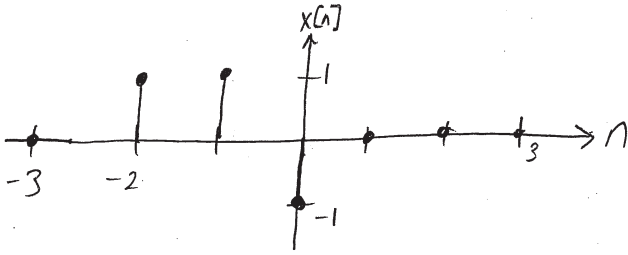
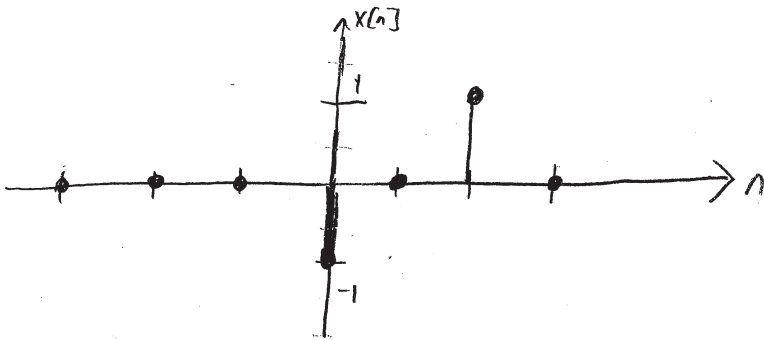


Question 32

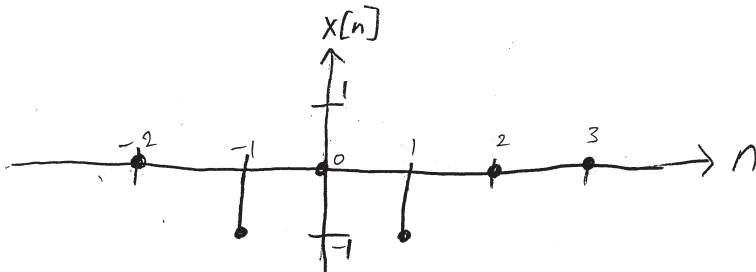
- $x[n] = u[n+2] - 2u[n] + u[n-1]$, $n = -2$ to $n = 3$



- $x[n] = (n+1)u[n+1] - 2u[n] - (n-1)u[n-3]$



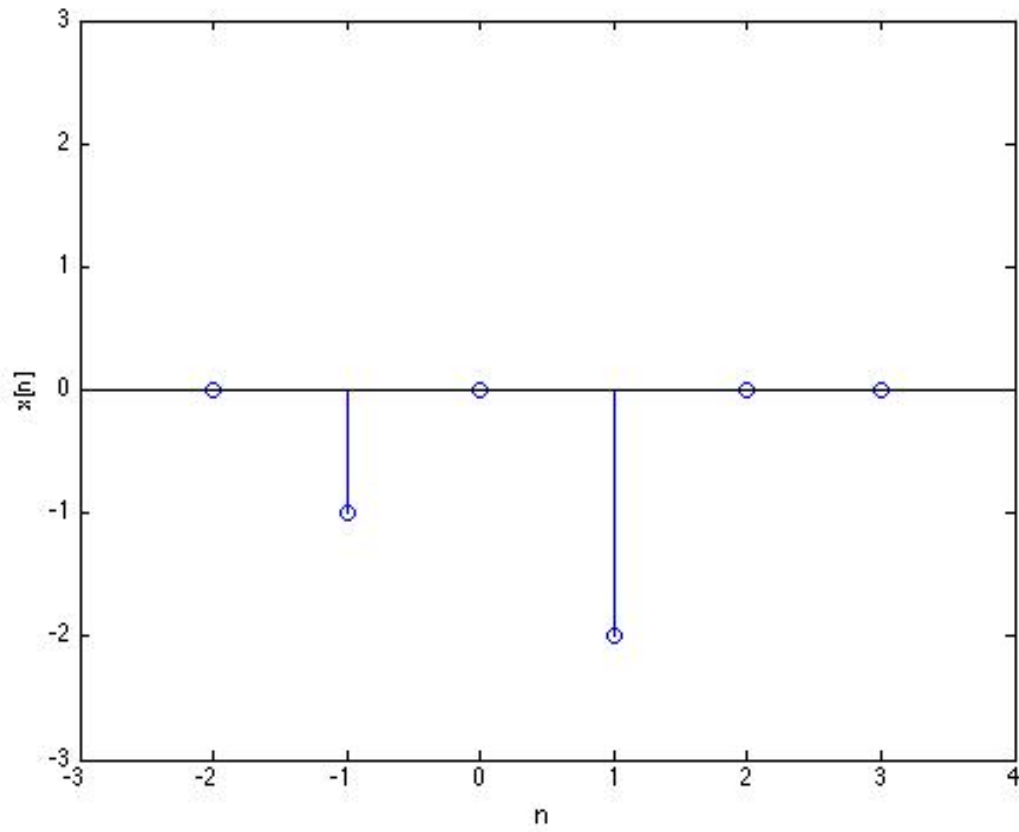
- $x[n] = \delta[n] - \delta[n-1] + u[n-2] - u[n+1]$



