

- You have 50 minutes to work the following four problems.
 - Be sure to show all your work to obtain full credit.
 - The exam is closed book and closed notes.
 - Calculators are **not** permitted.
1. (25 pts.) Consider the linear, time-invariant system defined by the difference equation

$$y[n] = x[n] - x[n-1] - y[n-1].$$

Assume that the system is initially at rest, i.e. $y[n] = 0, n < 0$.

- a. (6) For the following input signal $x[n]$, find the corresponding response $y[n]$ of the system.

n	...	-2	-1	0	1	2	3	4	5	...
$x[n]$...	0	0	1	1	1	1	0	0	...

- b. (6) Find a simple expression for the frequency response $H(\omega)$ of this system.
- c. (6) Based on your answer to part (b), find simple expressions for the magnitude $|H(\omega)|$ and phase $\angle H(\omega)$ of the frequency response of this system.
- d. (6) Based on your answer to part (c), carefully sketch the magnitude $|H(\omega)|$ and phase $\angle H(\omega)$ of the frequency response of this system.
- e. (1) Is this system bounded-input-bounded-output (BIBO) stable? State why or why not.

(a)

$$y[0] = 1 - 0 - 0 = 1$$

$$y[1] = 1 - 1 - 1 = -1$$

$$y[2] = 1 - 1 + 1 = 1$$

$$y[3] = 1 - 1 - 1 = -1$$

$$y[4] = 0 - 1 + 1 = 0$$

$$y[5] = 0 - 0 + 0 = 0$$

(b)

$$\text{Let } x[n] = e^{j\omega n}, \quad y[n] = H(\omega) e^{j\omega n}$$

$$\Rightarrow H(\omega) e^{j\omega n} = e^{j\omega n} - e^{j\omega(n-1)} - e^{j\omega(n-1)} H(\omega)$$

$$\Rightarrow H(\omega) e^{j\omega n} = e^{j\omega n} [1 - e^{-j\omega} - e^{-j\omega} H(\omega)]$$

$$\Rightarrow H(\omega) [1 + e^{-j\omega}] = 1 - e^{-j\omega}$$

1. (continued)

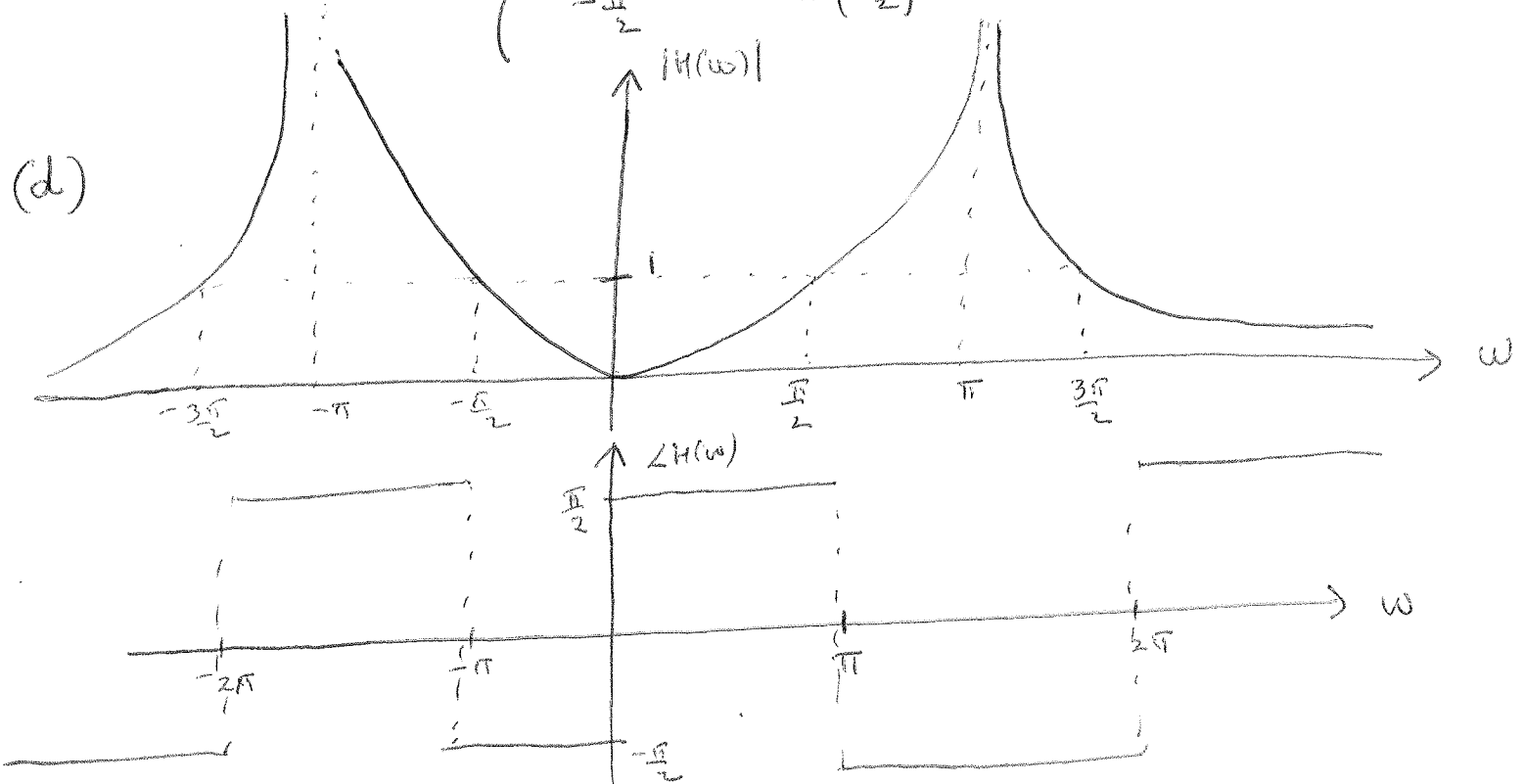
$$\Rightarrow H(\omega) = \frac{1 - e^{-j\omega}}{1 + e^{-j\omega}} = \frac{e^{-j\frac{\omega}{2}}}{e^{-j\frac{\omega}{2}}} \left[\frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} \right]$$

