

Two Functions of Two rvs 10/20/2022

Given two rvs X, Y , consider

$$Z = g(X, Y)$$

$$W = h(X, Y)$$

where $g: \mathbb{R}^2 \rightarrow \mathbb{R}$, $h: \mathbb{R}^2 \rightarrow \mathbb{R}$

For example,

$$\begin{bmatrix} Z \\ W \end{bmatrix} = A_{2 \times 2} \begin{bmatrix} X \\ Y \end{bmatrix}.$$

This can be used to represent rotation, scaling, projection in 2D, for example.

In this case,

$$g(x, y) = a_{11}x + a_{12}y$$

$$h(x, y) = a_{21}x + a_{22}y$$

Find f_{ZW} . We could find

$$F_{ZW}(z, w) = P((X, Y) \in D_{zw})$$

for some $D_{zw} \in \mathcal{B}(\mathbb{R}^2)$,

but finding D_{zw} in general is very difficult.

Instead, use a change-of-variables approach: ⁽²⁾

Assume that:

• the system

$$z = g(x, y)$$

$$w = h(x, y)$$

can be solved simultaneously for

$$x = g^{-1}(z, w)$$

$$y = h^{-1}(z, w)$$

For the linear transf. example, this means A_{22} is invertible, in which case

$$g^{-1}(z, w) = b_{11}z + b_{12}w$$

$$h^{-1}(z, w) = b_{21}z + b_{22}w$$

↑
elements
of A_{22}^{-1}

• $\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}, \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}$ all exist

Under these two assumptions, ⁽³⁾

$$f_{zw}(z, w) = \frac{f_{xy}(g^{-1}(z, w), h^{-1}(z, w))}{\left| \frac{\partial(z, w)}{\partial(x, y)} \right|}$$

Jacobian of the transformation

$$\left| \frac{\partial(z, w)}{\partial(x, y)} \right| \equiv \left| \begin{bmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{bmatrix} \right| = \left| \frac{\partial z}{\partial x} \frac{\partial w}{\partial y} - \frac{\partial z}{\partial y} \frac{\partial w}{\partial x} \right|$$

absolute value
of the determinant

Proof in Papoulis

This ^{result} assumes the Jacobian
is not 0

Example. X and Y are iid Gaussian
with $\mu_x = \mu_y = 0$, $\sigma_x = \sigma_y = \sigma$, $\rho = 0$

Let $R = \sqrt{X^2 + Y^2}$, $\Theta = \tan^{-1}\left(\frac{Y}{X}\right)$ (R parameter
of joint
Gaussian
pdf)

So $g(x, y) = \sqrt{x^2 + y^2}$, $h(x, y) = \tan^{-1}\left(\frac{y}{x}\right)$

$$f_{xy}(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{x^2 + y^2}{2\sigma^2}\right)$$

The formula for $f_{R\Theta}$ gives (4)

$$f_{R\Theta}(r, \theta) = \frac{r}{2\pi\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) u(r), \text{ for}$$
$$-\pi \leq \theta \leq \pi$$

We can find $f_R(r)$ by integrating

$$f_R(r) = \int_{-\pi}^{\pi} \frac{r}{2\pi\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) d\theta, \quad r \geq 0$$
$$= \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) u(r)$$

This is called the Rayleigh rv.

Note that if $Z = g(X, Y)$, can find $f_Z(z)$ by defining an 'auxiliary' variable W , find f_{ZW} , then integrating over w . Sometimes a good choice is $W = X$ or $W = Y$.

f_{ZW}

Joint expectation

(5)

Given rvs X, Y , and $Z = g(X, Y)$ for some $g: \mathbb{R}^2 \rightarrow \mathbb{R}$, we know that

$$E[Z] = \int_{-\infty}^{\infty} g f_Z(z) dz$$

from the defn. of exp. of a r.v.

It can be shown that

$$E[Z] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{XY}(x, y) dx dy$$

Proof in Papoulis

If X, Y are discrete, can use

$$E[Z] = \sum_{x \in R_x} \sum_{y \in R_y} g(x, y) \underset{\substack{\uparrow \\ \text{joint pdf}}}{p_{XY}(x, y)}$$

Some important joint expectations:

- The correlation between X and Y is

$$\text{Corr}(X, Y) \equiv E[XY]$$

- The covariance of X and Y is

$$\text{Cov}(X, Y) = E[(X - \bar{X})(Y - \bar{Y})] \quad (6)$$

- The correlation coefficient of X and Y is

$$r_{XY} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

Note:

— Sometimes called r or ρ

— $|r_{XY}| \leq 1$

Proof on HW

— If X and Y are ind., then $r_{XY} = 0$.

$$\text{Cov}(X, Y) =$$

$$E[(X - \bar{X})(Y - \bar{Y})] =$$

$$\begin{aligned} & \int \int (x - \bar{X})(y - \bar{Y}) f_X(x) f_Y(y) dx dy \\ &= \underbrace{\int_{-\infty}^{\infty} (x - \bar{X}) f_X(x) dx}_{\bar{X} - \bar{X}} \underbrace{\int_{-\infty}^{\infty} (y - \bar{Y}) f_Y(y) dy}_{\bar{Y} - \bar{Y}} \end{aligned}$$

So $\text{Cov} = 0$ and $r_{XY} = 0$

If $r_{XY} = 0$, then ⑦
 X, Y are not
necessarily ind.

— If $r_{XY} = 0$, then
 X, Y are said to be
uncorrelated

Equivalent definitions for
uncorrelatedness are:

— X and Y are uncorrelated iff
 $\text{Cov}(X, Y) = 0$, or

— X, Y are uncorrelated iff
 $E[XY] = \bar{X}\bar{Y}$

Final definition: X and Y are
orthogonal if $E[XY] = 0$