Final Exam of ECE301, Section 1 (Prof. Chih-Chun Wang)
1–3pm, Friday, December 13, 2016, EE 129.

1. Please make sure that it is your name printed on the exam booklet. Enter your student ID number, and signature in the space provided on this page, **NOW!**
2. This is a closed book exam.
3. This exam contains multiple choice questions and work-out questions. For multiple choice questions, there is no need to justify your answers. You have one hour to complete it. The students are suggested not spending too much time on a single question, and working on those that you know how to solve.
4. Use the back of each page for rough work.
5. Neither calculators nor help sheets are allowed.

Name:

Student ID:

I certify that I have neither given nor received unauthorized aid on this exam.

Signature: Date:

Question 1: [20%, Work-out question]

1. [1%] What is the difference between "AM synchronous demodulation" and "AM asynchronous demodulation"?

   Hint 1: The former requires a very specific component in its demodulator while the latter, also known as *envelope detector*, does not need that component. If you can write down the name of that component, you will receive the full credit.

   Hint 2: The said component is usually generated by a block called "PLL."

Prof. Wang wanted to transmit an AM-SSB signal. To that end, he wrote the following MATLAB code.

```
% Initialialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read two different .wav files
[x1, f_sample, N]=audioread('x1.wav');
x1=x1';
[x2, f_sample, N]=audioread('x2.wav');
x2=x2';

% Step 0: Initialize several parameters
W_1=pi*2000;
W_2=pi*4000;
W_3=pi*8000;
W_4=pi*3000;
W_5=pi*7000;
W_6=????;




% Step 1: Make the signals band-limited.
h=1/(pi*t).*(sin(W_1*t));
x1_new=ece301conv(x1, h);
x2_new=ece301conv(x2, h);
```

```
% Step 2: Multiply x1_new and x2_new with a cosine wave.
x1_h=x1_new.*sin(W_2*t);
x2_h=x2_new.*sin(W_3*t);

% Step 3: Keep one of the two side bands
h_one=1/(pi*t).*(2*sin(W_4*t)).*(cos(W_5*t));
h_two=1/(pi*t).*(2*sin(W_4*t)).*(cos(W_6*t));
x1_sb=ece301conv(x1_h, h_one);
x2_sb=ece301conv(x2_h, h_two);

% Step 4: Create the transmitted signal
y=x1_sb+x2_sb;
audiowrite('y.wav', y, f_sample);
```

2. [1.5%] What is the bandwidth (Hz) of the signal x1_new?

3. [1.5%] For the first signal x1_new, is this AM-SSB transmitting an upper-side-band signal or a lower-side-band signal?

4. [1.5%] What should the value of W_6 be in the MATLAB code, if we decide to use a lower-side-band transmission for the second signal x2_new?

5. [1.5%] What should the value of W_6 be in the MATLAB code, if we decide to use an upper-side-band transmission for the second signal x2_new?

Knowing that Prof. Wang used the above code to generate the "y.wav" file, a student tried to demodulate the output waveform "y.wav" by the following code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read the .wav files
[y, f_sample, N]=audioread('y.wav');
y=y';

% Initialize several parameters
W_8=????;
W_9=????;
W_10=????;
W_11=????;
W_12=????;


% Create the low-pass filter.
h_M=1/(pi*t).*(sin(W_8*t));

% demodulate signal 1
h_BPF1=1/(pi*t).*(sin(W_9*t))-1/(pi*t).*(sin(W_10*t));
y1_BPF=ece301conv(y,h_BPF1);
y1=4*y1_BPF.*sin(pi*4000*t);
x1_hat=ece301conv(y1,h_M);

sound(x1_hat,f_sample)

