Midterm #2 of ECE301, Prof. Wang's section

6:30-7:30pm Wednesday, October 13, 2010, EE 170,

1. Please make sure that it is your name printed on the exam booklet. Enter your student ID number, e-mail address, and signature in the space provided on this page, **NOW!**
2. This is a closed book exam.
3. This exam contains multiple choice questions and work-out questions. For multiple choice questions, there is no need to justify your answers. You have one hour to complete it. The students are suggested not spending too much time on a single question, and working on those that you know how to solve.
4. Neither calculators nor help sheets are allowed.

Name:

Student ID:

E-mail:

Signature:

Question 1: [26%, Work-out question]

1. [4%, Outcome 1] What does the acronym "LTI" stand for? What is the definition of an impulse response?

Consider the following discrete-time LTI system: When the input is a unit step function $x[n] = \mathcal{U}[n]$, the output is

$$y[n] = \begin{cases} 0 & \text{if } n < 0 \\ 2 - (0.5)^n & \text{if } n \geq 0 \end{cases}. \tag{1}$$

2. [10%, Outcome 3] What is the impulse response $h[n]$ of this system?

3. [12%, Outcome 3] When the input is

$$x_1[n] = \begin{cases} 0 & \text{if } n < 0 \\ 1 & \text{if } 0 \leq n < 1000 \\ 2 & \text{if } 1000 \leq n \end{cases}, \tag{2}$$

   find out the corresponding output $y_1[n]$. (If you do not know the answer to the previous sub-question, you can assume that $h[n] = e^{-n}\mathcal{U}[n]$. You will still get full credit if your answer is correct.)

Question 2: [16%, Work-out question, Outcomes 3 and 5] Consider a continuous-time LTI system with the impulse response being

$$h(t) = \begin{cases} e^{6t} & \text{if } t < 0 \\ 0 & \text{if } t \geq 0 \end{cases}. \tag{3}$$

Consider the following two different inputs: $x_1(t) = e^{j6t}$ and $x_1(t) = e^{j6\sqrt{3}t}$, and denote the corresponding outputs by $y_1(t)$ and $y_2(t)$. Find out the magnitudes $|y_1(1)|$ and $|y_2(1)|$ at time $t = 1$. Find out the phases of $\angle y_1(1)$ and $\angle y_2(1)$ at time $t = 1$.

Question 3: [24%, Work-out question] Consider a discrete time LTI system, of which the input/output relationship is

$$y[n] = x[n-1] + y[n-4] \tag{4}$$

and the system is "initial rest," i.e., before we apply any input, the output is zero.

1. [12%, Outcome 2] Find out the impulse response $h[n]$ of this system.

2. [12%, Outcome 4] Find out the Fourier series representation of $h[n]$. (If you do not know the answer to the previous sub-question, you can assume that $h[n] = e^{-n}$ for all $0 \leq n \leq 99$ and $h[n]$ is of period 100. You will still get full credit if your answer is correct.)

Question 4: [26%, Work-out question] Consider the following periodic signal $x(t)$ with period 2π.

$$x(t) = \begin{cases} 1 + \cos(2t) & |t| \leq \frac{\pi}{2} \\ 0 & \frac{\pi}{2} < |t| \leq \pi \end{cases}. \tag{5}$$

1. [10%, Outcome 1] Plot $x(t)$ for the range of $-3\pi < t < 3\pi$.
2. [16%, Outcome 4] Find out the Fourier series representation of $x(t)$.

Question 5: [10% Outcome 1] The following questions are yes-no questions and there is no need to justify your answers. Consider two LTI systems with impulse responses:

$$\begin{aligned} \text{System 1: } h_1(t) &= 2^{\cos(t)} \\ \text{System 2: } h_2[n] &= \mathcal{U}[n+5] - \mathcal{U}[n] \end{aligned}$$

1. [5%, Outcome 1] Is System 1 stable? Is System 1 causal? Is System 1 memoryless?

2. [5%, Outcome 1] Is System 2 stable? Is System 2 causal? Is System 2 memoryless?

