Text segmentation for MRC Document compression using a Markov Random Field model

Final dissertation by Eri Haneda

Advisory committee:

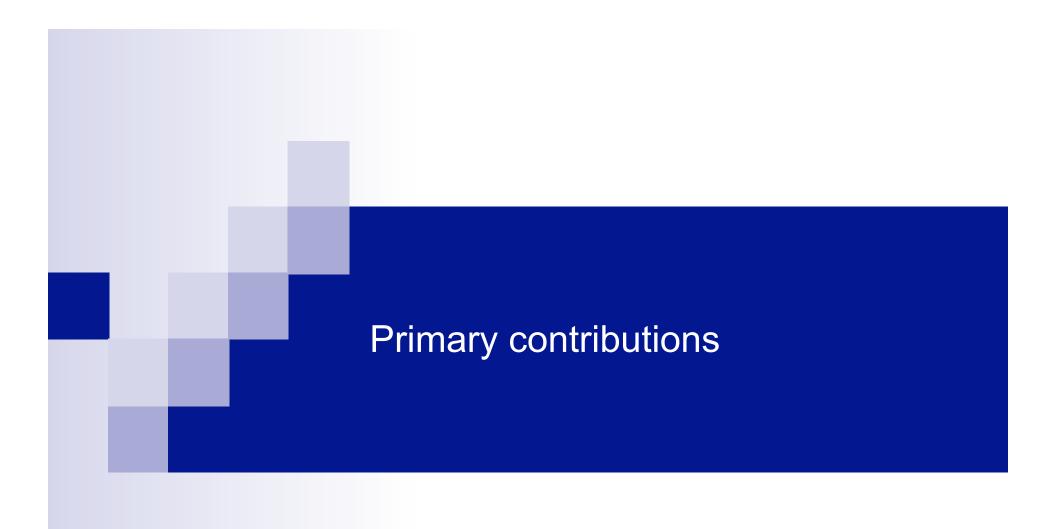
Prof. Charles Bouman (Chair)

Prof. Jan Allebach

Prof. Peter Doerschuk

Prof. George Chiu

February 25th, 2011





Primary projects

- 1) Text segmentation for MRC document with Samsung Co. Ltd.
 - Multiscale-COS/CCC algorithm
- 2) Next generation image capture device development with Samsung Co. Ltd.
 - Motion/Lamp control
 - □ Scanner image quality bench mark
 - Snap-to-White contrast enhancement
- 3) CT baggage reconstruction (In progress)
 - □ Multislice helical scan CT reconstruction code development
 - □ Image reconstruction using a substitute prior model

Brief summary of snap-to-white project

 The background of scanned images sometimes appears too dark because of the paper material (e.g. newspapers)

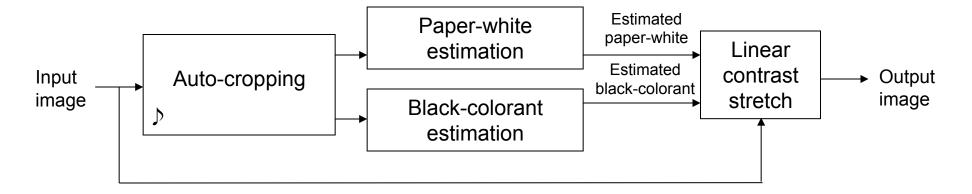


Low color contrast

· Background is not white



Overview



- Auto-cropping removes extra white or black which is sometimes included around the borders of the image
- Paper-white/black-colorant estimation determines respective RGB values using extrema and region growing
- Linear contrast stretch snaps the estimated paper-white and blackcolorant to the largest and smallest encoded value to increase the dynamic range

