

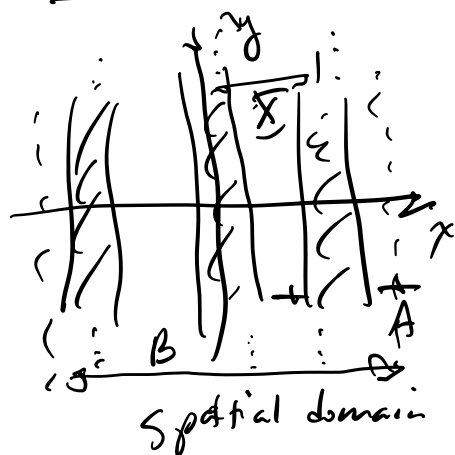
ECE 438 Lecture April 21, 2023

Announcements

- ① HW 10 is posted
- ② Solutions will be provided on Monday
- ③ No coverage of computed tomography on final exam

Module 2.1.4 2D Signals & Systems - Periodic Structures

Example 3



The analysis will NOT follow posted notes.

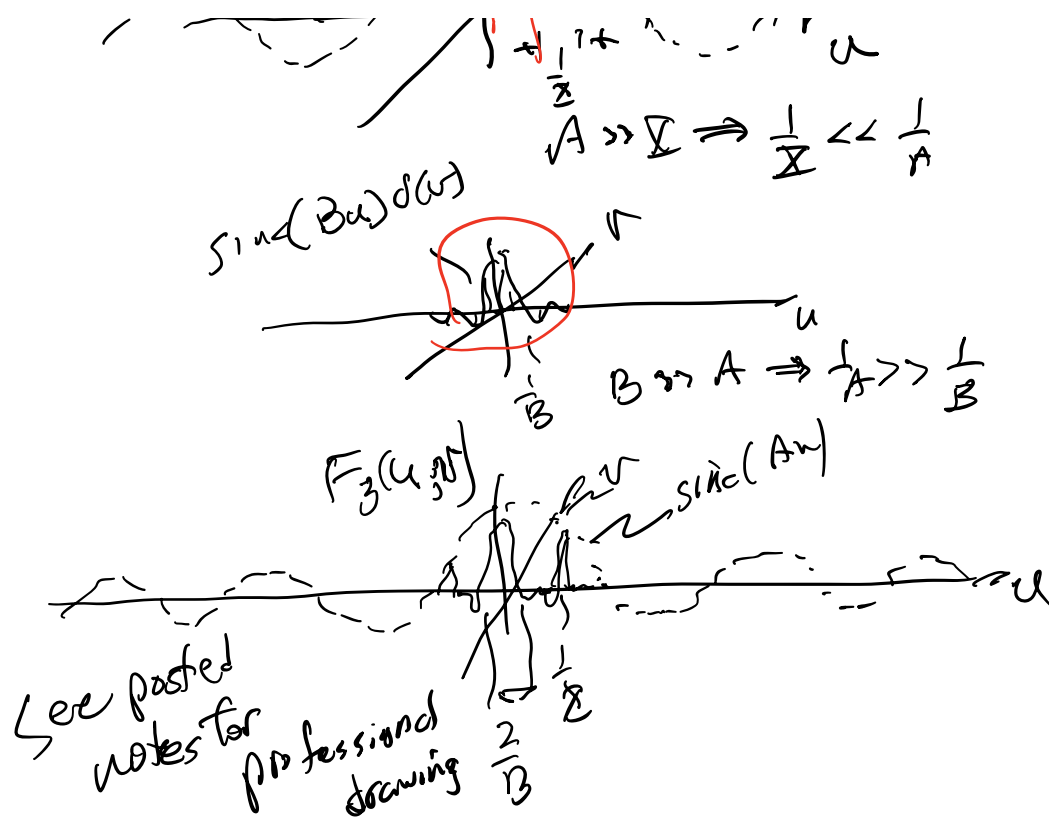
I am taking a simpler approach using separability

$$f_3(x, y) = \text{rect}\left[\frac{x}{A}\right] \text{rect}\left[\frac{x}{B}\right] \cdot 1(y)$$

$$F_3(u, v) = \frac{AB}{X} \text{comb} \left[\frac{1}{X} \left[\text{sinc}(Au) \right] * \text{sinc}(Bu) \right] \cdot \delta(v)$$

