Purdue

COURSENAME/SECTIONNUMBER EXAM TITLE

NAME	PUID

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- 1. Make sure your name and PUID are clearly written at the top of every page, including any additional blank pages you use.
- 2. Write only on the front of the exam pages.
- 3. Add any additional pages used to the back of the exam before turning it in.
- 4. Ensure that all pages are facing the same direction.
- 5. Answer all questions in the area designated for that answer. Do not run over into the next question space.

Final Exam of ECE 301-004, (CRN: 13890) 3:30–5:30pm, Thursday, May 5, 2022, PHYS 112.

- 1. Do not write answers on the back of pages!
- 2. After the exam ended, you will have 5 additional minutes to write down your name and Purdue ID on each of the pages.
- 3. If you need additional sheets to write down your answers, please let the instructor/TA know. We will hand out additional answer sheets then.
- 4. Enter your student ID number, and signature in the space provided on this page.
- 5. This is a closed book exam.

Name:

- 6. This exam contains multiple-choice questions and work-out questions. For multiple choice questions, there is no need to justify your answers. You have two hours to complete it. The students are suggested not spending too much time on a single question, and first working on those that you know how to solve.
- 7. If needed and requested by students, the instructor/TA will hand out loose sheets of paper for the rough work.
- 8. Neither calculators nor help sheets are allowed.

Student ID:	
	uing academic excellence, I pledge to be at I do. Accountable together — We are
Signature:	Date:

```
Question 1: [22%, Work-out question]
```

1. [1%] What does the acronym FDM stand for?

Prof. Wang wanted to transmit an AM-SSB signal. To that end, he wrote the following MATLAB code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;
% Read two different .wav files
[x1, f_sample, N] = audioread('x1.wav');
x1=x1';
[x2, f_sample, N]=audioread('x2.wav');
x2=x2';
% Step 0: Initialize several parameters
W_1=3000*pi;
W_2=1500*pi;
W_3 = ????;
W_4=????;
W_5=????;
W_6 = ????;
W_7=8000*pi;
% Step 1: Make the signals band-limited.
h=1/(pi*t).*(sin(W_1*t));
x1_new=ece301conv(x1, h);
x2_{new}=ece301conv(x2, h);
% Step 2: Multiply x1_new and x2_new with a sinusoidal wave.
x1_h=x1_new.*sin(W_2*t);
x2_h=x2_new.*sin(W_3*t);
% Step 3: Keep one of the two side bands
h_{one=1/(pi*t).*(sin(W_4*t).*(2*cos(W_5*t)));}
h_{two=1/(pi*t).*(sin(W_6*t)-sin(W_7*t))};
x1_sb=ece301conv(x1_h, h_one);
```

```
x2_sb=ece301conv(x2_h, h_two);
% Step 4: Create the transmitted signal
y=x1_sb+x2_sb;
audiowrite('y.wav', y, f_sample);
```

- 2. [1%] What is the carrier frequency (Hz) of the signal x1_new?
- 3. [4%] Our goal is to transmit either the lower-side band (LSB) or the upper side band (USB). However, it turns out that for the x1 signal, only one of the two options (LSB and USB) is possible. Explain in details which option (LSB or USB) is possible for the x1 signal.

Hint: You need to carefully justify your answer. An answer without justification will receive zero point.

- 4. [3%] Continue from the previous sub-question. What would be the right values of W_4 and W_5 ?
- 5. [3%] If I would like to transmit the upper side band of the x2 signal. What would be my choice of W_3 and W_6 values? When answering this sub-question, please always assume the value of W_6 is no less than $W_7 = 8000\pi$. I.e., $W_6 \ge 8000\pi$.
- 6. [2%] If I would like to transmit the lower side band of the x2 signal. What would be my choice of W_3 and W_6 values? When answering this sub-question, please always assume the value of W_6 is no less than $W_7 = 8000\pi$. I.e., $W_6 \ge 8000\pi$.

Prof. Wang decided to use **the upper-side-band transmission** for both the x1 and the x2 signals, and used the code in the previous page to generate the "y.wav" file.

A student tried to demodulate the output waveform "y.wav" by the following code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;
% Read the .wav files
[y, f_sample, N]=audioread('y.wav');
y=y';
% Initialize several parameters
W_8=????;
W_9=6000*pi;
W_10=1500*pi;
W_11=1500*pi;
W_12=7000*pi;
W_13=????;
% Create a new low-pass filter.
h_M=1/(pi*t).*(sin(W_8*t));
% We construct new BPFs
h_{three}=1/(pi*t).*(sin(W_9*t)-sin(W_10*t));
h_four=1/(pi*t).*(sin(W_11*t).*(2*cos(W_12*t)));
% demodulate signal 1
y11=ece301conv(y, h_three);
v1=v11.*sin(1500*pi*t);
x1_hat=4*ece301conv(y1,h_M);
sound(x1_hat,f_sample)
```

```
% demodulate signal 2
y21=ece301conv(y, h_four);
y2=y21.*sin(W_13*t);
x2_hat=4*ece301conv(y2,h_M);
sound(x2_hat,f_sample)
```