Original/Adjusted Samsung



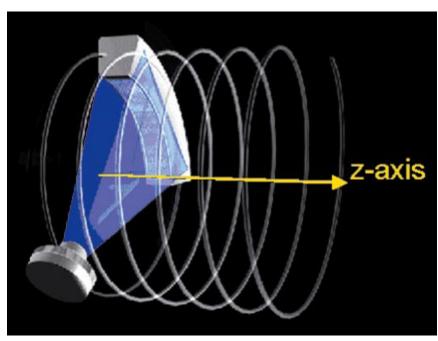
Original Samsung



Adjusted Samsung

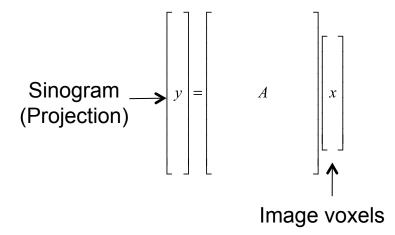
Pilot research for CT baggage reconstruction #1

- Short-term goals
 - Write preliminary multislice helical CT reconstruction code
 - □ Develop a statistical model for accurate CT baggage reconstruction/segmentation



Multislice helical CT (Source & Detector) "Multislice CT, M.F. Reiser (2004)"

Forward projection



Reconstruction

$$\hat{x}_{MAP} = \arg\max_{x} \left\{ -\frac{1}{2} (y - Ax)^{T} D(y - Ax) + U(x) \right\}$$
Weighting Smoothing

Pilot research for CT baggage reconstruction #2

- We are trying to develop a new generalized prior model for MAP estimate
- In general, the prior term p(x) needs to be modeled under strong assumption

$$\widehat{X}_{MAP} = \underset{x \ge 0}{\operatorname{arg\,max}} \left\{ -\frac{1}{2} (y - Ax)^T D(y - Ax) + \log p(x) \right\}$$

Our approach is to generate a second order polynomial approximation to the function $\log p(x)$ about an initial image x' with the form

$$\log p(x) \ge f(x;x')$$

$$= -\frac{1}{2}(x-x')B(x-x') + d^t(x-x') + c$$
If we assume dependencies only on neighbors, the expression is dramatically simplified

Text segmentation for MRC Document compression using a Markov Random Field model

What is text segmentation?

 Text segmentation is extracting text components from a document



Fig. 1. An example of text segmentation

(Binary)

(Color)



Why is text segmentation useful?

- Useful for layer based document compression
 - □ Layer based document compression is defined in ITU-T. T.44,
 Mixed Raster Content (MRC) encoding
 - Good text segmentation achieves high document compression and preserves high image quality
- Useful for other applications such as OCR etc.



- Our goal is to generate segmentation which is:
 - Accurate
 - Robust
 - Computationally inexpensive

20

Motivations: Mixed Raster Content

 Mixed Raster Content (MRC) is a standard for layer based document compression defined in ITU-T. T.44

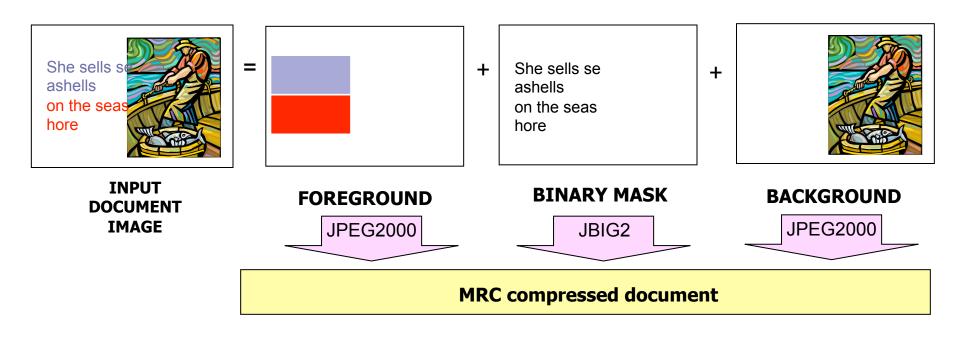


Fig. 2. Illustration of MRC document compression

Past text segmentation research

- Top-down/Bottom-Up approach
 - □ X-Y cut algorithm [1], Run Length Smearing Algorithm [2] (RLSA)
- Thresholding approach
 - Otsu, Niblack, Sauvola, Kapur, and Tsai method [3]
- Statistical approach
 - ☐ Hidden Markov Model (HMM)
 - The most known commercial software DjVu uses HMM model [4]
 - □ Markov Random Field (MRF)
 - Zhen et al. used an MRF model to exploit the contextual information for noise removal [5]
 - Kumar and Kuk also incorporates their proposed prior model to MAP-MRF text segmentation
 - □ Conditional Random Field (CRF)
 - New emerging model, originally proposed by Lafferty [6]
 - It directly models the posterior distribution of labels given observations
 - It has been applied to pixel-wise segmentation