Discrete-time Fourier series

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n} \tag{1}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(2\pi/N)n} \tag{2}$$

Continuous-time Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t} \tag{3}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt \tag{4}$$

Continuous-time Fourier transform

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \tag{5}$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \tag{6}$$

Discrete-time Fourier transform

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(j\omega) e^{j\omega n} d\omega \tag{7}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \tag{8}$$

Laplace transform

$$x(t) = \frac{1}{2\pi} e^{\sigma t} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{j\omega t} d\omega \tag{9}$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt \tag{10}$$

Z transform

$$x[n] = r^n \mathcal{F}^{-1}(X(re^{j\omega})) \tag{11}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n} \tag{12}$$

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left.\begin{array}{l} x(t) \\ y(t) \end{array}\right\}$ Periodic with period T and fundamental frequency $\omega_0 = 2\pi/T$	a_k b_k
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t}x(t) = e^{jM(2\pi/T)t}x(t)$	a_{k-M}
Conjugation	3.5.6	$x^*(t)$	a^*_{-k}
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	a_k
Periodic Convolution		$\int_T x(\tau)y(t-\tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk\frac{2\pi}{T}a_k$
Integration		$\int_{-\infty}^{t} x(t)\,dt$ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a^*_{-k} \\ \Re e\{a_k\} = \Re e\{a_{-k}\} \\ \Im m\{a_k\} = -\Im m\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \mathcal{E}v\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}d\{x(t)\} & [x(t) \text{ real}] \end{cases}$	$\Re e\{a_k\}$ $j\Im m\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T}\int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

three examples, we illustrate this. The last example in this section then demonstrates how properties of a signal can be used to characterize the signal in great detail.

Example 3.6

Consider the signal $g(t)$ with a fundamental period of 4, shown in Figure 3.10. We could determine the Fourier series representation of $g(t)$ directly from the analysis equation (3.39). Instead, we will use the relationship of $g(t)$ to the symmetric periodic square wave $x(t)$ in Example 3.5. Referring to that example, we see that, with $T = 4$ and $T_1 = 1$,

$$g(t) = x(t-1) - 1/2. \quad (3.6$$

Thus, in general, *none* of the finite partial sums in eq. (3.52) yield the exact values of $x(t)$, and convergence issues, such as those considered in Section 3.4, arise as we consider the problem of evaluating the limit as the number of terms approaches infinity.

3.7 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

There are strong similarities between the properties of discrete-time and continuous-time Fourier series. This can be readily seen by comparing the discrete-time Fourier series properties summarized in Table 3.2 with their continuous-time counterparts in Table 3.1.

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Periodic Signal	Fourier Series Coefficients
	$\left.\begin{array}{l} x[n] \\ y[n] \end{array}\right\}$ Periodic with period N and fundamental frequency $\omega_0 = 2\pi/N$	$\left.\begin{array}{l} a_k \\ b_k \end{array}\right\}$ Periodic with period N
Linearity	$Ax[n] + By[n]$	$Aa_k + Bb_k$
Time Shifting	$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting	$e^{jM(2\pi/N)n} x[n]$	a_{k-M}
Conjugation	$x^*[n]$	a^*_{-k}
Time Reversal	$x[-n]$	a_{-k}
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period mN)	$\frac{1}{m} a_k \begin{pmatrix}\text{viewed as periodic} \\ \text{with period } mN\end{pmatrix}$
Periodic Convolution	$\sum_{r=\langle N\rangle} x[r]y[n-r]$	$Na_k b_k$
Multiplication	$x[n]y[n]$	$\sum_{l=\langle N\rangle} a_l b_{k-l}$
First Difference	$x[n] - x[n-1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum	$\sum_{k=-\infty}^{n} x[k] \begin{pmatrix}\text{finite valued and periodic only} \\ \text{if } a_0 = 0\end{pmatrix}$	$\left(\frac{1}{(1 - e^{-jk(2\pi/N)})}\right) a_k$
Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} a_k = a^*_{-k} \\ \mathcal{Re}\{a_k\} = \mathcal{Re}\{a_{-k}\} \\ \mathcal{Im}\{a_k\} = -\mathcal{Im}\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \measuredangle a_k = -\measuredangle a_{-k} \end{cases}$
Real and Even Signals	$x[n]$ real and even	a_k real and even
Real and Odd Signals	$x[n]$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = \mathcal{Ev}\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = \mathcal{Od}\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\mathcal{Re}\{a_k\}$ $j\mathcal{Im}\{a_k\}$
Parseval's Relation for Periodic Signals	$\frac{1}{N}\sum_{n=\langle N\rangle} \lvert x[n]\rvert^2 = \sum_{k=\langle N\rangle} \lvert a_k\rvert^2$	