

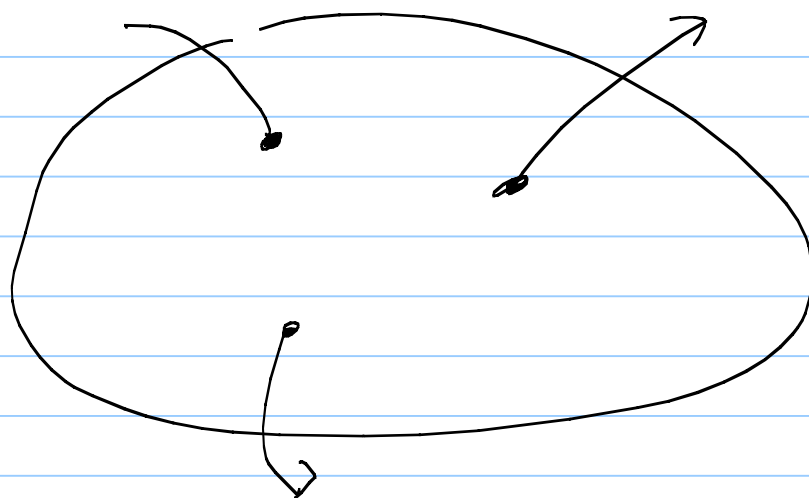
Random processes

P. 231

Note Title

4/22/2011

∞ -dim R.V.



Sample
space

Example

$$P(X(t) = f_1(t)) = 0.5$$

$$P(X(t) = f_2(t)) = 0.3$$

$$P(X(t) = f_3(t)) = 0.2$$

Q: $P(X(4) > 0)$

Ans:

Q: $P(X(t) < 0 \text{ for some } t)$

Ans:

We call the "random function $X(t)$ " as a Random process.

Remark: $X(t)$ is a

$X(1), X(2,3), X(-1)$ are

$(X(3), X(\pi))$ are

Q: Find the pmf of X_n (say X_6)

Ans:

Q: Find the joint pmf of X_n, X_{n+k}
(say X_1, X_5)

Ans:

* Random Process $X(t)$ or $X[n]$

Sample space: \mathcal{F}

W.A: Two methods of describing
the W.A.

Method 1: We write $X(t) = X(t, \zeta)$

where ζ represents the "Random part"

and we specify the W.A of ζ .

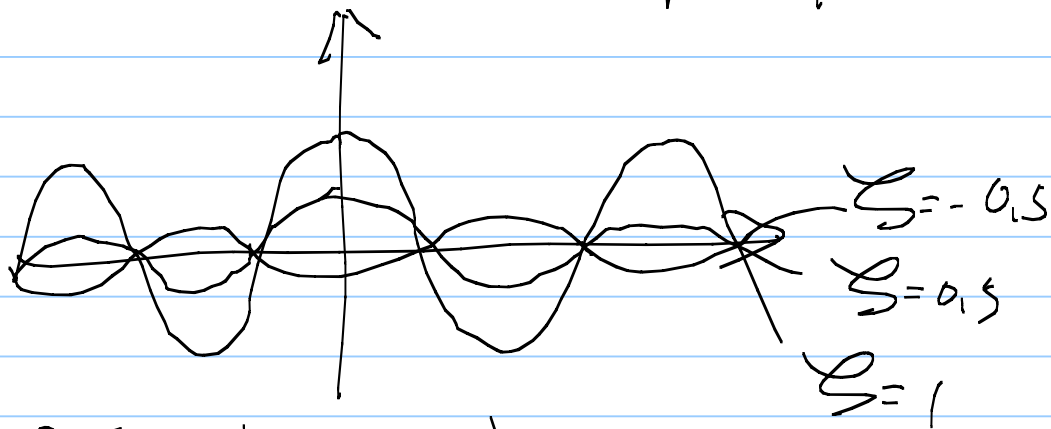
$$\text{Ex: } X(t, \xi) = \sum \cos(2\pi i t)$$

$\underbrace{\hspace{10em}}_{\text{Not random}}$
 $\underbrace{\hspace{10em}}_{\text{random}}$

ξ is uniformly distri between $[-1, 1]$

Q: What are the sample paths?

Ans:



Q: $P(X(\frac{1}{4}) = 0)$

Ans:

Q: $P(|X(0) - X(\frac{1}{2})| < 0.5)$

Ans:

Method 2: Sometimes it is impossible to specify the weights for individual sample paths. For example the trend of Dow-Jones in the future.

Instead, Specify the joint pdf/pdf for any k sample R.V.s.

