Final Exam of ECE301, Prof. Wang's section

8–10am Tuesday, May 6, 2014, EE 129.

1. Please make sure that it is your name printed on the exam booklet. Enter your student ID number, e-mail address, and signature in the space provided on this page, **NOW!**
2. This is a closed book exam.
3. This exam contains multiple choice questions and work-out questions. For multiple choice questions, there is no need to justify your answers. You have one hour to complete it. The students are suggested not spending too much time on a single question, and working on those that you know how to solve.
4. Use the back of each page for rough work.
5. Neither calculators nor help sheets are allowed.

Name:

Student ID:

E-mail:

Signature:

Question 1: [15%, Work-out question]

1. [1%] What does the acronym "AM-DSB" stands for?

Prof. Wang wanted to transmit an AM-SSB signal. To that end, he wrote the following MATLAB code.

```
% Initialialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read two different .wav files
[x1, f_sample, N]=wavread('x1');
x1=x1';
[x2, f_sample, N]=wavread('x2');
x2=x2';

% Step 0: Initialize several parameters
W_1=pi*3000;
W_2=pi*4000;
W_3=pi*12000;
W_4=pi*7000;
W_5=pi*4000;
W_6=?????;
W_7=????;


% Step 1: Make the signals band-limited.
h=1/(pi*t).*(sin(W_1*t));
x1_new=ece301conv(x1, h);
x2_new=ece301conv(x2, h);

% Step 2: Multiply x1_new and x2_new with a cosine wave.
x1_h=x1_new.*cos(W_2*t);
x2_h=x2_new.*cos(W_3*t);

% Step 3: Keep one of the two side bands
h_one=1/(pi*t).*(sin(W_4*t))-1/(pi*t).*(sin(W_5*t));
h_two=1/(pi*t).*(sin(W_6*t))-1/(pi*t).*(sin(W_7*t));
```

```
x1_sb=ece301conv(x1_h, h_one);
x2_sb=ece301conv(x2_h, h_two);

% Step 4: Create the transmitted signal
y=x1_sb+x2_sb;
wavwrite(y', f_sample, N, 'y.wav');
```

2. [1.5%] What is the bandwidth (Hz) of the signal x1_new?
3. [2.5%] Is this AM-SSB transmitting an upper-side-band signal or a lower-side-band signal?
4. [4%] What should the values of W_6 and W_7 be in the MATLAB code?

Knowing that Prof. Wang used the above code to generate the "y.wav" file, a student tried to demodulate the output waveform "y.wav" by the following code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read the .wav files
[y, f_sample, N]=wavread('y');
y=y';

% Initialize several parameters
W_8=????;
W_9=????;
W_10=????;

% Create the low-pass filter.
h_M=1/(pi*t).*(sin(W_8*t));

% Create two band-pass filters.
hBPF_1=1/(pi*t).*(sin(pi*4000*t))-1/(pi*t).*(sin(pi*1000*t));
hBPF_2=1/(pi*t).*(sin(pi*15000*t))-1/(pi*t).*(sin(pi*12000*t));


% demodulate signal 1
y1BPF=ece301conv(y,hBPF_1);
y1=4*y1BPF.*cos(W_9*t);
x1_hat=ece301conv(y1,h_M);

sound(x1_hat,f_sample)

% demodulate signal 2
y2BPF=ece301conv(y,hBPF_2);
y2=4*y2BPF.*cos(W_10*t);
x2_hat=ece301conv(y2,h_M);