% demodulate signal 2
h_BPF2=1/(pi*t).*(sin(W_11*t))-1/(pi*t).*(sin(W_12*t));
y2_BPF=ece301conv(y,h_BPF2);
y2=4*y2_BPF.*sin(pi*W_3*t);
x2_hat=ece301conv(y2,h_M);

sound(x2_hat,f_sample)
```

6. [7.5%] Continue from the previous questions. What should the values of W_8 to W_12 be in the MATLAB code? When answering this question, please assume that the second radio x2_new is transmitted using the *upper side-band*.

7. [2.5%] Suppose that Prof. Wang decides to use the *upper-side-band* transmission for x2_new but at the same time wants to make the "frequency bands" of x1_new and x2_new as close to each other as possible. Question: What is the smallest value of W_3 that Prof. Wang can still use while not affecting the sound quality of either x1_new or x2_new?

8. [3%] Continue from the previous sub-question. In addition to changing the value of W_3, the values of W_6, W_11, and W_12 also need to be changed. Question: What are their new values?

   Hint: If you do not know the answers of Q1.2 to Q1.8, please simply draw the AMSSB modulation and demodulation diagrams and mark carefully all the parameter values. You will receive 10 points for Q1.2 to Q1.8.

Question 2: [12%, Work-out question]

1. [4%] Consider the following discrete time signal

$$x_1[n] = \sin\left(\frac{4\pi}{3}n\right). \tag{1}$$

   Let $X_1(e^{j\omega})$ denote the corresponding DTFT. Find the expression of $X_1(e^{j\omega})$ and plot $X_1(e^{j\omega})$ for the range of $-2\pi < \omega < 2\pi$.

2. [4%] Consider a discrete time signal $x_2[n]$ with the corresponding DTFT being

$$X_2(e^{j\omega}) = \sin\left(5\omega + \frac{\pi}{4}\right). \tag{2}$$

   Find the expression of $x_2[n]$.

3. [4%] Consider the following discrete time signal

$$x_3[n] = \begin{cases} n & \text{if } -100 \leq n \leq 100 \\ 0 & \text{otherwise} \end{cases}. \tag{3}$$

   Let $X_3(e^{j\omega})$ denote the corresponding DTFT. Find the value of $\int_{\omega=100\pi}^{102\pi} X_3(e^{j\omega})d\omega$.

Question 3: [17%, Work-out question]

Consider a continuous time signal $x(t) = \cos(15\pi t) + \sin(10\pi t)$ and we use a digital voice recorder to convert the continuous time signal $x(t)$ to its discrete time counterpart $x[n]$ with sampling frequency 10Hz. Answer the following questions.

1. [3%] Write the explicit expression of $x[n]$ in this question. Namely, your answer should be something like $x[n] = \cos\ldots.$

2. [3%] Plot $x[n]$ for the range of $-4 \leq n \leq 4$.

3. [3%] Continue from the previous question. We use "zero-order hold" to reconstruct the original signal. We denote the output by $\hat{x}_{\text{ZOH}}(t)$. Plot $\hat{x}_{\text{ZOH}}(t)$ for the range of $-0.5 < t < 0.5$.

   [Alternative question:] If you do not know the answer to this question, you can assume that the sampling period is $T = \frac{1}{5}$ and the sampled values are $x[n] = \sin(0.5\pi n)$. Plot the Zero-Order-Hold output $\hat{x}_{\text{ZOH}}(t)$ for the range of $t = -1$ to 1. If your answer is correct, you will receive 2.5 points.

4. [4%] Let $x_p(t)$ denote the *impulse train-sampled signal* of $x(t)$. Plot $x_p(t)$ for the range of $-0.5 < t < 0.5$.

5. [4%] Consider an LTI system with impulse response

$$h_2(t) = \frac{\sin(10\pi t))}{10\pi t} \tag{4}$$

   Let $y_2(t)$ denote the convolution $y_2(t) = x_p(t) * h_2(t)$. Find the expression of $y_2(t)$ and plot $y_2(t)$ for the range of $-0.5 < t < 0.5$.

   Hint 1: This is a relatively harder question. You should not spend too much time on this question if you do not know how to approach it.