$$= \frac{2j}{j} \frac{\sin(\omega/2)}{\cos(\omega/2)} = j \tan\left(\frac{\omega}{2}\right)$$

(c) $|H(\omega)| = \left| \tan\left(\frac{\omega}{2}\right) \right|$

$$\angle H(\omega) = \angle j + \angle \tan\left(\frac{\omega}{2}\right)$$

$$= \begin{cases} \frac{\pi}{2} & \tan\left(\frac{\omega}{2}\right) > 0 \\ -\frac{\pi}{2} & \tan\left(\frac{\omega}{2}\right) < 0 \end{cases}$$



(e) No, since $|H(\omega)| \rightarrow \infty$ as $\omega \rightarrow \pi$
OR

$$h[n] = \delta[n] + 2(-1)^n \delta[n-1]$$

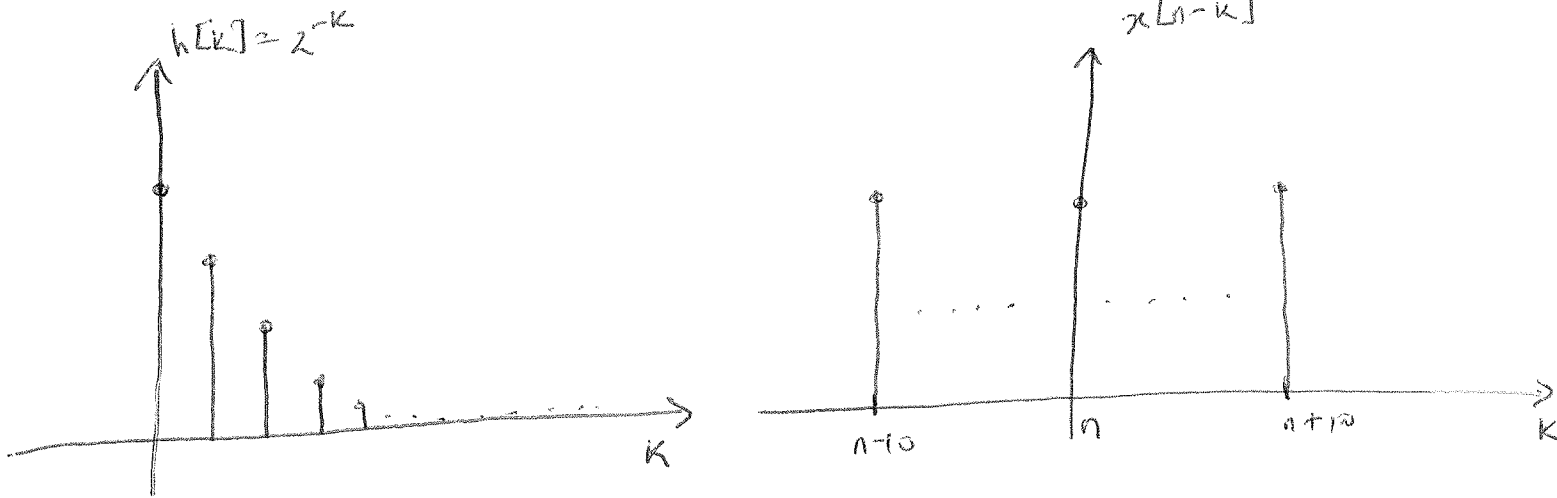
$\sum_{n=-\infty}^{\infty} |h[n]| = \infty$ so system is NOT BIBO stable!