sound(x2_hat,f_sample)
```

5. [3%] Continue from the previous question. What should the values of W_8 to W_10 in the MATLAB code?

6. [4%] It turns out that using the above MATLAB code, we can hear the sound properly when playing "sound(x2_hat,f_sample)" but there is some problem when

playing “sound(x1_hat,f_sample)”. Please (i) describe how it will sound when playing “sound(x1_hat,f_sample)” and (ii) Describe how we can fix the code so that we can hear x1_hat propertly.

Hint: If you do not know the answers of Q1.2 to Q1.6, please simply draw the AMSSB modulation and demodulation diagrams and mark carefully all the parameter values. You will receive 9 points for Q1.2 to Q1.6.

Question 2: [27%, Work-out question] We sample a continuous-time signal $x(t)$ with a sampling frequency 3Hz. The sampled value array $x[n] = \delta[n-1]$.

1. [1%] What is the sampling period? (Make sure you write down the correct unit.)

2. [3%] We use $x_{\text{sync}}(t)$ to denote the reconstructed signal based on the optimal band-limited reconstruction. Plot $x_{\text{sync}}(t)$ for the range of $-1 \leq t \leq 1$.

We sample another continuous-time signal $y(t)$ with a sampling frequency 3Hz. The sampled value array is

$$y[n] = \begin{cases} 0 & \text{if } n = 0 \text{ or } 2 \\ 1 & \text{if } n = 1 \\ -1 & \text{if } n = -1 \\ \text{periodic with period 4} & \end{cases} \tag{1}$$

3. [4%] We use $y_{\text{LIN}}(t)$ to denote the reconstructed signal based on linear interpolation. Plot $y_{\text{LIN}}(t)$ for the range of $-1 \leq t \leq 1$.
   We use $y_{\text{ZOH}}(t)$ to denote the reconstructed signal based on Zero-Order Hold. Plot $y_{\text{ZOH}}(t)$ for the range of $-1 \leq t \leq 1$.

4. [3%] Which one of the following statements can possibly be true?
   (i) $y(t) = \sum_{k=\infty}^{\infty} \delta(t-1-4k) - \delta(t-3-4k)$;
   (ii) $y(t) = \cos(\frac{\pi t}{2})$;
   (iii) $y(t) = \sin(\frac{3\pi t}{2})$;
   (iv) $y(t) = \cos(2\pi t)$; and
   (v) None of the above.

   Hint 1: This is a multiple choice question. You do not need to justify your answer.

   Hint 2: This question basically asks you to look at the sampled values $y[n]$ and deduce which of the above three signals can possibly be the original $y(t)$ signal?

5. [6%] Find out the DTFT of $y[n]$.

   Hint: You should be able to answer this sub-question without using the answers to the previous 2 sub-questions.

6. [5%] Let $y_p(t)$ denote the impulse-train-sampled signal with the sampling period 3 Hz. Plot $Y_p(j\omega)$ for the range of $-8\pi < \omega < 8\pi$.

   Hint: You would need to use the DTFT of $y[n]$ found in the previous sub-question to find the answer for this sub-question. If you do not know the answer to the previous sub-question, you can assume that the DTFT of $y[n]$ is

$$Y(e^{j\omega}) = \begin{cases} 1 & \text{if } 0 \leq |\omega| \leq \frac{\pi}{2} \\ 0 & \text{if } \frac{\pi}{2} < |\omega| \leq \pi \\ \text{periodic with period } 2\pi & \end{cases} \tag{2}$$

7. [2.5%, advanced] We use $y_{\text{sync}}(t)$ to denote the reconstructed signal based on the optimal reconstruction. Write down the expression of $y_{\text{sync}}(t)$.

8. [2.5%, advanced] We now perform some discrete-time signal processing with $w[n] = y[n] + y[n+3]$ and use $w_{\text{sync}}(t)$ to denote the reconstructed signal based on the optimal reconstruction. Write down the expression of $w_{\text{sync}}(t)$.