- 7. [3%] Continue from the previous questions. What should the values of W₋8 and W₋13 be in the MATLAB code?
- 8. [5%] It turns out that the above MATLAB code is not written correctly and part of the end results do not sound right. Answer the following questions
 - (a) Is signal x1_new correctly/perfectly demodulated? If yes, then go to subquestion (d). If no, then continue answering the following sub-questions.
 - (b) Use 2 to 3 sentences to answer (i) what kind of problem does x1_new have, i.e., how does the problem impact the sound quality of "sound(x1_hat,f_sample)"?
 - (c) How can the MATLAB code be corrected so that the playback/demodulation can be successful?
 - (d) Is signal x2_new correctly/perfectly demodulated? If yes, then your answer to Q1.8 is complete. If no, then continue answering the following sub-questions.
 - (e) Use 2 to 3 sentences to answer (i) what kind of problem does x2_new have, i.e., how does the problem impact the sound quality of "sound(x2_hat,f_sample)"?
 - (f) How can the MATLAB code be corrected so that the playback/demodulation can be successful?

Hint: If you do not know the answers of Q1.3 to Q1.8, please simply draw the AMSSB modulation (using lower side band) and demodulation diagrams and mark carefully all the parameter values. You will receive 12 points for Q1.3 to Q1.8 if your system diagrams are correct and all parameter values are marked correctly.

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Question 2: [14%, Work-out question]

Consider a continuous time signal:

$$x(t) = U(t+5) - U(t-5)$$
(1)

where U(t) is the unit-step signal.

- 1. [1%] Plot x(t) for the range of $-10 \le t \le 10$.
- 2. [3%] Plot $X(j\omega)$, the CTFT of x(t), for the range of $-\pi \leq \omega \leq \pi$.

We construct another signal $y(t) = x(t) \cdot \cos(\pi t)$.

3. [5%] Plot $Y(j\omega)$, the CTFT of y(t), for the range of $-1.4\pi \le \omega \le 1.4\pi$.

Hint 1: If you don't know how to answer this question, you can write down the relationship between $X(j\omega)$ and $Y(j\omega)$. You will receive 2.5 points if your answer is correct.

Suppose we perform amplitude modulation to convert an acoustic $w(t) = \sin(\pi t)$ to a new signal $z(t) = w(t) \cdot \sin(4000\pi t)$.

4. [5%] If we demodulate the signal z(t) by the asynchronous demodulation. Denote the final output by $\hat{w}(t)$. Plot $\hat{w}(t)$ for the range of $-4 \le t \le 4$.

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Question 3: [12%, Work-out question]

1. [4%] Consider a continuous time signal

$$x(t) = \begin{cases} 2t + 2 & \text{if } -1 \le t < 0\\ 2 & \text{if } 0 \le t < 0.5\\ 3 - 2t & \text{if } 0.5 \le t < 1.5\\ 0 & \text{otherwise} \end{cases}$$
 (2)

We sample x(t) with the sampling frequency 2Hz and denote the sampled values by x[n]. Plot x[n] for the range of $-5 \le n \le 5$.

- 2. [3%] We also perform 2Hz Impulse Train Sampling (ITS) on x(t) and the resulting signal is $x_p(t)$. Plot $x_p(t)$ for the range of $-5 \le t \le 5$.
- 3. [5%] Define another signal

$$h(t) = \begin{cases} 1 & \text{if } |t| < 0.25\\ 0 & \text{otherwise} \end{cases}$$
 (3)

Denote $y(t) = x_p(t) * h(t)$. Plot y(t) for the range of $-5 \le t \le 5$.

Hint: If you do not know the answer to this subquestion, you can assume $y(t) = \sin(\pi t) * \delta(t-1.5)$ and plot y(t) for the range of $-5 \le t \le 5$. You will receive 2 points if your answer is correct.