2. (25 pts.) Consider a linear, shift-invariant system with impulse response

$$h[n] = \left(\frac{1}{2}\right)^n u[n]. \text{ Find an expression for the response } y[n] \text{ to the input}$$

$$x[n] = \begin{cases} 1, & |n| \leq 10 \\ 0, & \text{else} \end{cases} \text{ by evaluating the convolution sum } y[n] = \sum_{k=-\infty}^{\infty} h[n-k]x[k].$$

Simplify your answer as much as possible.



Case 1: $n+10 \leq 0 \Rightarrow n < -10$

$y[n] = 0$, since no overlap between h and x

Case 2: $n+10 > 0$ and $n-10 \leq 0 \Rightarrow -10 \leq n \leq 10$

$$y[n] = \sum_{k=0}^{n+10} \left(\frac{1}{2}\right)^k = \frac{1 - \left(\frac{1}{2}\right)^{n+11}}{1 - \frac{1}{2}} = 2 \left[1 - \left(\frac{1}{2}\right)^{n+11} \right]$$

Case 3: $n-10 > 0 \Rightarrow n > 10$

$$y[n] = \sum_{k=n-10}^{n+10} \left(\frac{1}{2}\right)^k, \text{ let } m = k - (n-10)$$

$$\Rightarrow y[n] = \sum_{m=0}^{20} \left(\frac{1}{2}\right)^{m+(n-10)} = \left(\frac{1}{2}\right)^{n-10} \sum_{m=0}^{20} \left(\frac{1}{2}\right)^m$$

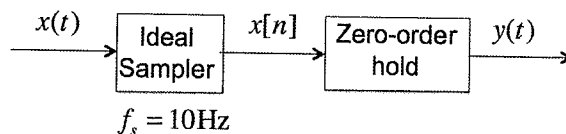
$$= \left(\frac{1}{2}\right)^{n-10} \left[\frac{1 - \left(\frac{1}{2}\right)^{21}}{1 - \frac{1}{2}} \right]$$

$$= \left(\frac{1}{2}\right)^n \left[2^{11} - 2^{-10} \right]$$

2. (continued)

$$y[n] = \begin{cases} 0 & n < -10 \\ 2 \left[1 - \left(\frac{1}{2} \right)^{n+11} \right] & -10 \leq n \leq 10 \\ \left(\frac{1}{2} \right)^n \left[2^{11} - 2^{-10} \right] & n > 10 \end{cases}$$

3. (25) Consider the system shown in the block diagram below:



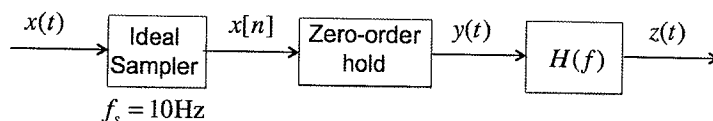
The operation of the zero-order hold unit can be described as:

$$y(t) = \sum_{n=-\infty}^{\infty} x[n] \text{rect}\left(\frac{t - 0.1n - 0.05}{0.1}\right).$$