The above signal graph for 8(c) is incorrect. The correct graph is given below.

Corrected Solution for Q8 part (c)

$$x[n] = \delta[n] - \delta[n - 1] + u[n - 2] - u[n + 1]$$



Question 33

$$\bullet \quad x[n] = \sum_{k=-\infty}^{\infty} a_k \delta[n-k]$$

We know for some $l \in \mathbb{Z}$

$$x[l] = x[n] \delta[n-l]$$

$$x[l] = \sum_{k=-\infty}^{\infty} a_k \delta[n-k] \delta[n-l]$$

$$x[l] = \begin{cases} a_k & l=k \\ 0 & l \neq k \end{cases}$$

$$\Rightarrow \boxed{a_k = x[k]}$$

$$\bullet \quad x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

$$= \sum_{k=-\infty}^{\infty} x[k] (u[n-k] - u[n-k-1]) = \sum_{k=-\infty}^{\infty} x[k] u[n-k] - \sum_{k=-\infty}^{\infty} x[k] u[n-k-1]$$

$$\text{let } l = k+1 \quad k = l-1$$

$$= \sum_{k=-\infty}^{\infty} x[k] u[n-k] - \sum_{l=-\infty}^{\infty} x[l-1] u[n-l]$$

now redefine l with k

$$= \sum_{k=-\infty}^{\infty} x[k] u[n-k] - \sum_{k=-\infty}^{\infty} x[k-1] u[n-k]$$

$$= \sum_{k=-\infty}^{\infty} (x[k] - x[k-1]) u[n-k]$$

$$= \sum_{k=-\infty}^{\infty} \beta_k u[n-k] \quad \Rightarrow \boxed{\beta_k = x[k] - x[k-1]}$$

$$\bullet X(t) = \int_{-\infty}^{\infty} \alpha_s \delta(t-s) ds$$

if we consider any realization of t , say r , we have

$$X(r) = \int_{-\infty}^{\infty} \alpha_s \delta(r-s) ds$$

$$X(r) = \alpha_s \int_{-\infty}^{\infty} \delta(r-s) ds$$

$$X(r) = \alpha_s \cdot 1$$

$$X(r) = \alpha_s$$

$$\Rightarrow \boxed{\alpha_s = X(t)}$$

Question 34

1.27)

a.) $y(t) = x(t-2) + x(2-t)$

1.) Memoryless?

system **has memory** since it depends on past values of the input $- x(t-2)$

2.) Time Invariant?

let $x_1(t) = x(t-t_0)$

$$x_1(t) \xrightarrow{\text{system}} x_1(t-2) + x_1(2-t) = x(t-2-t_0) + x(2-t-t_0)$$

$$y(t-t_0) = x((t-t_0)-2) + x(2-(t-t_0)) = x(t-2-t_0) + x(2-t+t_0)$$

since the two outputs are different \Rightarrow **Time Variant**

3.) Linear?