1D convolution





Continue with Module 2.1.4
2D rep & comb operators

Definitions

$$\text{comb}_{\delta x} [f(x, y)] = \left[\sum_{k \in \mathbb{Z}} f(k \delta x, y) \delta(x - k \delta x, y - l \delta y) \right]$$

$$\text{rep}_{\delta x \delta y} [f(x, y)] = \sum_{k \in \mathbb{Z}} \sum_{l \in \mathbb{Z}} f(x - k \delta x, y - l \delta y)$$

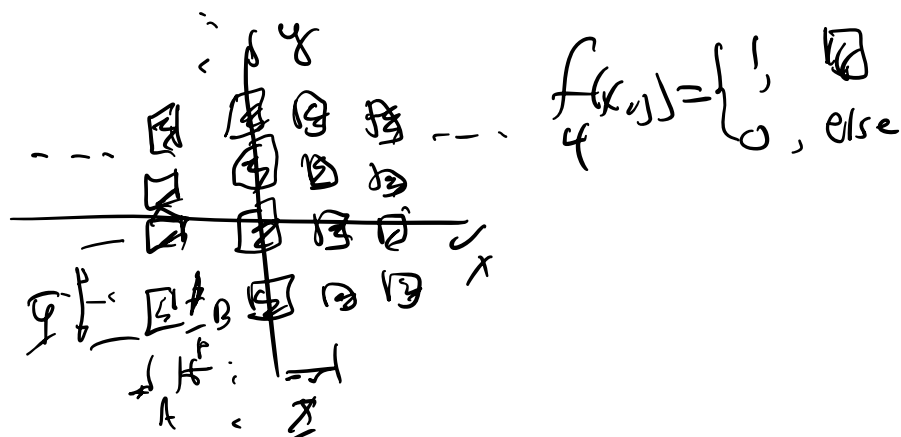
transform pairs

$$\text{rep}_{\delta x \delta y} [f(x, y)] \xrightarrow{\text{2D CSFT}} \frac{1}{\delta x \delta y} \text{comb}_{\frac{1}{\delta x} \frac{1}{\delta y}} [F(u, v)]$$

by reciprocity, also have

$$\text{comb}_{\Sigma \Pi} (x, y) \xrightarrow{\text{CFFT}} \frac{1}{\Sigma \Pi} \text{rep}_{\frac{1}{\Sigma} \frac{1}{\Pi}} [F(u, v)]$$

Example 4

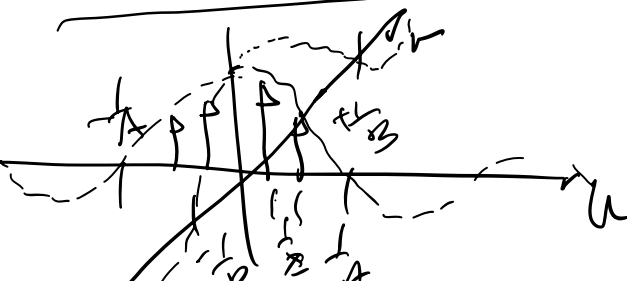


$$f_4(x, y) = \text{rep}_{\Sigma \Pi} \left[\text{rect} \left(\frac{x}{A}, \frac{y}{B} \right) \right]$$