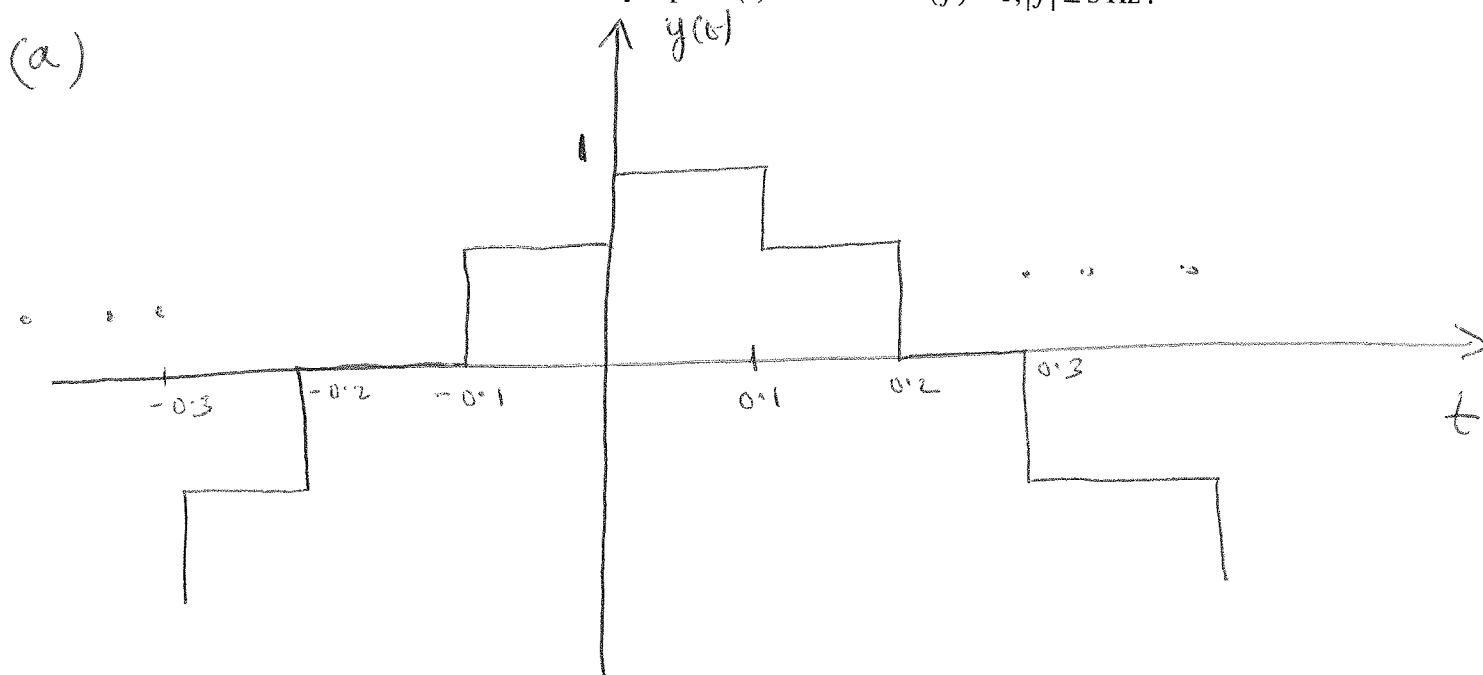
Suppose that the input to this system is $x(t) = \cos(2\pi(10/8)t)$.

- (8) Carefully and accurately sketch the output $y(t)$ of the zero-order hold.
- (9) Find an expression for the continuous-time Fourier transform (CTFT) $Y(f)$ of the output $y(t)$ for the specific input $x(t) = \cos(2\pi(10/8)t)$ to the system. Your answer should be simplified as much as possible, and should not contain any operators.
- (4) Sketch $Y(f)$.

Now consider placing an analog filter with frequency response $H(f)$ at the output of the system shown above to yield the following system:



- (4) Find the desired frequency response $H(f)$ of the filter so that the system output $z(t) \equiv x(t)$, for any input $x(t)$ for which $X(f) = 0, |f| \geq 5 \text{ Hz}$.



