Question 1: [12.5%, Work-out question] Consider a discrete time signal x[n]

$$x[n] = \begin{cases} n & \text{if } 0 \le n \le 2\\ 3 & \text{if } 3 \le n \le 100 \\ 0 & \text{otherwise} \end{cases}$$
 (1)

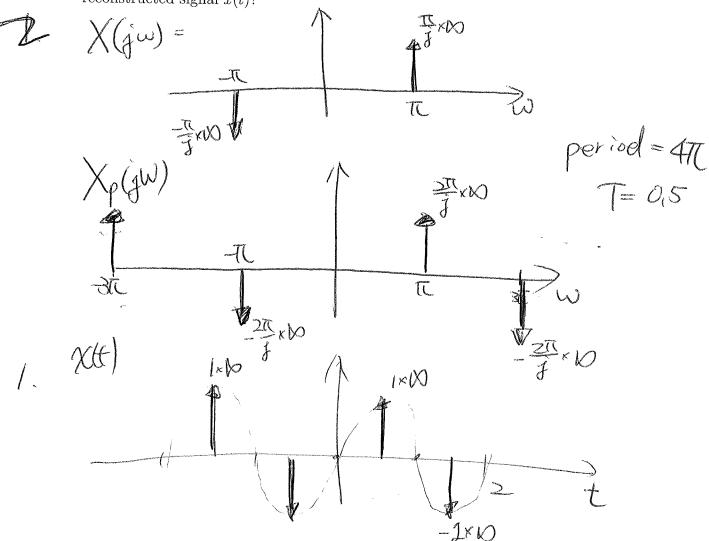
Suppose y[n] = x[-n-1].

- 1. [7.5%] Find the discrete time Fourier transform of x[n].
- 2. [5%] Find the discrete time Fourier transform of y[n]. If you do not know the answer to the first sub-question, you can assume  $x[n] = (n+1)2^{-n}\mathcal{U}[n]$  and you will still get full credit if your answer is correct.

2. 
$$3En = XEn - 1$$
  
 $Z(e^{j\omega}) = e^{-j\omega} X(e^{j\omega})$   
 $y[n] = 3E-n] = XE-n - 1$   
 $= Z(e^{-j\omega}) = e^{j\omega} X(e^{-j\omega})$   
 $= Z(e^{j\omega}) = e^{j\omega} X(e^{-j\omega})$   
 $= e^{j\omega} (e^{j\omega}) = e^{j\omega} (e^{-j\omega})$ 

Question 2: [12.5%, Work-out question] Consider a continuous time signal  $x(t) = \sin(\pi t)$ . We pass it through an impulse train sampler. Let  $x_p(t)$  denote the result of impulse train sampling.

- 1. [2%] Suppose the sampling frequency is 2 Hz. Draw  $x_p(t)$  for the range -1.25 < t < 2.75.
- 2. [3%] Continue from the previous question, Draw  $X_p(j\omega)$  for the range  $-4\pi < \omega < 4\pi$ . (The unit of  $\omega$  is radian/sec, not Hz.)
- 3. [3%] How do we reconstruct the original signal from  $x_p(t)$  using the *optimal reconstruction* (also known as the ideal bandlimited interpolation). You need to specify the cutoff frequencies of your filter(s) and any necessary scaling terms.
- 4. [2.5%] Suppose the sampling frequency is now reduced to 1 Hz. Draw  $X_p(j\omega)$  for the range  $-4\pi < \omega < 4\pi$ . (The unit of  $\omega$  is radian/sec, not Hz.)
- 5. [2%] Continue from the previous question. What is the new  $x_p(t)$ ? And what is the reconstructed signal  $\hat{x}(t)$ ?



3. A low-pass filter with cut-off freg II.

then amplify it by 0,5

4. 
$$\times p(\widehat{A}\omega) = 0$$

5. 
$$\chi_{\rho}(t) = 0$$
  $\widehat{\chi}(t) = 0$ 

Question 3: [12.5%, Work-out question] Consider a sampling plus discrete time signal processing system as follows.