$$x_3(t) = \alpha_1 x_1(t) + \alpha_2 x_2(t)$$

$$x_3(t) \xrightarrow{\text{system}} x_3(t-2) + x_3(2-t)$$

$$= \alpha_1 x_1(t-2) + \alpha_2 x_2(t-2) + \alpha_1 x_1(2-t) + \alpha_2 x_2(2-t) \quad (1)$$

$$x_1(t) \xrightarrow{\text{sys}} [x_1(t-2) + x_1(2-t)] \alpha_1$$

$$x_2(t) \xrightarrow{\text{sys}} [x_2(t-2) + x_2(2-t)] \alpha_2$$



$$= \alpha_1 x_1(t-2) + \alpha_2 x_2(t-2) +$$

$$\alpha_1 x_1(2-t) + \alpha_2 x_2(2-t) \quad (2)$$

since (1) = (2)

system **is Linear**

4.) Causal?

if $t < 2$, the system depends on a future value

ex. $y(0) = x(-2) + x(2)$

\Rightarrow **not Causal**

5.) stable?

if the input $x(t)$ is bounded by B , that is $|x(t)| < B$,
then for $y(t) = x(t-2) + x(2-t)$, $|y(t)| \leq |x(t-2)| + |x(2-t)| \leq 2B$
for all $t \Rightarrow$ stable

b.) $y(t) = [\cos(3t)] x(t)$

1.) Memory less?

The system is memoryless because it only depends on the current value of t

2.) Time-Invariant?

$$x_1(t) = x(t-t_0)$$

$$x_1(t) \xrightarrow{\text{sys}} [\cos(3t)] x_1(t) = [\cos(3t)] x(t-t_0) \quad \textcircled{1}$$

$$y(t-t_0) = [\cos(3(t-t_0))] x(t-t_0) \quad \textcircled{2}$$

$$\textcircled{1} \neq \textcircled{2} \Rightarrow \text{Time-Variant}$$

3.) Linear?

$$x_3(t) = \alpha_1 x_1(t) + \alpha_2 x_2(t)$$

$$x_3(t) \xrightarrow{\text{sys}} \cos(3t) x_3(t) = \cos(3t) \alpha_1 x_1(t) + \cos(3t) \alpha_2 x_2(t) \quad \textcircled{1}$$

$$\begin{array}{l} x_1(t) \xrightarrow{\text{sys}} \cos(3t) x_1(t) \xrightarrow{\alpha_1} \\ x_2(t) \xrightarrow{\text{sys}} \cos(3t) x_2(t) \xrightarrow{\alpha_2} \end{array} \begin{array}{c} \oplus \\ \oplus \end{array} \rightarrow = \alpha_1 \cos(3t) x_1(t) + \alpha_2 \cos(3t) x_2(t) \quad \textcircled{2}$$

$$\textcircled{1} = \textcircled{2} \Rightarrow \text{system is Linear}$$

4.) Causal?

the system is causal because it doesn't depend on any future values of time.

5.) if $|x(t)| < B$, then $|y(t)| \leq |\cos(3t)| |x(t)| \leq B$

for all $t \Rightarrow$ system is stable

$$c.) y(t) = \int_{-\infty}^{2t} x(\tau) d\tau$$

1.) Memoryless?

system **has memory** because it depends on past values of time
(times $-\infty$ to t)

2.) Time-Invariant?

$$x_1(t) = x(t-t_0)$$

$$x_1(t) \xrightarrow{\text{sys}} \int_{-\infty}^{2t} x_1(\tau) d\tau = \int_{-\infty}^{2t} x(\tau-t_0) d\tau \Rightarrow \int_{-\infty}^{2t-t_0} x(s) ds \quad (1)$$

$$y(t-t_0) = \int_{-\infty}^{2(t-t_0)} x(\tau) d\tau = \int_{-\infty}^{2t-2t_0} x(\tau) d\tau \quad (2)$$

$$(1) \neq (2) \Rightarrow \text{Time-Variant}$$


3.) Linear?