   Hint 2: You should first plot $y_2(t)$ and try to "guess" what is the expression of $y_2(t)$ and then write two to four sentences to justify your guess.

   Hint 3: If you do not know the answer to this sub-question, you can plot $h_2(t)$ for the range of $-0.5 < t < 0.5$. and then plot $y_2(t)$ for the range of $-0.5 < t < 0.5$ without finding the expression of $y_2(t)$. You will still receive 3 points if your answers are correct.

Question 4: [10%, Work-out question]

Consider a digital voice recorder that converts a continuous time waveform $x(t)$ into a discrete time array $x[n]$ with sampling frequency 44.1kHz. The $x[n]$ is stored in a .wav file. Answer the following questions.

1. [4%] Suppose I pass $x[n]$ through the following discrete-time signal processing equation:

$$y[n] = x[n] * h[n] \tag{5}$$

where

$$h[n] = \frac{\sin(0.5\pi n)}{\pi n}. \tag{6}$$

After processing $x[n]$ to generate $y[n]$ and storing it into a new .wav file, when I play the new wav file (containing $y[n]$), how will the new music file sound?

Hint 1: A couple of sentences describing the qualitative behavior will be enough. There is no need to have very exact expression.

Hint 2: If you do not know the answer, you can assume $h[n] = \frac{1}{5}(\sum_{k=-2}^{2} \delta[n-k])$ and answer the following alternative question instead: Is this signal processing block a low-pass filter or a high-pass filter? You will receive 3 points if your answer is correct.

2. [4%] Suppose my very old MP3 player can only play audio files that are sampled at 22.05kHz. Also suppose that I did not know the limitation of my MP3 player and incorrectly fed my recorded array $x[n]$ to the old MP3 player. How will the music file sound in the old MP3 player when the "sampling frequency 44.1kHz" is now twice as large as the "playback frequency 22.05kHz"? A quick sentence or two that explain how the sound quality will change is sufficient.

3. [2%] What kind of processing do we need to apply to $x[n]$ first (before playing back using the old MP3 player) so that the new $x_{\text{new}}[n]$ can be properly played by the old MP3 player?

Question 5: [9%, Work-out question]

Consider the following discrete-time signals

$$x[n] = 0.5^n \mathcal{U}[n - 100] \tag{7}$$

1. [1%] What does "ROC" stand for?
2. [3.5%] Denote the Z-transform of $x[n]$ by $X(z)$. Find out the value of $X(1 + \sqrt{3}j)$. Namely evaluate $X(z)$ when $z = 1 + \sqrt{3}j$.
3. [4.5%] Find the Z-transform $X(z)$ for general z values and carefully specify and draw its ROC in the corresponding z-plane.

   Hint: To decide the ROC, you need to carefully check whether you can apply the following formula that solves a geometric series.

$$\sum_{k=1}^{\infty} ar^{k-1} = \frac{a}{1-r} \quad \text{if } |r| < 1. \tag{8}$$

Question 6: [9%, Work-out question]

Consider a CT LTI system with impulse response

$$h(t) = \frac{\sin(3t)}{\pi t} \tag{9}$$

1. [6%] Find the output $y(t)$ when the input is $x(t) = \cos(2t) + \sin(\pi t)$.
2. [1.5%] Is $x(t)$ periodic? Use 1 sentence to justify your answer.
3. [1.5%] Is $y(t)$ periodic? Use 1 sentence to justify your answer.

   Hint: If you do not know the answer of $y(t)$, you can assume $y(t) = e^{\cos(\pi t)+\sin(3\pi t)^2}$. You will be given full credit if your answer is correct.

Question 7: [8%, Work-out question]

Consider the following continuous time system.

$$y(t) = \begin{cases} \int_{s=t-1}^{t} x(s)ds & \text{if } 0 < t \\ \int_{s=t-2}^{t} x(s)ds & \text{if } t \leq 0 \end{cases}. \tag{10}$$

Prove that the above system is not time-invariant. You need to write down the detailed steps in the proof.

