-8000k) + \frac{1}{2} \right]$$

+ S(f+3000-8000K)+S(f-7000-8000K)+S(f+7000-8000K)}









$$h[n] = \delta[n] + \delta[n-1] + \delta[n-2]$$

$$x[n] = \delta[n] + \frac{2}{3}\delta[n-1] + \frac{1}{3}\delta[n-2]$$

(Step 1) After upsampling,

$$y[n] = \delta[n] + \frac{2}{3}\delta[n-3] + \frac{1}{3}\delta[n-6]$$
 ... 3 pts (Step 1)

(Step 2 and 3) After filtering with h[n],

$$z[n] = y[n] * h[n]$$
 ... 1 pt (Step 2 – method 1)
$$= \delta[n] + \delta[n-1] + \delta[n-2] + \frac{2}{3}(\delta[n-3] + \delta[n-4] + \delta[n-5])$$
 ... 2 pts (Step 3 – method 1)
$$\dots 2 \text{ pts (Step 3 – method 1)}$$

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DTFT of each signal or filter gives

$$H(w) = 1 + e^{-jw} + e^{-j2w}$$

$$Y(w) = 1 + \frac{2}{3}e^{-j3w} + \frac{1}{3}e^{-j6w}$$

$$Z(w) = Y(w)H(w) \qquad \dots 1 \text{ pt (Step 2 - method 2)}$$

$$= 1 + e^{-jw} + e^{-j2w} + \frac{2}{3}(e^{-j3w} + e^{-j4w} + e^{-j5w}) + \frac{1}{3}(e^{-j6w} + e^{-j7w} + e^{-j8w})$$

Inverse DTFT of Z(w) gives

$$z[n] = \delta[n] + \delta[n-1] + \delta[n-2] + \frac{2}{3}(\delta[n-3] + \delta[n-4] + \delta[n-5]) + \frac{1}{3}(\delta[n-6] + \delta[n-7] + \delta[n-8]) \qquad \dots 2 \text{ pts (Step 3 - method 2)}$$

#4. (b)

(Step 1)

$$H(w) = 1 + e^{-jw} + e^{-j2w}$$
 ... 4 pts (Step 1 – method 1)

or

$$H(w) = \frac{1 - e^{-j3w}}{1 - e^{-jw}} = \frac{e^{\frac{j3w}{2}} - e^{-\frac{j3w}{2}}}{e^{\frac{jw}{2}} - e^{-\frac{jw}{2}}} \cdot \frac{e^{-\frac{j3w}{2}}}{e^{-\frac{jw}{2}}} = \frac{\sin\left(\frac{3w}{2}\right)}{\sin\left(\frac{w}{2}\right)} e^{-jw}$$

$$= psinc_3(w)e^{-jw} \qquad ... 4 \text{ pts (Step 1 - method 2)}$$

or

$$H(w) = (e^{jw} + 1 + e^{-jw})e^{-jw}$$

= $(1 + 2\cos(w))e^{-jw}$... 4 pts (Step 1 – method 3)

(Step 2)

$$Z(w) = Y(w)H(w)$$

$$= X(3w)H(w) \qquad ... 4 \text{ pts (Step 2)}$$

(Step 3)

Therefore,

$$Z(w) = X(3w)(1 + e^{-jw} + e^{-j2w})$$
 ... 5 pts (Step 3 – method 1)

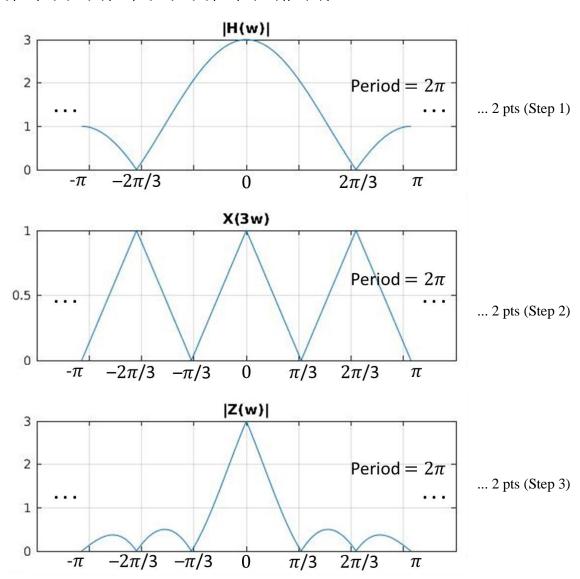
or

$$Z(w) = X(3w)psinc_3(w)e^{-jw}$$
 ... 5 pts (Step 3 – method 2)

or

$$Z(w) = X(3w)(1 + 2\cos(w))e^{-jw}$$
 ... 5 pts (Step 3 – method 3)

$$|Z(w)| = |Y(w)H(w)| = |X(3w)H(w)| = |X(3w)||H(w)|$$



- It is important to specify that the signal is periodic with a period of 2π . Answers without such do not get full credits.
- 2 points are given if rough shape is the same without a proper procedure.