$$x_3(t) = \alpha_1 x_1(t) + \alpha_2 x_2(t)$$

$$x_3(t) \xrightarrow{\text{sys}} \int_{-\infty}^{2t} x_3(\tau) d\tau = \int_{-\infty}^{2t} [\alpha_1 x_1(\tau) + \alpha_2 x_2(\tau)] d\tau \quad (1)$$

$$x_1(t) \xrightarrow{\text{sys}} \int_{-\infty}^{2t} x_1(\tau) d\tau$$

$$x_2(t) \xrightarrow{\text{sys}} \int_{-\infty}^{2t} x_2(\tau) d\tau$$



$$= \int_{-\infty}^{2t} \alpha_1 x_1(\tau) d\tau + \int_{-\infty}^{2t} \alpha_2 x_2(\tau) d\tau \quad (2)$$

$$(1) = (2) \Rightarrow \text{Linear}$$

4.) Causal?

system is **not causal** because it depends on future values
of time (up to $2t$)

5.) stable?

It is clear that the system is **not stable**. An example
is if $x(t) = 1 \leq 1$ for all t . Here $y(t) = \int_{-\infty}^{2t} 1 d\tau$

$$\text{if } t=0, |y(t)| = \left| \int_{-\infty}^0 1 d\tau \right| = |-\infty| = \infty$$

Question 35

1.28)

a.) $y[n] = x[-n]$

1.) Memoryless?

If $n > 0$, then the output depends on a past value of the input
 \Rightarrow **has memory**

2.) Time-Invariant?

$$\text{Let } x[n-N] = X_1[n] \xrightarrow{\text{sys}} X_1[-n] = X[-n-N] \quad (1)$$

$$y[n-N] = x[-(n-N)] = X[-n+N] \quad (2)$$

Since $(1) \neq (2) \Rightarrow$ **Time-Variant**

3.) Linear?

$$\alpha_1 X_1 + \alpha_2 X_2 = X_3 \xrightarrow{\text{sys}} X_3[-n] = \alpha_1 X_1[-n] + \alpha_2 X_2[-n] \quad (1)$$

$$\begin{array}{l} X_1[n] \xrightarrow{\text{sys}} X_1[-n] \xrightarrow{\alpha_1} \\ X_2[n] \xrightarrow{\text{sys}} X_2[-n] \xrightarrow{\alpha_2} \end{array} \begin{array}{c} \oplus \\ \uparrow \end{array} \rightarrow \alpha_1 X_1[-n] + \alpha_2 X_2[-n] \quad (2)$$

Since $(1) = (2) \Rightarrow$ **Linear**

4.) Causal?

if $n < 0$, then the output depends on a future value of the input
 \Rightarrow **not causal**

5.) Stable?

if $|x[n]| \leq B$, then $|y[n]| = |x[-n]| \leq B$

\Rightarrow **stable**

$$b.) y[n] = x[n-2] - 2x[n-8]$$

1.) Memoryless?

depends on past values of the input \Rightarrow has memory

2.) Time-Invariant?

$$x[n-N] = X_1[n] \xrightarrow{\text{sys}} X_1[n-2] - 2X_1[n-8] = x[n-N-2] - 2X[n-N-8] \quad (1)$$

$$y[n-N] = X[(n-N)-2] - 2X[(n-N)-8] \quad (2)$$

Since (1) = (2) \Rightarrow Time-Invariant

3.) Linear?

$$\begin{aligned} \alpha_1 X_1[n] + \alpha_2 X_2[n] &= X_3[n] \xrightarrow{\text{sys}} X_3[n-2] - 2X_3[n-8] \\ &= \alpha_1 X_1[n-2] + \alpha_2 X_2[n-2] - 2(\alpha_1 X_1[n-8] + \alpha_2 X_2[n-8]) \quad (1) \end{aligned}$$

$$\begin{array}{ccc} X_1[n] \xrightarrow{\text{sys}} X_1[n-2] - 2X_1[n-8] & \xrightarrow{\alpha_1} & \alpha_1 X_1[n-2] - 2\alpha_1 X_1[n-8] \\ X_2[n] \xrightarrow{\text{sys}} X_2[n-2] - 2X_2[n-8] & \xrightarrow{\alpha_2} & \alpha_2 X_2[n-2] - 2\alpha_2 X_2[n-8] \quad (2) \end{array}$$

since (1) = (2) \Rightarrow Linear

4.) Causal?