Alternative question: If you do not know how to approach the above question, you can prove that the above system is linear. You will still receive 7 points if your proof of linearity is correct.

Question 8: [15%, Multiple-choice question] Consider two signals

$$h_1(t) = e^{-|t|\cos(t^3)} \tag{11}$$

and

$$h_2[n] = \sin(0.5 \cdot |n+1| \cdot \pi) + \sin(0.5 \cdot (n+1) \cdot \pi) \tag{12}$$

1. [1.25%] Is $h_1(t)$ periodic?
2. [1.25%] Is $h_2[n]$ periodic?
3. [1.25%] Is $h_1(t)$ even or odd or neither?
4. [1.25%] Is $h_2[n]$ even or odd or neither?
5. [1.25%] Is $h_1(t)$ of finite energy?
6. [1.25%] Is $h_2[n]$ of finite energy?

Suppose the above two signals are also the impulse responses of two LTI systems: System 1 and System 2, respectively.

1. [1.25%] Is System 1 memoryless?
2. [1.25%] Is System 2 memoryless?
3. [1.25%] Is System 1 causal?
4. [1.25%] Is System 2 causal?
5. [1.25%] Is System 1 stable?
6. [1.25%] Is System 2 stable?

Discrete-time Fourier series

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n} \tag{1}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(2\pi/N)n} \tag{2}$$

Continuous-time Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t} \tag{3}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt \tag{4}$$

Continuous-time Fourier transform

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \tag{5}$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \tag{6}$$

Discrete-time Fourier transform

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(j\omega) e^{j\omega n} d\omega \tag{7}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \tag{8}$$

Laplace transform

$$x(t) = \frac{1}{2\pi} e^{\sigma t} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{j\omega t} d\omega \tag{9}$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt \tag{10}$$

Z transform

$$x[n] = r^n \mathcal{F}^{-1}(X(re^{j\omega})) \tag{11}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n} \tag{12}$$

TABLE 10.1 PROPERTIES OF THE z-TRANSFORM

Section	Property	Signal	z-Transform	ROC
		$x[n]$	$X(z)$	R
		$x_1[n]$	$X_1(z)$	R_1
		$x_2[n]$	$X_2(z)$	R_2
10.5.1	Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$	At least the intersection of R_1 and R_2
10.5.2	Time shifting	$x[n - n_0]$	$z^{-n_0}X(z)$	R, except for the possible addition or deletion of the origin
10.5.3	Scaling in the z-domain	$e^{j\omega_0 n}x[n]$	$X(e^{-j\omega_0}z)$	R
		$z_0^n x[n]$	$X\left(\frac{z}{z_0}\right)$	z_0R
		$a^n x[n]$	$X(a^{-1}z)$	Scaled version of R (i.e., $\|a\|R$ = the set of points $\{\|a\|z\}$ for z in R)
10.5.4	Time reversal	$x[-n]$	$X(z^{-1})$	Inverted R (i.e., R^{-1} = the set of points z^{-1}, where z is in R)
10.5.5	Time expansion	$x_{(k)}[n] = \begin{cases} x[r], & n = rk \\ 0, & n \neq rk \end{cases}$ for some integer r	$X(z^k)$	$R^{1/k}$ (i.e., the set of points $z^{1/k}$, where z is in R)
10.5.6	Conjugation	$x^*[n]$	$X^*(z^*)$	R
10.5.7	Convolution	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	At least the intersection of R_1 and R_2
10.5.7	First difference	$x[n] - x[n-1]$	$(1 - z^{-1})X(z)$	At least the intersection of R and $\|z\| > 0$
10.5.7	Accumulation	$\sum_{k=-\infty}^{n} x[k]$	$\frac{1}{1 - z^{-1}}X(z)$	At least the intersection of R and $\|z\| > 1$
10.5.8	Differentiation in the z-domain	$nx[n]$	$-z\frac{dX(z)}{dz}$	R
10.5.9	Initial Value Theorem If $x[n] = 0$ for $n < 0$, then $x[0] = \lim_{z \to \infty} X(z)$			

TABLE 10.2 SOME COMMON z-TRANSFORM PAIRS

Signal	Transform	ROC
1. $\delta[n]$	1	All z
2. $u[n]$	$\frac{1}{1-z^{-1}}$	$\lvert z\rvert > 1$
