

Help Sessions

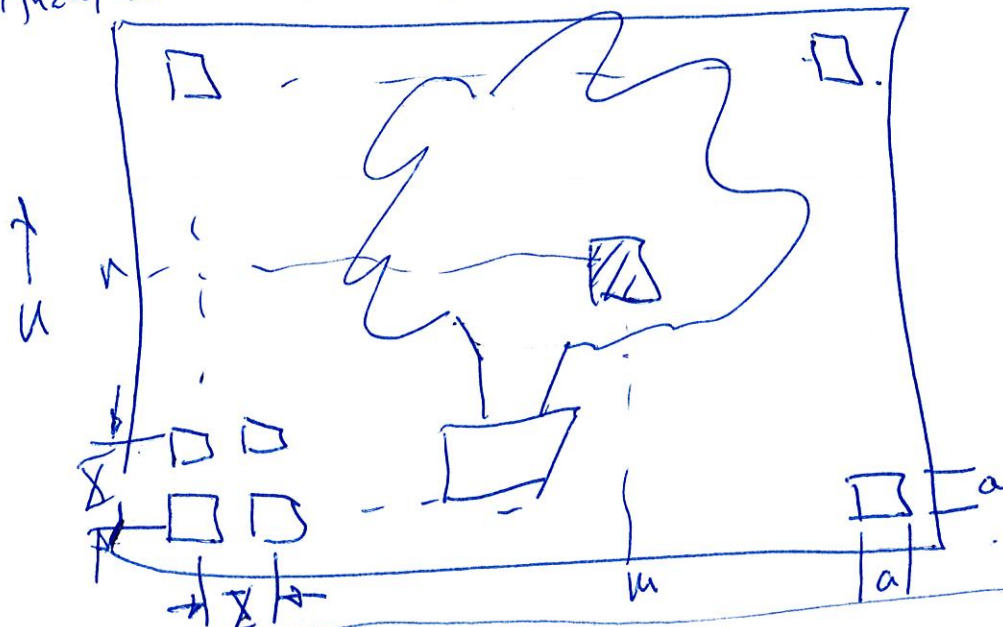
2:00 - 3:00p } EE 222
 5:00 - 6:00p }

Exam 3 - Wed. 17 April

Analysis of 2-D Signals & system (Continuous-parameter)
 (CS)

Analysis of focal plane array

Module 2.2.2



sampled signal $\rightarrow$

$$g[m, n] = \int_{m\Delta x - a/2}^{m\Delta x + a/2} \int_{n\Delta y - a/2}^{n\Delta y + a/2} f(x, y) dx dy$$

Representations $g[m, n]$ (DS)

CS $g_s(x, y) = \sum_m \sum_n g[m, n] \delta(x - m\Delta x, y - n\Delta y)$

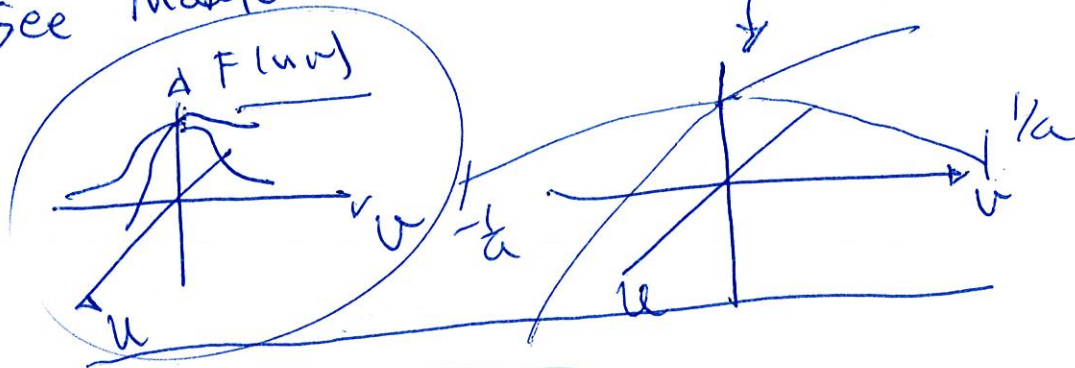
Recall development of relation between CTFT & DTFT