Research accomplishment

- Three novel algorithms have been developed
 - COS algorithm (Cost Optimized Segmentation)
 Used for initial segmentation. Formulated in a global cost optimization framework.

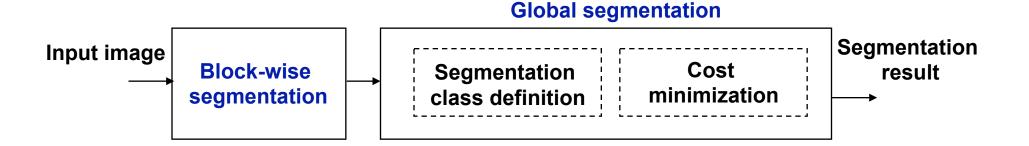
Post-Prelim

<u>CCC algorithm (Connected Component Classification)</u>
 Refines segmentation by classifying connected components into text and non-text using a Markov Random Field (MRF) model

Post-Prelim Multiscale-COS/CCC algorithm
 Comprehensive segmentation scheme using multiple resolutions.
 This improves simultaneous detection of large and small text.

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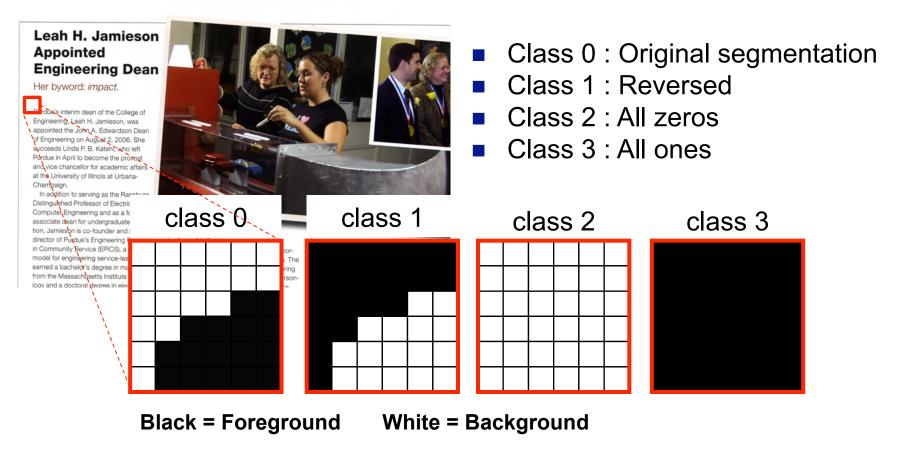
COS algorithm flowchart



- Block-wise segmentation
 - □ Image is divided into overlapping blocks
 - Each block segmented independently using clustering procedure
- Global segmentation
 - Four possible classes are defined for each block
 - □ The class of each block is chosen to minimize a global cost

Segmentation class definition

 After initial block segmentation, four possible classes are defined for each block



10

Cost minimization

$$Cost(S) = \sum_{i=0}^{M} \sum_{j=0}^{N} \left\{ E(s_{i,j}) + \lambda_1 V_1(s_{i,j-1}, s_{i,j}) + \lambda_2 V_2(s_{i-1,j}, s_{i,j}) + \lambda_3 V_3(s_{i,j}) \right\}$$

 $S_{i,j}$: Class of block at location (*i,j*). $S = \{S_{i,j}\}$

E: Total variance of gray levels of each group (0 or 1)