3. $-u[-n-1]$	$\frac{1}{1-z^{-1}}$	$\lvert z\rvert < 1$
4. $\delta[n-m]$	z^{-m}	All z, except 0 (if $m > 0$) or ∞ (if $m < 0$)
5. $\alpha^n u[n]$	$\frac{1}{1-\alpha z^{-1}}$	$\lvert z\rvert > \lvert\alpha\rvert$
6. $-\alpha^n u[-n-1]$	$\frac{1}{1-\alpha z^{-1}}$	$\lvert z\rvert < \lvert\alpha\rvert$
7. $n\alpha^n u[n]$	$\frac{\alpha z^{-1}}{(1-\alpha z^{-1})^2}$	$\lvert z\rvert > \lvert\alpha\rvert$
8. $-n\alpha^n u[-n-1]$	$\frac{\alpha z^{-1}}{(1-\alpha z^{-1})^2}$	$\lvert z\rvert < \lvert\alpha\rvert$
9. $[\cos\omega_0 n]u[n]$	$\frac{1-[\cos\omega_0]z^{-1}}{1-[2\cos\omega_0]z^{-1}+z^{-2}}$	$\lvert z\rvert > 1$
10. $[\sin\omega_0 n]u[n]$	$\frac{[\sin\omega_0]z^{-1}}{1-[2\cos\omega_0]z^{-1}+z^{-2}}$	$\lvert z\rvert > 1$
11. $[r^n\cos\omega_0 n]u[n]$	$\frac{1-[r\cos\omega_0]z^{-1}}{1-[2r\cos\omega_0]z^{-1}+r^2z^{-2}}$	$\lvert z\rvert > r$
12. $[r^n\sin\omega_0 n]u[n]$	$\frac{[r\sin\omega_0]z^{-1}}{1-[2r\cos\omega_0]z^{-1}+r^2z^{-2}}$	$\lvert z\rvert > r$

10.7.1 Causality

A causal LTI system has an impulse response $h[n]$ that is zero for $n < 0$, and therefore is right-sided. From Property 4 in Section 10.2 we then know that the ROC of $H(z)$ is the exterior of a circle in the z-plane. For some systems, e.g., if $h[n] = \delta[n]$, so that $H(z) = 1$, the ROC can extend all the way in to and possibly include the origin. Also, in general, for a right-sided impulse response, the ROC may or may not include infinity. For example, if $h[n] = \delta[n+1]$, then $H(z) = z$, which has a pole at infinity. However, as we saw in Property 8 in Section 10.2, for a causal system the power series

$$H(z) = \sum_{n=0}^{\infty} h[n]z^{-n}$$

does not include any positive powers of z. Consequently, the ROC includes infinity. Summarizing, we have the follow principle:

> A discrete-time LTI system is causal if and only if the ROC of its system function is the exterior of a circle, including infinity.

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left.\begin{matrix} x(t) \\ y(t)\end{matrix}\right\}$ Periodic with period T and fundamental frequency $\omega_0 = 2\pi/T$	$\begin{matrix} a_k \\ b_k \end{matrix}$
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} x(t) = e^{jM(2\pi/T)t} x(t)$	a_{k-M}
Conjugation	3.5.6	$x^*(t)$	a^*_{-k}
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	a_k
Periodic Convolution		$\int_T x(\tau)y(t - \tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk\frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^{t} x(t)\,dt$ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a^*_{-k} \\ \Re e\{a_k\} = \Re e\{a_{-k}\} \\ \Im m\{a_k\} = -\Im m\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \mathcal{E}v\{x(t)\} \quad [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}d\{x(t)\} \quad [x(t) \text{ real}] \end{cases}$	$\begin{matrix} \Re e\{a_k\} \\ j\Im m\{a_k\} \end{matrix}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T}\int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

three examples, we illustrate this. The last example in this section then demonstrates how properties of a signal can be used to characterize the signal in great detail.

Example 3.6

Consider the signal $g(t)$ with a fundamental period of 4, shown in Figure 3.10. We could determine the Fourier series representation of $g(t)$ directly from the analysis equation (3.39). Instead, we will use the relationship of $g(t)$ to the symmetric periodic square wave $x(t)$ in Example 3.5. Referring to that example, we see that, with $T = 4$ and $T_1 = 1$,

$$g(t) = x(t - 1) - 1/2. \quad (3.64)$$

