ECE 301, final exam of the session of Prof. Chih-Chun Wang

Saturday 10:20am–12:20pm , December 20, 2008, STEW 130,

1. Enter your name, student ID number, e-mail address, and signature in the space provided on this page, **NOW!**
2. This is a closed book exam.
3. This exam contains both multiple-choice and work-out questions. The students are suggested not spending too much time on a single question, and working on those that you know how to solve.
4. There are 24 pages in the exam booklet. Use the back of each page for rough work. The last pages are all the Tables. You may rip the last pages for easier reference. **Do not use your own copy of the Tables. Using your own copy of Tables will be considered as cheating.**
5. Neither calculators nor help sheets are allowed.

Name:

Student ID:

E-mail:

Signature:

Question 1: [30%] No need to write down justifications.

1. [10%] Let

$$x(t) = \cos(\frac{\pi t}{2}) + \sin(\frac{t}{3}) \tag{1}$$

   Is $x(t)$ periodic? (If Yes, what is the period?) Is $x(t)$ an odd signal? Is $x(t)$ of infinite or finite power? Is $x(t)$ of infinite or finite energy?

2. [10%] Let

$$y[n] = \sum_{k=-\infty}^{\infty} \cos(0.5\pi n)\delta[n-2k] \tag{2}$$

   Is $y[n]$ periodic? (If Yes, what is the period?) Is $y[n]$ an even signal? Is $y[n]$ of infinite or finite power? Is $y[n]$ of infinite or finite energy?

3. [5%] Plot $y[n]$ for the range between $n = -2$ to 6.

4. [5%] Let

$$z[n] = y[n]^2. \tag{3}$$

   Plot $z[n]$ for the range between $n = -2$ to 6.

Question 2: [35%]

1. [3%] Use one or two sentences to describe what is a *time-invariant* system.

2. [3%] Use one or two sentences to describe what is a *linear* system.

3. [8%] Consider a discrete-time linear time-invariant system with impulse response $h[n] = \frac{1}{4}(\mathcal{U}[n+3] - \mathcal{U}[n-1])$. Let $x[n] = 2^{-n}\mathcal{U}[n]$. Find out the corresponding output $y[n]$ of the given system.

4. [6%] Is the above system causal? Is it memoryless? Is it invertible? Is it stable? (No need to write down justifications for this subquestion.)

5. [5%] The above system is also termed a *moving-average* system. Why is it called a moving-average system? (You should specify exactly which input values $x[k]$ are *averaged* to generate $y[n]$.)

6. [5%] Consider one linear time-invariant system with impulse response $h_1[n]$. Explain how to check whether $h_1[n]$ is invertible. Hint: Your answer should involve the corresponding discrete-time Fourier transform $H_1(e^{j\omega})$.

7. [5%] Suppose the system is invertible and the impulse response of the *inverse system* is $h_2[n]$. Prove/show that $h_1[n]$ and $h_2[n]$ must satisfy

$$h_1[n] * h_2[n] = \delta[n] \tag{4}$$

   by considering the serial concatenation of the two systems.

Question 3: [35%]

1. [10%] Consider the following periodic continuous-time signal of period 3: Within the range $-1,5$ to 1.5, we have

$$w(t) = \begin{cases} \delta(t+1) + \delta(t-1) & \text{if } -1.5 < t \leq 1.5 \\ w(t-3) & \text{otherwise} \end{cases} \tag{5}$$

   Find the Fourier series coefficients a_k of $w(t)$. Hint: Use direct computation.

2. [8%] What is the Fourier transform of $w(t)$. If you do not know the answer to the above question, you can express $W(j\omega)$ in terms of a_k and you will get 5 points.

3. [10%] Consider a differential equation system:

$$2\frac{d}{dt}y(t) = -3y(t) + 4x(t). \tag{6}$$

   Find out the impulse response $h(t)$.

4. [7%] With an input $x(t) = e^{-2t}\mathcal{U}(t)$, find out the output $y(t)$.

Question 4: [30%]

1. [7%] A commercial AM radio system uses bandwidth from 520kHz to 1610kHz. If the content of each radio station is a band-limited signal with $X(j\omega) = 0$ if $|\omega| > 10$ kHz. How many radio stations can share the 520kHz to 1610kHz frequency if the AM-DSB modulation is used? How many radio stations can share the same amount of frequency if the AM-SSB modulation (using the upper side-band) is used.