Namely for any t_1, t_2, \dots, t_k ,
We specify the joint pdf/pdf of the k -dim R.V. $(X(t_1), X(t_2), \dots, X(t_k))$

Ex: A white Gaussian R.P

for any t_1, t_2, \dots, t_k ,
(say $k=3, t_1=\pi, t_2=-e, t_3=\sqrt{3}$)

$(X_{t_1}, \dots, X_{t_k}) \quad (X_{\pi}, X_{-e}, X_{\sqrt{3}})$

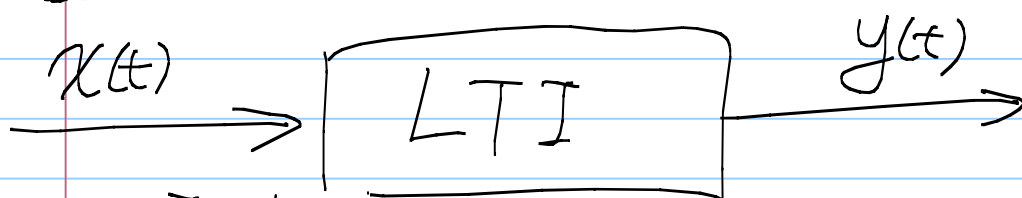
has joint pdf

$$\frac{1}{\sqrt{2\pi}} e^{-\frac{(X_{t_1})^2}{2}} \frac{1}{\sqrt{2\pi}} e^{-\frac{(X_{t_2})^2}{2}} \dots \frac{1}{\sqrt{2\pi}} e^{-\frac{(X_{t_k})^2}{2}}$$

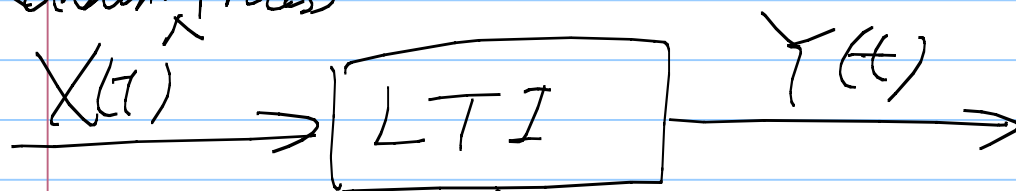
Examples 9.5, 9.6

Why studying R.P.

deterministic



Input.
Random Process



Noise is also random

Interested in

$P(\text{the received audio signal } Y(t) \text{ becomes inaudible}) = ?$

It is generally a very hard problem.

Recall: It is easy to find the mean & variance of a linear transform.

Therefore, most of the time we engineers focus on the mean & variance of a R.P.

★ The of a R.P.

★ The

the variance of
 $X(t)$ for a
given t .

★

★

How to compute the auto correlation / covariance function?

Ans: Find the joint pdf of X_{t_1}, X_{t_2} first, then treat them as X, Y & Find the expectation.

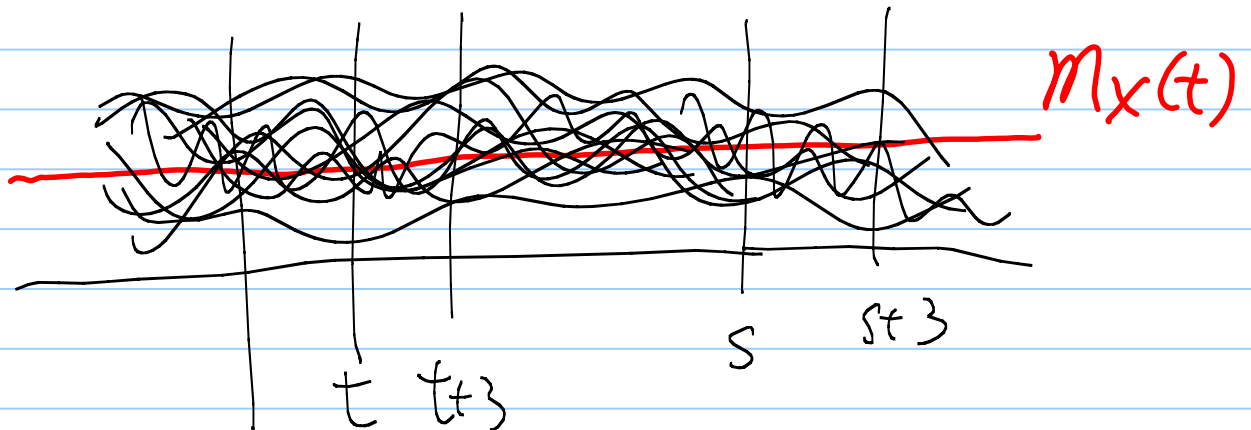
Ex: HW 15 Prob 9.2.

	X_{n+k}				
X_n	$\frac{1}{6}$				
		$\frac{1}{6}$			
			$\frac{1}{6}$		
				$\frac{1}{6}$	
					$\frac{1}{6}$

$$R_x(n, n+k) =$$

$$C_x(n, n+k) =$$

In many real systems
the correlation & covariance depends
only on the distance between t_1, t_2



& the mean function is
a flat horizontal line.

We say such a R.P is

* Wide Sense Stationary. (W.S.S)

& the ⁽¹⁾ $m_x(t) \longrightarrow$

⁽²⁾ $R_x(t_1, t_2) \longrightarrow$