Thus, in general, *none* of the finite partial sums in eq. (3.52) yield the exact values of $x(t)$, and convergence issues, such as those considered in Section 3.4, arise as we consider the problem of evaluating the limit as the number of terms approaches infinity.

3.7 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

There are strong similarities between the properties of discrete-time and continuous-time Fourier series. This can be readily seen by comparing the discrete-time Fourier series properties summarized in Table 3.2 with their continuous-time counterparts in Table 3.1.

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Periodic Signal	Fourier Series Coefficients
	$x[n]$, $y[n]$ Periodic with period N and fundamental frequency $\omega_0 = 2\pi/N$	a_k, b_k Periodic with period N
Linearity	$Ax[n] + By[n]$	$Aa_k + Bb_k$
Time Shifting	$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting	$e^{jM(2\pi/N)n}x[n]$	a_{k-M}
Conjugation	$x^*[n]$	a^*_{-k}
Time Reversal	$x[-n]$	a_{-k}
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period mN)	$\frac{1}{m}a_k \begin{pmatrix}\text{viewed as periodic} \\ \text{with period } mN\end{pmatrix}$
Periodic Convolution	$\sum_{r=\langle N\rangle} x[r]y[n-r]$	Na_kb_k
Multiplication	$x[n]y[n]$	$\sum_{l=\langle N\rangle} a_l b_{k-l}$
First Difference	$x[n] - x[n-1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum	$\sum_{k=-\infty}^{n} x[k] \begin{pmatrix}\text{finite valued and periodic only} \\ \text{if } a_0 = 0\end{pmatrix}$	$\left(\frac{1}{(1 - e^{-jk(2\pi/N)})}\right)a_k$
Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} a_k = a^*_{-k} \\ \Re e\{a_k\} = \Re e\{a_{-k}\} \\ \Im m\{a_k\} = -\Im m\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	$x[n]$ real and even	a_k real and even
Real and Odd Signals	$x[n]$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = \mathcal{E}v\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = \mathcal{O}d\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\Re e\{a_k\}$ $j\Im m\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{N}\sum_{n=\langle N\rangle} |x[n]|^2 = \sum_{k=\langle N\rangle} |a_k|^2$$

4.6 TABLES OF FOURIER PROPERTIES AND OF BASIC FOURIER TRANSFORM PAIRS

In the preceding sections and in the problems at the end of the chapter, we have considered some of the important properties of the Fourier transform. These are summarized in Table 4.1, in which we have also indicated the section of this chapter in which each property has been discussed.

In Table 4.2, we have assembled a list of many of the basic and important Fourier transform pairs. We will encounter many of these repeatedly as we apply the tools of

TABLE 4.1 PROPERTIES OF THE FOURIER TRANSFORM

Section	Property	Aperiodic signal	Fourier transform
		$x(t)$ $y(t)$	$X(j\omega)$ $Y(j\omega)$
4.3.1	Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
4.3.2	Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0}X(j\omega)$
4.3.6	Frequency Shifting	$e^{j\omega_0 t}x(t)$	$X(j(\omega - \omega_0))$
4.3.3	Conjugation	$x^*(t)$	$X^*(-j\omega)$
4.3.5	Time Reversal	$x(-t)$	$X(-j\omega)$
4.3.5	Time and Frequency Scaling	$x(at)$	$\frac{1}{\lvert a\rvert}X\left(\frac{j\omega}{a}\right)$
4.4	Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
4.5	Multiplication	$x(t)y(t)$	$\frac{1}{2\pi}\int_{-\infty}^{+\infty}X(j\theta)Y(j(\omega-\theta))d\theta$
4.3.4	Differentiation in Time	$\frac{d}{dt}x(t)$	$j\omega X(j\omega)$
4.3.4	Integration	$\int_{-\infty}^{t}x(t)dt$	$\frac{1}{j\omega}X(j\omega) + \pi X(0)\delta(\omega)$
4.3.6	Differentiation in Frequency	$tx(t)$	$j\frac{d}{d\omega}X(j\omega)$
