

# Probabilistic characterization of a rp

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We can define an  $n$ th ~~order~~  
order cdf for a rp  $X(t)$  as

$$F_{X(t_1) \dots X(t_n)}(x_1, \dots, x_n; t_1, \dots, t_n) =$$

$$P(X(t_1) \leq x_1, \dots, X(t_n) \leq x_n)$$

for any  $n \in \mathbb{N}$ , ~~and~~ any  
 $(t_1, \dots, t_n)^T \in \mathbb{R}^n$  and any  $(x_1, \dots, x_n)^T \in \mathbb{R}^n$

In practice, it is ~~never~~ often  
not possible to model the process  
this way. Instead, in many cases  
we use first and second-order  
moment functions. ~~instead~~

Defn. The mean function of a rp  
 $X(t)$  is

$$\mu_X(t) = E[X(t)] \quad \forall t \in T$$

Note  $E[X(t)] = \int_{-\infty}^{\infty} x f_{X(t)}(x) dx$  (2)

for each fixed  $t \in T$ ,

where  $f_{X(t)}$  is the pdf of the rv  $X(t)$ .

Defn. The autocorrelation function of a rp  $X(t)$  is

$$R_{XX}(t_1, t_2) = E[X(t_1)X(t_2)], \forall t_1, t_2 \in T$$

$$= \iint_{\mathbb{R}^2} x_1 x_2 \underbrace{f_{X(t_1), X(t_2)}(x_1, x_2)}_{\text{joint pdf of } X(t_1), X(t_2)} dx_1 dx_2$$

joint pdf of  $X(t_1), X(t_2)$

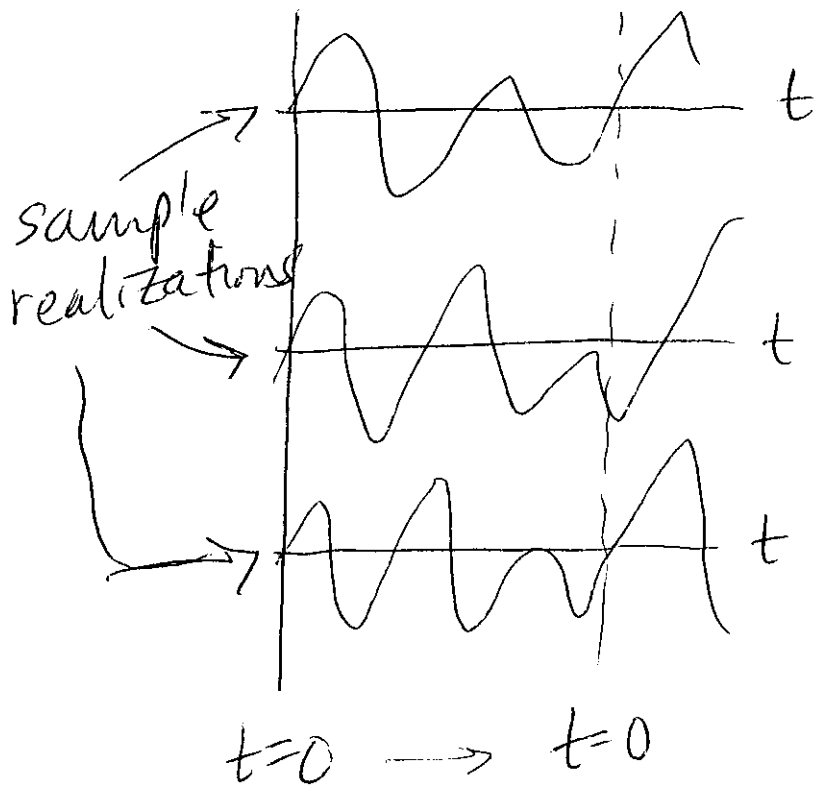
Defn. The autocovariance function of a rp  $X(t)$  is

$$C_{XX}(t_1, t_2) = E[(X(t_1) - \mu_X(t_1))(X(t_2) - \mu_X(t_2))]$$

Note: If  $X(t)$  is a ③  
 complex-valued rv, we use  
 $R_{XX}(t_1, t_2) = E[X(t_1) X^*(t_2)]$

## Stationarity

Do the probability distributions and mean/auto correlations of a rv depend on where the time origin is?



