

Question 44-Continued

e) \* result will be periodic, so only determine one period  

$$\begin{aligned}
& x(\tau) = \begin{cases} 1, -\frac{1}{2} < \tau < \frac{1}{2} \\ -1, -\frac{1}{2} < \tau < \frac{3}{2} \\ -1, -\frac{1}{2} < \tau < \frac{1}{2} \\ -1, -\frac{1}{2} < \tau < \frac{1}{2} \\ -1, -\frac{1}{2} < \tau < \frac{1}{2} \\ -1, -\frac{1}{2} \\ -1, -\frac{1}{2} \\ -\frac$$

**Question 46-Continued** 

e) 
$$h(t) = e^{-b|t|}$$
  
• not causal  
• stable  
g)  $h(t) = (2e^{-t} - e^{(t-100)}) u(t)$   
• causal  
• unstable  $(\int_{-\infty}^{\infty} 2e^{-t} dt + \int_{-\infty}^{\infty} e^{\frac{t-100}{100}} dt)$   
 $\int_{-\infty}^{100} t$   
 $\int_{-\infty}^{100} t$ 

$$\begin{array}{c} 2.40 \\ a) \ y(t) = \int e^{-(t-\tau)} x(\tau-2) \ d\tau \\ \stackrel{s=\tau-2}{\longrightarrow} (\tau=s+2) \\ \stackrel{s=\tau}{\longrightarrow} x(s) \ e^{-(t-(s+2))} \\ = \int x(s) \ e^{-(t-(s+2))} \\ \stackrel{s=\tau}{\longrightarrow} x(s) \ e^{-(t-(s+2))} \\ \stackrel{s=\tau}{\longrightarrow} x(s) \ e^{-(t-s)} \ ds \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{-(t-s)-2}{y(t) = \frac{t-1}{2}} \ ds \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t)}{x(t-s)} \\ \begin{array}{c} x(t) \\ x(t-s) \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{-(t-2)}{y(t) = \frac{t-2}{2}} \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{-(t-2)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{-(t-2)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t-2)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t-2)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t-2)}{y(t) = \frac{t-2}{2}} \ \frac{x(t-2)}{t+1} \ s \\ \stackrel{s=\tau-2}{\longrightarrow} \frac{x(t-2)$$

$$y[n] = x[n] - 0.5y[n-1] \qquad x[n] = 2^{-n}u[n]$$

$$i. h[0] = 9[n] = 1$$

$$h[1] = 9[n] - 0.5 = 0 - 0.5 = -\frac{1}{2}$$

$$h[2] = 9[n] - (-0.25) = \frac{1}{4}$$

$$h[3] = \frac{1}{8}$$

$$h[4] = -\frac{1}{10}$$

$$h[n] = (-1)^{n} 2^{-n}u[n] = \left((-\frac{1}{2})^{n}u[n]\right)$$

$$2. y[5] = x[5] + h[5]$$

$$= \sum_{n=-\infty}^{\infty} x[5-n]h[n] = (-\frac{1}{2})^{5} \sum_{n=0}^{5} (-1)^{n} = 0$$

$$= \frac{1}{2^{5}} \cdot (-\frac{1}{2})^{0} + \frac{1}{2^{4}} \cdot (-\frac{1}{2})^{1} + \frac{1}{2^{2}} (-\frac{1}{2})^{2} + \frac{1}{2^{2}} (-\frac{1}{2})^{5}$$

$$= 0$$

$$y[n] = \sum_{k=-\infty}^{\infty} (-2)^{(n-k)} 2^{-k} u[n] u[n-k]$$

$$= \sum_{k=0}^{n} 2^{-k} (-2)^{n+k} = (-2)^{n} \sum_{k=0}^{n} (-1)^{-k}$$

$$y[n] = \begin{cases} 0, n < 0 \\ 0, n < d \\ n > 0 \end{cases}$$

$$y(t) = \frac{1}{15} \int_{t-15}^{t} \chi(s) ds$$
1. yes, the system is LTI  

$$\chi(t) = \alpha, \chi.(t) + \alpha_{2} \chi_{2}(t)$$

$$y(t) = \frac{1}{15} \int_{t-15}^{t} \alpha_{15} \chi(s) + \alpha_{2} \chi_{2} ts)$$

$$y(t) = \frac{\alpha_{1}}{15} \int_{t-15}^{t} \chi.(s) ds + \frac{\alpha_{2}}{15} \int_{t-15}^{t} \chi_{2}(s) ds$$

$$(t+T) \xrightarrow{sys}{15} \frac{1}{15} \int_{t-15}^{t} \chi(s+T) ds$$

$$let s' = s+T$$

$$\frac{1}{15} \int_{t-15}^{t+T} \chi(s') ds' = y(t+T)$$

$$\chi(t+T) \xrightarrow{sys}{15} y(t+T) \qquad \therefore time-invariant$$
2.  $h(t) = \frac{1}{15} \int_{t-15}^{t} \chi(s) ds = \frac{1}{15} [u(s]]^{t}$ 

$$= \left[\frac{1}{15} (u[t] - u[t-15])\right]$$

Question 49

3. • not memoryless (has memory) • stable • causal (h(t) = 0 for t < 0) 4.  $x(t) = \cos(2\pi t)$   $y(t) = \frac{1}{15} \int_{t-15}^{t} \cos(2\pi s) ds = \frac{1}{15 \cdot 2\pi} \left[ \sin(2\pi s) \right]_{s=t-15}^{t}$   $y(t) = \frac{1}{30\pi} \sin(2\pi t) - \frac{1}{30\pi} \sin(2\pi (t-15))$ \* since  $\sin(2\pi t) = \sin(2\pi t - 30\pi r)$ , y(t) = 0

