

## 0/17 Questions Answered

## ECE641-F2020-M

## Q1

2 Points

**Rules:** I understand that this is an open book exam that shall be done within the allotted time of 120 minutes. I can use my notes, previous posted exams and exam solutions, and web resources. However, I will not communicate with any other person other than the official exam proctors during the exam, and I will not seek or accept help from any other persons other than the official proctors.

*Upload a scan of your signature here:*



Please select file(s)

Select file(s)

Save Answer

## Q2 MAP Estimation

36 Points

Consider a sensing system with the forward model given by

$$y = Ax + w$$

where  $x \sim N(0, R_x)$  and  $w \sim N(0, R_w)$  and  $A \in \mathbb{R}^{M \times N}$  where  $M < N$ .

## Q2.1

6 Points

Derive an expression for the forward model  $p(y|x)$  and the prior

Choose Files

No file chosen



Please select file(s)

Select file(s)

Save Answer

**Q2.2**

6 Points

Is the maximum likelihood estimate (MLE) well defined and unique? If yes, give the MLE. If no, justify your answer.



Please select file(s)

Select file(s)

Save Answer

**Q2.3**

6 Points

Are the MMSE estimate and the MAP estimate different? Justify your answer.

Enter your answer here

Save Answer

**Q2.4**

6 Points

Derive a closed form expression for the MAP estimate of  $x$  given  $y$ .



Please select file(s)

Select file(s)

Save Answer

**Q2.5**

Choose Files

No file chosen

---

6 Points

Calculate an expression for the gradient descent update using step size  $\alpha \geq 0$ .

 Please select file(s)

Select file(s)

Save Answer

**Q2.6**

6 Points

Calculate an expression for the coordinate descent update.

 Please select file(s)

Select file(s)

Save Answer

**Q3 Surrogate Functions**

35 Points

Consider a problem in which our goal is to minimize a function with the form

$$f(x) = \frac{1}{2}x^t Bx + b^t x$$

where  $B \in \Re^{N \times N}$  is a positive definite matrix and  $b \in \Re^N$  is a vector.

The goal of this problem will be to find a simplified surrogate function for  $f(x)$ . Furthermore, assume  $B$  is large, and the number of non-zero entries in  $B$  is  $NM_o$  where  $M_o \ll N$ .

**Q3.1**

7 Points

Derive an expression for the solution of

Choose Files No file chosen

$$\hat{x} = \arg \min_x f(x) .$$

 Please select file(s)

Select file(s)

Save Answer

### Q3.2

7 Points

Within a multiplicative constant, how many operations are required for the solution of part 3.1 above? Why is this computationally difficult?

 Please select file(s)

Select file(s)

Save Answer

### Q3.3

7 Points

Derive a surrogate function for  $f(x)$  with the form

$$\tilde{f}(x; x') = \frac{\alpha}{2} \|x\|^2 + c^t x$$

where  $\alpha \in \mathbb{R}$  and  $c \in \mathbb{R}^N$  are dependent on the point-of-approximation  $x'$ .

 Please select file(s)

Select file(s)

Save Answer

### Q3.4

7 Points

Derive the majorization minimization algorithm based on iterative minimization of the surrogate function  $\tilde{f}(x; x')$ .

 Please select file(s)

Select file(s)

Choose Files No file chosen

[Save Answer](#)**Q3.5**

7 Points

How many multiplications are required for each step of the majorization minimization algorithm in part 3.4 above? Why is this computationally efficient?



Please select file(s)

[Select file\(s\)](#)[Save Answer](#)**Q4 ADMM and PnP**

28 Points

Consider the MAP estimation problem with the form

$$\hat{x} = \arg \min_x \{f(x) + h(x)\}$$

where  $f(x) = -\log p(y|x)$  is the forward model and  $h(x) = -\log p(x)$  is the prior model.

**Q4.1**

7 Points

Use variable splitting along with the augmented Lagrangian method to derive an algorithm for solving this problem.



Please select file(s)

[Select file\(s\)](#)[Save Answer](#)**Q4.2**

7 Points

[Choose Files](#)

No file chosen

Derive the associated ADMM algorithm for solving this problem. Express your algorithm in terms of the two proximal maps  $F(v)$  and  $H(v)$ , and also give precise expressions for the forms of the two proximal maps.

 Please select file(s)

Select file(s)

Save Answer

### Q4.3

7 Points

Give the plug and play algorithm for solving the associated problem

$$\begin{aligned}x^* &= F(x - u) \\x^* &= \tilde{H}(x + u)\end{aligned}$$

where  $\tilde{H}$  is not necessarily a proximal map.

 Please select file(s)

Select file(s)

Save Answer

### Q4.4

7 Points

Describe how the function  $\tilde{H}$  can be learned using a training algorithm.

 Please select file(s)

Select file(s)

Save Answer

### Q5

3 Points

The Chinese general, Sun Tzu, wrote that "Strategy without tactics is the slowest route to victory. Tactics without strategy is the noise before

defeat."

Explain what this means, and give an example of how this advice can be of value in research.

Enter your answer here

Save Answer

Save All Answers

Submit & View Submission >