Question 3: [14%, Work-out question] Consider the following *impulse-train sampling* and reconstruction system, which contains the following 2 steps.

Step 1: For any given signal $x(t)$, we first perform impulse train sampling with sampling period 0.5 seconds. The final impulse-train sampled signal is denoted by $x_p(t)$.

Step 2: Use a perfect band-limited reconstruction to convert $x_p(t)$ back to $\hat{x}(t)$.

1. [2%] Write down the mathematical relationship between $x(t)$ and $x_p(t)$. Your answer should look like "$x_p(t) = x(t) \cdots$".

2. [3%] Suppose the CTFT of $x(t)$ is

$$X(j\omega) = \begin{cases} 1 & \text{if } -3\pi \leq \omega \leq 3\pi \\ 0 & \text{otherwise} \end{cases}. \tag{3}$$

   Plot $X_p(j\omega)$, the CTFT of $x_p(t)$, for the range of $-6\pi \leq \omega \leq 6\pi$.

3. [4%] Draw the diagram how to derive $\hat{x}(t)$ from $x_p(t)$. Your diagram (flow chart) needs to be carefully labeled.

4. [5%] Continue from the previous question. Plot $\hat{X}(j\omega)$, the CTFT of $\hat{x}(t)$, for the range of $-6\pi \leq \omega \leq 6\pi$.

   Hint: If you do not know the answer, you can assume

$$y(t) = (x(t)\cos(4\pi t)) * \left(\frac{\sin(2\pi t)}{\pi t}\right) \tag{4}$$

   and plot $Y(j\omega)$ for the range of $-6\pi \leq \omega \leq 6\pi$. You will get 4 points for this sub-question if your answer is correct.

Question 4: [7%, Work-out question]

1. [1%] What is the acronym "ROC" stands for (when considering the Z-transform)?

We know that

$$x[n] = \left(\frac{1}{4}\right)^n \mathcal{U}[2-n] \tag{5}$$

2. [6%] Find the Z-transform $X(z)$, write down the expression of the corresponding ROC, and plot the ROC.

   Hint: You may need to use the formula: $\sum_{k=1}^{\infty} ar^{k-1} = \frac{a}{1-r}$ if $|r| < 1$.

Question 5: [12%, Work-out question] Consider a continuous-time system:

$$y(t) = x(t+3) + \int_{t-2}^{t+2} x(s)ds. \tag{6}$$

1. [7%] Find the frequency response of the system $H(j\omega)$.

2. [5%] When the input is $x(t) = \sum_{k=1}^{2} \left(\frac{1}{2}\right)^k \cos\left(\frac{k\pi}{5}t\right)$, find the corresponding output $y(t)$.

   Hint: If you do not know how to solve this question, you can assume that

$$H(j\omega) = \begin{cases} \omega + \pi & \text{if } -\pi \leq \omega \leq 0 \\ \pi - \omega & \text{if } 0 \leq \omega \leq \pi \\ 0 & \text{otherwise} \end{cases} \tag{7}$$

   You will still receive full credit if your answer is correct using the given $H(j\omega)$.

Question 6: [9%, Work-out question] Consider two discrete-time signals

$$x[n] = \begin{cases} e^{j\frac{\pi}{40}n} & \text{if } 0 \leq n < 40 \\ 0 & \text{if } 40 \leq n < 80 \\ \text{periodic with period 80} & \end{cases} \tag{8}$$

1. [5%] Denote the DTFS $x[n]$ by a_k. Find the general expression of a_k for all possible k values.
   Hint: You may need to use the formula
   $\sum_{k=1}^{K} ar^{k-1} = \frac{a(1-r^K)}{1-r}$ when $r \neq 1$.

2. [2%] Find out the value of $\sum_{k=0}^{79} a_k$.

3. [2%] Find out the value of $\sum_{k=0}^{79} |a_k|^2$.

Question 7: [15%, Multiple-choice question] Consider two signals

$$h_1(t) = \begin{cases} t\sin(t) & \text{if } t \geq 0 \\ 0 & \text{if } t < 0 \end{cases} \tag{9}$$

and

$$h_2[n] = \cos(3n) + \sin(2n) \tag{10}$$

1. [1.25%] Is $h_1(t)$ periodic?
2. [1.25%] Is $h_2[n]$ periodic?
3. [1.25%] Is $h_1(t)$ even or odd or neither?
4. [1.25%] Is $h_2[n]$ even or odd or neither?
5. [1.25%] Is $h_1(t)$ of finite energy?
6. [1.25%] Is $h_2[n]$ of finite power?