Looking for a relationship for $g_s(x,y)$ or $G_s(u,v)$ in terms of $f(x,y)$ or $F(u,v)$ (2)

$$G_s(x,y) = \text{comb}_{xx} \left[\text{rect} \left(\frac{x}{a}, \frac{y}{a} \right) \times \underbrace{f(x,y)}_{\hat{F}(u,v)} \right]$$

$$\underline{G_s(u,v)} = \left(\frac{a^2}{\lambda^2} \right) \text{rep} \frac{1}{\lambda} \frac{1}{\lambda} \left[\underbrace{\text{sinc} \left(au, av \right)}_{\text{sinc} \left(\frac{u}{1/a}, \frac{v}{1/a} \right)} \underbrace{F(u,v)}_{\hat{F}(u,v)} \right]$$

See Module 2.2.3

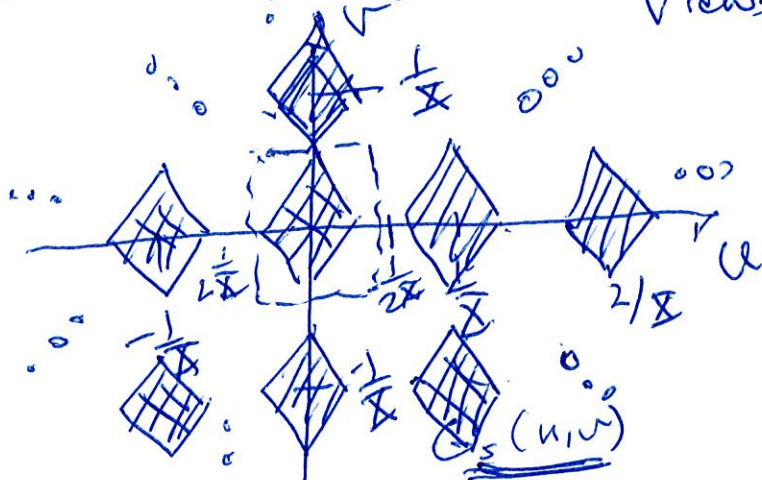
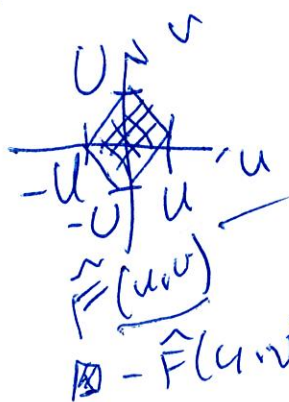


$\hat{F}(u,v) = \text{sinc} \left(\frac{u}{1/a}, \frac{v}{1/a} \right) F(u,v)$ rolls off a little faster as (u,v) relative to $F(u,v)$ [aperture effect]

How does $\tilde{f}(x,y)$ compare $f(x,y)$??

$\tilde{f}(x,y)$ will look a bit blurred (unsharp) relative to $f(x,y)$

Now consider effect of sampling (look at top views)



(3)

To recover $f(x,y)$ from $\hat{f}(x,y)$ apply a LSI filter with frequency response

$$H_c(u,v) = \begin{cases} \frac{1}{\text{sinc}(\pi u, \pi v)}, & |u|, |v| < \underline{U} \\ 0, & \text{else} \end{cases}$$

↑
correction

$$\text{Then } \hat{F}_c(u,v) = H_c(u,v) \hat{F}(u,v)$$

$$\text{or } f_c(x,y) = h_c(x,y) \ast \ast \hat{f}(x,y)$$

Let's assume that this correction has been done so: $g_s(x,y) = \text{comb}_{XX} [f(x,y)]$

$$\Rightarrow G_s(u,v) = \frac{1}{X^2} \text{rep } \frac{1}{X} \frac{1}{X} [F(u,v)]$$

To recover $f(x,y)$ from $g_s(x,y)$, apply an ideal low pass filter: $H_r(u,v) = X^2 \text{rect} \left(\frac{u}{\frac{1}{2}X}, \frac{v}{\frac{1}{2}X} \right)$

$$\Rightarrow h_r(x,y) = \frac{1}{X^2} \text{sinc} \left(\frac{x}{X}, \frac{y}{X} \right) = X^2 \text{rect} \left(\frac{x}{X}, \frac{y}{X} \right)$$

$$\text{so } f_r(x,y) = h_r(x,y) \ast \ast g_s(x,y)$$

$$\begin{aligned} \text{so } f_r(x,y) &= h_r(x,y) \ast \ast \text{comb}_{XX} [f(x,y)] \\ &= h_r(x,y) \ast \left[\sum_m \sum_n \underline{f(mx, ny)} \delta(x - mX, y - nX) \right] \end{aligned}$$