2. [10%] Prof. Wang wanted to transmit an AM signal. To that end, he wrote the following MATLAB code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read the .wav files
[x, f_sample, N]=wavread('x');
x=x';

% Step 1: Make the signal band-limited.
W_M=????;
h=1/(pi*t).*(sin(W_M*t));
x_new=ece301conv(x, h);

% Step 2: Multiply x_new with a sine wave instead of a cosine wave.
y=x_new.*sin(4000*pi*t);

wavwrite(y', f_sample, N, 'y.wav');
```

   What is the largest value of W_M that still ensures successful demodulation of x_new from the modulated signal y?

3. [8%] Knowing that Prof. Wang used the above code to generate the "y.wav" file, a student tried to demodulate the output waveform "y.wav" by writing the following code.

```
% Initialization
duration=8;
f_sample=44100;
t=(((0-4)*f_sample+0.5):((duration-4)*f_sample-0.5))/f_sample;

% Read the .wav files
```

```
[y, f_sample, N]=wavread('y');
y=y';


W_C=4000*pi;
h=1/(pi*t).*(sin(0.5*W_C*t));


y_new=2*y.*cos(W_C*t);

xhat=ece301conv(y_new,h);

wavplay(xhat,f_sample)
```

This student made two mistakes in his/her system (assuming that the largest W_M is used) and the resulting xhat is thus different from the original signal x_new. How to correct the two mistakes in the above code? (Each mistake worths 4 pts)

4. [5%] If the student did not correct the mistakes, what type of incorrect output would he/she hear after the "wavplay" command. (You should comment on whether it is a high-pitch sound or a low-frequency sound, or any other specific type of sound.)

   If you do not know how to write the MATLAB code, write down the system diagrams (flow charts, etc.) of AM and the corresponding synchronous demodulation. Carefully marks all the cutoff frequencies of the LPF, the carrier frequency, and the multiplication factor. You will get 65% of the overall credit if your answers are correct.

   If you do not know how to write down the system diagram, explain in words how will you modulate a AM signal and how would you demodulate the information-bearing signal. You will get 50% of the overall credit if your answers are correct.

Question 5: [34%]

1. [11%] Suppose $x(t) = \cos(3\pi t)$. Write down the expression of normal *discrete time* sampling $x_d[n]$ when the sampling period is $T = 0.5$? Plot $x_d[n]$ for $n = -1$ to 5.

2. [6%] Suppose *linear interpolation* is used to reconstruct $\hat{x}(t)$ from the sampled values, plot the reconstructed signal $\hat{x}(t)$ between $t = -0.5$ to $t = 2.5$. (If you do not know the answer to the previous question about sampling, you can assume a normal discrete sampling is used with

$$x_d[n] = 2^{-|n|} \text{ for all integer } n, \tag{7}$$

   and continue solving this question. You will still get full credit if your answer is correct.)

3. [5%] Is the system under-sampled or over-sampled?

4. [12%] What is the discrete-time Fourier transform of $x_d[n]$? Plot $X_d(e^{j\omega})$ for the range $-\pi < \omega < \pi$. Hint: Approach 1: You can solve the following sub-questions in sequence. Step 1: Consider impulse train sampling $x_p(t) = x(t)\sum_{k=-\infty}^{\infty}\delta(t - 0.5k)$, what is the continuous time Fourier transform $X_p(j\omega)$ of $x_p(t)$? Step 2: How to derive the DTFT $X_d(e^{j\omega})$ from $X_p(j\omega)$. Solving each step will give you partial credits (6% for each step). Approach 2: Direct computation.

Question 6: [36%] Compute the following transforms or inverse transforms.

1. [12%] Suppose a discrete-time Fourier transform is

$$X(e^{j\omega}) = 1 + 3e^{-j3\omega} + 3e^{-j10\omega}.$$

Find its inverse Fourier transform $x[n]$.