For any input signal x(t), it is sampled with sampling frequency 100 Hz, to generate a discrete-time signal x[n]. The discrete time signal is then processed through a discrete time linear-time invariant system with impulse response  $h_d[n] = 0.5^n \mathcal{U}[n]$ . The output is denoted by y[n]. Then y[n] is passed through an ideal reconstruction to generate y(t).

Answer the following question:

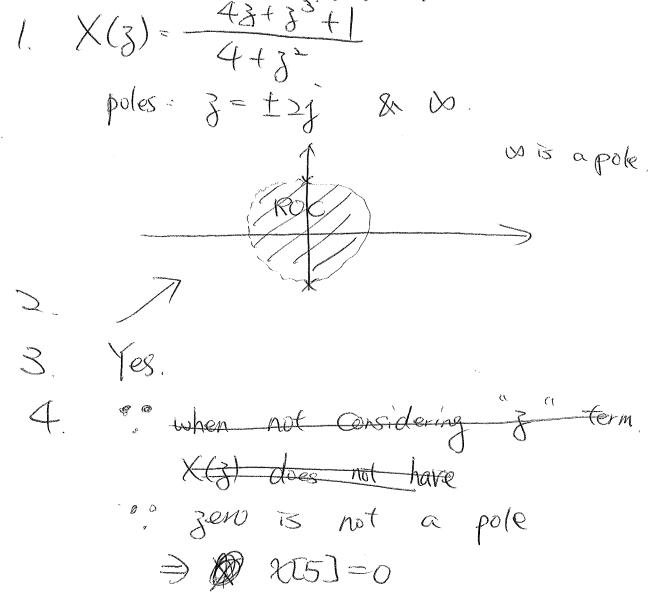
- 1. [1.5%] What is the DTFT  $H_d(e^{j\omega})$  of  $h_d[n]$ ?
- 2. [5%] What is the end-to-end frequency response  $H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$ ?
- 3. [3.5%] When the continuous time input is  $x(t) = e^{j80\pi t}$ , find the overall output y(t).
- 4. [2.5%] When the continuous time input is  $x(t) = e^{j200\pi t}$ , find the overall output y(t).

4. [2.5%] When the continuous time input is 
$$x(t) = e^{2\pi i \omega}$$
, and the overall output  $y(t)$ .

1.  $|-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1| = |-1|$ 

Question 4: [12.5%, Work-out question] Consider a discrete-time signal x[n] with the expression of its Z-transform being  $X(z) = \frac{1}{4+z^2} + z$ . Suppose we also know that x[n] is left-sided. Answer the following questions.

- 1. [2.5%] Find out all the poles of X(z) and draw them in a z-plane.
- 2. [2.5%] What is the ROC of the Z-transform X(z)?
- 3. [2%] Does the discrete-time Fourier transform of x[n] exist?
- 4. [2%] Is x[5] equal to zero or not?
- 5. [2%] Find out the value of x[0]. You may have to use the time-reversal property before applying the property table.
- 6. [1.5%] Find out the expression of x[n] by Taylor's expansion.



$$7(3) = \frac{1}{4+3} + \frac{1}{3} \quad \text{with poles}$$

$$7(3) = \frac{1}{4+3} + \frac{1}{3} \quad \text{with poles}$$

$$10 \quad \text{s not a pole}$$

Question 5: [12.5%, Work-out question] Consider two signals:  $x(t) = \mathcal{U}(t+2) - \mathcal{U}(t-2)$ and

$$h(t) = \begin{cases} 100 & \text{if } 0 < t \\ 50(1 + \cos(\frac{\pi t}{100})) & \text{if } t \le 0 \end{cases}$$
 (2)

Find y(t) = x(t) \* h(t).