5. not invertible (if you know the average of a function, there is not a unique mapping back to the original function)

$$\begin{split} y(t) &= -y(t) + x(t) \\ 1. \ y(t) &= e^{-t}u(t) \quad x(t) = g(t) \\ \frac{d}{dt} \left[ e^{-t}u(t) \right] &= -e^{-t}u(t) + g(t) \\ \frac{d}{dt} \left( e^{-t} \right) \cdot u(t) + e^{-t} \cdot \frac{d}{dt} \left( u(t) \right) &= -e^{-t}u(t) + g(t) \\ -e^{-t}u(t) + e^{-t}g(t) &= -e^{-t}u(t) + g(t) \end{split}$$

Question 50-Continued

\* the value of 
$$e^{-t}$$
 at  $t=0$  is  $e^{-t}=1$   
so  $e^{-t}=2(t)=2t$   
 $-e^{-t}u(t)+2(t)=-e^{-t}u(t)+2(t)$   
2. When  $x(t)=2(t)$ ,  $y(t)=e^{-t}u(t)$   
so  $h(t)=e^{-t}u(t)$ 

$$\begin{aligned} \chi_{1} &= \begin{pmatrix} \sqrt{2}/2 \\ -\sqrt{2}/2 \\ 0 \end{pmatrix} & \chi_{2} &= \begin{pmatrix} \sqrt{3}/3 \\ \sqrt{3}/3 \\ \sqrt{3}/3 \end{pmatrix} & \chi_{3} &= \begin{pmatrix} \sqrt{6}/6 \\ \sqrt{6}/6 \\ -2\sqrt{6}/6 \end{pmatrix} \\ & \sqrt{6}/6 \end{pmatrix} \\ & \cdot |\chi_{1}| &= |\chi_{2}| &= |\chi_{3}| &= 1 \\ \chi_{1} \cdot \chi_{2} &= \frac{\sqrt{2}}{2} \cdot \frac{\sqrt{3}}{3} &= -\frac{\sqrt{2}}{2} \cdot \frac{\sqrt{3}}{3} + 0 &= 0 \\ \chi_{1} \cdot \chi_{3} &= \frac{\sqrt{2}}{2} \cdot \frac{\sqrt{6}}{6} &= -\frac{\sqrt{2}}{2} \cdot \frac{\sqrt{6}}{6} + 0 &= 0 \\ \chi_{2} \cdot \chi_{3} &= \frac{\sqrt{3}}{3} \cdot \frac{\sqrt{6}}{6} + \frac{\sqrt{3}}{3} \cdot \frac{\sqrt{6}}{6} - \frac{\sqrt{3}}{3} \cdot \frac{2\sqrt{6}}{6} = 0 \\ & \cdot \{\chi_{1}, \chi_{2}, \chi_{3}\} \text{ forms an orthonormal basis for } \mathbb{R}^{3} \\ & \chi &= \left(\frac{7\sqrt{2}}{20} + \frac{3\sqrt{2}}{10} + \frac{\sqrt{6}}{15} \\ & -\frac{1\sqrt{2}}{20} + \frac{3\sqrt{2}}{10} + \frac{\sqrt{6}}{15} \\ & \frac{3\sqrt{5}}{20} - \frac{2\sqrt{6}}{15} + \frac{\sqrt{6}}{15} \\ & \frac{3\sqrt{5}}{20} - \frac{2\sqrt{6}}{15} \\ \end{aligned}$$

**Question 51-Continued** 

$$x'=(7/10, 3/10, 4/10) : \alpha, \overline{x_1^{T}} + \alpha_2 \overline{x_2^{T}} + \alpha_3 \overline{x_3^{T}}$$
since the vectors are orthonormal,  

$$\alpha_1 = \mathbf{x'} \cdot \mathbf{x}, \qquad \alpha_2 = \mathbf{x'} \cdot \mathbf{x}_2 \qquad \alpha_3 = \mathbf{x'} \cdot \mathbf{x}_3$$

$$\alpha_1 = \frac{7\sqrt{2}}{20} - \frac{3\sqrt{2}}{20} = \boxed{\frac{\sqrt{2}}{5}}$$

$$\alpha_2 = \frac{7\sqrt{3}}{30} + \frac{\sqrt{3}}{10} + \frac{2\sqrt{3}}{15} = \boxed{\frac{7\sqrt{3}}{15}}$$

$$\alpha_3 = \frac{7\sqrt{6}}{60} + \frac{\sqrt{6}}{20} - \frac{8\sqrt{6}}{60} = \boxed{\frac{\sqrt{6}}{30}}$$

If we can represent any arbitrary vector in R° as a linear combination of {X1, X2, X3}, then we can determine the output of any vector for a linear system by taking a linear combination of the outputs for each of the basis vectors, using the same coefficients {\alpha1, \alpha2, \alpha3}.