does not depend on any future value of time \Rightarrow Causal

5.) stable?

$$\begin{aligned} \text{let } |X[n]| \leq B, \text{ so } |y[n]| &= |x[n-2] - 2x[n-8]| \leq |x[n-2]| + |2x[n-8]| \\ &\leq 3B \quad \Rightarrow \quad \text{stable} \end{aligned}$$

$$c.) y[n] = n x[n]$$

1.) Memoryless?

output only depends on current value of input \Rightarrow memoryless

2.) Time-Invariant?

$$X[n-N] = X_1[n] \xrightarrow{\text{sys}} n X_1[n] = n X[n-N] \quad (1)$$

$$Y[n-N] = (n-N) X[n-N] \quad (2)$$

$$(1) \neq (2) \Rightarrow \boxed{\text{Time-Variant}}$$

3.) Linear?

$$\alpha_1 X_1[n] + \alpha_2 X_2[n] = X_3[n] \xrightarrow{\text{sys}} n X_3[n] = n \alpha_1 X_1[n] + n \alpha_2 X_2[n] \quad (1)$$

$$\begin{array}{l} X_1[n] \\ X_2[n] \end{array} \xrightarrow{\text{sys}} \begin{array}{l} n X_1[n] \\ n X_2[n] \end{array} \xrightarrow{\begin{array}{l} \alpha_1 \\ \alpha_2 \end{array}} \alpha_1 n X_1[n] + \alpha_2 n X_2[n] \quad (2)$$

$$(1) = (2) \Rightarrow \boxed{\text{Linear}}$$

4.) Causal?

doesn't depend on any future time input $\Rightarrow \boxed{\text{Causal}}$

5.) Stable?

if $X[n] = 1 \leq 1$, $Y[n] = n \cdot 1 = n$ which doesn't have a bound

$\Rightarrow \boxed{\text{not stable}}$

Question 36

1.28.)

$$e.) Y[n] = \begin{cases} X[n] & n \geq 1 \\ 0 & n = 0 \\ X[n+1] & n \leq -1 \end{cases}$$

1.) Memoryless?

output depends on a future value of the input $\Rightarrow \boxed{\text{has memory}}$

2.) Time-Invariant?

$$X[n-N] = X_1[n] \xrightarrow{\text{sys}} \begin{cases} X_1[n], & n \geq 1 \\ 0, & n = 0 \\ X_1[n+1], & n \leq -1 \end{cases} = \begin{cases} X[n-N], & n \geq 0 \\ 0, & n = 0 \\ X[n+1-N], & n \leq -1 \end{cases} \quad (1)$$

$$Y[n-N] = \begin{cases} X[n-N] & n-N \geq 1 \\ 0 & n-N = 0 \\ X[n-N+1] & n-N \leq -1 \end{cases} \quad (2)$$

$$(1) \neq (2) \Rightarrow \boxed{\text{Time-Variant}}$$

3.) Linear?

$$\alpha_1 x_1 + \alpha_2 x_2 = x_3 \xrightarrow{\text{sys}} \begin{cases} x_3[n] & n \geq 1 \\ 0 & n = 0 \\ x_3[n+1] & n \leq -1 \end{cases} = \begin{cases} \alpha_1 x_1[n] + \alpha_2 x_2[n] & n \geq 1 \\ 0 & n = 0 \\ \alpha_1 x_1[n+1] + \alpha_2 x_2[n+1] & n \leq -1 \end{cases} \quad (1)$$

$$\begin{matrix} x_1[n] \\ x_2[n] \end{matrix} \xrightarrow{\text{sys}} \begin{cases} x_1[n] & n \geq 1 \\ 0 & n = 0 \\ x_1[n+1] & n \leq -1 \end{cases} \quad \begin{matrix} \alpha_1 \\ \alpha_2 \end{matrix} \quad \begin{matrix} \downarrow \\ \uparrow \\ \oplus \end{matrix} \quad \begin{cases} \alpha_1 x_1[n] + \alpha_2 x_2[n] & n \geq 1 \\ 0 & n = 0 \\ \alpha_1 x_1[n+1] + \alpha_2 x_2[n+1] & n \leq -1 \end{cases} \quad (2)$$