3. (continued)

$$(b) \quad x(t) = \cos\left(2\pi\left(\frac{10}{8}\right)t\right)$$

$$x_s(t) = \underset{0.1}{\text{comb}} x(t)$$

$$x_r(t) = \text{rect}\left(\frac{t - 0.05}{0.1}\right)$$

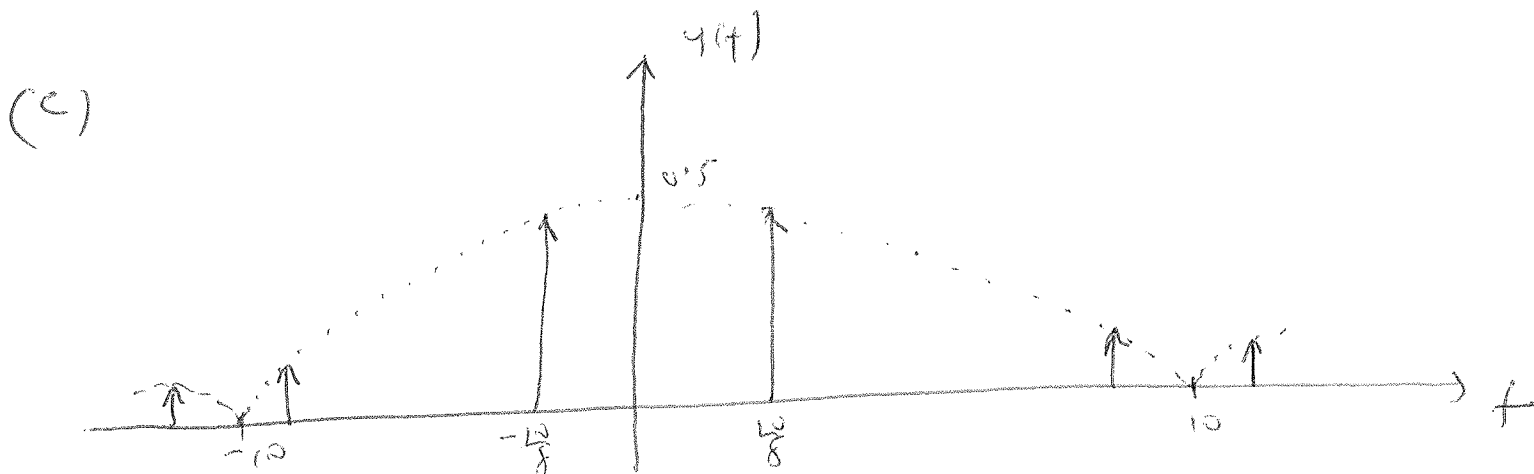
So, we have $y(t) = x_s * x_r(t)$

$$X(f) = \frac{1}{2} \left[\delta\left(f - \frac{10}{8}\right) + \delta\left(f + \frac{10}{8}\right) \right]$$

$$X_s(f) = \underset{0.1}{\frac{1}{0.1}} \underset{0.1}{\text{rep}} X(f) = 10 \underset{0.1}{\text{rep}} \left\{ \frac{1}{2} \left[\delta\left(f - \frac{10}{8}\right) + \delta\left(f + \frac{10}{8}\right) \right] \right\}$$

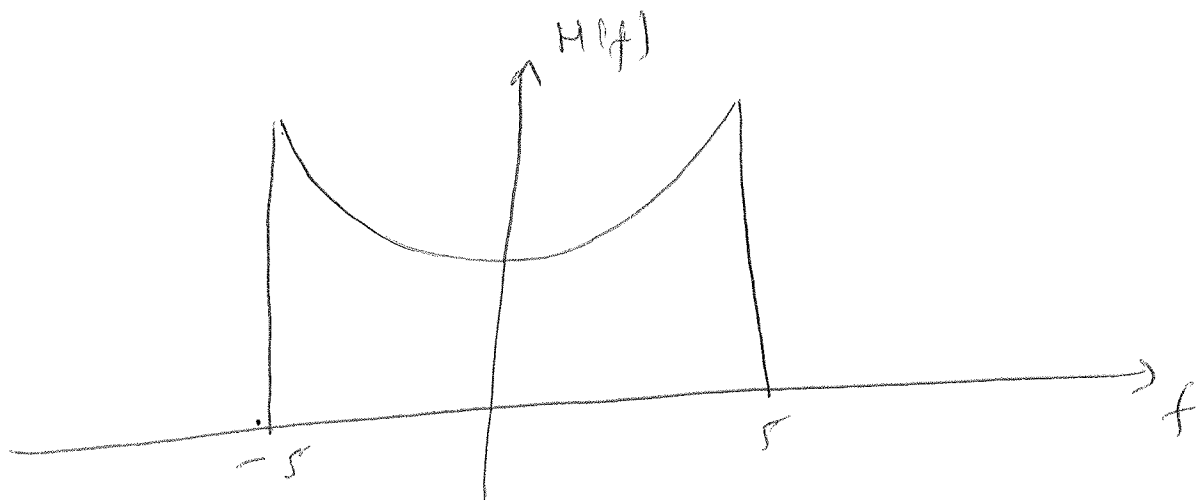
$$X_r(f) = 0.1 \text{sinc}(0.1f) e^{-j2\pi f(0.05)}$$