If the point  $t=0$  changes, do the pdfs change? What about  $R_{XX}$  and  $C_{XX}$ , and  $\mu_X$ ?

Two types of stationarity (4)  
will be discussed.

Defn. A rp  $X(t)$  is strict-sense stationary (SSS) if

$$F_{X(t_1), \dots, X(t_n)}(x_1, \dots, x_n) = F_{X(t_1+\tau), \dots, X(t_n+\tau)}(x_1, \dots, x_n)$$

$\forall n \in \mathbb{N}; \forall (t_1, \dots, t_n)^T \in T^n; \forall x_1, \dots, x_n;$   
for any  $\tau \in T$

Note: To ~~show~~ determine whether a  
rp is SSS, compute the  
rhs. If it does not depend  
on  $\tau$ , then  $X(t)$  is SSS,  
otherwise  $X(t)$  is not SSS.

Note that:

• If  $X(t)$  is SSS, then

~~$$f_{X(t)}(x) = f_{X(t+\tau)}(x)$$~~

$$f_{X(t)}(x) = f_{X(t+\tau)}(x) = f_X(x)$$

for any  $t, \tau$ , and  $x \in \mathbb{R}$  <sup>(5)</sup>

and some pdf  $f_x$

• If  $X(t)$  is SSS, then

$$f_{X(t_1)X(t_2)}(x_1, x_2) =$$

$$f_{X(t_1+\alpha)X(t_2+\alpha)}(x_1, x_2) =$$

$$f_{X_1 X_2}(x_1, x_2, \tau), \quad \forall t_1, t_2, x_1, x_2, \alpha$$

where  $\tau = t_2 - t_1$

$$\tau = t_2 + \alpha - (t_1 + \alpha) = t_2 - t_1$$

and  $f_{X_1 X_2}$  is ~~the~~ a

second order pdf

Defn. A r.p  $X(t)$  is wide-sense stationary (WSS) if it satisfies: (6)

$$(1) E[X(t)] = \mu_x \quad \forall t \in T$$

for some  $\mu_x \in \mathbb{R}$

$$(2) R_{xx}(t_1, t_2) = R_x(t_2 - t_1) = R_x(\tau)$$

for some function  $R_x: \mathbb{R} \rightarrow \mathbb{R}$ ,  
where  $\tau = t_2 - t_1$ , for  
all  $t_1, t_2 \in T$

Some properties:

- If  $X(t)$  is WSS, then  
—  $E[X^2(t)] = R_{xx}(t, t) = R_x(0)$ ,

and this means  
that  $R_x(0) \geq 0$

- $C_{xx}(t_1, t_2) = R_{xx}(t_1, t_2) - \mu_x(t_1)\mu_x(t_2)$   
 $= R_x(\tau) - \mu_x^2 = C_x(\tau), \tau = t_2 - t_1$

- If  $X(t)$  is SSS, then  $\textcircled{7}$   
 it is WSS, but the  
 converse is not necessarily  
 true Proof. omitted

Defn. A rp  $X(t)$  is a Gaussian  
 rp if  $X(t_1), X(t_2), \dots, X(t_n)$  are  
 jointly Gaussian rvs,  $\forall n \in \mathbb{N}$   
 and any  $(t_1, \dots, t_n) \in T^n$   
 The  $n$ th-order char. fn of a  
 Gaussian rp is

$$\Phi_{X(t_1), \dots, X(t_n)}(w_1, \dots, w_n) =$$

$$\exp \left[ i \sum_{k=1}^n \mu_X(t_k) w_k - \frac{1}{2} \sum_{j=1}^n \sum_{k=1}^n C_{XX}(t_j, t_k) w_j w_k \right],$$

for  $n \in \mathbb{N}$ ,  $(t_1, \dots, t_n) \in T^n$ ,

$$(w_1, \dots, w_n)^T \in \mathbb{R}^n$$