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Question 4: [13%, Work-out question]

- 1. [5%] Consider a continuous time signal $x(t) = \sin(\pi t)$. We sample x(t) via impulse train sampling with sampling period 0.2. Denote the final impulse-train-sampled signal by $x_p(t)$. Plot $X_p(j\omega)$, the CTFT of $x_p(t)$, for the range of $-15\pi < \omega < 15\pi$;
- 2. [3%] We pass $x_p(t)$ through an ideal band-pass filter of cutoff frequencies $W_L = 8\pi$ and $W_H = 12\pi$ and denote the output by y(t). Plot $Y(j\omega)$, the CTFT of y(t), for the range of $-15\pi < \omega < 15\pi$;

Hint 1: if you do not know the answer to Q4.1 and Q4.2, you can simply write down the impulse response of the ideal BPF with $W_L = 8\pi$ and $W_H = 12\pi$. You will receive 1.5 points if your answer is correct.

3. [5%] Find the expression of y(t).

Hint 2: You do not need to plot y(t). Just writing down the mathematical expression of y(t) would suffice.

Hint 3: This process is sometimes termed the *Amplitude Modulation Via Impulse Train Sampling*. This "name" should be helpful when you are answering Q4.3.

Hint 4: If you do not know the answer to Q4.2, you can assume

$$Y(j\omega) = \sum_{k=1}^{2} e^{j0.5\pi \cdot k} \delta(\omega - (8+k)\pi) + \sum_{k=-2}^{-1} e^{j0.5\pi \cdot k} \delta(\omega - (k-8)\pi)$$

You will receive full credit if your answer is correct.

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This sheet is for Question 4.		

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Purdue ID:

 $Question~5: [8\%, \, \text{Work-out question}]$

Consider the following discrete time signals

$$x[n] = \begin{cases} n \cdot e^{j0.25\pi n} & \text{if } 1 \le n \le 4\\ 1+j & \text{if } 5 \le n \le 20 \\ \text{periodic with period } N = 20 \end{cases}$$
 (4)

Denote the DTFS coefficients of x[n] by a_k .

- 1. [4%] Find the value of $\sum_{k=0}^{39} a_k$.
- 2. [4%] Find the value of $\sum_{k=10}^{29} |a_k|^2$.

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Question 6: [8%, Work-out question] Define the following two signals:

$$x(t) = e^{-3(t-1)}U(t-1)$$
(5)

$$h(t) = e^{-2t}U(t) \tag{6}$$

Find the expression of

$$y(t) = x(t) * h(t). \tag{7}$$

Hint: Table 4.2 may be useful when answering this question.

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Question 7: [8%, Work-out question] Consider a DT signal $x[n] = \cos(0.2\pi n)$. Define $p[n] = \sum_{k=-\infty}^{\infty} \delta[n-5k]$.

- 1. [3%] Define $x_p[n] = x[n] \cdot p[n]$. Plot $x_p[n]$ for the range of $-10 \le n \le 10$.
- 2. [5%] Find the DTFS coefficients a_k of the DT signal $x_p[n]$. Hint: If you do not know the answer of Q7.1, you can assume $x_p[n] = \sum_{k=-\infty}^{\infty} \delta[n-2-5k]$. You will receive 3.5 points if your answer is correct.

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First Name:

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Question 8: [15%, Multiple-choice question] Consider two signals

$$h_1(t) = e^{\int_{-t}^t \cos(s) + s^2 \sin(s) ds}$$
 (8)

and

$$h_2[n] = \sum_{k=0}^{\infty} 2^{-n} e^{j1000n} U[n - 5k]$$
(9)

- 1. [1.25%] Is $h_1(t)$ periodic?
- 2. [1.25%] Is $h_2[n]$ periodic?
- 3. [1.25%] Is $h_1(t)$ even or odd or neither?
- 4. [1.25%] Is $h_2[n]$ even or odd or neither?
- 5. [1.25%] Is $h_1(t)$ of finite power?
- 6. [1.25%] Is $h_2[n]$ of finite power?

Suppose the above two signals are also the impulse responses of two LTI systems: System 1 and System 2, respectively.

- 1. [1.25%] Is System 1 memoryless?
- 2. [1.25%] Is System 2 memoryless?
- 3. [1.25%] Is System 1 causal?
- 4. [1.25%] Is System 2 causal?
- 5. [1.25%] Is System 1 stable?
- 6. [1.25%] Is System 2 stable?

Last Name:	First Name:	Purdue ID:
This sheet is for Question 8.		