(1) = (2) \Rightarrow Linear

4.) Causal?

depends on a future value of the input for $n \leq -1 \Rightarrow$ not causal

5.) stable?

if $|x[n]| \leq B$, then $|y[n]| = \begin{cases} |x[n]| & n \geq 1 \\ 0 & n = 0 \\ |x[n+1]| & n \leq -1 \end{cases} \leq \begin{cases} B \\ 0 \\ B \end{cases} \leq B$

\Rightarrow stable

f.) $y[n] = \begin{cases} x[n] & n \geq 1 \\ 0 & n = 0 \\ x[n] & n \leq -1 \end{cases}$

1.) memoryless?

only depends on current value of input \Rightarrow memoryless

2.) Time-Invariant?

$$x[n-N] = x_1[n] \xrightarrow{\text{sys}} \begin{cases} x_1[n] & n \geq 1 \\ 0 & n = 0 \\ x_1[n] & n \leq -1 \end{cases} = \begin{cases} x[n-N] & n \geq 1 \\ 0 & n = 0 \\ x[n-N] & n \leq -1 \end{cases} \quad (1)$$

$$y[n-N] = \begin{cases} x[n-N] & n-N \geq 1 \\ 0 & n-N = 0 \\ x[n-N] & n-N \leq -1 \end{cases} \quad (2)$$

(1) \neq (2) \Rightarrow Time-Variant

3.) Linear?

$$\alpha_1 X_1 + \alpha_2 X_2 = X_3 \xrightarrow{\text{sys}} \begin{cases} X_3[n], & n \geq 1 \\ 0, & n = 0 \\ X_3[n], & n \leq -1 \end{cases} = \begin{cases} \alpha_1 X_1[n] + \alpha_2 X_2[n], & n \geq 1 \\ 0, & n = 0 \\ \alpha_1 X_1[n] + \alpha_2 X_2[n], & n \leq -1 \end{cases} \quad (1)$$

Block diagram showing two inputs $X_1[n]$ and $X_2[n]$ entering a summing junction with gains α_1 and α_2 . The output is $\alpha_1 X_1[n] + \alpha_2 X_2[n]$.

$$\begin{matrix} X_1[n] \\ X_2[n] \end{matrix} \xrightarrow{\text{sys}} \begin{cases} X_1[n], & n \geq 1 \\ 0, & n = 0 \\ X_1[n], & n \leq -1 \end{cases} \begin{matrix} \alpha_1 \\ \alpha_2 \end{matrix} \oplus = \begin{cases} \alpha_1 X_1[n] + \alpha_2 X_2[n], & n \geq 1 \\ 0, & n = 0 \\ \alpha_1 X_1[n] + \alpha_2 X_2[n], & n \leq -1 \end{cases} \quad (2)$$

(1) = (2) \Rightarrow **Linear**

4.) Causal?

output doesn't depend on future values of input \Rightarrow **Causal**

5.) Stable?

if $|X[n]| \leq B$, then $|Y[n]| = \begin{cases} |X[n]| & n \geq 1 \\ |0| & n = 0 \\ |X[n]| & n \leq -1 \end{cases} \leq \begin{cases} B \\ 0 \\ B \end{cases} \leq B$

\Rightarrow **Stable**

g.) $y[n] = X[4n+1]$

1.) Memoryless?

output doesn't depend only on the current input \Rightarrow **has memory**

2.) Time-Invariant?

$$X[n-N] = X_1[n] \xrightarrow{\text{sys}} X_1[4n+1] = X[(4n+1)-N] = X[4n+1-N] \quad (1)$$

$$Y[n-N] = X[4(n-N)+1] = X[4n-4N+1] \quad (2)$$

(1) \neq (2) \Rightarrow **Time-Variant**

3.) Linear?

