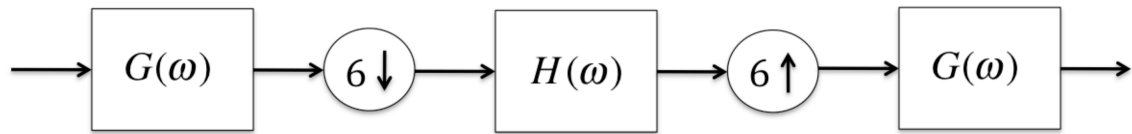


1. Consider the digital filter described by the following difference equation

$$y[n] = \frac{1}{3}(x[n] + x[n-1] + x[n-2])$$

- Find a simple expression for the frequency response  $H(\omega)$  of this filter.
- Sketch the magnitude of  $H(\omega)$ .

Now consider the following digital system



where  $H(\omega)$  is the filter from parts a and b and  $G(\omega)$  is an ideal low-pass filter with a cutoff frequency of  $\pi/6$  rad/sample and unity gain in the passband.

- Find the overall frequency response  $F(\omega)$  for this system.
  - Sketch the magnitude of  $F(\omega)$ .
  - Discuss the possible advantages of a system like that shown above compared to directly implementing a digital filter with frequency response  $F(\omega)$  as a single stage.
2. For the signals below, do the following: (i) sketch the signal, (ii) find the ZT if it exists, (iii) sketch the ROC for the ZT, showing all poles and zeros.

- $x[n] = \left(\frac{1}{5}\right)^n \cos(\pi n/5) u[n]$

- $$x[n] = \begin{cases} \left(\frac{1}{2}\right)^n, & n \geq 0 \\ 3^n, & n \leq -1 \end{cases}$$

- $$x[n] = \begin{cases} 3^n, & n \geq 0 \\ \left(\frac{1}{2}\right)^n, & n \leq -1 \end{cases}$$

*Hint:* You should, as much as possible, use known signal-ZT pairs and ZT properties, rather than evaluating the ZT sum directly.

3. Consider the ZT

$$X(z) = \frac{1}{\left(1 - \frac{1}{3}z^{-1}\right)\left(1 + 3z^{-1}\right)}$$

Sketch the 3 different ROC's that are possible for this ZT; and for each ROC, find the corresponding signal  $x[n]$ . Simplify your answers as much as possible. Also, for each of the three signals  $x[n]$ , state whether or not the DTFT  $X(\omega)$  exists for that signal.

4. Consider a causal LTI system with transfer function

$$H(z) = \frac{\left(1 - \frac{1}{4}z^{-2}\right)}{\left(1 + \frac{1}{4}z^{-2}\right)}$$

- Sketch the locations of the poles and zeros.
- Use the graphical approach to determine the magnitude and phase of the frequency response  $H(\omega)$ , for  $\omega = 0, \pi/6, \pi/3$ , and  $\pi/2$ . Based on these values, sketch the magnitude and phase of the frequency response for  $-\pi \leq \omega \leq \pi$ . (Be sure to show your work.)
- Is the system stable, Explain why or why not?
- Find the difference equation for  $y[n]$  in terms of  $x[n]$ , corresponding to this transfer function  $H(z)$ .