Discrete-time Fourier series

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n} \tag{1}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(2\pi/N)n} \tag{2}$$

Continuous-time Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t}$$
(3)

$$a_k = \frac{1}{T} \int_T x(t)e^{-jk(2\pi/T)t}dt \tag{4}$$

Continuous-time Fourier transform

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)e^{j\omega t} d\omega \tag{5}$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t}dt \tag{6}$$

Discrete-time Fourier transform

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega \tag{7}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$$
(8)

Laplace transform

$$x(t) = \frac{1}{2\pi} e^{\sigma t} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{j\omega t} d\omega$$
 (9)

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st}dt \tag{10}$$

Z transform

$$x[n] = r^n \mathcal{F}^{-1}(X(re^{j\omega})) \tag{11}$$

$$X(z) = \sum_{n = -\infty}^{\infty} x[n]z^{-n}$$
(12)

Chap. 3

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

TABLE 3.1 PROPERTIES	Section	Periodic Signal	Fourier Series Coefficients
Property		$x(t)$ Periodic with period T and $y(t)$ fundamental frequency $\omega_0 = 2\pi/T$	a_k b_k
	3.5.1	Ax(t) + By(t)	$Aa_k + Bb_k$ $a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Time Shifting	3.5.2	$x(t-t_0)$ $e^{jM\omega_0 t}x(t) = e^{jM(2\pi/T)t}x(t)$	a_{k-M}
Frequency Shifting Conjugation	3.5.6	$x^*(t)$	a_{-k}^* a_{-k}
Time Reversal	3.5.3	x(-t)	a_{-k} a_k
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	
Periodic Convolution		$\int_T x(\tau)y(t-\tau)d\tau$	Ta_kb_k
Multiplication	3.5.5	x(t)y(t)	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^{t} x(t) dt $ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)^k$ $\left\{a_k = a_{-k}^*\right\}$
Conjugate Symmetry for Real Signals	3.5.6	x(t) real	$\Re \mathscr{C}\{a_k\} = \Re \mathscr{C}\{a_{-k}\}$ $\Im \mathscr{C}\{a_k\} = -\Im \mathscr{C}\{a_{-k}\}$ $ a_k = a_{-k} $ $ a_k = -\langle a_{-k} \rangle$
Real and Even Signals Real and Odd Signals Even-Odd Decomposition	3.5.6 3.5.6	x(t) real and even x(t) real and odd $\begin{cases} x_e(t) = \mathcal{E}_{\mathcal{V}}\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}_{\mathcal{U}}\{x(t)\} & [x(t) \text{ real}] \end{cases}$	a_k real and even a_k purely imaginary and of $\Re \{a_k\}$ $j \Im \{a_k\}$
of Real Signals			
		Parseval's Relation for Periodic Signals	
		$\frac{1}{T}\int_{T} x(t) ^{2}dt = \sum_{k=-\infty}^{+\infty} a_{k} ^{2}$	

three examples, we illustrate this. The last example in this section then demonstrates have properties of a signal can be used to characterize the signal in great detail.

Example 3.6

Consider the signal g(t) with a fundamental period of 4, shown in Figure 3.10. could determine the Fourier series representation of g(t) directly from the analysis extra (2.20). The total f(t) are the fourier series representation of g(t) directly from the analysis extra (2.20). The total f(t) is the first f(t) and tion (3.39). Instead, we will use the relationship of g(t) to the symmetric periodic space f(t) in Example 2.5. Defends to wave x(t) in Example 3.5. Referring to that example, we see that, with T=4 $T_1 = 1$,

$$g(t) = x(t-1) - 1/2.$$

100

Thus, in general, *none* of the finite partial sums in eq. (3.52) yield the exact values of x(t), and convergence issues, such as those considered in Section 3.4, arise as we consider the problem of evaluating the limit as the number of terms approaches infinity.

3.7 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

There are strong similarities between the properties of discrete-time and continuous-time Fourier series. This can be readily seen by comparing the discrete-time Fourier series properties summarized in Table 3.2 with their continuous-time counterparts in Table 3.1.

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Periodic Signal	Fourier Series Coefficient
	$x[n]$ Periodic with period N and $y[n]$ fundamental frequency $\omega_0 = 2\pi/N$	$\begin{bmatrix} a_k \\ b_k \end{bmatrix}$ Periodic with
Linearity Time Shifting Frequency Shifting Conjugation Time Reversal	$Ax[n] + By[n]$ $x[n - n_0]$ $e^{jM(2\pi l/N)n}x[n]$ $x^*[n]$ $x[-n]$	$Aa_k + Bb_k$ $a_k e^{-jk(2\pi/N)n_0}$ a_{k-M} a_{-k}^-
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period mN)	$\frac{1}{m}a_k$ (viewed as periodic) with period mN
Periodic Convolution	$\sum_{r=\langle N\rangle} x[r]y[n-r]$	Na_kb_k
Multiplication	x[n]y[n]	$\sum_{l=\langle N\rangle} a_l b_{k-l}$
First Difference	x[n] - x[n-1]	$(1 - e^{-jk(2\pi/N)})a_{\nu}$
Running Sum	$\sum_{k=-\infty}^{n} x[k] \begin{pmatrix} \text{finite valued and periodic only} \\ \text{if } a_0 = 0 \end{pmatrix}$	$\left(\frac{1}{(1-e^{-jk(2\pi/N)})}\right)a_k$
Conjugate Symmetry for Real Signals	x[n] real	$egin{array}{l} a_k &= a_{-k}^* \ \Re e\{a_k\} &= \Re e\{a_{-k}\} \ \Im m\{a_k\} &= -\Im m\{a_{-k}\} \ a_k &= a_{-k} \ orall a_k &= - otin a_{-k} \end{array}$
Real and Even Signals Real and Odd Signals	x[n] real and even $x[n]$ real and odd	a_k real and even a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = 8v\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = 9d\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\Re\{a_k\}$ $j \Im\{a_k\}$
	Parseval's Relation for Periodic Signals	
	$\frac{1}{N}\sum_{n=\langle N\rangle} x[n] ^2=\sum_{k=\langle N\rangle} a_k ^2$	