Suppose the above two signals are also the impulse responses of two LTI systems: System 1 and System 2, respectively.

1. [1.25%] Is System 1 memoryless?
2. [1.25%] Is System 2 memoryless?
3. [1.25%] Is System 1 causal?
4. [1.25%] Is System 2 causal?
5. [1.25%] Is System 1 stable?
6. [1.25%] Is System 2 stable?

Discrete-time Fourier series

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n} \tag{1}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(2\pi/N)n} \tag{2}$$

Continuous-time Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t} \tag{3}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt \tag{4}$$

Continuous-time Fourier transform

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \tag{5}$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \tag{6}$$

Discrete-time Fourier transform

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(j\omega) e^{j\omega n} d\omega \tag{7}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \tag{8}$$

Laplace transform

$$x(t) = \frac{1}{2\pi} e^{\sigma t} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{j\omega t} d\omega \tag{9}$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt \tag{10}$$

Z transform

$$x[n] = r^n \mathcal{F}^{-1}(X(re^{j\omega})) \tag{11}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n} \tag{12}$$

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left.\begin{matrix} x(t) \\ y(t) \end{matrix}\right\}$ Periodic with period T and fundamental frequency $\omega_0 = 2\pi/T$	a_k b_k
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} x(t) = e^{jM(2\pi/T)t} x(t)$	a_{k-M}
Conjugation	3.5.6	$x^*(t)$	a^*_{-k}
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	a_k
Periodic Convolution		$\int_T x(\tau)y(t-\tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk\frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^{t} x(t)\,dt$ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a^*_{-k} \\ \mathcal{Re}\{a_k\} = \mathcal{Re}\{a_{-k}\} \\ \mathcal{Im}\{a_k\} = -\mathcal{Im}\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \mathcal{Ev}\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{Od}\{x(t)\} & [x(t) \text{ real}] \end{cases}$	$\mathcal{Re}\{a_k\}$ $j\mathcal{Im}\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T}\int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

three examples, we illustrate this. The last example in this section then demonstrates how properties of a signal can be used to characterize the signal in great detail.

Example 3.6

Consider the signal $g(t)$ with a fundamental period of 4, shown in Figure 3.10. We could determine the Fourier series representation of $g(t)$ directly from the analysis equation (3.39). Instead, we will use the relationship of $g(t)$ to the symmetric periodic square wave $x(t)$ in Example 3.5. Referring to that example, we see that, with $T = 4$ and $T_1 = 1$,

$$g(t) = x(t - 1) - 1/2. \quad (3.6\ldots)$$

Thus, in general, *none* of the finite partial sums in eq. (3.52) yield the exact values of $x(t)$, and convergence issues, such as those considered in Section 3.4, arise as we consider the problem of evaluating the limit as the number of terms approaches infinity.

3.7 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

There are strong similarities between the properties of discrete-time and continuous-time Fourier series. This can be readily seen by comparing the discrete-time Fourier series properties summarized in Table 3.2 with their continuous-time counterparts in Table 3.1.