$$\begin{aligned} \Rightarrow Y(f) &= X_s(f) X_r(f) \\ &= \underset{0.1}{\text{rep}} \left\{ \frac{1}{2} \left[\delta\left(f - \frac{10}{8}\right) + \delta\left(f + \frac{10}{8}\right) \right] \right\} \text{sinc}(0.1f) e^{-j2\pi f(0.05)} \end{aligned}$$

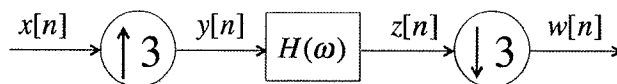


3. (continued)

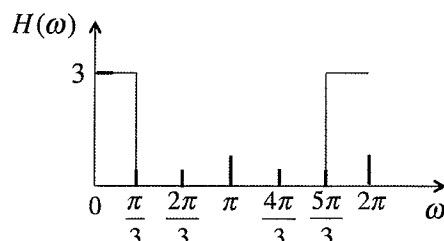
$$(d) \quad H(f) = \begin{cases} \frac{1}{\sin(\pi f)} e^{-j\pi f(0.5)} & -5 \leq f \leq 5 \\ 0 & \text{otherwise} \end{cases}$$



4. (25 pts) Consider the system shown below:



Here the filter $H(\omega)$ has the frequency response:



Let uppercase symbols denote the DTFTs of their corresponding lowercase quantities.

- (3) Find a simple expression for $W(\omega)$ in terms of $Z(\omega)$.
- (3) Find a simple expression for $Z(\omega)$ in terms of $Y(\omega)$.
- (3) Find a simple expression for $Y(\omega)$ in terms of $X(\omega)$.
- (8) Combine your answers to parts (a) – (c) above to find a simple expression for $W(\omega)$ in terms of $X(\omega)$.
- (8) Suppose $X(\omega)$ is given by $X(\omega) = 1 - \left|\frac{\omega}{\pi}\right|$, $0 \leq |\omega| \leq \pi$. Sketch $X(\omega)$, $Y(\omega)$, $Z(\omega)$, and $W(\omega)$.

$$(a) \quad W(\omega) = \frac{1}{3} \sum_{k=0}^2 Z\left(\frac{\omega - 2\pi k}{3}\right)$$

$$(b) \quad Z(\omega) = Y(\omega) H(\omega)$$

$$(c) \quad Y(\omega) = X(3\omega)$$

$$(d) \quad W(\omega) = \frac{1}{3} \sum_{k=0}^2 Y\left(\frac{\omega - 2\pi k}{3}\right) H\left(\frac{\omega - 2\pi k}{3}\right) \\ = \frac{1}{3} \sum_{k=0}^2 X(\omega - 2\pi k) H\left(\frac{\omega - 2\pi k}{3}\right)$$