onclude from

(3.100)

sequence in (3.106), the one, we have

f eqs. iodic h M = 1;

f values on o represent

4.6 TABLES OF FOURIER PROPERTIES AND OF BASIC FOURIER TRANSFORM PAIRS

In the preceding sections and in the problems at the end of the chapter, we have considered some of the important properties of the Fourier transform. These are summarized in Table 4.1, in which we have also indicated the section of this chapter in which each property has been discussed.

In Table 4.2, we have assembled a list of many of the basic and important Fourier transform pairs. We will encounter many of these repeatedly as we apply the tools of

TABLE 4.1 PROPERTIES OF THE FOURIER TRANSFORM

4.3.1 Linearity at 4.3.2 Time Shifting x 4.3.6 Frequency Shifting et 4.3.3 Conjugation x 4.3.5 Time Reversal x 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication	(t) (t) $(x(t) + by(t)$ $(t - t_0)$ $(t^{j\omega_0 t}x(t)$ $(x'(t) + b^{-1}x(t))$		$X(j\omega)$ $Y(j\omega)$ $aX(j\omega) + bY(j\omega)$ $e^{-j\omega t_0}X(j\omega)$
4.3.1 Linearity a 4.3.2 Time Shifting x 4.3.6 Frequency Shifting e 4.3.3 Conjugation x 4.3.5 Time Reversal x 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.6 Differentiation in Time 4.7 Integration 4.8 Differentiation in Frequency 4.9 Conjugate Symmetry for Real Signals 4.10 Symmetry for Real and Even Signals 4.11 Even Signals 4.12 Even Signals 4.13 Symmetry for Real and Even Signals 4.14 Symmetry for Real and	(t) $(x(t) + by(t))$ $(t(t - t_0))$ $(t^{j\omega_0 t}x(t))$ $(t^*(t))$		$aX(j\omega) + bY(j\omega)$ $e^{-j\omega t_0}X(j\omega)$
4.3.1 Linearity a 4.3.2 Time Shifting x 4.3.6 Frequency Shifting e 4.3.3 Conjugation x 4.3.5 Time Reversal x 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.7 Conjugate Symmetry for Real Signals 4.3.8 Symmetry for Real and Even Signals 4.3.9 Symmetry for Real and Even Signals 4.3.1 Symmetry for Real and Even Signals 4.3.2 Symmetry for Real and Even Signals	$ \begin{aligned} & (x(t) + by(t)) \\ & (t - t_0) \\ & (t^{j\omega_0 t}x(t)) \\ & (t^*(t)) \end{aligned} $		$e^{-j\omega t_0}X(j\omega)$
4.3.1 Enterty 4.3.2 Time Shifting x 4.3.6 Frequency Shifting e 4.3.3 Conjugation x 4.3.5 Time Reversal x 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.7 Conjugate Symmetry for Real Signals 4.3.8 Symmetry for Real and Even Signals 4.3.9 Symmetry for Real and Even Signals 4.3.1 Enterty for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals	$x(t-t_0)$ $x^{j\omega_0t}x(t)$ $x^*(t)$ x(-t)		$e^{-j\omega t_0}X(j\omega)$
4.3.1 Enterty 4.3.2 Time Shifting x 4.3.6 Frequency Shifting e 4.3.3 Conjugation x 4.3.5 Time Reversal x 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.7 Conjugate Symmetry for Real Signals 4.3.8 Symmetry for Real and Even Signals 4.3.9 Symmetry for Real and Even Signals 4.3.1 Enterty for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals	$x(t-t_0)$ $x^{j\omega_0t}x(t)$ $x^*(t)$ x(-t)		
4.3.2 Interstining 4.3.6 Frequency Shifting 4.3.3 Conjugation 4.3.5 Time Reversal 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals 5 Symmetry for Real and	$x^{(j)\omega_0 t} x(t)$ $x^*(t)$ $x(-t)$		
4.3.6 Frequency Sixtures 4.3.7 Time Reversal 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.7 Conjugate Symmetry for Real Signals 4.3.8 Symmetry for Real and Even Signals 4.3.9 Symmetry for Real and Even Signals 5 Symmetry for Real and	$x^*(t)$ $x(-t)$		$X(j(\omega-\omega_0))$
