

Conditional Probability 9/8/2022

We know that $\forall A \in \mathcal{F}$, there is a prob. $P(A)$. Often we want to know the prob. of event A given the occurrence of another event B . This is called a cond. prob.

ex. Roll a fair die.

$$\text{Let } S = \{1, 2, 3, 4, 5, 6\}$$

Consider two events:

$A = \{2, 4, 6\}$, or A is the event "outcome is even"

$$P(A) = \frac{1}{2}$$

$B = \{4, 5, 6\}$, or "outcome > 3 "

$$P(B) = \frac{1}{2}$$

Pr What is the prob. of A given B occurs?

Intuitively, it is

$$\frac{|A \cap B|}{|B|} = \frac{2}{3}$$

To generalize this basic idea to make it work for any random exp., we use:

Defn. Given A and $B \in \mathcal{F}$, the ~~conditional~~ conditional probability of A given B

is
$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \text{if } P(B) > 0.$$

If $P(B) = 0$, $P(A|B)$ is undefined (in this class).

Note that $P(\cdot|B): \mathcal{F} \rightarrow [0, 1]$ is a valid prob. measure for any fixed $B \in \mathcal{F}$ with $P(B) > 0$.

Proof omitted.

Also, $P(\cdot|B)$ is part of the prob. space $(\mathcal{S}, \mathcal{F}, P(\cdot|B))$

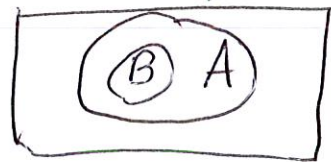
Some properties:



1. If $A \subset B$, then
$$P(A|B) = \frac{P(A)}{P(B)} = \frac{P(A)}{P(A)}$$

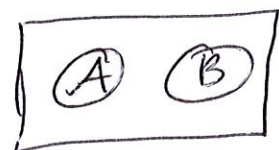
2. If $B \subset A$, then (3)

$$P(A|B) = \frac{P(B)}{P(B)} = 1$$



3. If $A \cap B = \emptyset$, then

$$P(A|B) = \frac{P(\emptyset)}{P(B)} = 0$$



Bayes Theorem

Let (S, \mathcal{F}, P) be a prob. space and $A, B \in \mathcal{F}$ with $P(A), P(B) > 0$.

We can write

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \text{ and } P(B|A) = \frac{P(A \cap B)}{P(A)}$$

From the defn. of cond. prob.

So $P(A|B)P(B) = P(B|A)P(A)$, or

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

This is Bayes' Theorem

The Total Probability Law (TPL) (4)

Let A_1, \dots, A_n , with $P(A_i) > 0 \forall A_i \in \mathcal{G}$,
be a partition of \mathcal{S} . Let $B \in \mathcal{G}$.

Then the TPL states that

$$P(B) = \sum_{i=1}^n P(B|A_i) P(A_i)$$

Proof. $P(B) = P(B \cap \mathcal{S})$

$$= P(B \cap \left(\bigcup_{i=1}^n A_i\right))$$

$$= \cancel{P\left(\bigcup_{i=1}^n (B \cap A_i)\right)} = P\left(\bigcup_{i=1}^n (B \cap A_i)\right)$$

(since \cap distributes
over union)

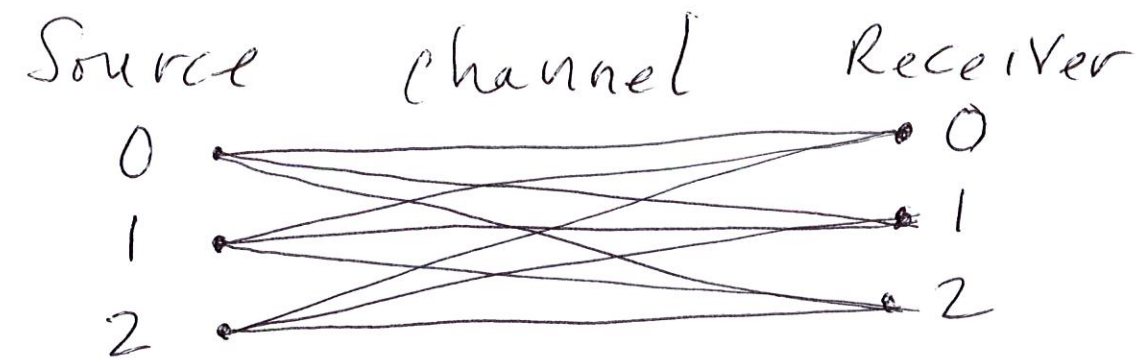
$$= \sum_{i=1}^n P(B \cap A_i) \quad \text{from Axiom 3,}$$

since A_1, \dots, A_n
are disjoint.

$$\text{So } P(B) = \sum_{i=1}^n P(B|A_i) P(A_i) \quad \text{from}$$

the defn. of cond.
prob.

Example. Consider a (5)
communications system with
a 3-symbol alphabet $\{0, 1, 2\}$



Let $\mathcal{S} = \{(i, j) : i \text{ is sent, } j \text{ is received; } i, j \in \{0, 1, 2\}\}$

Consider two events:

$A = \{(0, 0), (0, 1), (0, 2)\}$, or 0 is sent

$B = \{(0, 0), (1, 0), (2, 0)\}$, or 0 is received.

Then $P(A|B) = P(0 \text{ s} | 0 \text{ r})$

This prob. is what we want to know, but it is difficult to estimate directly.

Using Bayes' Theorem, (6)
we have

$$P(O_s|O_r) = \frac{P(O_r|O_s)P(O_s)}{P(O_r)}$$

Now we need

- $P(O_r|O_s)$

In practice, estimate this using "channel modeling"

- $P(O_s)$

Estimate this using "source modeling"

- $P(O_r)$

Use the TPL to write this in terms of the channel and source probs.

To find $P(O_r)$:

Let $A_i = \{(i,0), (i,1), (i,2)\}$ ①

Then A_0, A_1, A_2 form a
partition

$$\text{Then } P(O_r) = \sum_{i=0}^2 P(O_r|A_i)P(A_i)$$

final result

$$P(O_s|O_r) = \frac{P(O_r|O_s)P(O_s)}{\sum_{i=0}^2 P(O_r|A_i)P(A_i)}$$