 V_1 : Number of mismatches in horizontal overlap region

 V_2 : Number of mismatches in vertical overlap region

 V_3 : Number of '1' pixels inside block

 λ_k : Weight coefficients, k=1,2,3

Cost function may be minimized using dynamic programming

Cost Optimized Segmentation problems

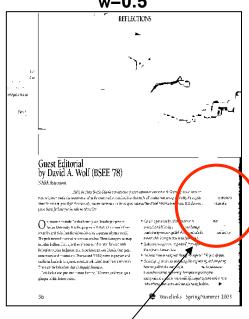
• Optimal parameters $\{\lambda_k\}$ determined by minimizing weighted error

$$error = (1 - \omega)N_{missed} + \omega N_{false} \quad \omega \in [0, 1]$$

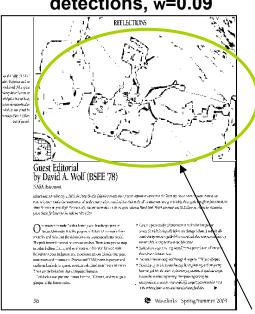
Original



Errors equally weighted w=0.5



Greater weighting on missed detections, w=0.09



Missed detections

False detections

Approach: Minimize missed detections, and eliminate false detections in a later stage.

Motivation for CCC algorithm

NA.

Connected component classification (CCC)

- Refines the COS results by eliminating non-text components using a Markov Random Field (MRF) model
- Classification procedure

Step1: Extract connected component *CCi*

Step2: Calculate feature vector Yi

Step3: Each CC_i is classified as either text $(X_i=1)$ or non-text $(X_i=0)$

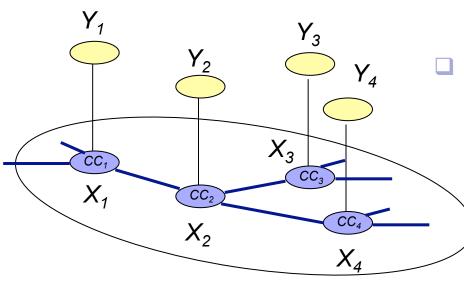
using MRF-MAP framework



CCC statistical model

■ Classification of each $x_i \in \{0,1\}$ determined by maximizing posterior density (MAP)

$$\underset{x \in \{0,1\}^{N}}{\operatorname{arg\,max}} \{ \log p(x \mid y) \} = \underset{x \in \{0,1\}^{N}}{\operatorname{arg\,max}} \{ \log p(y \mid x) + \log p(x) \}$$



Neighbors

- Data term p(ylx) assumed to be conditionally independent
- Prior term p(x) for true segmentation labels is modeled by an MRF

$$Y=\{Y_1, Y_2, ... Y_N\}$$
~ Observed data (feature vectors)

$$X=\{X_1, X_2, ...X_N\}$$
 ~ Classification of CC

10

Data model, p(y|x)

- Feature vector, Y_i
 - □ Boundary edge depth statistics
 - Color uniformity
- \blacksquare Y_i are conditionally independent given associated X_i

$$p(y \mid x) = \prod_{i=1}^{N} p(y_i \mid x_i)$$

 Feature vector for both text and non-text modeled as a multivariate Gaussian mixture

$$p(y_i \mid x_i = k) = \sum_{m=0}^{M_k - 1} \frac{a_{k,m}}{(2\pi)^{D/2}} |R_{k,m}|^{-1/2} \exp\left\{-\frac{1}{2} (y_i - \mu_{k,m})^t R_{k,m}^{-1} (y_i - \mu_{k,m})\right\}$$

 $k \in \{0,1\}$: class label

 M_0, M_1 : number of sub-clusters in each Gaussian mixture



Prior model, p(x)

- MRF used to model local interaction between neighboring elements
- An MRF is a density satisfying the Markov property:

$$p(x_s \mid x_r \text{ for } r \neq s) = p(x_s \mid x_s)$$

MRF may be expressed as a Gibbs distribution (Hammersley-Clifford theorem):