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Periodic Signal	Fourier Series Coefficients
	$\left.\begin{array}{l}x[n]\\y[n]\end{array}\right\}$ Periodic with period N and fundamental frequency $\omega_0 = 2\pi/N$	$\left.\begin{array}{l}a_k\\b_k\end{array}\right\}$ Periodic with period N
Linearity	$Ax[n] + By[n]$	$Aa_k + Bb_k$
Time Shifting	$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting	$e^{jM(2\pi/N)n}x[n]$	a_{k-M}
Conjugation	$x^*[n]$	a^*_{-k}
Time Reversal	$x[-n]$	a_{-k}
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period mN)	$\frac{1}{m}a_k \begin{pmatrix}\text{viewed as periodic}\\ \text{with period } mN\end{pmatrix}$
Periodic Convolution	$\sum_{r=\langle N\rangle} x[r]y[n-r]$	Na_kb_k
Multiplication	$x[n]y[n]$	$\sum_{l=\langle N\rangle} a_l b_{k-l}$
First Difference	$x[n] - x[n-1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum	$\sum_{k=-\infty}^{n} x[k] \begin{pmatrix}\text{finite valued and periodic only}\\ \text{if } a_0 = 0\end{pmatrix}$	$\left(\frac{1}{(1 - e^{-jk(2\pi/N)})}\right)a_k$
Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} a_k = a^*_{-k} \\ \Re e\{a_k\} = \Re e\{a_{-k}\} \\ \Im m\{a_k\} = -\Im m\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	$x[n]$ real and even	a_k real and even
Real and Odd Signals	$x[n]$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = \mathcal{E}v\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = \mathcal{O}d\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\Re e\{a_k\}$ $j\Im m\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{N}\sum_{n=\langle N\rangle} |x[n]|^2 = \sum_{k=\langle N\rangle} |a_k|^2$$

4.6 TABLES OF FOURIER PROPERTIES AND OF BASIC FOURIER TRANSFORM PAIRS

In the preceding sections and in the problems at the end of the chapter, we have considered some of the important properties of the Fourier transform. These are summarized in Table 4.1, in which we have also indicated the section of this chapter in which each property has been discussed.

In Table 4.2, we have assembled a list of many of the basic and important Fourier transform pairs. We will encounter many of these repeatedly as we apply the tools of

TABLE 4.1 PROPERTIES OF THE FOURIER TRANSFORM

Section	Property	Aperiodic signal	Fourier transform
		$x(t)$ $y(t)$	$X(j\omega)$ $Y(j\omega)$
4.3.1	Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
4.3.2	Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0}X(j\omega)$
4.3.6	Frequency Shifting	$e^{j\omega_0 t}x(t)$	$X(j(\omega - \omega_0))$
4.3.3	Conjugation	$x^*(t)$	$X^*(-j\omega)$
4.3.5	Time Reversal	$x(-t)$	$X(-j\omega)$
4.3.5	Time and Frequency Scaling	$x(at)$	$\frac{1}{\|a\|}X\left(\frac{j\omega}{a}\right)$
4.4	Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
4.5	Multiplication	$x(t)y(t)$	$\frac{1}{2\pi}\int_{-\infty}^{+\infty}X(j\theta)Y(j(\omega-\theta))d\theta$
4.3.4	Differentiation in Time	$\frac{d}{dt}x(t)$	$j\omega X(j\omega)$
4.3.4	Integration	$\int_{-\infty}^{t} x(t)dt$	$\frac{1}{j\omega}X(j\omega) + \pi X(0)\delta(\omega)$
4.3.6	Differentiation in Frequency	$tx(t)$	$j\frac{d}{d\omega}X(j\omega)$
4.3.3	Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \mathcal{R}e\{X(j\omega)\} = \mathcal{R}e\{X(-j\omega)\} \\ \mathcal{I}m\{X(j\omega)\} = -\mathcal{I}m\{X(-j\omega)\} \\ \|X(j\omega)\| = \|X(-j\omega)\| \\ \sphericalangle X(j\omega) = -\sphericalangle X(-j\omega) \end{cases}$