2. [12%] Suppose a discrete-time Fourier transform is

$$Y(e^{j\omega}) = \frac{e^{j2\omega}}{1 - 0.5e^{-j\omega}}.$$

Find its inverse Fourier transform $y[n]$.

3. [12%] Suppose

$$x(t) = -2^t \mathcal{U}(t-2)$$

find its Laplace transform expression and plot the Region of Convergence (ROC).

TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left.\begin{array}{l} x(t) \\ y(t) \end{array}\right\}$ Periodic with period T and fundamental frequency $\omega_0 = 2\pi/T$	a_k b_k
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} x(t) = e^{jM(2\pi/T)t} x(t)$	a_{k-M}
Conjugation	3.5.6	$x^*(t)$	a^*_{-k}
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	a_k
Periodic Convolution		$\int_T x(\tau) y(t - \tau) d\tau$	$T a_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk\frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^{t} x(t)\, dt$ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right) a_k = \left(\frac{1}{jk(2\pi/T)}\right) a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\left\{\begin{array}{l} a_k = a^*_{-k} \\ \mathcal{R}e\{a_k\} = \mathcal{R}e\{a_{-k}\} \\ \mathcal{I}m\{a_k\} = -\mathcal{I}m\{a_{-k}\} \\ \lvert a_k \rvert = \lvert a_{-k} \rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{array}\right.$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\left\{\begin{array}{ll} x_e(t) = \mathcal{E}v\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}d\{x(t)\} & [x(t) \text{ real}] \end{array}\right.$	$\mathcal{R}e\{a_k\}$ $j\mathcal{I}m\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T}\int_T \lvert x(t)\rvert^2 dt = \sum_{k=-\infty}^{+\infty} \lvert a_k \rvert^2$$

three examples, we illustrate this. The last example in this section then demonstrates how properties of a signal can be used to characterize the signal in great detail.

Example 3.6

Consider the signal $g(t)$ with a fundamental period of 4, shown in Figure 3.10. We could determine the Fourier series representation of $g(t)$ directly from the analysis equation (3.39). Instead, we will use the relationship of $g(t)$ to the symmetric periodic square wave $x(t)$ in Example 3.5. Referring to that example, we see that, with $T = 4$ and $T_1 = 1$,

$$g(t) = x(t - 1) - 1/2. \tag{3.69}$$

Thus, in general, *none* of the finite partial sums in eq. (3.52) yield the exact values of $x(t)$, and convergence issues, such as those considered in Section 3.4, arise as we consider the problem of evaluating the limit as the number of terms approaches infinity.

3.7 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

There are strong similarities between the properties of discrete-time and continuous-time Fourier series. This can be readily seen by comparing the discrete-time Fourier series properties summarized in Table 3.2 with their continuous-time counterparts in Table 3.1.

TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES

Property	Periodic Signal	Fourier Series Coefficients
	$\left.\begin{matrix} x[n] \\ y[n] \end{matrix}\right\}$ Periodic with period N and fundamental frequency $\omega_0 = 2\pi/N$	$\left.\begin{matrix} a_k \\ b_k \end{matrix}\right\}$ Periodic with period N
Linearity	$Ax[n] + By[n]$	$Aa_k + Bb_k$
Time Shifting	$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting	$e^{jM(2\pi/N)n}x[n]$	a_{k-M}
Conjugation	$x^*[n]$	a^*_{-k}
Time Reversal	$x[-n]$	a_{-k}
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period mN)	$\frac{1}{m}a_k \begin{pmatrix}\text{viewed as periodic} \\ \text{with period } mN\end{pmatrix}$
Periodic Convolution	$\sum_{r=\langle N\rangle} x[r]y[n-r]$	Na_kb_k
Multiplication	$x[n]y[n]$	$\sum_{l=\langle N\rangle} a_l b_{k-l}$