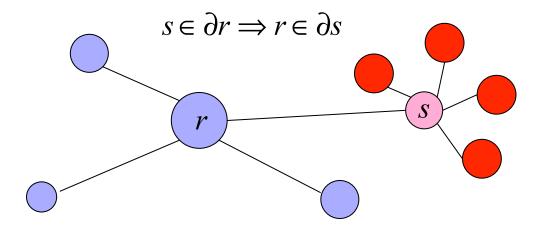
$$p(x) = \frac{1}{Z} \exp \left\{ -\frac{1}{T} \sum_{c \in C} V_c(x) \right\}$$
 Z: normalization factor
T: "temperature"

 V_c : clique potentials

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Component-wise MRF

- Neighborhood system
 - k-nearest neighbors, based on physical distance
 - □ Enforce neighbors to be mutual



- Clique potential
 - Dissimilarity measure between neighboring components



Dissimilarity measure, Di,j

- Augmented feature vector, Z_i
 Original feature vector, concatenated with center location of component
- Dissimilarity measure, $D_{i,j}$ Normalized Mahalanobis distance between feature vectors Z_i and Z_j

$$d_{i,j} = \sqrt{(z_i - z_j)^T \Sigma^{-1} (z_i - z_j)}$$

$$D_{i,j} = \frac{d_{i,j}}{\frac{1}{2}(\overline{d}_{i,\partial i} + \overline{d}_{j,\partial j})}$$

S: feature vector covariance

$$\overline{d}_{i,\partial i} = \frac{1}{|\partial i|} \sum_{k \in \partial i} d_{i,k}$$

$$\overline{d}_{j,\partial j} = \frac{1}{|\partial j|} \sum_{k \in \partial j} d_{j,k}$$

r,e

Clique potential

Let P denote all neighboring component pairs.
 Then the labels, X, are distributed as

$$p(x) = \frac{1}{Z} \exp \left\{ -\sum_{\{i,j\} \in P} w_{i,j} \delta(x_i \neq x_j) \right\}$$

$$w_{i,j} = \frac{b}{D_{i,j}^p + a} \qquad \text{a, b, and } p \text{ are scalar parameters}$$

- Class probability p(x) decreases from neighboring pairs having different class labels
- \blacksquare Decrease is more pronounced when distance $D_{i,j}$ is small

MAP optimization

 Combining data and prior models, compute the MAP estimate for the optimal set of classification labels X

$$\hat{x}_{MAP} = \underset{x \in \{0,1\}^{N}}{\min} \left\{ -\sum_{i \in S} \log p(y_i \mid x_i) + \sum_{\{i,j\} \in P} w_{i,j} \delta(x_i \neq x_j) - c_{txt} \delta(x_i = 1) \right\}$$

- Ctxt controls the trade-off between missed and false detections
- Approximate solution using iterative conditional modes (ICM)

Step1 : Initialize each class label X_i with ML estimate

Step2: For each component, update label

Step3: If no change occurs to the labels, then stop.
Otherwise go to Step2

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Parameter estimation

- Gaussian mixture parameters in data term estimated using expectation maximization (EM) algorithm
- Prior model parameters, f = [p, a, b], estimated using pseudo-likelihood maximization (Besag, 1975)

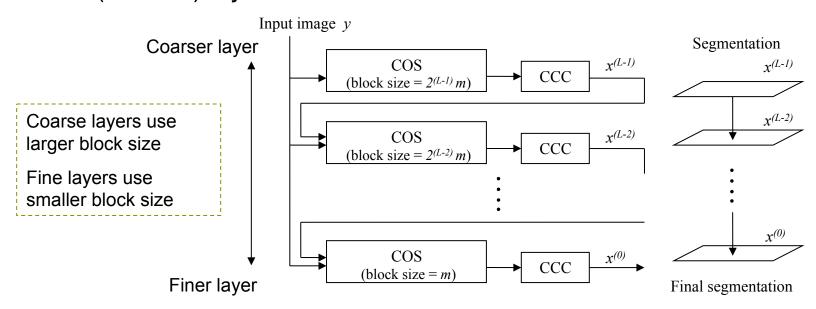
$$\hat{\phi} = \arg \max_{\phi} \prod_{i \in S} p_{\phi}(x_i \mid x_{\partial i})$$

$$= \arg \min_{\phi} \sum_{i \in S} \left\{ \log C_i + \sum_{j \in \partial i} w_{i,j}(\phi) \ \delta(x_i \neq x_j) \right\}$$

$$where \quad C_i = \sum_{x_i \in \{0,1\}} \exp \left\{ -\sum_{j \in \partial i} w_{i,j} \ \delta(x_i \neq x_j) \right\}$$