4.3.5 Time Reversal 4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 5 Symmetry for Real and Even Signals 5 Symmetry for Real and Even Signals 5 Symmetry for Real and	$\chi(-t)$		$X^*(-j\omega)$
4.3.5 Time and Frequency Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals 5 Symmetry for Real and			$X(-j\omega)$
4.3.5 Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and			$\frac{1}{ a }X\left(\frac{j\omega}{a}\right)$
Scaling 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and	x(at)		$\overline{ a }^{A} \setminus a$
 4.4 Convolution 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.7 Conjugate Symmetry for Real Signals 4.3.8 Symmetry for Real and Even Signals 4.3.9 Symmetry for Real and Even Signals 4.3.1 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 			$Y(i\omega)Y(i\omega)$
 4.5 Multiplication 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	x(t) * y(t)		1 (+°° a) 10
 4.3.4 Differentiation in Time 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	x(t)y(t)		$\frac{X(j\omega)Y(j\omega)}{\frac{1}{2\pi}} \begin{cases} x(j\theta)Y(j(\omega-\theta))d\theta \end{cases}$
 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 			7 60
 4.3.4 Integration 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	$\frac{d}{dt}x(t)$		$j\omega X(j\omega)$
 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	dt		
 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	ft or		$\frac{1}{i\omega}X(j\omega)+\pi X(0)\delta(\omega)$
 4.3.6 Differentiation in Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and 	$\int_{-\infty}^{t} x(t)dt$		
Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and	J-60		$j\frac{d}{d\omega}X(j\omega)$
Frequency 4.3.3 Conjugate Symmetry for Real Signals 4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and	tx(t)		uw
for Real Signals 4.3.3 Symmetry for Real and Even Signals Symmetry for Real and			$(X(i\omega) = X^*(-j\omega))$
for Real Signals 4.3.3 Symmetry for Real and Even Signals Symmetry for Real and			$Q_{\alpha}(V(i\omega)) = \Re\{X(-j\omega)\}$
for Real Signals 4.3.3 Symmetry for Real and Even Signals Symmetry for Real and			$(\mathcal{A}(\mathcal{A}(\mathcal{A}))) = -(\mathcal{A}(\mathcal{A}))$
for Real Signals 4.3.3 Symmetry for Real and Even Signals Symmetry for Real and	x(t) real		$\{g_{m}\{X(j\omega)\}=g_{m}\{X(j\omega)\}\}$
4.3.3 Symmetry for Real and Even Signals 4.3.3 Symmetry for Real and			$ X(j\omega) = X(-j\omega) $
Even Signals 4 3 3 Symmetry for Real and			$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \Re{e\{X(j\omega)\}} = \Re{e\{X(-j\omega)\}} \\ \Im{m\{X(j\omega)\}} = -\Im{m\{X(-j\omega)\}} \\ X(j\omega) = X(-j\omega) \\ \Im{x}(j\omega) = -\Im{x}(-j\omega) \end{cases}$
Even Signals 4 3 3 Symmetry for Real and	(a1 -md assen		$X(j\omega)$ real and even
Even Signals 4 3 3 Symmetry for Real and	x(t) real and even		
4.3.3 Symmetry for Real and Odd Signals	(3 1 and odd		$X(j\omega)$ purely imaginary and
Odd Signals	x(t) real and odd		
0 = = 0	$x_e(t) = \mathcal{E}\nu\{x(t)\}$	[x(t) real]	$\Re e\{X(j\omega)\}$
4.3.3 Even-Odd Decompo-	$x_e(t) = \text{GV}(\lambda(t))$	[x(t) real]	
4.3.3 Even-Odd Decomposition for Real Sig-	$x_o(t) = \mathfrak{O}d\{x(t)\}$	[x(i)]	Jon-6- 0 17
nals			