4.3.3	Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
4.3.3	Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
4.3.3	Even-Odd Decomposition for Real Signals	$x_e(t) = \mathcal{E}v\{x(t)\}$ [$x(t)$ real] $x_o(t) = \mathcal{O}d\{x(t)\}$ [$x(t)$ real]	$\mathcal{R}e\{X(j\omega)\}$ $j\mathcal{I}m\{X(j\omega)\}$

4.3.7 Parseval's Relation for Aperiodic Signals

$$\int_{-\infty}^{+\infty}|x(t)|^2dt = \frac{1}{2\pi}\int_{-\infty}^{+\infty}|X(j\omega)|^2d\omega$$

TABLE 4.2 BASIC FOURIER TRANSFORM PAIRS

Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$	a_k
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0$, otherwise
$\cos \omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0$, otherwise
$\sin \omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0$, otherwise
$x(t) = 1$	$2\pi\delta(\omega)$	$a_0 = 1, \quad a_k = 0, \ k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$)
Periodic square wave $x(t) = \begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & T_1 < \lvert t\rvert \leq \frac{T}{2} \end{cases}$ and $x(t+T) = x(t)$	$\sum_{k=-\infty}^{+\infty} \frac{2\sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \operatorname{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) = \frac{\sin k\omega_0 T_1}{k\pi}$
$\sum_{n=-\infty}^{+\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all k
$x(t) \begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & \lvert t\rvert > T_1 \end{cases}$	$\frac{2\sin \omega T_1}{\omega}$	—
$\frac{\sin Wt}{\pi t}$	$X(j\omega) = \begin{cases} 1, & \lvert\omega\rvert < W \\ 0, & \lvert\omega\rvert > W \end{cases}$	—
$\delta(t)$	1	—
$u(t)$	$\frac{1}{j\omega} + \pi\delta(\omega)$	—
$\delta(t - t_0)$	$e^{-j\omega t_0}$	—
$e^{-at}u(t), \mathcal{R}e\{a\} > 0$	$\frac{1}{a + j\omega}$	—
$te^{-at}u(t), \mathcal{R}e\{a\} > 0$	$\frac{1}{(a + j\omega)^2}$	—
$\frac{t^{n-1}}{(n-1)!} e^{-at}u(t)$, $\mathcal{R}e\{a\} > 0$	$\frac{1}{(a + j\omega)^n}$	—

TABLE 5.1 PROPERTIES OF THE DISCRETE-TIME FOURIER TRANSFORM

Section	Property	Aperiodic Signal	Fourier Transform
		$x[n]$ $y[n]$	$\left.\begin{array}{l} X(e^{j\omega}) \\ Y(e^{j\omega}) \end{array}\right\}$ periodic with period 2π
5.3.2	Linearity	$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$
5.3.3	Time Shifting	$x[n - n_0]$	$e^{-j\omega n_0}X(e^{j\omega})$
5.3.3	Frequency Shifting	$e^{j\omega_0 n}x[n]$	$X(e^{j(\omega-\omega_0)})$
5.3.4	Conjugation	$x^*[n]$	$X^*(e^{-j\omega})$
5.3.6	Time Reversal	$x[-n]$	$X(e^{-j\omega})$
5.3.7	Time Expansion	$x_{(k)}[n] = \begin{cases} x[n/k], & \text{if } n = \text{multiple of } k \\ 0, & \text{if } n \neq \text{multiple of } k \end{cases}$	$X(e^{jk\omega})$
5.4	Convolution	$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$
5.5	Multiplication	$x[n]y[n]$	$\frac{1}{2\pi}\int_{2\pi} X(e^{j\theta})Y(e^{j(\omega-\theta)})d\theta$
5.3.5	Differencing in Time	$x[n] - x[n-1]$	$(1 - e^{-j\omega})X(e^{j\omega})$
5.3.5	Accumulation	$\sum_{k=-\infty}^{n} x[k]$	$\frac{1}{1-e^{-j\omega}}X(e^{j\omega})$ $+\pi X(e^{j0})\sum_{k=-\infty}^{+\infty}\delta(\omega - 2\pi k)$
5.3.8	Differentiation in Frequency	$nx[n]$	$j\frac{dX(e^{j\omega})}{d\omega}$
5.3.4	Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} X(e^{j\omega}) = X^*(e^{-j\omega}) \\ \mathcal{R}e\{X(e^{j\omega})\} = \mathcal{R}e\{X(e^{-j\omega})\} \\ \mathcal{I}m\{X(e^{j\omega})\} = -\mathcal{I}m\{X(e^{-j\omega})\} \\ \lvert X(e^{j\omega})\rvert = \lvert X(e^{-j\omega})\rvert \\ \sphericalangle X(e^{j\omega}) = -\sphericalangle X(e^{-j\omega}) \end{cases}$