Multiscale-COS/CCC segmentation

- Incorporation of COS/CCC algorithms into a multiscale framework to improve detection of varying size text
- Progress from coarse to fine scales, where coarser scales use larger COS block size
- Segmentation for each layer incorporates result from previous (coarser) layer



NA.

Cost function for multiscale-COS/CCC

 New term in the COS cost function represents the number of pixel mismatches between current and previous layers

$$Cost(S^{(n)}) = \sum_{i=0}^{M} \sum_{j=0}^{N} \left\{ E(s_{i,j}^{(n)}) + \lambda_1 V_1(s_{i,j-1}^{(n)}, s_{i,j}^{(n)}) + \lambda_2 V_2(s_{i-1,j}^{(n)}, s_{i,j}^{(n)}) + \lambda_3 V_3(s_{i,j}^{(n)}) + \underbrace{\lambda_4 V_4(s_{i,j}^{(n)}, x_{i,j}^{(n+1)})}_{\text{New term}} \right\}$$

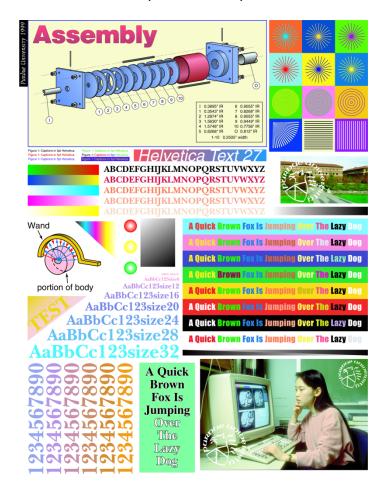
 $S_{i,j}^{(n)}$: Class of block at location (*i,j*) on n_{th} layer.

$$S^{(n)} = \left\{ S_{i,j}^{(n)} \right\}$$

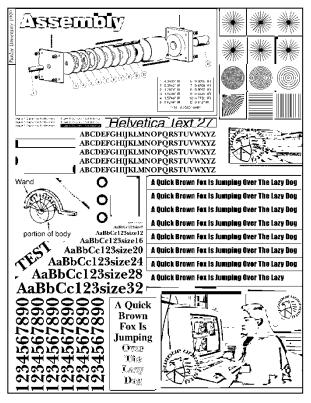
■ The new term V_4 enforces consistency with coarser segmentation results

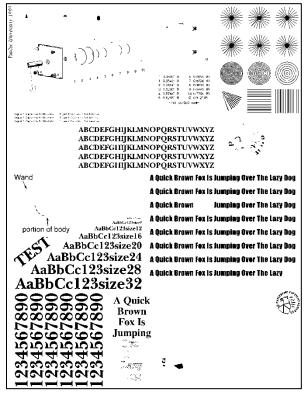
Results for complex test image

Comparison of multiscale-COS/CCC and MRC commercial products: DjVu (LizardTech) and LuraDocument (LuraTech)