4.3.7 Parseval's Relation for Aperiodic Signals
$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega$$

FORM PAIRS

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important Fourier ipply the tools of

transform

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 $(0)\delta(\omega)$

- jω) · $\Re e\{X(-j\omega)\}$ $-\mathcal{I}m\{X(-j\omega)\}$

 $-j\omega)$ $(X(-j\omega))$

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iginary and odd

TABLE 4.2 BASIC FOURIER TRANSFORM PAIRS

Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi\sum_{k=-\infty}^{+\infty}a_k\delta(\omega-k\omega_0)$	a_k
e ^{jω} u ^t	$2\pi\delta(\omega-\omega_0)$	$a_1 = 1$ $a_k = 0$, otherwise
cos ω ₀ t	$\pi[\delta(\omega-\omega_0)+\delta(\omega+\omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0, \text{otherwise}$
sinω ₀ t	$\frac{\pi}{j}[\delta(\omega-\omega_0)-\delta(\omega+\omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0, \text{otherwise}$
x(t) = 1	$2\pi\delta(\omega)$	$a_0 = 1$, $a_k = 0$, $k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$

i citodic squate wave			
$x(t) = \begin{cases} 1, & t < T_1 \\ 0, & T_1 < t \le \frac{T}{2} \end{cases}$ and	$\sum_{k=-\infty}^{+\infty} \frac{2\sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi}$ sinc $\left(\frac{k\omega_0 T_1}{\pi}\right)$	$=\frac{\sin k\omega_0 T_1}{k\pi}$
x(t+T) = x(t)			

$$\sum_{n=-\infty}^{+\infty} \delta(t-nT) \qquad \frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right) \qquad a_k = \frac{1}{T} \text{ for all } k$$

$$x(t) \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases} \frac{2 \sin \omega T_1}{\omega}$$

$$\frac{\sin Wt}{\pi t} \qquad X(j\omega) = \begin{cases} 1, & |\omega| < W \\ 0, & |\omega| > W \end{cases}$$

$$\delta(t)$$
 1 ____

$$u(t)$$
 $\frac{1}{j\omega} + \pi \,\delta(\omega)$ _____

$$\frac{\delta(t-t_0)}{e^{-j\omega t_0}} \qquad \qquad -\frac{1}{2}$$

$$e^{-at}u(t)$$
, $\Re e\{a\} > 0$ $\frac{1}{a+j\omega}$

$$te^{-at}u(t)$$
, $\Re\{a\} > 0$
$$\frac{1}{(a+j\omega)^2}$$

$$\frac{\int_{(n-1)}^{n-1} e^{-at} u(t),}{\operatorname{Re}\{a\} > 0} \frac{1}{(a+j\omega)^n}$$

TABLE 5.1 PROPERTIES OF THE DISCRETE-TIME FOURIER TRANSFORM

Section	Property	Aperiodic Signal		Fourier Transform
		x[n]		$X(e^{j\omega})$ periodic with
		y[n]		$Y(e^{j\omega})$ period 2π
5.3.2	Linearity	ax[n] + by[n]		$aX(e^{j\omega}) + bY(e^{j\omega})$
5.3.3	Time Shifting	$x[n-n_0]$		$e^{-j\omega n_0}X(e^{j\omega})$
5.3.3	Frequency Shifting	$e^{j\omega_0 n}x[n]$		$X(e^{j(\omega-\omega_0)})$
5.3.4	Conjugation	$x^*[n]$		$X^{\bullet}(e^{-j\omega})$
5.3.6	Time Reversal	x[-n]		$X(e^{-j\omega})$
5.3.7	Time Expansion	$x_{(k)}[n] = \begin{cases} x[n/k], \\ 0, \end{cases}$	if $n = \text{multiple of } k$ if $n \neq \text{multiple of } k$	$X(e^{jk\omega})$
5.4	Convolution	x[n] * y[n]	r	$X(e^{j\omega})Y(e^{j\omega})$
5.5	Multiplication	x[n]y[n]		$\frac{1}{2\pi}\int_{2\pi}X(e^{j\theta})Y(e^{j(\omega-\theta)})d\theta$
5.3.5	Differencing in Time	x[n]-x[n-1]		$(1-e^{-j\omega})X(e^{j\omega})$
5.3.5	Accumulation	$\sum_{k=-\infty}^{n} x[k]$		$\frac{1}{1-e^{-j\omega}}X(e^{j\omega})$
5.3.8	Differentiation in Frequency	nx[n]		$+\pi X(e^{j0}) \sum_{k=-\infty}^{+\infty} \delta(\omega - 2\pi k)$ $j \frac{dX(e^{j\omega})}{d\omega}$
5.3.4	Conjugate Symmetry for Real Signals	x[n] real		$\begin{cases} X(e^{j\omega}) = X^*(e^{-j\omega}) \\ \Re\{X(e^{j\omega})\} = \Re\{X(e^{-j\omega})\} \\ \Im\{X(e^{j\omega})\} = -\Im\{X(e^{-j\omega})\} \\ X(e^{j\omega}) = X(e^{-j\omega}) \end{cases}$
				$\int \langle X(e^{j\omega}) = -\langle X(e^{-j\omega}) \rangle$
5.3.4	Symmetry for Real, Even Signals	x[n] real an even		$X(e^{j\omega})$ real and even
5.3.4	Symmetry for Real, Odd Signals	x[n] real and odd		$X(e^{j\omega})$ purely imaginary and odd
5.3.4	Even-odd Decomposition	$x_e[n] = \mathcal{E}\nu\{x[n]\}$	[x[n] real]	$\Re\{X(e^{j\omega})\}$
	of Real Signals	$x_o[n] = Od\{x[n]\}$		$i \mathcal{I}m\{X(e^{j\omega})\}$
5.3.9	Parseval's Re	lation for Aperiodic Si		J. C-V. 77
	1 44	$x^2 = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) ^2 dt$		