4.3.3	Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \mathcal{R}e\{X(j\omega)\} = \mathcal{R}e\{X(-j\omega)\} \\ \mathcal{I}m\{X(j\omega)\} = -\mathcal{I}m\{X(-j\omega)\} \\ \lvert X(j\omega)\rvert = \lvert X(-j\omega)\rvert \\ \sphericalangle X(j\omega) = -\sphericalangle X(-j\omega) \end{cases}$
4.3.3	Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
4.3.3	Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
4.3.3	Even-Odd Decomposition for Real Signals	$x_e(t) = \mathcal{E}v\{x(t)\}$ [$x(t)$ real] $x_o(t) = \mathcal{O}d\{x(t)\}$ [$x(t)$ real]	$\mathcal{R}e\{X(j\omega)\}$ $j\mathcal{I}m\{X(j\omega)\}$

4.3.7 Parseval's Relation for Aperiodic Signals

$$\int_{-\infty}^{+\infty}|x(t)|^2dt = \frac{1}{2\pi}\int_{-\infty}^{+\infty}|X(j\omega)|^2d\omega$$

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TABLE 4.2 BASIC FOURIER TRANSFORM PAIRS

Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$	a_k
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0$, otherwise
$\cos\omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0$, otherwise
$\sin\omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0$, otherwise
$x(t) = 1$	$2\pi\delta(\omega)$	$a_0 = 1,\quad a_k = 0,\ k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$)
Periodic square wave $x(t) = \begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & T_1 < \lvert t\rvert \le \frac{T}{2} \end{cases}$ and $x(t + T) = x(t)$	$\sum_{k=-\infty}^{+\infty} \frac{2\sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \operatorname{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) = \frac{\sin k\omega_0 T_1}{k\pi}$
$\sum_{n=-\infty}^{+\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all k
$x(t)\begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & \lvert t\rvert > T_1 \end{cases}$	$\frac{2\sin\omega T_1}{\omega}$	—
$\frac{\sin Wt}{\pi t}$	$X(j\omega) = \begin{cases} 1, & \lvert\omega\rvert < W \\ 0, & \lvert\omega\rvert > W \end{cases}$	—
$\delta(t)$	1	—
$u(t)$	$\frac{1}{j\omega} + \pi\delta(\omega)$	—
$\delta(t - t_0)$	$e^{-j\omega t_0}$	—
$e^{-at}u(t), \Re e\{a\} > 0$	$\frac{1}{a + j\omega}$	—
$te^{-at}u(t), \Re e\{a\} > 0$	$\frac{1}{(a + j\omega)^2}$	—
$\frac{t^{n-1}}{(n-1)!}e^{-at}u(t)$, $\Re e\{a\} > 0$	$\frac{1}{(a + j\omega)^n}$	—

TABLE 5.1 PROPERTIES OF THE DISCRETE-TIME FOURIER TRANSFORM

Section	Property	Aperiodic Signal	Fourier Transform
		$x[n]$ $y[n]$	$\left.\begin{array}{l}X(e^{j\omega})\\Y(e^{j\omega})\end{array}\right\}$ periodic with period 2π
5.3.2	Linearity	$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$
5.3.3	Time Shifting	$x[n - n_0]$	$e^{-j\omega n_0}X(e^{j\omega})$
5.3.3	Frequency Shifting	$e^{j\omega_0 n}x[n]$	$X(e^{j(\omega-\omega_0)})$
5.3.4	Conjugation	$x^*[n]$	$X^*(e^{-j\omega})$
5.3.6	Time Reversal	$x[-n]$	$X(e^{-j\omega})$
5.3.7	Time Expansion	$x_{(k)}[n] = \begin{cases} x[n/k], & \text{if } n = \text{multiple of } k \\ 0, & \text{if } n \neq \text{multiple of } k \end{cases}$	$X(e^{jk\omega})$
5.4	Convolution	$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$
5.5	Multiplication	$x[n]y[n]$	$\frac{1}{2\pi}\int_{2\pi} X(e^{j\theta})Y(e^{j(\omega-\theta)})d\theta$
5.3.5	Differencing in Time	$x[n] - x[n-1]$	$(1 - e^{-j\omega})X(e^{j\omega})$
5.3.5	Accumulation	$\sum_{k=-\infty}^{n} x[k]$	$\frac{1}{1 - e^{-j\omega}}X(e^{j\omega})$ $+\pi X(e^{j0}) \sum_{k=-\infty}^{+\infty} \delta(\omega - 2\pi k)$
5.3.8	Differentiation in Frequency	$nx[n]$	$j\frac{dX(e^{j\omega})}{d\omega}$