Segmentation comparison





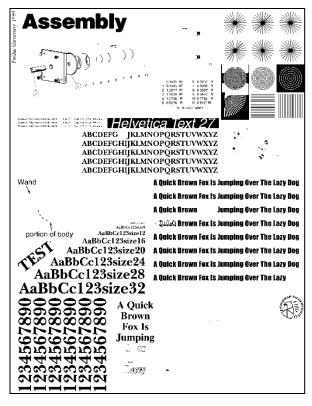


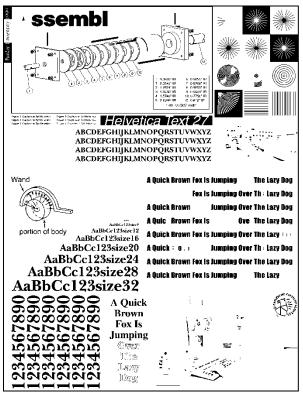
COS only

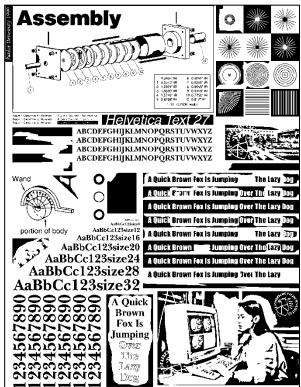
COS/CCC

Multiscale-COS/CCC

Comparison with commercial products







Multiscale-COS/CCC

DjVu

LuraDocument

Closer look (Picture regions)

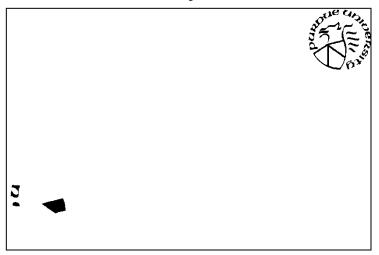


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Original



DjVu



Luratech

Multiscale-COS/CCC

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Closer look (Text regions)

AaBbCc123size4

AaBbCc123size8
Cc123size12

Original

AaBbCc123size4

AaBbCc123size8 Cc123size12

Luratech

AaBh(

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AaBbCc123size8
Cc123size12

DjVu

AaBbCc123size4

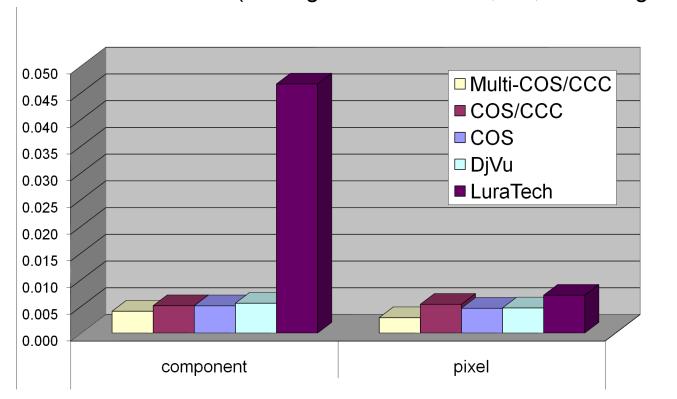
AaBbCc123size8
Cc123size12

Multiscale-COS/CCC

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Segmentation error comparison

Missed text detection % (Averaged over EPSON, HP, Samsung scanners)



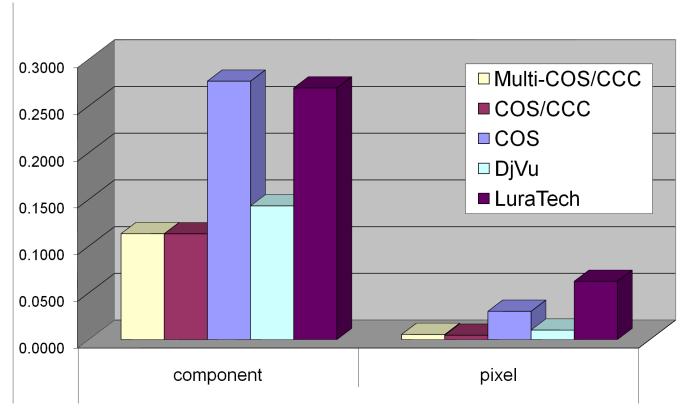
Component = (# missed components) / (# components in ground truth)
Pixel = (# pixels of missed components) / (image size)

Multiscale-COS/CCC has fewer missed detection than the other algorithms

NA.