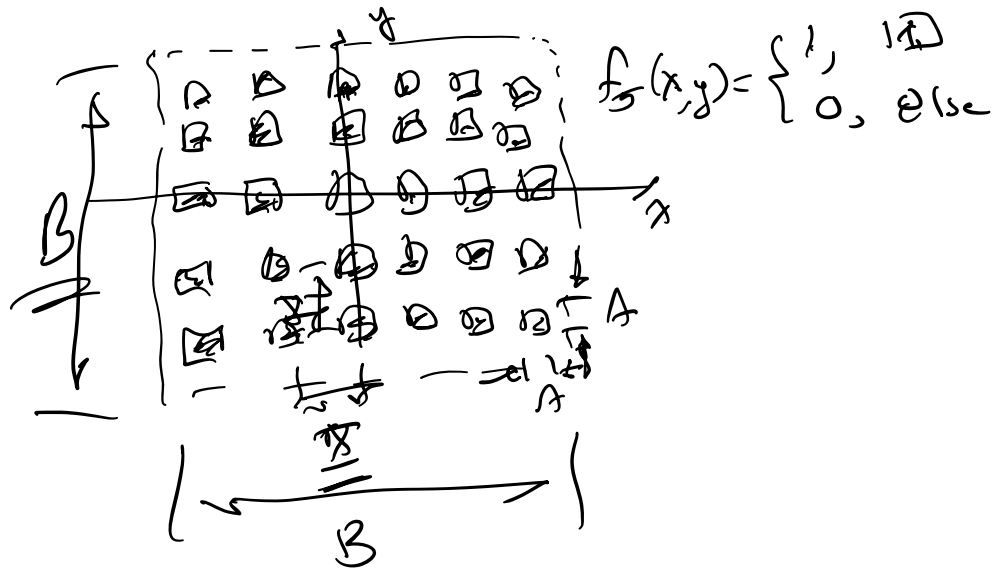
$$F_4(u, v) = \frac{1}{\Sigma \Pi} \text{comb}_{\frac{1}{\Sigma} \frac{1}{\Pi}} \left\{ AB \text{sinc} \left(Au, Bv \right) \right\}$$

$$= \frac{AB}{\Sigma \Pi} \sum_k \sum_l \text{sinc} \left(\frac{A}{\Sigma} k, \frac{B}{\Pi} l \right) f \left(u - \frac{k}{\Sigma}, v - \frac{l}{\Pi} \right)$$

See posted notes for a better drawing



Now consider Example 5:



$$F_4(u, v) = \frac{A^2}{\pi^2} \text{rep}_{\frac{1}{\pi}, \frac{1}{\pi}} \left[\text{sinc}(Au, Bv) \right]$$

$$= \frac{A^2}{\pi^2} \sum_k \sum_l \text{sinc}\left(\frac{Ak}{\pi}, \frac{Bl}{\pi}\right) \delta\left(u - \frac{k}{\pi}, v - \frac{l}{\pi}\right)$$

$$f_5(x, y) = f_4(x, y) * \text{rect}\left(\frac{x}{B}, \frac{y}{B}\right)$$

$$F_5(u, v) = F_4(u, v) \cdot B^2 \text{sinc}(Bu, Bv)$$

$$B \gg \frac{1}{\pi} \Rightarrow \frac{1}{B} \ll \frac{1}{\pi}$$

$$F_5(u, v) = \frac{A^2 B^2}{\pi^2} \sum_k \sum_l \text{sinc}\left(\frac{Ak}{\pi}, \frac{Bl}{\pi}\right) \text{rect}\left[B\left(u - \frac{k}{\pi}\right), B\left(v - \frac{l}{\pi}\right)\right]$$

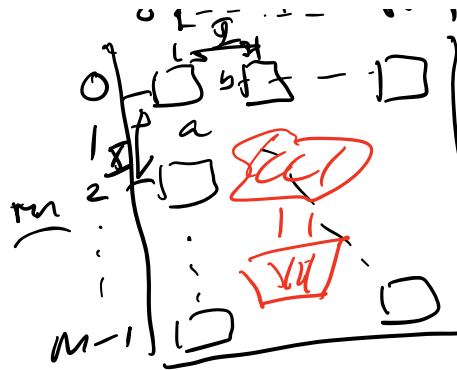
Comments:
General relationship between spatial & frequency domain

end of
module
2.1.4

What's next!
Module 2.2.1 - Overview of scanning technologies
(2 pages)

Start on p5 of Module 2.22:

21 5 21



$$\underbrace{f_d[m, n]}_{\text{digital}} = \int_{m\Delta x - a/2}^{m\Delta x + a/2} \int_{n\Delta y - b/2}^{n\Delta y + b/2} f_a(x, y) dx dy$$

analog

Want to use our tools to analyze this system

blurred

Answer: $\tilde{f}_a(x, y) = f_a(x, y) \ast \text{rect}\left(\frac{x}{a}, \frac{y}{b}\right)$

As aperture size (a, b) increases, capture more photons

⇒ camera is "faster". BUT the captured image

is blurred