a duality relationship between the discrete-time Fourier transform and the continuous-time Fourier series. This relation is discussed in Section 5.7.2.

5.7.1 Duality in the Discrete-Time Fourier Series

Since the Fourier series coefficients a_k of a periodic signal x[n] are themselves a periodic sequence, we can expand the sequence a_k in a Fourier series. The duality property for discrete-time Fourier series implies that the Fourier series coefficients for the periodic sequence a_k are the values of (1/N)x[-n] (i.e., are proportional to the values of the original

nd $X_2(e^{j\omega})$. The periodic convolu-

nple 5.15.

crete-time Fourier
l. In Table 5.2, we
r transform pairs

nmetry or duality No corresponding tion (5.8) for the rete-time Found addition, there is

TABLE 5.2 BASIC DISCRETE-TIME FOURIER TRANSFORM PAIRS

Signal	Fourier Transform	Fourier Series Coefficients (if periodic)
$\sum_{k=\langle N\rangle} a_k e^{jk(2n/N)n}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	a_k
$e^{j\omega_0 n}$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - \omega_0 - 2\pi l)$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} 1, & k = m, m \pm N, m \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational \Rightarrow The signal is aperiodic
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{+\infty} \left\{ \delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l) \right\}$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} \frac{1}{2}, & k = \pm m, \pm m \pm N, \pm m \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational \Rightarrow The signal is aperiodic
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi r}{N}$ $a_k = \begin{cases} \frac{1}{2j}, & k = r, r \pm N, r \pm 2N, \dots \\ -\frac{1}{2j}, & k = -r, -r \pm N, -r \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational \Rightarrow The signal is aperiodic
x[n] = 1	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - 2\pi l)$	$a_k = \begin{cases} 1, & k = 0, \pm N, \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$
Periodic square wave $x[n] = \begin{cases} 1, & n \le N_1 \\ 0, & N_1 < n \le N/2 \end{cases}$ and $x[n+N] = x[n]$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{\sin[(2\pi k/N)(N_1 + \frac{1}{2})]}{N \sin[2\pi k/2N]}, \ k \neq 0, \pm N, \pm 2N, \dots$ $a_k = \frac{2N_1 + 1}{N}, \ k = 0, \pm N, \pm 2N, \dots$
$\sum_{k=-\infty}^{+\infty} \delta[n-kN]$	$\frac{2\pi}{N}\sum_{k=-\infty}^{+\infty}\delta\!\left(\!\omega-\frac{2\pi k}{N}\right)$	$a_k = \frac{1}{N}$ for all k
$a^n u[n], a < 1$	$\frac{1}{1-ae^{-j\omega}}$	_
$x[n] = \begin{cases} 1, & n \le N_1 \\ 0, & n > N_1 \end{cases}$	$\frac{\sin[\omega(N_1+\frac{1}{2})]}{\sin(\omega/2)}$	
$\frac{\sin Wn}{\pi n} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wn}{\pi}\right)$ $0 < W < \pi$	$X(\omega) = \begin{cases} 1, & 0 \le \omega \le W \\ 0, & W < \omega \le \pi \end{cases}$ $X(\omega) \text{ periodic with period } 2\pi$	——————————————————————————————————————
$\delta[n]$	1	
u[n]	$\frac{1}{1-e^{-j\omega}}+\sum_{k=-\infty}^{+\infty}\pi\delta(\omega-2\pi k)$	_
$\delta[n-n_0]$	$e^{-j\omega n_0}$	
$(n+1)a^nu[n], a <1$	$\frac{1}{(1-ae^{-j\omega})^2}$	
$\frac{(n+r-1)!}{n!(r-1)!}a^nu[n], a < 1$	$\frac{1}{(1-ae^{-j\omega})^r}$	