$$y(t) = \int_{S=-\infty}^{\infty} \chi(s) h(t-s) ds$$

$$h(t-s) = \int_{S=-\infty}^{\infty} (00) ds$$

$$\int_{S=-\infty}^{\infty} \int_{S=-\infty}^{\infty} \int_{S=-\infty}^{\infty}$$

$$|500|(1+ \cos(\frac{\pi(t-s)}{100}))|f|$$

$$= \int_{-2}^{2} |-h(t-s)| ds$$

$$|50(1+\cos(\frac{\pi(t-s)}{100})|f|$$

$$= \int_{-2}^{2} |-h(t-s)| ds$$

$$= \int_{-2}^{2} |-h(t-s)| ds$$

$$= \int_{-2}^{2} |-h(t-s)| ds$$

$$= \int_{-2}^{2} |-h(t-s)| ds$$

(ase 1. 
$$7$$
  $t < -2$ ,  
 $y(t) = \int_{-2}^{2} 50 \left( 1 + \cos \left( \frac{\pi(t-s)}{100} \right) \right) ds$ 

$$= 50s + 50 \times \sin \left( \frac{\pi(t-s)}{100} \right) / 2$$

$$= 200 + \frac{5000 \times \sin \left( \frac{\pi(t+s)}{100} \right) - \sin \left( \frac{\pi(t+s)}{100} \right)}{-\pi}$$

$$\begin{array}{l}
(68e) 2 - 2 < t < 2 \\
= \int_{0}^{\infty} |\cos ds| + \int_{0}^{\infty} |\sin (\frac{\pi(t-s)}{|\cos s|}) ds \\
= |\cos s| + \int_{-\infty}^{\infty} |\cos s| + \int_{-\infty}^{\infty}$$

Question 6: [20%, Multiple-choice question] Consider two signals  $h_1(t) = \cos(\pi t) \cdot \sin(t)$ and  $h_2[n] = e^{-n(1+j)}\mathcal{U}[(n-2)^2]$ 

- 1. [1%] Is  $h_1(t)$  periodic?
- 2. [1%] Is  $h_2[n]$  periodic?
- 3. [1%] Is  $h_1(t)$  even or odd or neither?
- 4. [1%] Is  $h_2[n]$  even or odd or neither?
- 5. [1%] Is  $h_1(t)$  of finite energy?
- 6. [1%] Is  $h_2[n]$  of finite energy?

Suppose the above two signals are also the impulse responses of two LTI systems: System 1 and System 2, respectively.

- 1. [1%] Is System 1 causal?
- 2. [1%] Is System 2 causal?
- 3. [1%] Is System 1 stable?
- 4. [1%] Is System 2 stable?
- 5. [1.5%] Is System 1 invertible?
- 6. [1%] Is System 2 invertible?

> No. 3. odd

4 neither.

5. No.

6. No.

7. No. 8. No.

9. No

( both answers will get credit)

Question 7: [12.5% Work-out question]

- 1. [6%]  $x(t) = \cos(2\pi t) + \sin(3/4\pi t) + e^{j\pi t}$ . Find its Fourier series representation.
- 2. [6.5%] Consider a periodic signal y[n] with period 1000. We also know that

$$y[n] = \begin{cases} 1 & \text{if } 500 \le n < 1000 \\ 5 & \text{if } 1000 \le n < 1250 \\ 0 & \text{if } 1250 \le n < 1500 \end{cases}$$
 (3)

Find the Fourier series representation of y[n].

1. 
$$T = \frac{2\pi}{2\pi} = 1$$

$$T_{3} = \frac{2\pi}{16} = 2$$

$$LCM(1, \frac{1}{3}, 2) = 6$$

$$2k = \frac{1}{8} \times 4$$

$$2k = \frac{1}{8} \times$$

$$=\frac{1}{1000} \times \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} = \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} \times \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} = \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} \times \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} = \frac{1}{1-e^{-jk\frac{2\pi}{1000}} \times 500} =$$

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Question 8: [12.5% Work-out question] Let  $z(t) = e^{-2t}\mathcal{U}(t)$ . Suppose we know the input/output relationship of a system satisfies  $y(t) = \frac{dy(t)}{dt} + z(t) * x(t)$ . Find the impulse response of the above system.

$$\frac{Y(j\omega)}{X(j\omega)} = \frac{1}{2+j\omega} (1-j\omega)$$

$$= \frac{1}{3}$$

$$= \frac{1}{3}$$

$$= \frac{1}{3}$$

$$= \frac{1}{3}$$

$$= \frac{1}{3}$$

$$= \frac{1}{3}$$