5.3.4	Symmetry for Real, Even Signals	$x[n]$ real an even	$X(e^{j\omega})$ real and even
5.3.4	Symmetry for Real, Odd Signals	$x[n]$ real and odd	$X(e^{j\omega})$ purely imaginary and odd
5.3.4	Even-odd Decomposition of Real Signals	$x_e[n] = \mathcal{E}v\{x[n]\}$ $[x[n]$ real$]$ $x_o[n] = \mathcal{O}d\{x[n]\}$ $[x[n]$ real$]$	$\mathcal{R}e\{X(e^{j\omega})\}$ $j\mathcal{I}m\{X(e^{j\omega})\}$
5.3.9	Parseval's Relation for Aperiodic Signals $\sum_{n=-\infty}^{+\infty}\lvert x[n]\rvert^2 = \frac{1}{2\pi}\int_{2\pi}\lvert X(e^{j\omega})\rvert^2 d\omega$		

a duality relationship between the discrete-time Fourier transform and the continuous-time Fourier series. This relation is discussed in Section 5.7.2.

5.7.1 Duality in the Discrete-Time Fourier Series

Since the Fourier series coefficients a_k of a periodic signal $x[n]$ are themselves a periodic sequence, we can expand the sequence a_k in a Fourier series. The duality property for discrete-time Fourier series implies that the Fourier series coefficients for the periodic sequence a_k are the values of $(1/N)x[-n]$ (i.e., are proportional to the values of the original

TABLE 5.2 BASIC DISCRETE-TIME FOURIER TRANSFORM PAIRS

Signal	Fourier Transform	Fourier Series Coefficients (if periodic)
$\sum_{k=\langle N\rangle} a_k e^{jk(2\pi/N)n}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	a_k
$e^{j\omega_0 n}$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - \omega_0 - 2\pi l)$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} 1, & k = m, m \pm N, m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} \frac{1}{2}, & k = \pm m, \pm m \pm N, \pm m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi r}{N}$ $a_k = \begin{cases} \frac{1}{2j}, & k = r, r \pm N, r \pm 2N, \ldots \\ -\frac{1}{2j}, & k = -r, -r \pm N, -r \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$x[n] = 1$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - 2\pi l)$	$a_k = \begin{cases} 1, & k = 0, \pm N, \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$
Periodic square wave $x[n] = \begin{cases} 1, & \|n\| \leq N_1 \\ 0, & N_1 < \|n\| \leq N/2 \end{cases}$ and $x[n + N] = x[n]$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{\sin[(2\pi k/N)(N_1 + \frac{1}{2})]}{N \sin[2\pi k/2N]}, \ k \neq 0, \pm N, \pm 2N, \ldots$ $a_k = \frac{2N_1 + 1}{N}, \ k = 0, \pm N, \pm 2N, \ldots$
$\sum_{k=-\infty}^{+\infty} \delta[n - kN]$	$\frac{2\pi}{N} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{1}{N}$ for all k
$a^n u[n], \quad \|a\| < 1$	$\frac{1}{1 - ae^{-j\omega}}$	—
$x[n] = \begin{cases} 1, & \|n\| \leq N_1 \\ 0, & \|n\| > N_1 \end{cases}$	$\frac{\sin[\omega(N_1 + \frac{1}{2})]}{\sin(\omega/2)}$	—
$\frac{\sin Wn}{\pi n} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wn}{\pi}\right)$ $0 < W < \pi$	$X(\omega) = \begin{cases} 1, & 0 \leq \|\omega\| \leq W \\ 0, & W < \|\omega\| \leq \pi \end{cases}$ $X(\omega)$ periodic with period 2π	—
$\delta[n]$	1	—
$u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{+\infty} \pi\delta(\omega - 2\pi k)$	—
$\delta[n - n_0]$	$e^{-j\omega n_0}$	—
$(n + 1)a^n u[n], \quad \|a\| < 1$	$\frac{1}{(1 - ae^{-j\omega})^2}$	—
$\frac{(n + r - 1)!}{n!(r - 1)!} a^n u[n], \quad \|a\| < 1$	$\frac{1}{(1 - ae^{-j\omega})^r}$	—

TABLE 10.1 PROPERTIES OF THE z-TRANSFORM

Section	Property	Signal	z-Transform	ROC
		$x[n]$	$X(z)$	R
		$x_1[n]$	$X_1(z)$	R_1
		$x_2[n]$	$X_2(z)$	R_2