First Difference	$x[n] - x[n-1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum	$\sum_{k=-\infty}^{n} x[k] \begin{pmatrix}\text{finite valued and periodic only} \\ \text{if } a_0 = 0\end{pmatrix}$	$\left(\frac{1}{(1 - e^{-jk(2\pi/N)})}\right)a_k$
Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} a_k = a^*_{-k} \\ \mathcal{R}e\{a_k\} = \mathcal{R}e\{a_{-k}\} \\ \mathcal{I}m\{a_k\} = -\mathcal{I}m\{a_{-k}\} \\ \lvert a_k\rvert = \lvert a_{-k}\rvert \\ \sphericalangle a_k = -\sphericalangle a_{-k} \end{cases}$
Real and Even Signals	$x[n]$ real and even	a_k real and even
Real and Odd Signals	$x[n]$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = \mathcal{E}v\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = \mathcal{O}d\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\mathcal{R}e\{a_k\}$ $j\mathcal{I}m\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{N}\sum_{n=\langle N\rangle} \lvert x[n]\rvert^2 = \sum_{k=\langle N\rangle} \lvert a_k\rvert^2$$

4.6 TABLES OF FOURIER PROPERTIES AND OF BASIC FOURIER TRANSFORM PAIRS

In the preceding sections and in the problems at the end of the chapter, we have considered some of the important properties of the Fourier transform. These are summarized in Table 4.1, in which we have also indicated the section of this chapter in which each property has been discussed.

In Table 4.2, we have assembled a list of many of the basic and important Fourier transform pairs. We will encounter many of these repeatedly as we apply the tools of

TABLE 4.1 PROPERTIES OF THE FOURIER TRANSFORM

Section	Property	Aperiodic signal	Fourier transform
		$x(t)$ $y(t)$	$X(j\omega)$ $Y(j\omega)$
4.3.1	Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
4.3.2	Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0}X(j\omega)$
4.3.6	Frequency Shifting	$e^{j\omega_0 t}x(t)$	$X(j(\omega - \omega_0))$
4.3.3	Conjugation	$x^*(t)$	$X^*(-j\omega)$
4.3.5	Time Reversal	$x(-t)$	$X(-j\omega)$
4.3.5	Time and Frequency Scaling	$x(at)$	$\frac{1}{\|a\|}X\left(\frac{j\omega}{a}\right)$
4.4	Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
4.5	Multiplication	$x(t)y(t)$	$\frac{1}{2\pi}\int_{-\infty}^{+\infty}X(j\theta)Y(j(\omega-\theta))d\theta$
4.3.4	Differentiation in Time	$\frac{d}{dt}x(t)$	$j\omega X(j\omega)$
4.3.4	Integration	$\int_{-\infty}^{t} x(t)dt$	$\frac{1}{j\omega}X(j\omega) + \pi X(0)\delta(\omega)$
4.3.6	Differentiation in Frequency	$tx(t)$	$j\frac{d}{d\omega}X(j\omega)$
4.3.3	Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \mathcal{R}e\{X(j\omega)\} = \mathcal{R}e\{X(-j\omega)\} \\ \mathcal{I}m\{X(j\omega)\} = -\mathcal{I}m\{X(-j\omega)\} \\ \|X(j\omega)\| = \|X(-j\omega)\| \\ \sphericalangle X(j\omega) = -\sphericalangle X(-j\omega) \end{cases}$
4.3.3	Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
4.3.3	Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
4.3.3	Even-Odd Decomposition for Real Signals	$x_e(t) = \mathcal{E}v\{x(t)\}$ [$x(t)$ real] $x_o(t) = \mathcal{O}d\{x(t)\}$ [$x(t)$ real]	$\mathcal{R}e\{X(j\omega)\}$ $j\mathcal{I}m\{X(j\omega)\}$

4.3.7 Parseval's Relation for Aperiodic Signals

$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi}\int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega$$

TABLE 4.2 BASIC FOURIER TRANSFORM PAIRS

Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$	a_k
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0$, otherwise
$\cos\omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0$, otherwise
$\sin\omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0$, otherwise
$x(t) = 1$	$2\pi\delta(\omega)$	$a_0 = 1, \quad a_k = 0, \ k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$)