Segmentation error comparison

False detection % (Averaged over EPSON, HP, Samsung scanners)

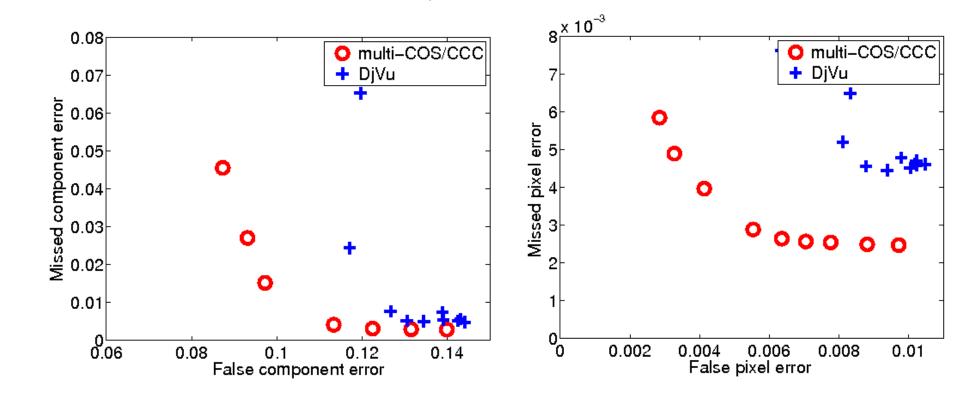


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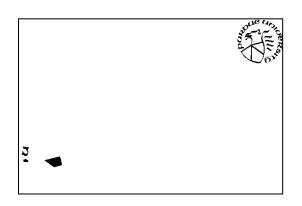
Trade-off between missed and false detections

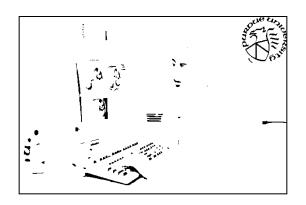
Multiscale-COS/CCC vs. DjVu (Best commercial product)



- Averaged over EPSON, HP, and Samsung scanner data
- Multiscale-COS/CCC has superior error rates over DjVu

Decoded MRC image comparison #1













Multiscale-COS/CCC (289:1)

DjVu (281:1)

LuraDocument (242:1)



Decoded MRC image comparison #2

Multiscale-COS/CCC (289:1)

AaBbCc123size4

AaBbCc123size8

AaBbCc123size4

AaBbCc123size8

Cc123size12 Cc123size12

DjVu (281:1) AaBb(

AaBbCc123size8

AaBbC | 128-11-1

AaBbCc123size8

Cc123size12 Cc123size12

LuraDocument (242:1)

AaBbCc123size4

AaBbCc123size8

AaBbCc123size4

AaBbCc123size8

Cc123size12 Cc123size12



Summary

- Developed three novel algorithms for text segmentation: COS, COS/CCC, Multiscale-COS/CCC
 - □ Accurate text extraction compared to commercial products
 - ☐ Flexible for future developments
 - Robust over various paper materials, scanner types, and various image backgrounds
- Can extend segmentation to other applications such as Optical Character Recognition (OCR)



Publications/Patents

- Multiscale text segmentation for MRC document (Two conference papers, One journal paper, One patent)
 - □ "Segmentation for MRC compression," in Proc. of SPIE Conf. on Color Imaging XII, 2007
 - "Multiscale segmentation for MRC compression using a Markov Random Field (MRF) model" in IEEE ICASSP, March 2010
 - "Text segmentation for MRC document compression" accepted by IEEE Trans. on Image Processing on Oct 2010
 - □ Patents: combined declaration by Samsung Co. Ltd and Purdue University, United States
- Next generation image capture device development (Two patents for snap-to-white algorithm)
 - Apparatus and method of segmenting an image in an image coding and/or decoding system
 Application 20080175477
 - Auto-cropping method for image capture device Application 20090323129

Reference

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- 3. P. Stathis, E. Kavallieratou, and N. Papamarkos, "An evaluation survey of binarization algorithms on historical documents," in 19th International Conference on Pattern Recognition, 2008, pp. 1–4.
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