$$\alpha_1 X_1 + \alpha_2 X_2 = X_3[n] \xrightarrow{\text{sys}} X_3[4n+1] = \alpha_1 X_1[4n+1] + \alpha_2 X_2[4n+1] \quad (1)$$

Block diagram showing two inputs $X_1[4n+1]$ and $X_2[4n+1]$ entering a summing junction with gains α_1 and α_2 . The output is $\alpha_1 X_1[4n+1] + \alpha_2 X_2[4n+1]$.

$$\begin{matrix} X_1 \xrightarrow{\text{sys}} X_1[4n+1] \\ X_2 \xrightarrow{\text{sys}} X_2[4n+1] \end{matrix} \begin{matrix} \alpha_1 \\ \alpha_2 \end{matrix} \oplus = \alpha_1 X_1[4n+1] + \alpha_2 X_2[4n+1] \quad (2)$$

(1) = (2) \Rightarrow **Linear**

4.) Causal?

output depends on a future value of the input \Rightarrow not causal

5.) stable?

if $|x[n]| \leq B$, then $|y[n]| = |x[4n+1]| \leq B$

\Rightarrow Stable

Question 37

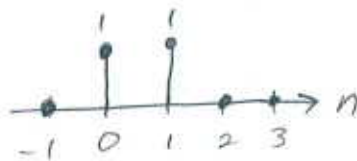
$$\delta[n] \xrightarrow[\text{LTI}]{\text{system}} 2^n e^{j^n} u[n-1]$$

1.) $x[n] = \delta[n-1] \xrightarrow{\text{sys}} y[n] = ?$

because system is Time-Invariant $x[n-N] \xrightarrow{\text{sys}} y[n-N]$

$$y[n-1] = \boxed{2^{n-1} e^{j(n-1)} u[n-2]}$$

2.) $x[n] = u[n] - u[n-2]$
 $= \delta[n] + \delta[n-1]$



use linearity and time invariance to say

$$\boxed{y[n] = 2^n e^{j^n} u[n-1] + 2^{n-1} e^{j(n-1)} u[n-2]}$$

Question 38

1.30)

a.) $y(t) = x(t-4)$

let $t' = t-4 \Rightarrow t = t'+4$

$x(t) = y(t'+4)$

\Rightarrow invertible with $x(t) = y(t+4)$

$$b.) y(t) = \cos(x(t))$$

$x(t) = \cos^{-1}(y(t))$, but cosine is periodic with period 2π

$$x_1(t) = x(t) \xrightarrow{\text{sys}} \cos(x(t))$$

$$x_2(t) = x(t) + 2\pi \xrightarrow{\text{sys}} \cos(x(t) + 2\pi) = \cos(x(t))$$

different input produced the same output \Rightarrow not invertible

$$c.) y[n] = nx[n]$$

$$x[n] = \frac{y[n]}{n} \quad \text{unable to reconstruct input at index } 0$$

$$\delta[n] \xrightarrow{\text{sys}} 0$$

$$2\delta[n] \xrightarrow{\text{sys}} 0$$

\Rightarrow not invertible

$$e.) y[n] = \begin{cases} x[n-1] & n \geq 1 \\ 0 & n = 0 \\ x[n] & n \leq -1 \end{cases}$$

$$\rightarrow x[n] = \begin{cases} y[n+1], & n \geq 0 \\ y[n], & n \leq -1 \end{cases}$$

Invertible

Question 39

1.30)

$$f.) y[n] = x[n]x[n-1]$$

because the system multiplies the input with a time delayed version of the input, the ability to determine the sign of the input is lost

$$x[n] \xrightarrow{\text{sys}} x[n]x[n-1]$$

$$-x[n] \xrightarrow{\text{sys}} (-x[n])(-x[n-1]) = x[n]x[n-1]$$

\Rightarrow not invertible

$$g.) y[n] = x[1-n]$$

$$n' = 1-n \Rightarrow n = 1-n'$$

$$x[n'] = y[1-n']$$

invertible with $x[n] = y[1-n]$

$$j.) y(t) = \frac{dx(t)}{dt}$$

$$x(t) = \int y(t) dt$$

recall that integration results in an additional $+C$ term that can only be determined given initial conditions. This results from many functions having the same derivative

$$\frac{d}{dt}(x) = 1 \quad \text{and} \quad \frac{d}{dt}(x+C) = 1 \quad \text{where } C \in \mathbb{R}$$

