We have introduced SSS, which says that a rp is SSS if all of its nthrovder distributions do not depend on where the time origin is.

A weaker form of stationarty

- (3) (second type of stationarity)

 A rp XI is wide-sense

 Stationary (WSS) if
 - $\mu_X(t) = \mu_X$ does not depend on to and
 - $R_{XX}(t_1,t_2)=E\left[X\left(t_1\right)X\left(t_2\right)
 ight]=R_X(au)$ for some function

 $R_X: \mathbb{R} \to \mathbb{R}_{\mathcal{I}}$

where $au=t_2-t_1$

 $\begin{array}{cccc}
t_1 & t_2 & t_3 & t_4
\end{array}$

The correlation of X(ti), X(ti) equals the correlation of X(ti), X(ty) since $t_2 - t_1 = t_4 - t_3 = T$.

In mis case, can

write $R_X(\tau) = E[X(t)X(t+\tau)]$ Note: the second property of a USS rp holds if $E[X(t)X(t+\tau)]$ does not depend on t.

Note that if $\chi(t)$ is WSS, then $C_{XX}(t_1,t_2)=R_{XX}(t_1,t_2)-\mu_X(t_1)\,\mu_X(t_2)$

le comes

$$C_{XX}(t_1, t_2) = C_X(\tau) = R_X(\tau) - \mu_X^2$$

Dehr. A vp X(t) is a whitenoise process it it is WSS and $\mu_X = 0$, and

• $R_X(\tau) = N\delta(\tau)$

dirac-delta for some NEIR, N=0, where N is called the "noise Abwer"

Communt:

· White noise has $E\left[X\left(t_{1}\right)X\left(t_{2}\right)\right]=0$ if $t_1 \neq t_2$, so $X(t_1)$, $X(t_2)$ are

orthogonal for white noise, and thus, since Mx(t)=0, Xtt), X(k2) are un correlated · The "Frequency content" of a WSS rp W defined as the Fourier Transform of Rx (t). With this definition, unite notse has a confant frequencies, since S(t) \$\frac{1}{4} \for all trequencies wER

Linear Time-Invariant Systems with Random Input Signals

From ECE 30(: An LTT system can be characterized by its impulse response 8(t) -> [t] h(t) Then $x(t) \longrightarrow h(t) \longrightarrow y(t) = x(t) * h(t)$ What if the input is a rp? $X(t) \longrightarrow h(t) \longrightarrow Y(t)$ The means $X(t,w) \longrightarrow h(t) \longrightarrow Y(t,\omega)$ So for each wes? $Y(t,\omega) = h(t) * X(t,\omega)$

In practice, often want to know the mean function My(t) and the autocome letien

function Ryy (t₁, t₂), since these two functions are commonly used to characterize vps: $\mu_{Y}(t) = E[Y(t)] = E\left[\int_{-\infty}^{\infty} X(t - \alpha) h(\alpha) d\alpha\right]$ $= \int_{-\infty}^{\infty} E[X(t-\alpha)] h(\alpha) d\alpha$ $\int \rho \left(\mu_{Y}(t) = \mu_{X}(t) * h(t), \forall t \right)$ A (68) $R_{YY}(t_1, t_2) = E[Y(t_1) Y(t_2)]$ $= E \left[\int_{-\infty}^{\infty} X(t_1 - \alpha) h(\alpha) d\alpha \int_{-\infty}^{\infty} X(t_2 - \beta) h(\beta) d\beta \right]$ $= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E\left[X\left(t_{1} - \alpha\right) X\left(t_{2} - \beta\right)\right] h\left(\alpha\right) h\left(\beta\right) d\alpha d\beta$ $S_{0} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R_{XX}(t_{1} - \alpha, t_{2} - \beta) h(\alpha) h(\beta) d\alpha d\beta$ for drouble understand how this was derived. If we assume that XL+) is WSS with $\mu_X(t) = \mu_X, R_{XX}(t_1, t_2) = R_X(\tau)$

with
$$au=t_2-t_1$$

Then
$$\mu_Y(t) = \int_{-\infty}^{\infty} \mu_X h\left(\alpha\right) d\alpha$$

$$= \mu_X \int_{-\infty}^{\infty} h\left(\alpha\right) d\alpha = \mu_Y,$$
 hoes not defined on t

$$R_{YY}(t_{1}, t_{2}) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R_{X}(t_{2} - t_{1} - \beta + \alpha) h(\alpha) h(\beta) d\alpha d\beta$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} R_{X}(t_{2} - t_{1} + \alpha - \beta) h(\beta) d\beta \right] h(\alpha) d\alpha$$

$$(R_{X} * h) (\tau + \alpha)$$

$$R_{YY}(t_1,t_2) = \int_{-\infty}^{\infty} (R_X*h) (\tau + \alpha) h(\alpha) d\alpha$$

To write this more compactly,

(it $\lambda = -\alpha$. Then

 $R_Y(\tau) = \int_{-\infty}^{\infty} h(-\lambda) (h*R_X) (\tau - \lambda) dx$

Now let
$$\tilde{h}(t) = h(-t)$$
. Then
$$\begin{bmatrix} R_Y(\tau) = \left(\tilde{h}*h*R_X\right)(\tau) \end{bmatrix}$$
 Have shown that if $X(t)$ is WSS, $Y(t)$ has constant mean, and autoconvolation function that depends on $t_2-t=2$. As Ing as $\int_{-\infty}^{\infty} h(\alpha) d\alpha < \infty$, $Y(t)$ is WSS, txemple. Let $X(t)$ be a whole noise groces with $R_X(\tau) = N_0\delta(\tau), N_0 > 0$ and $X(t) = e^{-t}u(t)$ If $X(t)$ is followed by

h(t), then
$$\mu_{Y}(t) = \mu_{X} \int_{-\infty}^{\infty} h(t) dt = 0$$
Since white voise is Zerr-we in
$$KSO,$$

$$R_{y}(\tau) = e^{\tau}u(-\tau) * e^{-\tau}u(\tau) * N_{0}\delta(\tau),$$

$$R_{Y}(\tau) = \frac{N_{0}}{2}e^{-|\tau|}; \tau \in \mathbb{R}$$

$$K_{X}[T]$$

$$Kofe that
$$K[t_{1}], X[t_{2}] \text{ are uncorrelated}$$

$$K[t_{1}], Y[t_{2}] \text{ have}$$

$$Correlation \frac{N_{0}}{2}e^{-|t_{2}-t_{1}|}$$$$

· Filtering ce of can be used to create "colored noise" from white noise. This is offen done in nursic. Also, there are products that deliver white nowe and various types of coloned noise, created using different Afters h(t). Some people report that there
products help 800 the
them and help them
sleep but I do not know
if there is any scientific
evidence for this.