Periodic square wave $x(t) = \begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & T_1 < \lvert t\rvert \leq \frac{T}{2} \end{cases}$ and $x(t + T) = x(t)$	$\sum_{k=-\infty}^{+\infty} \frac{2\sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \operatorname{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) = \frac{\sin k\omega_0 T_1}{k\pi}$
$\sum_{n=-\infty}^{+\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all k
$x(t)\begin{cases} 1, & \lvert t\rvert < T_1 \\ 0, & \lvert t\rvert > T_1 \end{cases}$	$\frac{2\sin\omega T_1}{\omega}$	—
$\frac{\sin Wt}{\pi t}$	$X(j\omega) = \begin{cases} 1, & \lvert\omega\rvert < W \\ 0, & \lvert\omega\rvert > W \end{cases}$	—
$\delta(t)$	1	—
$u(t)$	$\frac{1}{j\omega} + \pi\delta(\omega)$	—
$\delta(t - t_0)$	$e^{-j\omega t_0}$	—
$e^{-at}u(t), \mathcal{R}e\{a\} > 0$	$\frac{1}{a + j\omega}$	—
$te^{-at}u(t), \mathcal{R}e\{a\} > 0$	$\frac{1}{(a + j\omega)^2}$	—
$\frac{t^{n-1}}{(n-1)!} e^{-at}u(t)$, $\mathcal{R}e\{a\} > 0$	$\frac{1}{(a + j\omega)^n}$	—

TABLE 5.1 PROPERTIES OF THE DISCRETE-TIME FOURIER TRANSFORM

Section	Property	Aperiodic Signal	Fourier Transform
		$x[n]$ $y[n]$	$\left.\begin{matrix} X(e^{j\omega}) \\ Y(e^{j\omega}) \end{matrix}\right\}$ periodic with period 2π
5.3.2	Linearity	$ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$
5.3.3	Time Shifting	$x[n - n_0]$	$e^{-j\omega n_0}X(e^{j\omega})$
5.3.3	Frequency Shifting	$e^{j\omega_0 n}x[n]$	$X(e^{j(\omega-\omega_0)})$
5.3.4	Conjugation	$x^*[n]$	$X^*(e^{-j\omega})$
5.3.6	Time Reversal	$x[-n]$	$X(e^{-j\omega})$
5.3.7	Time Expansion	$x_{(k)}[n] = \begin{cases} x[n/k], & \text{if } n = \text{multiple of } k \\ 0, & \text{if } n \neq \text{multiple of } k \end{cases}$	$X(e^{jk\omega})$
5.4	Convolution	$x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$
5.5	Multiplication	$x[n]y[n]$	$\frac{1}{2\pi}\int_{2\pi} X(e^{j\theta})Y(e^{j(\omega-\theta)})d\theta$
5.3.5	Differencing in Time	$x[n] - x[n-1]$	$(1 - e^{-j\omega})X(e^{j\omega})$
5.3.5	Accumulation	$\sum_{k=-\infty}^{n} x[k]$	$\frac{1}{1-e^{-j\omega}}X(e^{j\omega})$ $+\pi X(e^{j0})\sum_{k=-\infty}^{+\infty}\delta(\omega - 2\pi k)$
5.3.8	Differentiation in Frequency	$nx[n]$	$j\frac{dX(e^{j\omega})}{d\omega}$
5.3.4	Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} X(e^{j\omega}) = X^*(e^{-j\omega}) \\ \mathcal{Re}\{X(e^{j\omega})\} = \mathcal{Re}\{X(e^{-j\omega})\} \\ \mathcal{Im}\{X(e^{j\omega})\} = -\mathcal{Im}\{X(e^{-j\omega})\} \\ \lvert X(e^{j\omega})\rvert = \lvert X(e^{-j\omega})\rvert \\ \sphericalangle X(e^{j\omega}) = -\sphericalangle X(e^{-j\omega}) \end{cases}$
5.3.4	Symmetry for Real, Even Signals	$x[n]$ real an even	$X(e^{j\omega})$ real and even
5.3.4	Symmetry for Real, Odd Signals	$x[n]$ real and odd	$X(e^{j\omega})$ purely imaginary and odd
5.3.4	Even-odd Decomposition of Real Signals	$x_e[n] = \mathcal{E}v\{x[n]\}$ $[x[n]$ real$]$ $x_o[n] = \mathcal{O}d\{x[n]\}$ $[x[n]$ real$]$	$\mathcal{Re}\{X(e^{j\omega})\}$ $j\mathcal{Im}\{X(e^{j\omega})\}$
5.3.9	Parseval's Relation for Aperiodic Signals $\sum_{n=-\infty}^{+\infty} \lvert x[n]\rvert^2 = \frac{1}{2\pi}\int_{2\pi} \lvert X(e^{j\omega})\rvert^2 d\omega$		

a duality relationship between the discrete-time Fourier transform and the continuous-time Fourier series. This relation is discussed in Section 5.7.2.

5.7.1 Duality in the Discrete-Time Fourier Series

Since the Fourier series coefficients a_k of a periodic signal $x[n]$ are themselves a periodic sequence, we can expand the sequence a_k in a Fourier series. The duality property for discrete-time Fourier series implies that the Fourier series coefficients for the periodic sequence a_k are the values of $(1/N)x[-n]$ (i.e., are proportional to the values of the original