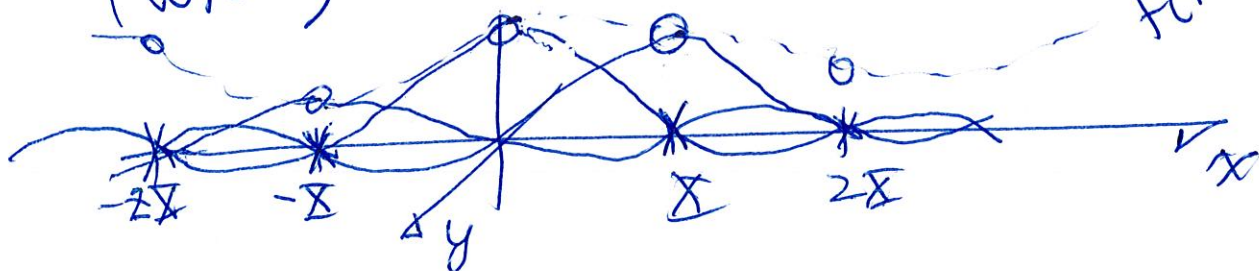
$$f_r(x,y) = \sum_m \sum_n f[m\Delta, n\Delta] h_r(x-y, y-n\Delta) \quad (4)$$

$$= \sum_m \sum_n f[m\Delta, n\Delta] h_r(x-m\Delta, y-n\Delta)$$

$$f_r(x,y) = \sum_m \sum_n f[m\Delta, n\Delta] \text{sinc}\left(\frac{x-m\Delta}{\Delta}, \frac{y-n\Delta}{\Delta}\right)$$

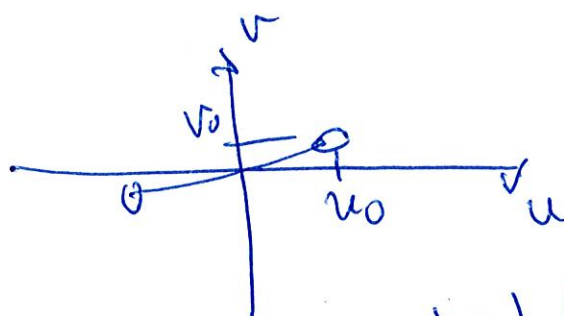
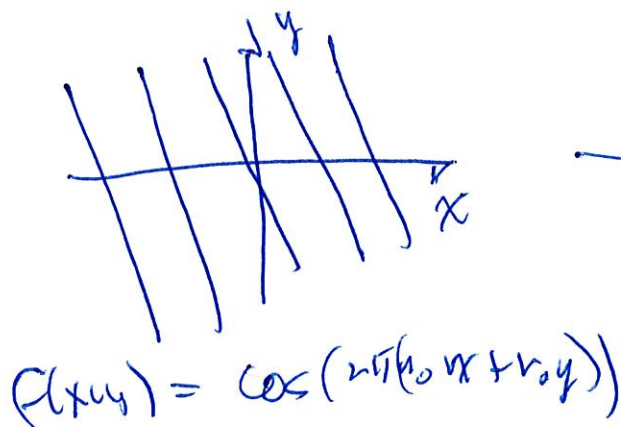
Shannon sampling expansion
(WKS)

$$\Rightarrow f_r(m\Delta, n\Delta) \equiv f(m\Delta, n\Delta)$$



Reconstruction is perfect only if
 $F(u,v) = 0, |u|, |v| > \frac{1}{2\Delta}$

$\Rightarrow U < \frac{1}{2\Delta}$ Nyquist sampling condition
 otherwise we have aliasing



$$f_r(u,v) = \frac{1}{2} \delta(u-u_0, v-v_0) + \frac{1}{2} \delta(u+u_0, v+v_0)$$