5.3.4	Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} X(e^{j\omega}) = X^*(e^{-j\omega}) \\ \Re e\{X(e^{j\omega})\} = \Re e\{X(e^{-j\omega})\} \\ \Im m\{X(e^{j\omega})\} = -\Im m\{X(e^{-j\omega})\} \\ \lvert X(e^{j\omega})\rvert = \lvert X(e^{-j\omega})\rvert \\ \sphericalangle X(e^{j\omega}) = -\sphericalangle X(e^{-j\omega}) \end{cases}$
5.3.4	Symmetry for Real, Even Signals	$x[n]$ real an even	$X(e^{j\omega})$ real and even
5.3.4	Symmetry for Real, Odd Signals	$x[n]$ real and odd	$X(e^{j\omega})$ purely imaginary and odd
5.3.4	Even-odd Decomposition of Real Signals	$x_e[n] = \mathcal{E}v\{x[n]\}$ $[x[n]$ real$]$ $x_o[n] = \mathcal{O}d\{x[n]\}$ $[x[n]$ real$]$	$\Re e\{X(e^{j\omega})\}$ $j\Im m\{X(e^{j\omega})\}$
5.3.9	Parseval's Relation for Aperiodic Signals $\sum_{n=-\infty}^{+\infty} \lvert x[n]\rvert^2 = \frac{1}{2\pi}\int_{2\pi} \lvert X(e^{j\omega})\rvert^2 d\omega$		

a duality relationship between the discrete-time Fourier transform and the continuous-time Fourier series. This relation is discussed in Section 5.7.2.

5.7.1 Duality in the Discrete-Time Fourier Series

Since the Fourier series coefficients a_k of a periodic signal $x[n]$ are themselves a periodic sequence, we can expand the sequence a_k in a Fourier series. The duality property for discrete-time Fourier series implies that the Fourier series coefficients for the periodic sequence a_k are the values of $(1/N)x[-n]$ (i.e., are proportional to the values of the original

TABLE 5.2 BASIC DISCRETE-TIME FOURIER TRANSFORM PAIRS

Signal	Fourier Transform	Fourier Series Coefficients (if periodic)
$\sum_{k=\langle N\rangle} a_k e^{jk(2\pi/N)n}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	a_k
$e^{j\omega_0 n}$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - \omega_0 - 2\pi l)$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} 1, & k = m, m \pm N, m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} \frac{1}{2}, & k = \pm m, \pm m \pm N, \pm m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi r}{N}$ $a_k = \begin{cases} \frac{1}{2j}, & k = r, r \pm N, r \pm 2N, \ldots \\ -\frac{1}{2j}, & k = -r, -r \pm N, -r \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$x[n] = 1$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - 2\pi l)$	$a_k = \begin{cases} 1, & k = 0, \pm N, \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$
Periodic square wave $x[n] = \begin{cases} 1, & \lvert n\rvert \le N_1 \\ 0, & N_1 < \lvert n\rvert \le N/2 \end{cases}$ and $x[n+N] = x[n]$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{\sin[(2\pi k/N)(N_1 + \frac{1}{2})]}{N \sin[2\pi k/2N]}, \; k \neq 0, \pm N, \pm 2N, \ldots$ $a_k = \frac{2N_1 + 1}{N}, \; k = 0, \pm N, \pm 2N, \ldots$
$\sum_{k=-\infty}^{+\infty} \delta[n - kN]$	$\frac{2\pi}{N} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{1}{N}$ for all k
$a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{1 - ae^{-j\omega}}$	—
$x[n] = \begin{cases} 1, & \lvert n\rvert \le N_1 \\ 0, & \lvert n\rvert > N_1 \end{cases}$	$\frac{\sin[\omega(N_1 + \frac{1}{2})]}{\sin(\omega/2)}$	—
$\frac{\sin Wn}{\pi n} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wn}{\pi}\right)$ $0 < W < \pi$	$X(\omega) = \begin{cases} 1, & 0 \le \lvert\omega\rvert \le W \\ 0, & W < \lvert\omega\rvert \le \pi \end{cases}$ $X(\omega)$ periodic with period 2π	—
$\delta[n]$	1	—
$u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{+\infty} \pi\delta(\omega - 2\pi k)$	—
$\delta[n - n_0]$	$e^{-j\omega n_0}$	—
$(n+1)a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{(1 - ae^{-j\omega})^2}$	—
$\frac{(n+r-1)!}{n!(r-1)!} a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{(1 - ae^{-j\omega})^r}$	—