TABLE 5.2 BASIC DISCRETE-TIME FOURIER TRANSFORM PAIRS

Signal	Fourier Transform	Fourier Series Coefficients (if periodic)
$\sum_{k=\langle N\rangle} a_k e^{jk(2\pi/N)n}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	a_k
$e^{j\omega_0 n}$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - \omega_0 - 2\pi l)$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} 1, & k = m, m \pm N, m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\cos \omega_0 n$	$\pi \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) + \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi m}{N}$ $a_k = \begin{cases} \frac{1}{2}, & k = \pm m, \pm m \pm N, \pm m \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$\sin \omega_0 n$	$\frac{\pi}{j} \sum_{l=-\infty}^{+\infty} \{\delta(\omega - \omega_0 - 2\pi l) - \delta(\omega + \omega_0 - 2\pi l)\}$	(a) $\omega_0 = \frac{2\pi r}{N}$ $a_k = \begin{cases} \frac{1}{2j}, & k = r, r \pm N, r \pm 2N, \ldots \\ -\frac{1}{2j}, & k = -r, -r \pm N, -r \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$ (b) $\frac{\omega_0}{2\pi}$ irrational $\Rightarrow$ The signal is aperiodic
$x[n] = 1$	$2\pi \sum_{l=-\infty}^{+\infty} \delta(\omega - 2\pi l)$	$a_k = \begin{cases} 1, & k = 0, \pm N, \pm 2N, \ldots \\ 0, & \text{otherwise} \end{cases}$
Periodic square wave $x[n] = \begin{cases} 1, & \lvert n\rvert \le N_1 \\ 0, & N_1 < \lvert n\rvert \le N/2 \end{cases}$ and $x[n+N] = x[n]$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{\sin[(2\pi k/N)(N_1 + \frac{1}{2})]}{N \sin[2\pi k/2N]}, \quad k \neq 0, \pm N, \pm 2N, \ldots$ $a_k = \frac{2N_1 + 1}{N}, \quad k = 0, \pm N, \pm 2N, \ldots$
$\sum_{k=-\infty}^{+\infty} \delta[n - kN]$	$\frac{2\pi}{N} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{N}\right)$	$a_k = \frac{1}{N}$ for all k
$a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{1 - ae^{-j\omega}}$	—
$x[n] = \begin{cases} 1, & \lvert n\rvert \le N_1 \\ 0, & \lvert n\rvert > N_1 \end{cases}$	$\frac{\sin[\omega(N_1 + \frac{1}{2})]}{\sin(\omega/2)}$	—
$\frac{\sin Wn}{\pi n} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wn}{\pi}\right)$ $0 < W < \pi$	$X(\omega) = \begin{cases} 1, & 0 \le \lvert\omega\rvert \le W \\ 0, & W < \lvert\omega\rvert \le \pi \end{cases}$ $X(\omega)$ periodic with period 2π	—
$\delta[n]$	1	—
$u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{+\infty} \pi\delta(\omega - 2\pi k)$	—
$\delta[n - n_0]$	$e^{-j\omega n_0}$	—
$(n+1)a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{(1 - ae^{-j\omega})^2}$	—
$\frac{(n+r-1)!}{n!(r-1)!} a^n u[n], \quad \lvert a\rvert < 1$	$\frac{1}{(1 - ae^{-j\omega})^r}$	—

Discrete-time Fourier series

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk(2\pi/N)n} \tag{1}$$

$$a_k = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk(2\pi/N)n} \tag{2}$$

Continuous-time Fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t} \tag{3}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt \tag{4}$$

Continuous-time Fourier transform

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \tag{5}$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \tag{6}$$

Discrete-time Fourier transform

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(j\omega) e^{j\omega n} d\omega \tag{7}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \tag{8}$$

Continuous-time Laplace transform

$$x(t) = \frac{1}{2\pi} e^{\sigma t} \int_{-\infty}^{\infty} X(\sigma + j\omega) e^{j\omega t} d\omega \tag{9}$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt \tag{10}$$