10.5.1	Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$	At least the intersection of R_1 and R_2
10.5.2	Time shifting	$x[n - n_0]$	$z^{-n_0}X(z)$	R, except for the possible addition or deletion of the origin
10.5.3	Scaling in the z-domain	$e^{j\omega_0 n}x[n]$	$X(e^{-j\omega_0}z)$	R
		$z_0^n x[n]$	$X\left(\frac{z}{z_0}\right)$	z_0R
		$a^n x[n]$	$X(a^{-1}z)$	Scaled version of R (i.e., $\lvert a\rvert R$ = the set of points $\{\lvert a\rvert z\}$ for z in R)
10.5.4	Time reversal	$x[-n]$	$X(z^{-1})$	Inverted R (i.e., R^{-1} = the set of points z^{-1}, where z is in R)
10.5.5	Time expansion	$x_{(k)}[n] = \begin{cases} x[r], & n = rk \\ 0, & n \neq rk \end{cases}$ for some integer r	$X(z^k)$	$R^{1/k}$ (i.e., the set of points $z^{1/k}$, where z is in R)
10.5.6	Conjugation	$x^*[n]$	$X^*(z^*)$	R
10.5.7	Convolution	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	At least the intersection of R_1 and R_2
10.5.7	First difference	$x[n] - x[n-1]$	$(1 - z^{-1})X(z)$	At least the intersection of R and $\lvert z\rvert > 0$
10.5.7	Accumulation	$\sum_{k=-\infty}^{n} x[k]$	$\dfrac{1}{1 - z^{-1}}X(z)$	At least the intersection of R and $\lvert z\rvert > 1$
10.5.8	Differentiation in the z-domain	$nx[n]$	$-z\dfrac{dX(z)}{dz}$	R
10.5.9	Initial Value Theorem If $x[n] = 0$ for $n < 0$, then $x[0] = \lim_{z\to\infty} X(z)$			

TABLE 10.2 SOME COMMON z-TRANSFORM PAIRS

Signal	Transform	ROC
1. $\delta[n]$	1	All z
2. $u[n]$	$\frac{1}{1 - z^{-1}}$	$\lvert z\rvert > 1$
3. $-u[-n-1]$	$\frac{1}{1 - z^{-1}}$	$\lvert z\rvert < 1$
4. $\delta[n-m]$	z^{-m}	All z, except 0 (if $m > 0$) or ∞ (if $m < 0$)
5. $\alpha^n u[n]$	$\frac{1}{1 - \alpha z^{-1}}$	$\lvert z\rvert > \lvert\alpha\rvert$
6. $-\alpha^n u[-n-1]$	$\frac{1}{1 - \alpha z^{-1}}$	$\lvert z\rvert < \lvert\alpha\rvert$
7. $n\alpha^n u[n]$	$\frac{\alpha z^{-1}}{(1 - \alpha z^{-1})^2}$	$\lvert z\rvert > \lvert\alpha\rvert$
8. $-n\alpha^n u[-n-1]$	$\frac{\alpha z^{-1}}{(1 - \alpha z^{-1})^2}$	$\lvert z\rvert < \lvert\alpha\rvert$
9. $[\cos \omega_0 n]u[n]$	$\frac{1 - [\cos \omega_0]z^{-1}}{1 - [2\cos \omega_0]z^{-1} + z^{-2}}$	$\lvert z\rvert > 1$
10. $[\sin \omega_0 n]u[n]$	$\frac{[\sin \omega_0]z^{-1}}{1 - [2\cos \omega_0]z^{-1} + z^{-2}}$	$\lvert z\rvert > 1$
11. $[r^n \cos \omega_0 n]u[n]$	$\frac{1 - [r\cos \omega_0]z^{-1}}{1 - [2r\cos \omega_0]z^{-1} + r^2 z^{-2}}$	$\lvert z\rvert > r$
12. $[r^n \sin \omega_0 n]u[n]$	$\frac{[r\sin \omega_0]z^{-1}}{1 - [2r\cos \omega_0]z^{-1} + r^2 z^{-2}}$	$\lvert z\rvert > r$

10.7.1 Causality

A causal LTI system has an impulse response $h[n]$ that is zero for $n < 0$, and therefore is right-sided. From Property 4 in Section 10.2 we then know that the ROC of $H(z)$ is the exterior of a circle in the z-plane. For some systems, e.g., if $h[n] = \delta[n]$, so that $H(z) = 1$, the ROC can extend all the way in to and possibly include the origin. Also, in general, for a right-sided impulse response, the ROC may or may not include infinity. For example, if $h[n] = \delta[n+1]$, then $H(z) = z$, which has a pole at infinity. However, as we saw in Property 8 in Section 10.2, for a causal system the power series

$$H(z) = \sum_{n=0}^{\infty} h[n]z^{-n}$$

does not include any positive powers of z. Consequently, the ROC includes infinity. Summarizing, we have the follow principle:

> A discrete-time LTI system is causal if and only if the ROC of its system function is the exterior of a circle, including infinity.