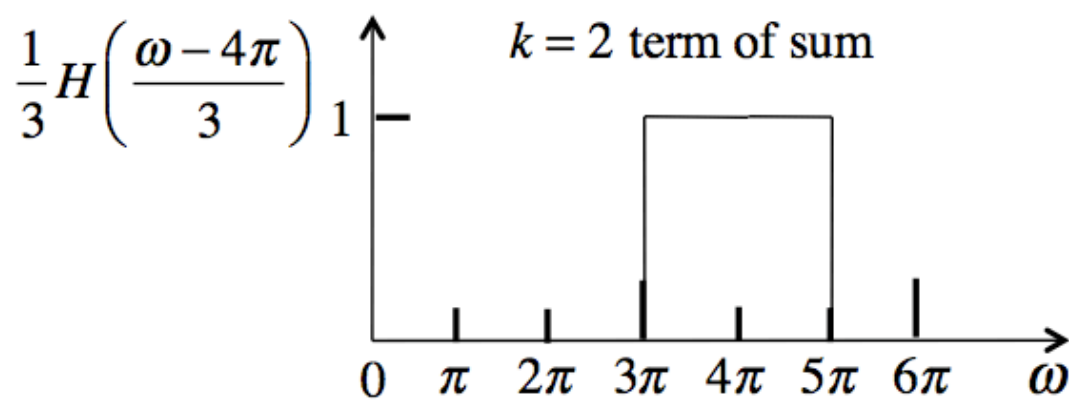
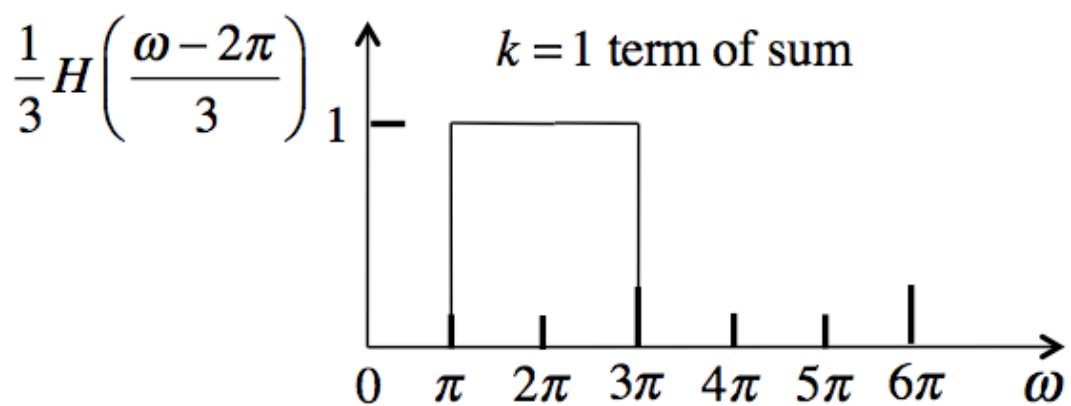
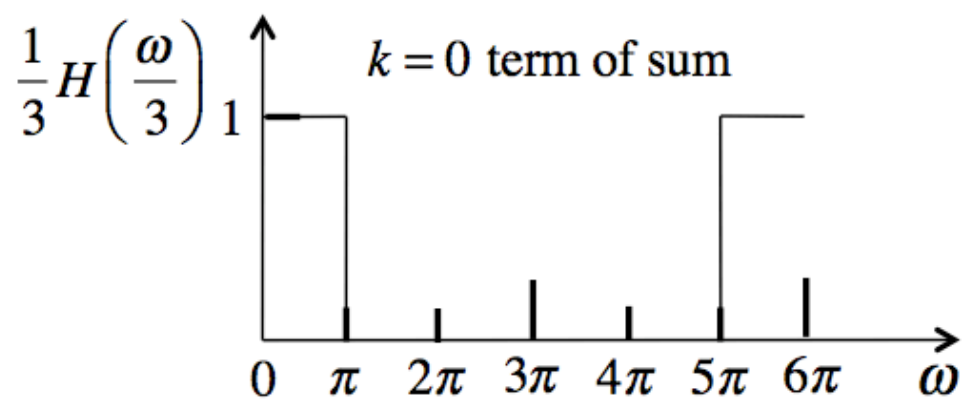
After further simplification

$$W(\omega) = X(\omega)$$

Specifically, since $X(\omega - 2\pi k) = X(\omega)$ for any integer k ,

$$\text{we have } W(\omega) = X(\omega) \frac{1}{3} \sum_{k=0}^2 H\left(\frac{\omega - 2\pi k}{3}\right).$$

$$\text{But } \frac{1}{3} \sum_{k=0}^2 H\left(\frac{\omega - 2\pi k}{3}\right) = 1. \text{ See figure on next page.}$$



4. (continued)

(e)