\Rightarrow not invertible

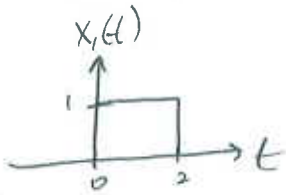
$$n.) y[n] = \begin{cases} x[n/2] & , n \text{ even} \\ 0 & , n \text{ odd} \end{cases}$$

$x[n] = y[2n]$
invertible

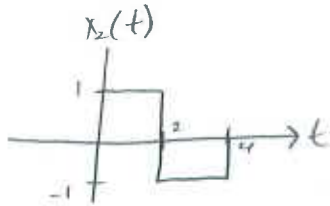
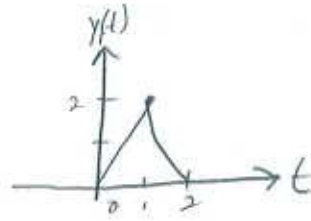
Question 40

1.31)

a.)



LTI System

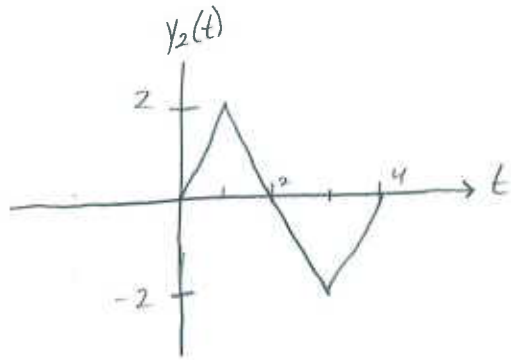


LTI System

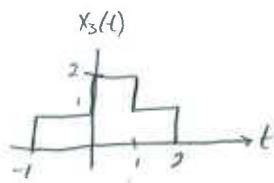
?

$$x_2(t) = x_1(t) - x_1(t-2)$$

System is LTI \rightarrow time shifts and linear combinations hold

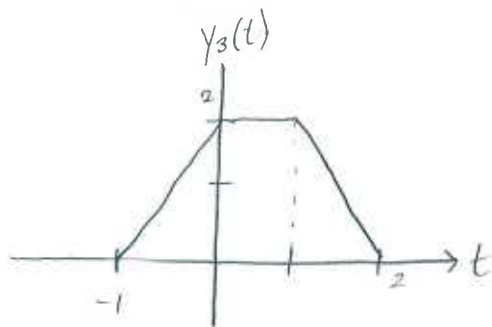


b.)



$$x_3(t) = x_1(t) + x_1(t+1)$$

System is LTI so time shifts + linear combinations hold



Question 41

1.43 a) Since the system is time-invariant,

$$x(t+T) \longrightarrow y(t+T)$$

and

$$x[n+N] \longrightarrow y[n+N]$$

Therefore, $y(t)/y[n]$ is also periodic with period T/N

Question 42 - Optional

1.62 a) True

b) False $y_1(t) = x(t) + 1$ $y_2(t) = x(t) - 1$ $\left. \begin{array}{l} \text{both nonlinear, but} \\ \text{linear when connected} \\ \text{in series} \end{array} \right\}$

$$c) y_1[n] = \begin{cases} x[n/2], & n \text{ even} \\ 0, & n \text{ odd} \end{cases}$$

$$y_2[n] = x[n] + \frac{1}{2}x[n-1] + \frac{1}{4}x[n-2]$$

$$y_3[n] = x[2n]$$

$$y[n] = y_1[2n] + \frac{1}{2}y_1[2n-1] + \frac{1}{4}y_1[2n-2]$$

$$y[n] = x[n] + \frac{1}{2}x[n-1] + \frac{1}{4}x[n-2]$$

LTI system